



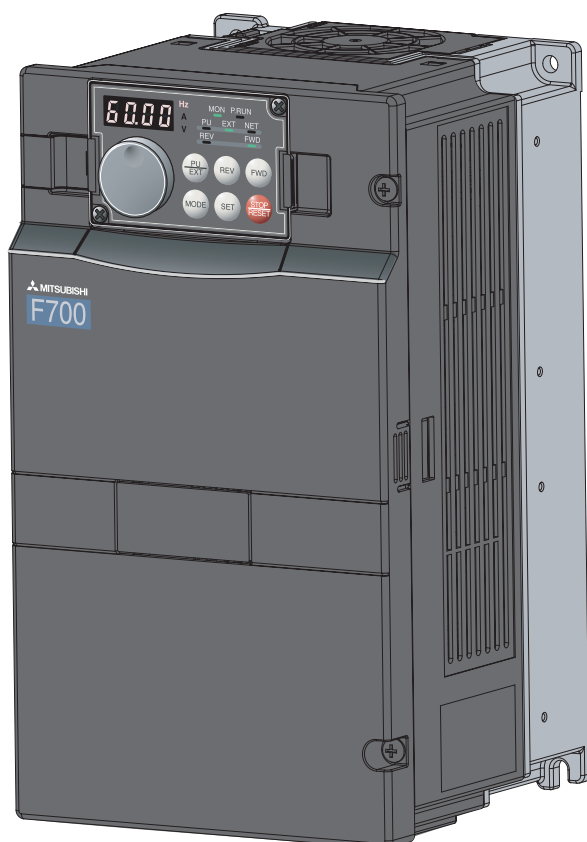
# INVERTER

## F700



# INSTRUCTION MANUAL (Applied)

## FR-F720-00046 to 04750-NA FR-F740-00023 to 12120-NA



WIRING

1

PRECAUTIONS FOR USE  
OF THE INVERTER

2

PARAMETERS

3

PROTECTIVE FUNCTIONS

4

SPECIFICATIONS

5

Thank you for choosing this Mitsubishi Inverter.

This Instruction Manual (applied) provides instructions for advanced use of the FR-F700 series inverters.

Incorrect handling might cause an unexpected fault. Before using the inverter, always read this instruction manual and the instruction manual (basic) [IB-0600216ENG] packed with the product carefully to use the equipment to its optimum.

### This section is specifically about safety matters

Do not attempt to install, operate, maintain or inspect the inverter until you have read through instruction manual (basic) and appended documents carefully and can use the equipment correctly. Do not use the inverter until you have a full knowledge of the equipment, safety information and instructions. In this instruction manual, the safety instruction levels are classified into "WARNING" and "CAUTION".

#### WARNING

Assumes that incorrect handling may cause hazardous conditions, resulting in death or severe injury.

#### CAUTION

Assumes that incorrect handling may cause hazardous conditions, resulting in medium or slight injury, or may cause physical damage only.

Note that even the  CAUTION level may lead to a serious consequence according to conditions. Please follow strictly the instructions of both levels because they are important to personnel safety.

### 1. Electric Shock Prevention

#### WARNING

- While power is on or when the inverter is running, do not open the front cover. Otherwise you may get an electric shock.
- Do not run the inverter with the front cover or wiring cover removed. Otherwise, you may access the exposed high-voltage terminals or the charging part of the circuitry and get an electric shock.
- Even if power is off, do not remove the front cover except for wiring or periodic inspection. You may access the charged inverter circuits and get an electric shock.
- Before starting wiring or inspection, check to make sure that the operation panel indicator is off, wait for at least 10 minutes after the power supply has been switched off, and check that there are no residual voltage using a tester or the like. The capacitor is charged with high voltage for some time after power off and it is dangerous.
- This inverter must be grounded. Grounding must conform to the requirements of national and local safety regulations and electrical codes. (JIS, NEC section 250, IEC 536 class 1 and other applicable standards)
- Any person who is involved in the wiring or inspection of this equipment should be fully competent to do the work.
- Always install the inverter before wiring. Otherwise, you may get an electric shock or be injured.
- Perform setting dial and key operations with dry hands to prevent an electric shock. Otherwise you may get an electric shock.
- Do not subject the cables to scratches, excessive stress, heavy loads or pinching. Otherwise you may get an electric shock.
- Do not replace the cooling fan while power is on. It is dangerous to replace the cooling fan while power is on.
- Do not touch the printed circuit board with wet hands. You may get an electric shock.

### 2. Fire Prevention

#### CAUTION

- Mount the inverter to incombustible material. Mounting it to or near combustible material can cause a fire.
- If the inverter has become faulty, switch off the inverter power. A continuous flow of large current could cause a fire.
- Do not connect a resistor directly to the DC terminals P/+, N/-. This could cause a fire.

### 3. Injury Prevention

#### CAUTION

- Apply only the voltage specified in the instruction manual to each terminal. Otherwise, burst, damage, etc. may occur.
- Ensure that the cables are connected to the correct terminals. Otherwise, burst, damage, etc. may occur.
- Always make sure that polarity is correct to prevent damage, etc. Otherwise, burst, damage, etc. may occur.
- While power is on or for some time after power-off, do not touch the inverter as it is hot and you may get burnt.

### 4. Additional Instructions

Also note the following points to prevent an accidental failure, injury, electric shock, etc.

#### (1) Transportation and installation

#### CAUTION

- When carrying products, use correct lifting gear to prevent injury.
- Do not stack the inverter boxes higher than the number recommended.
- Ensure that installation position and material can withstand the weight of the inverter. Install according to the information in the instruction manual.
- Do not install or operate the inverter if it is damaged or has parts missing. This can result in breakdowns.
- When carrying the inverter, do not hold it by the front cover or setting dial; it may fall off or fail.
- Do not stand or rest heavy objects on the product.
- Check the inverter mounting orientation is correct.
- Prevent other conductive bodies such as screws and metal fragments or other flammable substance such as oil from entering the inverter.
- As the inverter is a precision instrument, do not drop or subject it to impact.
- Use the inverter under the following environmental conditions. Otherwise, the inverter may be damaged.

|             |                     |                       |                                                                                                                                                                                                                            |
|-------------|---------------------|-----------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Environment | Ambient temperature | LD                    | -10°C to +50°C (14°F to 122°F)(non-freezing)                                                                                                                                                                               |
|             |                     | SLD (initial setting) | -10°C to +40°C (14°F to 104°F)(non-freezing)                                                                                                                                                                               |
|             | Ambient humidity    |                       | 90% RH or less (non-condensing)                                                                                                                                                                                            |
|             | Storage temperature |                       | -20°C to +65°C *1 (-4°F to 149°F)                                                                                                                                                                                          |
|             | Atmosphere          |                       | Indoors (free from corrosive gas, flammable gas, oil mist, dust and dirt)                                                                                                                                                  |
|             | Altitude, vibration |                       | Maximum 1000m (3280.80feet) above sea level for standard operation. After that derate by 3% for every extra 500m (1640.40feet) up to 2500m (8202feet) (92%) 5.9m/s <sup>2</sup> or less *2 (conforming to JIS C 60068-2-6) |

\*1 Temperature applicable for a short time, e.g. in transit.

\*2 2.9m/s<sup>2</sup> or less for the FR-F740-04320 or more.

#### (2) Wiring

#### CAUTION

- Do not install a power factor correction capacitor or surge suppressor on the inverter output side.
- The connection orientation of the output cables U, V, W to the motor will affect the direction of rotation of the motor.

#### (3) Test operation and adjustment

#### CAUTION

- Before starting operation, confirm and adjust the parameters. A failure to do so may cause some machines to make unexpected motions.

#### (4) Operation

#### WARNING

- When you have chosen the retry function, stay away from the equipment as it will restart suddenly after an alarm stop.
- The  key is valid only when the appropriate function setting has been made. Prepare an emergency stop switch separately.
- Make sure that the start signal is off before resetting the inverter alarm. A failure to do so may restart the motor suddenly.
- The load used should be a three-phase induction motor only. Connection of any other electrical equipment to the inverter output may damage the inverter as well as equipment.
- Do not modify the equipment.
- Do not perform parts removal which is not instructed in this manual. Doing so may lead to fault or damage of the inverter.

#### CAUTION

- The electronic thermal relay function does not guarantee protection of the motor from overheating.
- Do not use a magnetic contactor on the inverter input for frequent starting/stopping of the inverter.
- Use a noise filter to reduce the effect of electromagnetic interference. Otherwise nearby electronic equipment may be affected.
- Take measures to suppress harmonics. Otherwise power supply harmonics from the inverter may heat/damage the power factor correction capacitor and generator.
- When a 400V class motor is inverter-driven, please use an insulation-enhanced motor or measures taken to suppress surge voltages. Surge voltages attributable to the wiring constants may occur at the motor terminals, deteriorating the insulation of the motor.
- When parameter clear or all clear is performed, reset the required parameters before starting operations. Each parameter returns to the initial value.
- The inverter can be easily set for high-speed operation. Before changing its setting, fully examine the performances of the motor and machine.
- In addition to the inverter's holding function, install a holding device to ensure safety.
- Before running an inverter which had been stored for a long period, always perform inspection and test operation.
- For prevention of damage due to static electricity, touch nearby metal before touching this product to eliminate static electricity from your body.

#### (5) Emergency stop

#### CAUTION

- Provide a safety backup such as an emergency brake which will prevent the machine and equipment from hazardous conditions if the inverter fails.
- When the breaker on the inverter input side trips, check for the wiring fault (short circuit), damage to internal parts of the inverter, etc. Identify the cause of the trip, then remove the cause and power on the breaker.
- When the protective function is activated, take the corresponding corrective action, then reset the inverter, and resume operation.

#### (6) Maintenance, inspection and parts replacement

#### CAUTION

- Do not carry out a megger (insulation resistance) test on the control circuit of the inverter.

#### (7) Disposing of the inverter

#### CAUTION

- Treat as industrial waste.

#### General instructions

Many of the diagrams and drawings in this instruction manual show the inverter without a cover, or partially open. Never run the inverter in this status. Always replace the cover and follow this instruction manual when operating the inverter.

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# 1 WIRING

This chapter describes the basic "WIRING" for use of this product.

Always read the instructions before using the equipment

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| 1.5 | Connection of stand-alone option units ..... | 22 |

## <Abbreviations>

|                                        |                                                                           |
|----------------------------------------|---------------------------------------------------------------------------|
| DU .....                               | Operation panel (FR-DU07)                                                 |
| PU .....                               | Operation panel (FR-DU07) and parameter unit (FR-PU04)                    |
| Inverter .....                         | Mitsubishi inverter FR-F700 series                                        |
| FR-F700 .....                          | Mitsubishi inverter FR-F700 series                                        |
| Pr. ....                               | Parameter Number                                                          |
| PU operation .....                     | Operation using the PU (FR-DU07/FR-PU04).                                 |
| External operation .....               | Operation using the control circuit signals                               |
| Combined operation .....               | Combined operation using the PU (FR-DU07/FR-PU04) and external operation. |
| Mitsubishi standard motor .....        | SF-JR                                                                     |
| Mitsubishi constant-torque motor ..... | SF-HRCA                                                                   |

## <Trademarks>

- LONWORKS is a registered trademark of Echelon Corporation in the U.S.A
- Other company and product names herein are the trademarks and registered trademarks of their respective owners.

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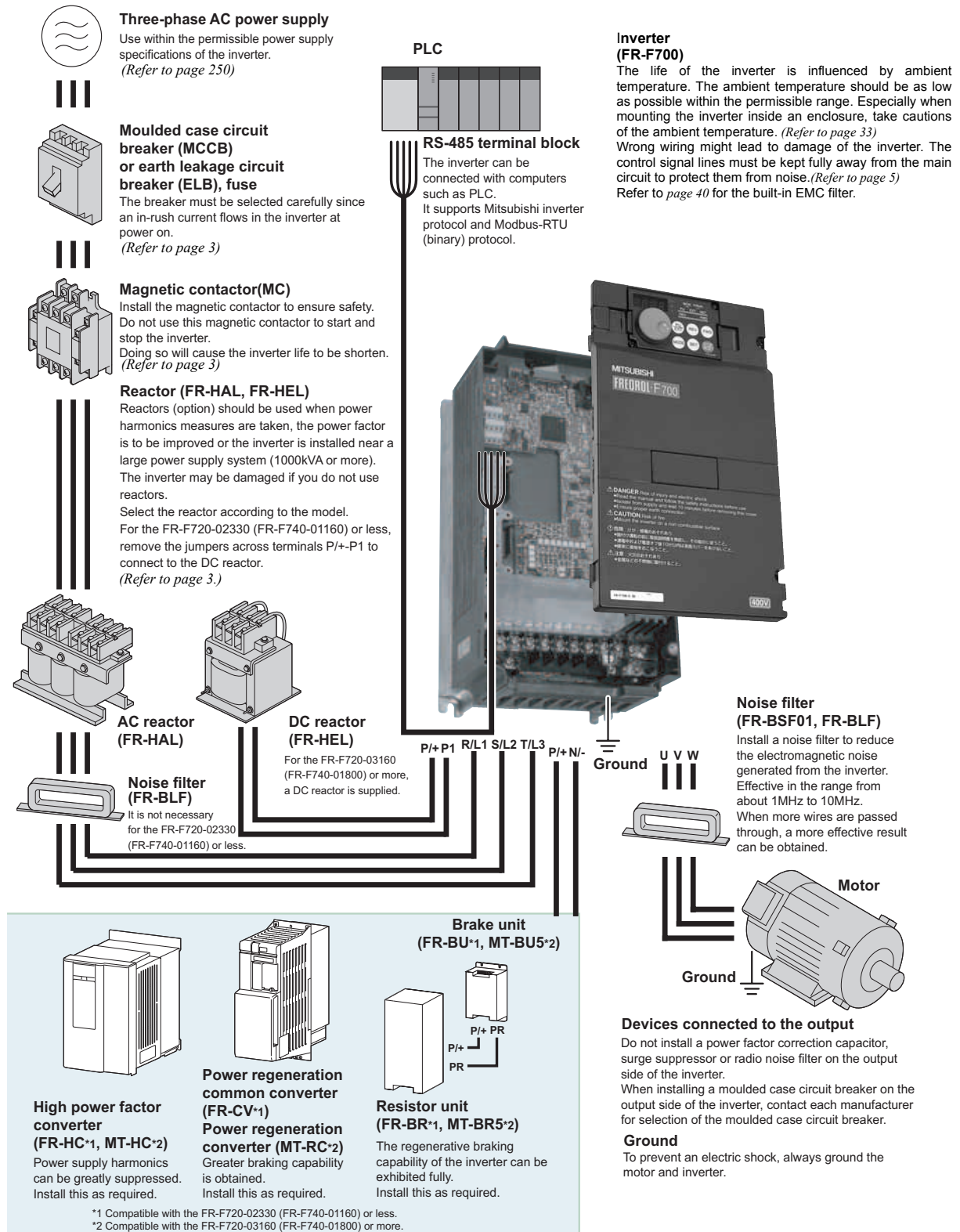
3

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5



## 1.1 Inverter and peripheral devices



### CAUTION

- Do not install a power factor correction capacitor or surge suppressor on the inverter output side. This will cause the inverter to trip or the capacitor, and surge suppressor to be damaged. If any of the above devices are connected, immediately remove them.
- Electromagnetic wave interference  
The input/output (main circuit) of the inverter includes high frequency components, which may interfere with the communication devices (such as AM radios) used near the inverter. In this case, set the EMC filter valid to minimize interference.  
(Refer to page 40.)
- Refer to the instruction manual of each option and peripheral devices for details of peripheral devices.



### 1.1.1 Peripheral devices

Check the motor capacity of the inverter you purchased. Appropriate peripheral devices must be selected according to the capacity. Refer to the following list and prepare appropriate peripheral devices:

#### 200V class

| Motor Output (kW(HP))<br>*1 | Applicable Inverter Type | Breaker Selection*2,4 |            |                                        | Input Side Magnetic Contactor*3 |            |
|-----------------------------|--------------------------|-----------------------|------------|----------------------------------------|---------------------------------|------------|
|                             |                          | Reactor connection    |            | with commercial power-supply operation | Reactor connection              |            |
|                             |                          | without               | with       |                                        | without                         | with       |
| 0.75 (1)                    | FR-F720-00046-NA         | 30AF 10A              | 30AF 10A   | 30AF 10A                               | S-N10                           | S-N10      |
| 1.5 (2)                     | FR-F720-00077-NA         | 30AF 15A              | 30AF 15A   | 30AF 15A                               | S-N10                           | S-N10      |
| 2.2 (3)                     | FR-F720-00105-NA         | 30AF 20A              | 30AF 15A   | 30AF 20A                               | S-N10                           | S-N10      |
| 3.7 (5)                     | FR-F720-00167-NA         | 30AF 30A              | 30AF 30A   | 30AF 30A                               | S-N20, N21                      | S-N10      |
| 5.5 (7.5)                   | FR-F720-00250-NA         | 50AF 50A              | 50AF 40A   | 50AF 50A                               | S-N25                           | S-N20, N21 |
| 7.5 (10)                    | FR-F720-00340-NA         | 100AF 60A             | 50AF 50A   | 100AF 60A                              | S-N25                           | S-N25      |
| 11 (15)                     | FR-F720-00490-NA         | 100AF 75A             | 100AF 75A  | 100AF 75A                              | S-N35                           | S-N35      |
| 15 (20)                     | FR-F720-00630-NA         | 225AF 125A            | 100AF 100A | 225AF 125A                             | S-N50                           | S-N50      |
| 18.5 (25)                   | FR-F720-00770-NA         | 225AF 150A            | 225AF 125A | 225AF 150A                             | S-N65                           | S-N50      |
| 22 (30)                     | FR-F720-00930-NA         | 225AF 175A            | 225AF 150A | 225AF 175A                             | S-N80                           | S-N65      |
| 30 (40)                     | FR-F720-01250-NA         | 225AF 225A            | 225AF 175A | 225AF 225A                             | S-N95                           | S-N80      |
| 37 (50)                     | FR-F720-01540-NA         | 400AF 250A            | 225AF 225A | 400AF 250A                             | S-N150                          | S-N125     |
| 45 (60)                     | FR-F720-01870-NA         | 400AF 300A            | 400AF 300A | 400AF 350A                             | S-N180                          | S-N150     |
| 55 (75)                     | FR-F720-02330-NA         | 400AF 400A            | 400AF 350A | 600AF 500A                             | S-N220                          | S-N180     |
| 75 (100)                    | FR-F720-03160-NA         | —                     | 400AF 400A | 400AF 400A                             | —                               | S-N300     |
| 90 (125)                    | FR-F720-03800-NA         | —                     | 400AF 400A | 600AF 500A                             | —                               | S-N300     |
| 110 (150)                   | FR-F720-04750-NA         | —                     | 600AF 500A | 600AF 600A                             | —                               | S-N400     |

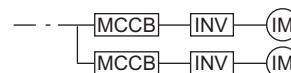
\*1 Selections for use of the Mitsubishi 4-pole standard motor with power supply voltage of 200VAC 50Hz.

\*2 Select the MCCB according to the inverter power supply capacity.

Install one MCCB per inverter.

For installations in the United States or Canada, use the fuse certified by the UL and cUL.

(Refer to the Instruction Manual (basics).)



\*3 The electrical durability of magnetic contactor is 500,000 times. When the magnetic contactor is used for emergency stop during motor driving, the electrical durability is 25 times.

When using the MC for emergency stop during motor driving or using on the motor side during commercial-power supply operation, select the MC with class AC-3 rated current for the motor rated current.

\*4 When the breaker on the inverter primary side trips, check for the wiring fault (short circuit), damage to internal parts of the inverter, etc. Identify the cause of the trip, then remove the cause and power on the breaker.



## 400V class

| Motor Output<br>(kW(HP))<br>*1 | Applicable Inverter Type | Breaker Selection*2,4 |              |                                        | Input Side Magnetic Contactor*3 |                        |
|--------------------------------|--------------------------|-----------------------|--------------|----------------------------------------|---------------------------------|------------------------|
|                                |                          | Reactor connection    |              | with commercial power-supply operation | Reactor connection              |                        |
|                                |                          | without               | with         |                                        | without                         | with                   |
| 0.75 (1)                       | FR-F740-00023-NA         | 30AF 5A               | 30AF 5A      | 30AF 5A                                | S-N10                           | S-N10                  |
| 1.5 (2)                        | FR-F740-00038-NA         | 30AF 10A              | 30AF 10A     | 30AF 10A                               | S-N10                           | S-N10                  |
| 2.2 (3)                        | FR-F740-00052-NA         | 30AF 10A              | 30AF 10A     | 30AF 15A                               | S-N10                           | S-N10                  |
| 3.7 (5)                        | FR-F740-00083-NA         | 30AF 20A              | 30AF 15A     | 30AF 20A                               | S-N10                           | S-N10                  |
| 5.5 (7.5)                      | FR-F740-00126-NA         | 30AF 30A              | 30AF 20A     | 30AF 30A                               | S-N20                           | S-N11, N12             |
| 7.5 (10)                       | FR-F740-00170-NA         | 30AF 30A              | 30AF 30A     | 30AF 30A                               | S-N20                           | S-N20                  |
| 11 (15)                        | FR-F740-00250-NA         | 50AF 50A              | 50AF 40A     | 50AF 50A                               | S-N20                           | S-N20                  |
| 15 (20)                        | FR-F740-00310-NA         | 100AF 60A             | 50AF 50A     | 100AF 60A                              | S-N25                           | S-N20                  |
| 18.5 (25)                      | FR-F740-00380-NA         | 100AF 75A             | 100AF 60A    | 100AF 75A                              | S-N25                           | S-N25                  |
| 22 (30)                        | FR-F740-00470-NA         | 100AF 100A            | 100AF 75A    | 100AF 100A                             | S-N35                           | S-N25                  |
| 30 (40)                        | FR-F740-00620-NA         | 225AF 125A            | 225AF 100A   | 225AF 125A                             | S-N50                           | S-N50                  |
| 37 (50)                        | FR-F740-00770-NA         | 225AF 150A            | 225AF 125A   | 225AF 150A                             | S-N65                           | S-N50                  |
| 45 (60)                        | FR-F740-00930-NA         | 225AF 175A            | 225AF 150A   | 225AF 175A                             | S-N80                           | S-N65                  |
| 55 (75)                        | FR-F740-01160-NA         | 225AF 200A            | 225AF 175A   | 225AF 200A                             | S-N80                           | S-N80                  |
| 75 (100)                       | FR-F740-01800-NA         | —                     | 225AF 225A   | 225AF 225A                             | —                               | S-N95                  |
| 90 (125)                       | FR-F740-01800-NA         | —                     | 225AF 225A   | 400AF 300A                             | —                               | S-N150                 |
| 110 (150)                      | FR-F740-02160-NA         | —                     | 225AF 225A   | 400AF 350A                             | —                               | S-N180                 |
| 132 (200)                      | FR-F740-02600-NA         | —                     | 400AF 400A   | 400AF 400A                             | —                               | S-N220                 |
| 160 (250)                      | FR-F740-03250-NA         | —                     | 400AF 400A   | 600AF 500A                             | —                               | S-N300                 |
| 185 (300)                      | FR-F740-03610-NA         | —                     | 400AF 400A   | 600AF 500A                             | —                               | S-N300                 |
| 220 (350)                      | FR-F740-04320-NA         | —                     | 600AF 500A   | 600AF 600A                             | —                               | S-N400                 |
| 250 (400)                      | FR-F740-04810-NA         | —                     | 600AF 600A   | 600AF 600A                             | —                               | S-N600                 |
| 280 (450)                      | FR-F740-05470-NA         | —                     | 600AF 600A   | 800AF 800A                             | —                               | S-N600                 |
| 315 (500)                      | FR-F740-06100-NA         | —                     | 800AF 700A   | 800AF 800A                             | —                               | S-N600                 |
| 355 (550)                      | FR-F740-06830-NA         | —                     | 800AF 800A   | 800AF 800A                             | —                               | S-N600                 |
| 400 (600)                      | FR-F740-07700-NA         | —                     | 1000AF 900A  | 1000AF 1000A                           | —                               | S-N800                 |
| 450 (700)                      | FR-F740-08660-NA         | —                     | 1000AF 1000A | 1000AF 1000A                           | —                               | 1000A<br>Rated product |
| 500 (750)                      | FR-F740-09620-NA         | —                     | 1200AF 1200A | 1200AF 1200A                           | —                               | 1000A<br>Rated product |
| 560 (800)                      | FR-F740-10940-NA         | —                     | 1600AF 1500A | 1600AF 1600A                           | —                               | 1200A<br>Rated product |
| 630 (850)                      | FR-F740-12120-NA         | —                     | 2000AF 2000A | 2000AF 2000A                           | —                               | 1400A<br>Rated product |

\*1 Selections for use of the Mitsubishi 4-pole standard motor with power supply voltage of 400VAC 50Hz.

\*2 Select the MCCB according to the inverter power supply capacity.

Install one MCCB per inverter.

For installations in the United States or Canada, use the fuse certified by the UL and cUL.

(Refer to the Instruction Manual (basics).)



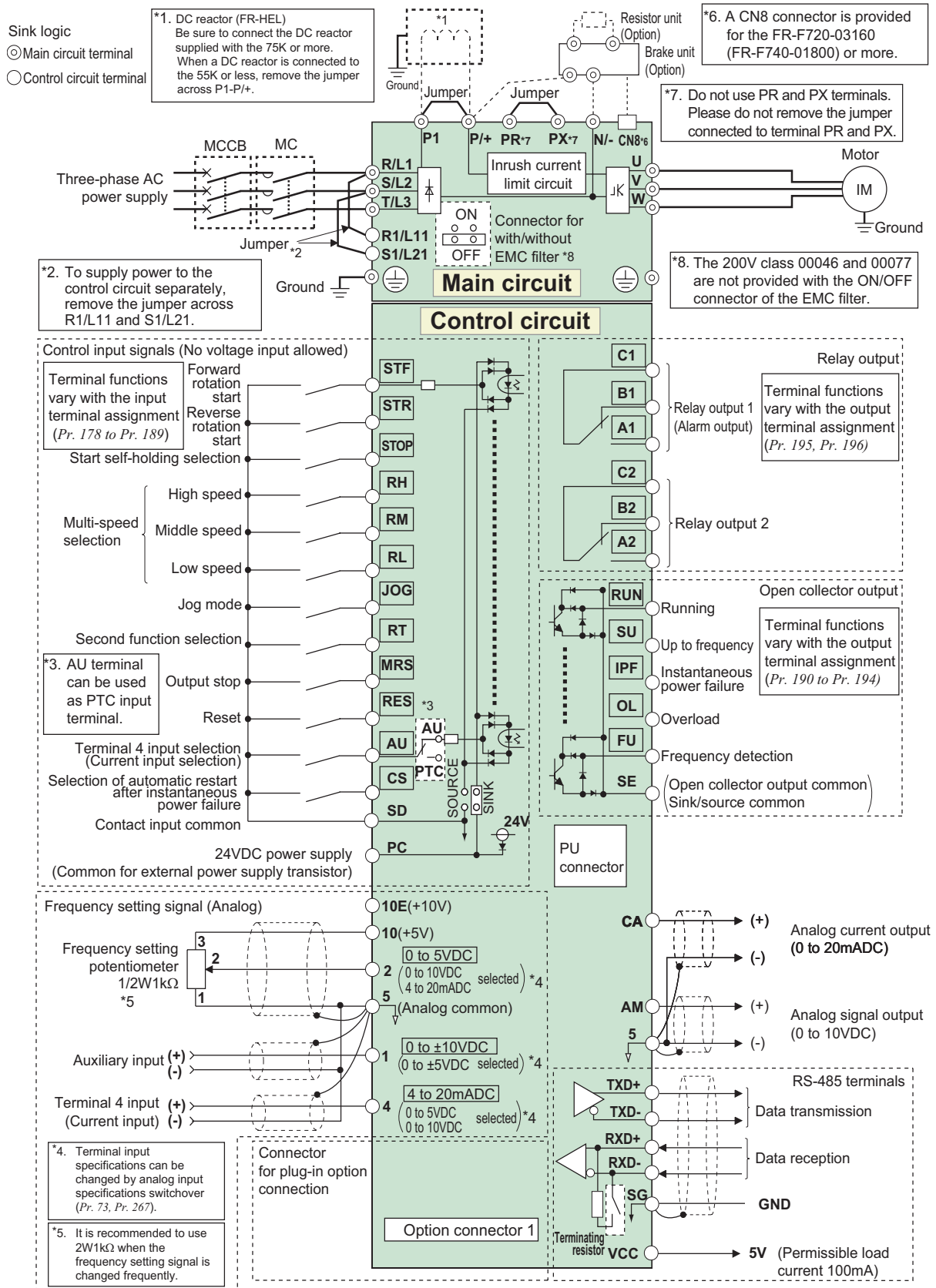
\*3 The electrical durability of magnetic contactor is 500,000 times. When the magnetic contactor is used for emergency stop during motor driving, the electrical durability is 25 times.

When using the MC for emergency stop during motor driving or using on the motor side during commercial-power supply operation, select the MC with class AC-3 rated current for the motor rated current.

\*4 When the breaker on the inverter primary side trips, check for the wiring fault (short circuit), damage to internal parts of the inverter, etc. Identify the cause of the trip, then remove the cause and power on the breaker.

## 1.2 Wiring

### 1.2.1 Terminal connection diagram



#### CAUTION

- To prevent a malfunction due to noise, keep the signal cables more than 10cm (3.94inches) away from the power cables.
- After wiring, wire offcuts must not be left in the inverter. Wire offcuts can cause an alarm, failure or malfunction. Always keep the inverter clean.
- When drilling mounting holes in an enclosure etc., take care not to allow chips and other foreign matter to enter the inverter.



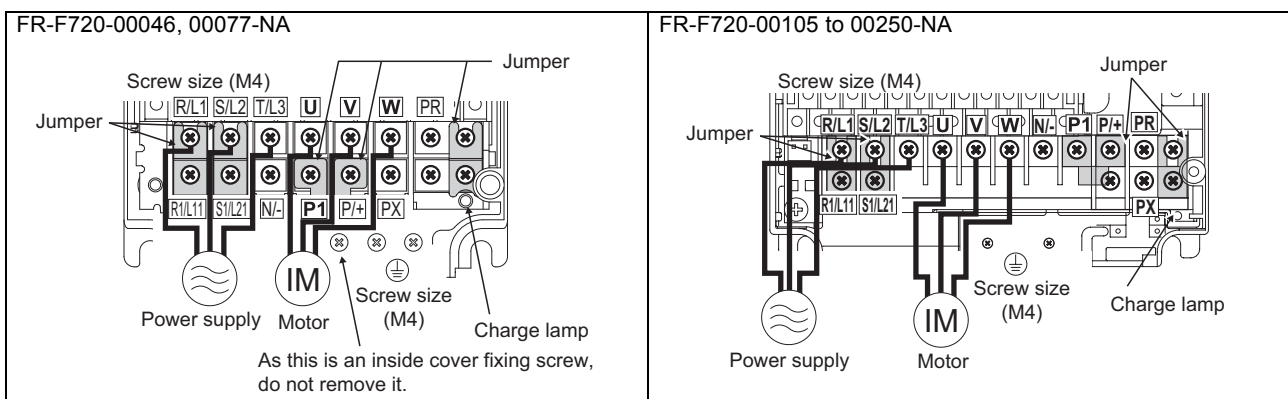
## 1.3 Main circuit terminal specifications

### 1.3.1 Specification of main circuit terminal

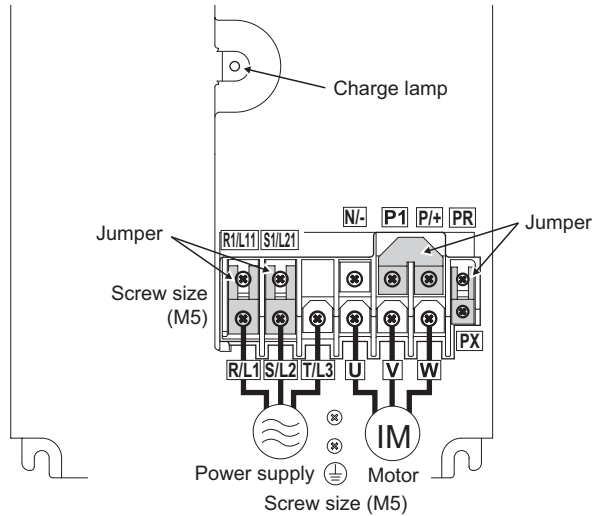
| Terminal Symbol                                                                     | Terminal Name                                                            | Description                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |
|-------------------------------------------------------------------------------------|--------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| R/L1,<br>S/L2,<br>T/L3                                                              | AC power input                                                           | Connect to the commercial power supply.<br>Keep these terminals open when using the high power factor converter (FR-HC, MT-HC) or power regeneration common converter (FR-CV).                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |
| U, V, W                                                                             | Inverter output                                                          | Connect a three-phase squirrel-cage motor.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |
| R1/L11,<br>S1/L21                                                                   | Power supply for control circuit                                         | Connected to the AC power supply terminals R/L1 and S/L2. To retain the alarm display and alarm output or when using the high power factor converter (FR-HC, MT-HC) or power regeneration common converter (FR-CV), remove the jumpers from terminals R/L1-R1/L11 and S/L2-S1/L21 and apply external power to these terminals.<br>Do not turn off the power supply for control circuit (R1/L11, S1/L21) with the main circuit power (R/L1, S/L2, T/L3) on. Doing so may damage the inverter. The circuit should be configured so that the main circuit power (R/L1, S/L2, T/L3) is also turned off when the power supply for control circuit (R1/L11, S1/L21) is off.<br>FR-F720-00770 (FR-F740-00380) or less : 60VA,<br>FR-F720-00930 (FR-F740-00470) or more : 80VA |
| P/+, N/-                                                                            | Brake unit connection                                                    | Connect the brake unit (FR-BU, BU and MT-BU5), power regeneration common converter (FR-CV), high power factor converter (FR-HC and MT-HC) or power regeneration converter (MT-RC).                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |
| P/+, P1                                                                             | DC reactor connection                                                    | For the FR-F720-02330 (FR-F740-01160) or less, remove the jumper across terminals P/+ - P1 and connect the DC reactor. (For the FR-F720-03160 (FR-F740-01800) or more, a DC reactor is supplied as standard.)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |
| PR, PX                                                                              | Please do not remove or use terminals PR and PX or the jumper connected. |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |
|  | Ground                                                                   | For grounding the inverter chassis. Must be grounded.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |

### 1.3.2 Terminal arrangement of the main circuit terminal, power supply and the motor wiring.

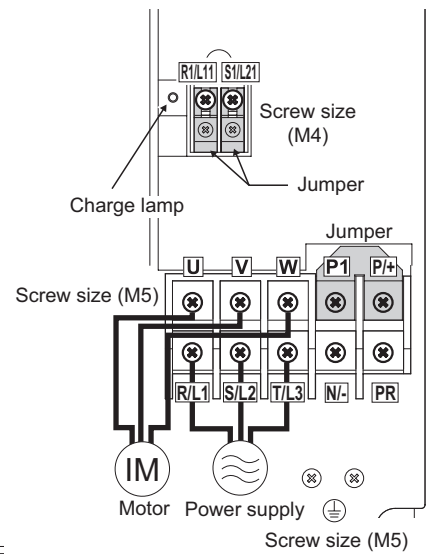
#### 200V class



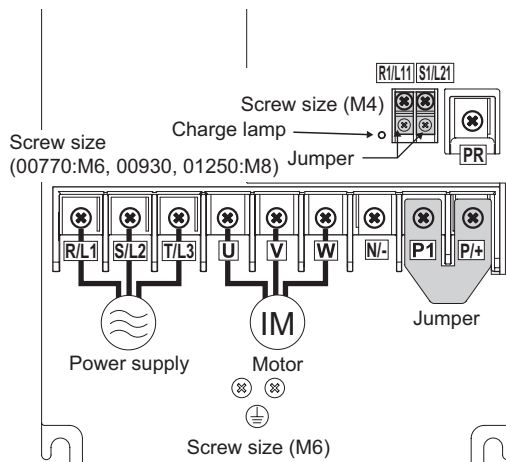
FR-F720-00340, 00490-NA



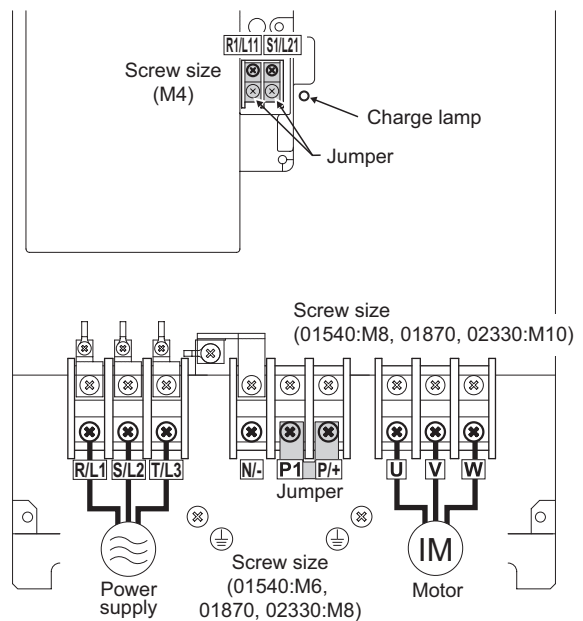
FR-F720-00630-NA



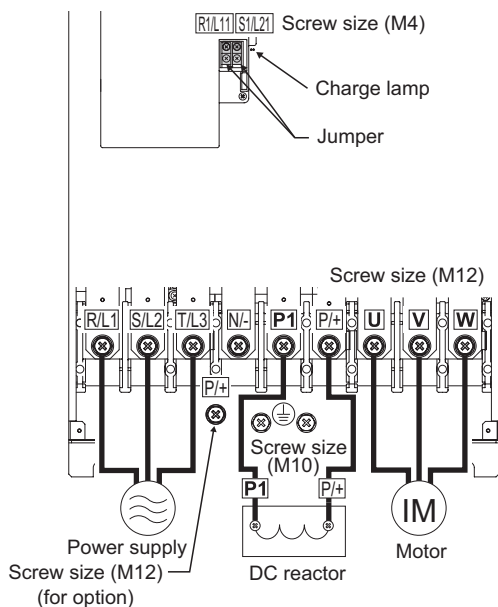
FR-F720-00770 to 01250-NA



FR-F720-01540 to 02330-NA



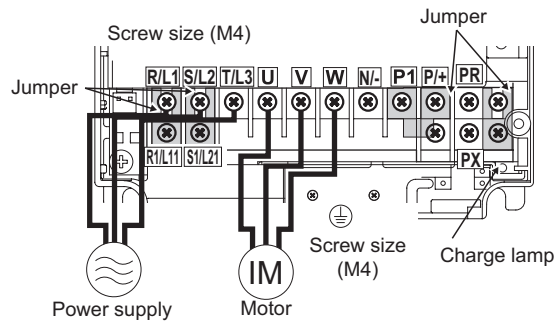
FR-F720-03160 to 04750-NA



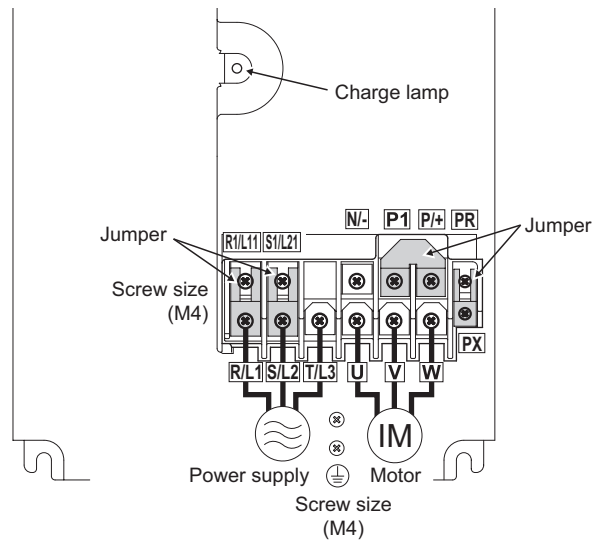


## 400V class

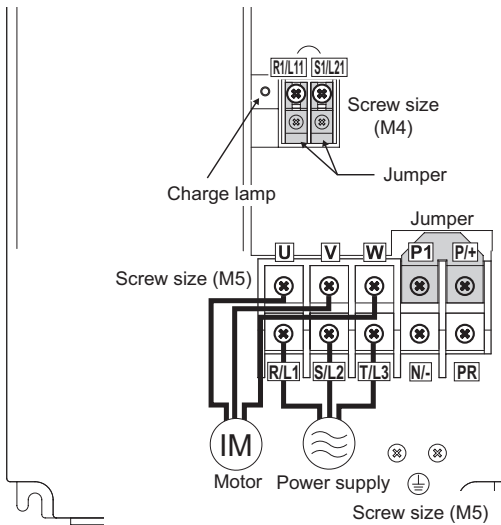
FR-F740-00023 to 00126-NA



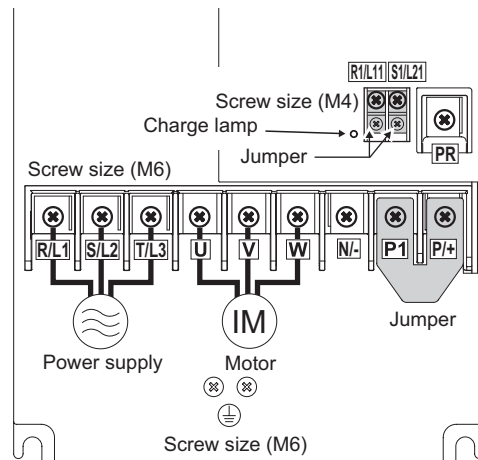
FR-F740-00170, 00250-NA



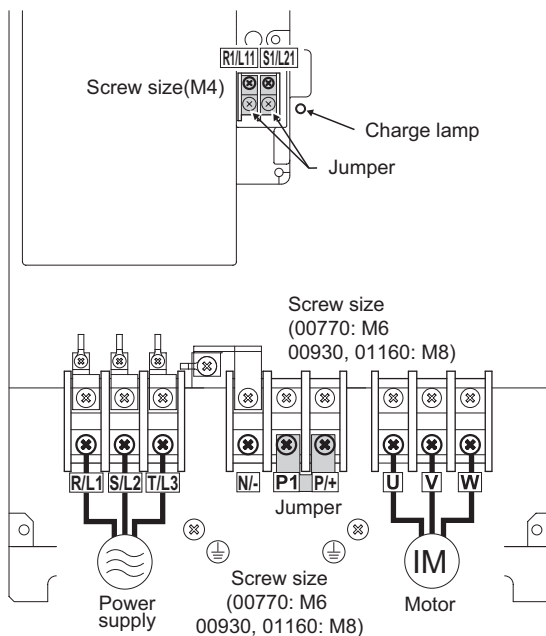
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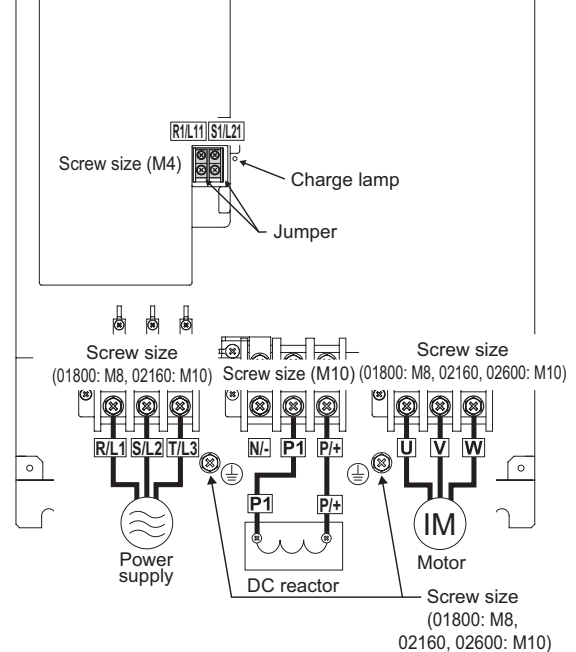
FR-F740-00470, 00620-NA



FR-F740-00770 to 01160-NA

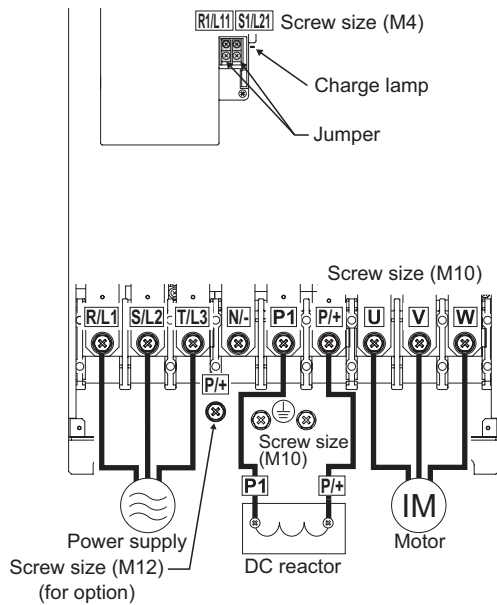


FR-F740-01800 to 02600-NA

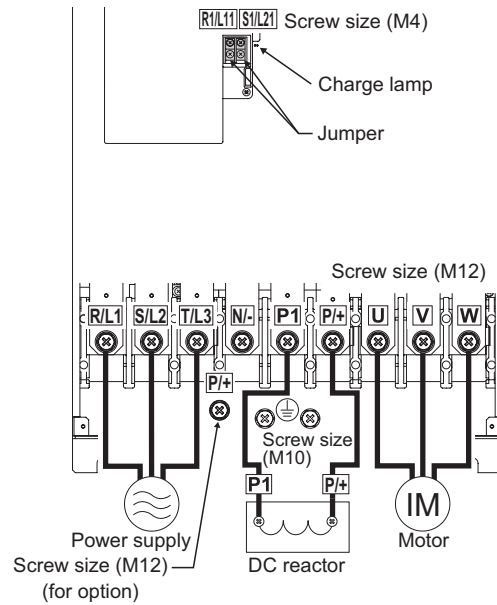




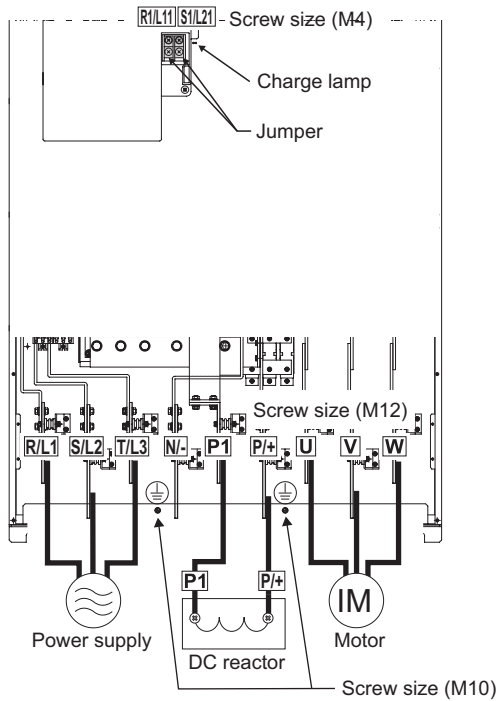
FR-F740-03250, 03610-NA



FR-F740-04320, 04810-NA

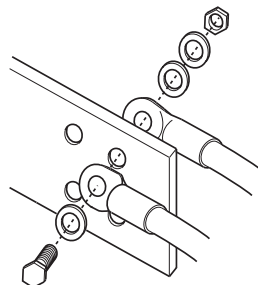


FR-F740-05470 to 12120-NA



### CAUTION

- The power supply cables must be connected to R/L1, S/L2, T/L3. Never connect the power cable to the U, V, W of the inverter. Doing so will damage the inverter. (Phase sequence needs not to be matched.)
- Connect the motor to U, V, W. At this time, turning on the forward rotation switch (signal) rotates the motor in the counterclockwise direction when viewed from the motor shaft.
- When wiring the inverter main circuit conductor of the FR-F740-05470 or more, tighten a nut from the right side of the conductor. When wiring two wires, place wires on both sides of the conductor. (Refer to the drawing below.) For wiring, use bolts (nuts) provided with the inverter.





### 1.3.3 Cables and wiring length

#### (1) Applied cable size

Select the recommended cable size to ensure that a voltage drop will be 2% max.

If the wiring distance is long between the inverter and motor, a main circuit cable voltage drop will cause the motor torque to decrease especially at the output of a low frequency.

The following table indicates a selection example for the wiring length of 20m (65.62feet).

#### 200V class (when input power supply is 220V)

| Applicable Inverter Type  | Terminal Screw Size *4 | Tightening Torque N·m | Crimping Terminal |         | Cable Sizes                     |         |              |                  |         |                                 |         |              |
|---------------------------|------------------------|-----------------------|-------------------|---------|---------------------------------|---------|--------------|------------------|---------|---------------------------------|---------|--------------|
|                           |                        |                       |                   |         | HIV, etc. (mm <sup>2</sup> ) *1 |         |              | AWG *2           |         | PVC, etc. (mm <sup>2</sup> ) *3 |         |              |
|                           |                        |                       | R/L1, S/L2, T/L3  | U, V, W | R/L1, S/L2, T/L3                | U, V, W | Ground Cable | R/L1, S/L2, T/L3 | U, V, W | R/L1, S/L2, T/L3                | U, V, W | Ground Cable |
| FR-F720-00046 to 00105-NA | M4                     | 1.5                   | 2-4               | 2-4     | 2                               | 2       | 2            | 14               | 14      | 2.5                             | 2.5     | 2.5          |
| FR-F720-00167-NA          | M4                     | 1.5                   | 5.5-4             | 5.5-4   | 3.5                             | 3.5     | 3.5          | 12               | 12      | 4                               | 4       | 4            |
| FR-F720-00250-NA          | M4                     | 1.5                   | 5.5-4             | 5.5-4   | 5.5                             | 5.5     | 5.5          | 10               | 10      | 6                               | 6       | 6            |
| FR-F720-00340-NA          | M5                     | 2.5                   | 14-5              | 8-5     | 14                              | 8       | 14           | 6                | 8       | 16                              | 10      | 16           |
| FR-F720-00490-NA          | M5                     | 2.5                   | 14-5              | 14-5    | 14                              | 14      | 14           | 6                | 6       | 16                              | 16      | 16           |
| FR-F720-00630-NA          | M5                     | 2.5                   | 22-5              | 22-5    | 22                              | 22      | 14           | 4                | 6 (*5)  | 25                              | 25      | 16           |
| FR-F720-00770-NA          | M6                     | 4.4                   | 38-6              | 38-6    | 38                              | 38      | 22           | 2                | 2       | 50                              | 50      | 25           |
| FR-F720-00930-NA          | M8/M6                  | 7.8                   | 38-8              | 38-8    | 38                              | 38      | 22           | 2                | 2       | 50                              | 50      | 25           |
| FR-F720-01250-NA          | M8/M6                  | 7.8                   | 60-8              | 60-8    | 60                              | 60      | 38           | 1/0              | 1/0     | 50                              | 50      | 25           |
| FR-F720-01540-NA          | M8/M6                  | 7.8                   | 80-8              | 80-8    | 80                              | 80      | 38           | 3/0              | 3/0     | 70                              | 70      | 35           |
| FR-F720-01870-NA          | M10/M8                 | 14.7                  | 100-10            | 100-10  | 100                             | 100     | 60           | 4/0              | 4/0     | 95                              | 95      | 50           |
| FR-F720-02330-NA          | M10/M8                 | 14.7                  | 100-10            | 100-10  | 100                             | 100     | 60           | 4/0              | 4/0     | 95                              | 95      | 50           |
| FR-F720-03160-NA          | M12                    | 24.5                  | 150-12            | 150-12  | 125                             | 125     | 38           | MCM250           | MCM250  | —                               | —       | —            |
| FR-F720-03800-NA          | M12                    | 24.5                  | 150-12            | 150-12  | 150                             | 150     | 38           | 2×4/0            | 2×4/0   | —                               | —       | —            |
| FR-F720-04750-NA          | M12                    | 24.5                  | 100-12            | 100-12  | 2×100                           | 2×100   | 38           | 2×4/0            | 2×4/0   | —                               | —       | —            |

\*1 The recommended cable size is that of the cable (e.g. HIV cable (600V class 2 vinyl-insulated cable)) with continuous maximum permissible temperature of 75°C (167°F). Assumes that the ambient temperature is 50°C (122°F) or less and the wiring distance is 20m (65.62feet) or less.

\*2 The recommended cable size is that of the cable (THHW cable) with continuous maximum permissible temperature of 75°C (167°F). Assumes that the ambient temperature is 40°C (104°F) or less and the wiring distance is 20m (65.62feet) or less.

\*3 For the FR-F720-00930 or less, the recommended cable size is that of the cable (PVC cable) with continuous maximum permissible temperature of 70°C (158°F). Assumes that the ambient temperature is 40°C (104°F) or less and the wiring distance is 20m (65.62feet) or less.

For the FR-F720-01250 or more, the recommended cable size is that of the cable (XLPE cable) with continuous maximum permissible temperature of 90°C (194°F). Assumes that the ambient temperature is 40°C (104°F) or less and wiring is performed in an enclosure.

\*4 The terminal screw size indicates the terminal size for R/L1, S/L2, T/L3, U, V, W, and a screw for grounding. For the FR-F720-00930 to 02330, screw sizes are different. (R/L1, S/L2, T/L3, U, V, W, and a screw for grounding)

\*5 When connecting the option unit to P/+, P1, N/-, use THHN cables for the option and terminals R/L1, S/L2, T/L3, U, V, W.



400V class (when input power supply is 440V based on the rated current for 110% overload for 1 minute)

| Applicable Inverter Type  | Terminal Screw Size *4 | Tightening Torque N·m | Crimping (Compression) Terminal |         | Cable Sizes                     |         |              |                  |         |                                 |         |              |
|---------------------------|------------------------|-----------------------|---------------------------------|---------|---------------------------------|---------|--------------|------------------|---------|---------------------------------|---------|--------------|
|                           |                        |                       |                                 |         | HIV, etc. (mm <sup>2</sup> ) *1 |         |              | AWG *2           |         | PVC, etc. (mm <sup>2</sup> ) *3 |         |              |
|                           |                        |                       | R/L1, S/L2, T/L3                | U, V, W | R/L1, S/L2, T/L3                | U, V, W | Ground Cable | R/L1, S/L2, T/L3 | U, V, W | R/L1, S/L2, T/L3                | U, V, W | Ground Cable |
| FR-F740-00023 to 00083-NA | M4                     | 1.5                   | 2-4                             | 2-4     | 2                               | 2       | 2            | 14               | 14      | 2.5                             | 2.5     | 2.5          |
| FR-F740-00126-NA          | M4                     | 1.5                   | 2-4                             | 2-4     | 2                               | 2       | 3.5          | 12               | 14      | 2.5                             | 2.5     | 4            |
| FR-F740-00170-NA          | M4                     | 1.5                   | 5.5-4                           | 5.5-4   | 3.5                             | 3.5     | 3.5          | 12               | 12      | 4                               | 4       | 4            |
| FR-F740-00250-NA          | M4                     | 1.5                   | 5.5-4                           | 5.5-4   | 5.5                             | 5.5     | 8            | 10               | 10      | 6                               | 6       | 10           |
| FR-F740-00310-NA          | M5                     | 2.5                   | 8-5                             | 8-5     | 8                               | 8       | 8            | 8                | 8       | 10                              | 10      | 10           |
| FR-F740-00380-NA          | M5                     | 2.5                   | 14-5                            | 8-5     | 14                              | 8       | 14           | 6                | 8       | 16                              | 10      | 16           |
| FR-F740-00470-NA          | M6                     | 4.4                   | 14-6                            | 14-6    | 14                              | 14      | 14           | 6                | 6       | 16                              | 16      | 16           |
| FR-F740-00620-NA          | M6                     | 4.4                   | 22-6                            | 22-6    | 22                              | 22      | 14           | 4                | 4       | 25                              | 25      | 16           |
| FR-F740-00770-NA          | M6                     | 4.4                   | 22-6                            | 22-6    | 22                              | 22      | 14           | 4                | 4       | 25                              | 25      | 16           |
| FR-F740-00930-NA          | M8                     | 7.8                   | 38-8                            | 38-8    | 38                              | 38      | 22           | 1                | 2       | 50                              | 50      | 25           |
| FR-F740-01160-NA          | M8                     | 7.8                   | 60-8                            | 60-8    | 60                              | 60      | 22           | 1/0              | 1/0     | 50                              | 50      | 25           |
| FR-F740-01800-NA          | M8                     | 7.8                   | 60-8                            | 60-8    | 60                              | 60      | 38           | 1/0              | 1/0     | 50                              | 50      | 25           |
| FR-F740-02160-NA          | M10                    | 14.7                  | 100-10                          | 100-10  | 80                              | 80      | 38           | 3/0              | 3/0     | 70                              | 70      | 35           |
| FR-F740-02600-NA          | M10                    | 14.7                  | 100-10                          | 150-10  | 100                             | 125     | 38           | 4/0              | 4/0     | 95                              | 95      | 50           |
| FR-F740-03250-NA          | M10                    | 14.7                  | 150-10                          | 150-10  | 125                             | 125     | 38           | MCM250           | MCM250  | 120                             | 120     | 70           |
| FR-F740-03610-NA          | M10                    | 14.7                  | 150-10                          | 150-10  | 150                             | 150     | 38           | MCM300           | MCM300  | 150                             | 150     | 95           |
| FR-F740-04320-NA          | M12/M10                | 24.5                  | 100-12                          | 100-12  | 2×100                           | 2×100   | 38           | 2×4/0            | 2×4/0   | 2×95                            | 2×95    | 95           |
| FR-F740-04810-NA          | M12/M10                | 24.5                  | 100-12                          | 100-12  | 2×100                           | 2×100   | 38           | 2×4/0            | 2×4/0   | 2×95                            | 2×95    | 95           |
| FR-F740-05470-NA          | M12/M10                | 24.5                  | 150-12                          | 150-12  | 2×125                           | 2×125   | 38           | 2×250            | 2×250   | 2×120                           | 2×120   | 120          |
| FR-F740-06100-NA          | M12/M10                | 24.5                  | 150-12                          | 150-12  | 2×150                           | 2×150   | 38           | 2×300            | 2×300   | 2×150                           | 2×150   | 150          |
| FR-F740-06830-NA          | M12/M10                | 24.5                  | 200-12                          | 200-12  | 2×200                           | 2×200   | 60           | 2×350            | 2×350   | 2×185                           | 2×185   | 2×95         |
| FR-F740-07700-NA          | M12/M10                | 24.5                  | C2-200                          | C2-200  | 2×200                           | 2×200   | 60           | 2×400            | 2×400   | 2×185                           | 2×185   | 2×95         |
| FR-F740-08660-NA          | M12/M10                | 24.5                  | C2-250                          | C2-250  | 2×250                           | 2×250   | 60           | 2×500            | 2×500   | 2×240                           | 2×240   | 2×120        |
| FR-F740-09620-NA          | M12/M10                | 24.5                  | C2-250                          | C2-250  | 2×250                           | 2×250   | 100          | 2×500            | 2×500   | 2×240                           | 2×240   | 2×120        |
| FR-F740-10940-NA          | M12/M10                | 24.5                  | C2-200                          | C2-200  | 3×200                           | 3×200   | 100          | 3×350            | 3×350   | 3×185                           | 3×185   | 2×150        |
| FR-F740-12120-NA          | M12/M10                | 24.5                  | C2-200                          | C2-200  | 3×200                           | 3×200   | 100          | 3×400            | 3×400   | 3×185                           | 3×185   | 2×150        |

\*1 For the FR-F740-01160 or less, the recommended cable size is that of the cable (e.g. HIV cable (600V class 2 vinyl-insulated cable)) with continuous maximum permissible temperature of 75°C (167°F). Assumes that the ambient temperature is 50°C (122°F) or less and the wiring distance is 20m (65.62feet) or less.

For the FR-F740-01800 or more, the recommended cable size is that of the cable (e.g. LMFC (heat resistant flexible cross-linked polyethylene insulated cable)) with continuous maximum permissible temperature of 90°C (194°F). Assumes that the ambient temperature is 50°C (122°F) or less and wiring is performed in an enclosure.

\*2 For the FR-F740-00930 or less, the recommended cable size is that of the cable (THHW cable) with continuous maximum permissible temperature of 75°C (167°F). Assumes that the ambient temperature is 40°C (104°F) or less and the wiring distance is 20m (65.62feet) or less.

For the FR-F740-01160 or more, the recommended cable size is that of the cable (THHN cable) with continuous maximum permissible temperature of 90°C (194°F). Assumes that the ambient temperature is 40°C (104°F) or less and wiring is performed in an enclosure.

\*3 For the FR-F740-00930 or less, the recommended cable size is that of the cable (PVC cable) with continuous maximum permissible temperature of 70°C (158°F). Assumes that the ambient temperature is 40°C (104°F) or less and the wiring distance is 20m (65.62feet) or less.

For the FR-F740-01160 or more, the recommended cable size is that of the cable (XLPE cable) with continuous maximum permissible temperature of 90°C (194°F). Assumes that the ambient temperature is 40°C (104°F) or less and wiring is performed in an enclosure.

\*4 The terminal screw size indicates the terminal size for R/L1, S/L2, T/L3, U, V, W, and a screw for grounding.

For the FR-F740-04320 or more, screw sizes are different. (R/L1, S/L2, T/L3, U, V, W, and a screw for grounding)

The line voltage drop can be calculated by the following formula:

$$\text{line voltage drop [V]} = \frac{\sqrt{3} \times \text{wire resistance [m}\Omega/\text{m}] \times \text{wiring distance [m]} \times \text{current [A]}}{1000}$$

Use a larger diameter cable when the wiring distance is long or when it is desired to decrease the voltage drop (torque reduction) in the low speed range.

#### CAUTION

- Tighten the terminal screw to the specified torque.
- A screw that has been tighten too loosely can cause a short circuit or malfunction.
- A screw that has been tighten too tightly can cause a short circuit or malfunction due to the unit breakage.
- Use crimping terminals with insulation sleeve to wire the power supply and motor.



## (2) Notes on grounding

- Always ground the motor and inverter.

1) Purpose of grounding Generally, an electrical apparatus has an ground terminal, which must be connected to the ground before use.

An electrical circuit is usually insulated by an insulating material and encased. However, it is impossible to manufacture an insulating material that can shut off a leakage current completely, and actually, a slight current flow into the case. The purpose of grounding the case of an electrical apparatus is to prevent operator from getting an electric shock from this leakage current when touching it.

To avoid the influence of external noises, this grounding is important to audio equipment, sensors, computers and other apparatuses that handle low-level signals or operate very fast.

2) Grounding methods and grounding work

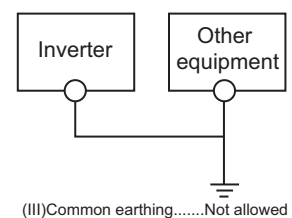
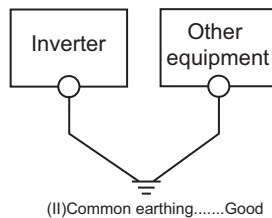
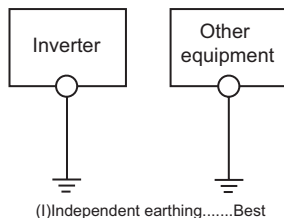
As described previously, grounding is roughly classified into an electrical shock prevention type and a noise-affected malfunction prevention type. Therefore, these two types should be discriminated clearly, and the following work must be done to prevent the leakage current having the inverter's high frequency components from entering the malfunction prevention type grounding:

- (a) Where possible, use independent grounding for the inverter. If independent grounding (I) is impossible, use joint grounding (II) where the inverter is connected with the other equipment at an grounding point. Joint grounding as in (III) must be avoided as the inverter is connected with the other equipment by a common ground cable.

Also a leakage current including many high frequency components flows in the ground cables of the inverter and inverter-driven motor. Therefore, they must use the independent grounding method and be separated from the grounding of equipment sensitive to the aforementioned noises.

In a tall building, it will be a good policy to use the noise malfunction prevention type grounding with steel frames and carry out electric shock prevention type grounding in the independent grounding method.

- (b) This inverter must be grounded. Grounding must conform to the requirements of national and local safety regulations and electrical codes. (JIS, NEC section 250, IEC 536 class 1 and other applicable standards).
- (c) Use the thickest possible ground cable. The ground cable should be of not less than the size indicated in the above table on the previous page.
- (d) The grounding point should be as near as possible to the inverter, and the ground wire length should be as short as possible.
- (e) Run the ground cable as far away as possible from the I/O wiring of equipment sensitive to noises and run them in parallel in the minimum distance.



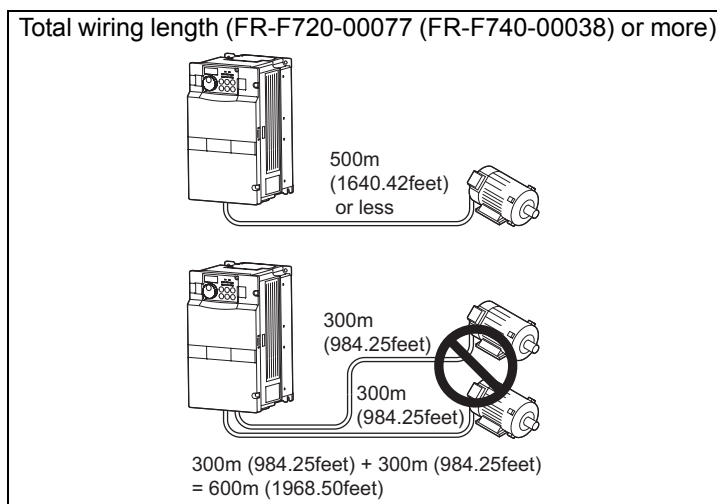
**To be compliant with the European Directive (Low Voltage Directive), refer to the *Instruction Manual (basics)*.**

### (3) Total wiring length

The overall wiring length for connection of a single motor or multiple motors should be within the value in the table below.

| <i>Pr. 72 PWM frequency selection setting</i><br>(carrier frequency) | FR-F720-00046<br>FR-F740-00023 | FR-F720-00077<br>FR-F740-00038 | FR-F720-00105 or more<br>FR-F740-00052 or more |
|----------------------------------------------------------------------|--------------------------------|--------------------------------|------------------------------------------------|
| 2 (2kHz) or less                                                     | 300m<br>(984.25 feet)          | 500m<br>(1640.42 feet)         | 500m<br>(1640.42 feet)                         |
| 3 to 15 (3kHz to 14.5kHz) *                                          | 200m<br>(656.19 feet)          | 300m<br>(984.25 feet)          | 500m<br>(1640.42 feet)                         |

\* For the FR-F720-03160 (FR-F740-01800) or more, the setting range of *Pr. 72 PWM frequency selection* is "0 to 6".



When driving a 400V class motor by the inverter, surge voltages attributable to the wiring constants may occur at the motor terminals, deteriorating the insulation of the motor.

Refer to *page 42* for measures against deteriorated insulation.

#### CAUTION

- Especially for long-distance wiring, the inverter may be affected by a charging current caused by the stray capacitances of the wiring, leading to a malfunction of the overcurrent protective function or fast response current limit function or a malfunction or fault of the equipment connected on the inverter output side. If fast-response current limit function malfunctions, disable this function. (For *Pr.156 Stall prevention operation selection*, refer to *page 61*.)
- For details of *Pr. 72 PWM frequency selection*, refer to *page 129*.



## 1.4 Control circuit specifications

### 1.4.1 Control circuit terminals

  indicates that terminal functions can be selected from Pr. 178 to Pr. 196 (I/O terminal function selection) (Refer to page 90.)

#### (1) Input signals

| Type          | Terminal Symbol                                                               | Terminal Name                                                                                                                                                                                                                                                                                                                                                                                                    | Description                                                                                                                                                                                                                                                                                                            |                                                                                       | Rated Specifications                                                                                 | Refer to |
|---------------|-------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------|----------|
| Contact input | STF                                                                           | Forward rotation start                                                                                                                                                                                                                                                                                                                                                                                           | Turn on the STF signal to start forward rotation and turn it off to stop.                                                                                                                                                                                                                                              | When the STF and STR signals are turned on simultaneously, the stop command is given. | Input resistance 4.7kΩ<br>Voltage at opening: 21 to 27VDC<br>Contacts at short-circuited: 4 to 6mADC | 90       |
|               | STR                                                                           | Reverse rotation start                                                                                                                                                                                                                                                                                                                                                                                           | Turn on the STR signal to start reverse rotation and turn it off to stop.                                                                                                                                                                                                                                              |                                                                                       |                                                                                                      |          |
|               | STOP                                                                          | Start self-holding selection                                                                                                                                                                                                                                                                                                                                                                                     | Turn on the STOP signal to self-hold the start signal.                                                                                                                                                                                                                                                                 |                                                                                       |                                                                                                      | 90       |
|               | RH, RM, RL                                                                    | Multi-speed selection                                                                                                                                                                                                                                                                                                                                                                                            | Multi-speed can be selected according to the combination of RH, RM and RL signals.                                                                                                                                                                                                                                     |                                                                                       |                                                                                                      | 90       |
|               | JOG                                                                           | Jog mode selection                                                                                                                                                                                                                                                                                                                                                                                               | Turn on the JOG signal to select Jog operation (initial setting) and turn on the start signal (STF or STR) to start Jog operation.                                                                                                                                                                                     |                                                                                       |                                                                                                      | 90       |
|               | RT                                                                            | Second acceleration/ deceleration time selection                                                                                                                                                                                                                                                                                                                                                                 | Turn on the RT signal to select second acceleration/ deceleration time.<br>When the second function such as "second torque boost" and "second V/F (base frequency)" are set, turning on the RT signal selects these functions.                                                                                         |                                                                                       |                                                                                                      | 90       |
|               | MRS                                                                           | Output stop                                                                                                                                                                                                                                                                                                                                                                                                      | Turn on the MRS signal (20ms or more) to stop the inverter output.<br>Use to shut off the inverter output when stopping the motor by electromagnetic brake.                                                                                                                                                            |                                                                                       |                                                                                                      | 90       |
|               | RES                                                                           | Reset                                                                                                                                                                                                                                                                                                                                                                                                            | Used to reset alarm output provided when protective function is activated.<br>Turn on the RES signal for more than 0.1s, then turn it off. Initial setting is for reset always. By setting <i>Pr.75</i> , reset can be set to enabled only at an inverter alarm occurrence. Recover about 1s after reset is cancelled. |                                                                                       |                                                                                                      | 90       |
|               | AU                                                                            | Terminal 4 input selection                                                                                                                                                                                                                                                                                                                                                                                       | Terminal 4 is made valid only when the AU signal is turned on. (The frequency setting signal can be set between 4 and 20mADC.)<br>Turning the AU signal on makes terminal 2 (voltage input) invalid.                                                                                                                   |                                                                                       |                                                                                                      | 130      |
|               |                                                                               | PTC input                                                                                                                                                                                                                                                                                                                                                                                                        | AU terminal is used as PTC input terminal (thermal protection of the motor). When using it as PTC input terminal, set the AU/ PTC switch to PTC.                                                                                                                                                                       |                                                                                       |                                                                                                      | 84       |
|               | CS                                                                            | Selection of automatic restart after instantaneous power failure                                                                                                                                                                                                                                                                                                                                                 | When the CS signal is left on, the inverter restarts automatically at power restoration. Note that restart setting is necessary for this operation. In the initial setting, a restart is disabled.<br>(Refer to <i>Pr.57 Restart coasting time page 114</i> )                                                          |                                                                                       |                                                                                                      | 90       |
| SD            | Contact input common (sink)                                                   | Common terminal for contact input terminal (sink logic).<br>Common output terminal for 24VDC 0.1A power supply (PC terminal).<br>Isolated from terminals 5 and SE.                                                                                                                                                                                                                                               |                                                                                                                                                                                                                                                                                                                        | —                                                                                     | —                                                                                                    |          |
| PC            | External transistor common, 24VDC power supply, contact input common (source) | When connecting the transistor output (open collector output), such as a programmable controller (PLC), when sink logic is selected, connect the external power supply common for transistor output to this terminal to prevent a malfunction caused by undesirable currents.<br>Can be used as 24VDC 0.1A power supply.<br>When source logic has been selected, this terminal serves as a contact input common. |                                                                                                                                                                                                                                                                                                                        | Power supply voltage range 19.2 to 28.8VDC<br>Current consumption 100mA               | 21                                                                                                   |          |



| Type              | Terminal Symbol | Terminal Name                  | Description                                                                                                                                                                                                                                                                                                                     | Rated Specifications                                                                                                                                                                                   | Refer to |
|-------------------|-----------------|--------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------|
| Frequency setting | 10E             | Frequency setting power supply | When connecting the frequency setting potentiometer at an initial status, connect it to terminal 10.                                                                                                                                                                                                                            | 10VDC $\pm$ 0.4V<br>Permissible load current 10mA                                                                                                                                                      | 130      |
|                   | 10              |                                | Change the input specifications when connecting it to terminal 10E. (Refer to Pr.73 Analog input selection in page 132.)                                                                                                                                                                                                        | 5.2VDC $\pm$ 0.2V<br>Permissible load current 10mA                                                                                                                                                     | 130      |
|                   | 2               | Frequency setting (voltage)    | Inputting 0 to 5VDC (or 0 to 10V, 4 to 20mA) provides the maximum output frequency at 5V (10V, 20mA) and makes input and output proportional. Use Pr.73 to switch from among input 0 to 5VDC (initial setting), 0 to 10VDC, and 0 to 20mA.                                                                                      | Voltage input:<br>Input resistance 10k $\Omega$ $\pm$ 1k $\Omega$<br>Maximum permissible voltage 20VDC<br>Current input:<br>Input resistance 250 $\Omega$ $\pm$ 2%<br>Maximum permissible current 30mA | 130      |
|                   | 4               | Frequency setting (current)    | Inputting 4 to 20mADC (or 0 to 5V, 0 to 10V) provides the maximum output frequency at 20mA (5V, 10V) makes input and output proportional. This input signal is valid only when the AU signal is on (terminal 2 input is invalid). Use Pr.267 to switch between the input 4 to 20mA and 0 to 5VDC, 0 to 10VDC (initial setting). |                                                                                                                                                                                                        | 130      |
|                   | 1               | Frequency setting auxiliary    | Inputting 0 to $\pm$ 5 VDC or 0 to $\pm$ 10VDC adds this signal to terminal 2 or 4 frequency setting signal. Use Pr.73 to switch between the input 0 to $\pm$ 5VDC and 0 to $\pm$ 10VDC (initial setting).                                                                                                                      | Input resistance 10k $\Omega$ $\pm$ 1k $\Omega$<br>Maximum permissible voltage $\pm$ 20VDC                                                                                                             | 130      |
|                   | 5               | Frequency setting common       | Common terminal for frequency setting signal (terminal 2, 1 or 4) and analog output terminal AM and CA. Do not ground.                                                                                                                                                                                                          | —                                                                                                                                                                                                      | 130      |

**(2) Output signals**

| Type           | Terminal Symbol | Terminal Name                 | Description                                                                                                                                                                                                                            | Rated Specifications                                                                                                                        | Refer to |
|----------------|-----------------|-------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------|----------|
| Relay          | A1, B1, C1      | Relay output 1 (alarm output) | 1 changeover contact output indicates that the inverter protective function has activated and the output stopped. Abnormal: No conduction across B-C (Across A-C Continuity), Normal: Across B-C Continuity (No conduction across A-C) | Contact capacity:<br>230VAC 0.3A<br>(Power factor=0.4)<br>30VDC 0.3A                                                                        | 96       |
|                | A2, B2, C2      | Relay output 2                | 1 changeover Contact output                                                                                                                                                                                                            |                                                                                                                                             | 96       |
| Open collector | RUN             | Inverter running              | Switched low when the inverter output frequency is equal to or higher than the starting frequency (initial value 0.5Hz). Switched high during stop or DC injection brake operation. *1                                                 | Alarm code (4bit) output (Refer to page 121.)<br><br>Permissible load 24VDC 0.1A<br>(A voltage drop is 3.4V maximum when the signal is on.) | 96       |
|                | SU              | Up to frequency               | Switched low when the output frequency reaches within the range of $\pm$ 10% (initial value) of the set frequency. Switched high during acceleration/deceleration and at a stop. *1                                                    |                                                                                                                                             | 96       |
|                | OL              | Overload alarm                | Switched low when stall prevention is activated by the stall prevention function. Switched high when stall prevention is cancelled. *1                                                                                                 |                                                                                                                                             | 96       |
|                | IPF             | Instantaneous power failure   | Switched low when an instantaneous power failure and under voltage protections are activated. *1                                                                                                                                       |                                                                                                                                             | 96       |
|                | FU              | Frequency detection           | Switched low when the inverter output frequency is equal to or higher than the preset detected frequency and high when less than the preset detected frequency. *1                                                                     |                                                                                                                                             | 96       |
|                | SE              | Open collector output common  | Common terminal for terminals RUN, SU, OL, IPF, FU                                                                                                                                                                                     | —                                                                                                                                           | —        |



| Type   | Terminal Symbol | Terminal Name         | Description                                                                                                                                         |                                                    | Rated Specifications                                                                                       | Refer to |
|--------|-----------------|-----------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------|------------------------------------------------------------------------------------------------------------|----------|
| Analog | CA              | Analog current output | Select one e.g. output frequency from monitor items. *2<br>The output signal is proportional to the magnitude of the corresponding monitoring item. | Output item:<br>Output frequency (initial setting) | Load impedance<br>200Ω to 450Ω<br>Output signal 0 to 20mADC                                                | 109      |
|        | AM              | Analog voltage output |                                                                                                                                                     |                                                    | Output signal 0 to 10VDC<br>Permissible load current 1mA (load impedance 10kΩ or more)<br>Resolution 8 bit | 109      |

\*1 Low indicates that the open collector output transistor is on (conducts).  
High indicates that the transistor is off (does not conduct).

\*2 Not output during inverter reset.

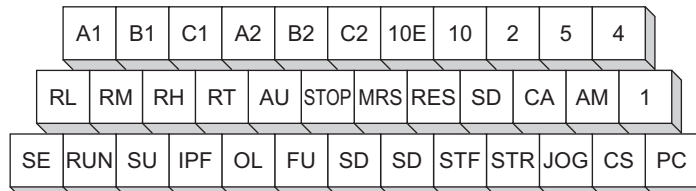
### (3) Communication

| Type   | Terminal Symbol  | Terminal Name | Description                                                                                                                                                                                                                                                                   | Refer to |
|--------|------------------|---------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------|
| RS-485 | PU connector     | PU connector  | With the PU connector, communication can be made through RS-485.<br>(for connection on a 1:1 basis only)<br>. Conforming standard : EIA-485(RS-485)<br>. Transmission format : Multidrop<br>. Communication speed : 4800 to 38400bps<br>. Overall length : 500m (1640.42feet) | 161      |
|        | RS-485 terminals | TXD+          | With the RS-485 terminals, communication can be made through RS-485.<br>Conforming standard : EIA-485(RS-485)<br>Transmission format : Multidrop link<br>Communication speed : 300 to 38400bps<br>Overall length : 500m (1640.42feet)                                         | 163      |
|        |                  | TXD-          |                                                                                                                                                                                                                                                                               |          |
|        |                  | RXD+          |                                                                                                                                                                                                                                                                               |          |
|        |                  | RXD-          |                                                                                                                                                                                                                                                                               |          |
|        | SG               | Ground        |                                                                                                                                                                                                                                                                               |          |

#### 1.4.2 Control circuit terminal layout

Terminal screw size: M3.5

Tightening torque: 1.2N·m



#### (1) Common terminals of the control circuit (SD, 5, SE)

Terminals SD, 5, and SE are all common terminals (0V) for I/O signals and are isolated from each other.

Avoid connecting the terminal SD and 5 and the terminal SE and 5.

Terminal SD is a common terminal for the contact input terminals (STF, STR, STOP, RH, RM, RL, JOG, RT, MRS, RES, AU, CS).

The open collector circuit is isolated from the internal control circuit by photocoupler.

Terminal 5 is a common terminal for frequency setting signal (terminal 2, 1 or 4), analog current output terminal (CA) and analog output terminal AM.

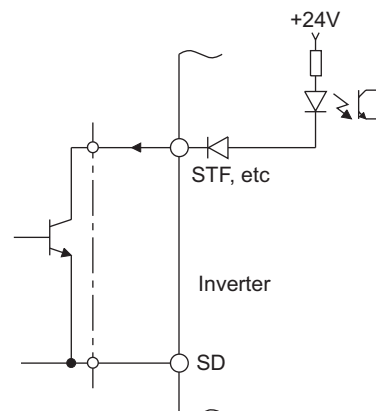
It should be protected from external noise using a shielded or twisted cable.

Terminal SE is a common terminal for the open collector output terminal (RUN, SU, OL, IPF, FU).

The contact input circuit is isolated from the internal control circuit by photocoupler.

## (2) Signal inputs by contactless switches

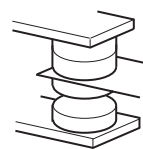
The contacted input terminals of the inverter (STF, STR, STOP, RH, RM, RL, JOG, RT, MRS, RES, AU, CS) can be controlled using a transistor instead of a contacted switch as shown on the right.



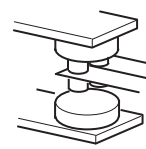
External signal input using transistor

### 1.4.3 Wiring instructions

- 1) Use shielded or twisted cables for connection to the control circuit terminals and run them away from the main and power circuits (including the 200V relay sequence circuit).
- 2) Use two or more parallel micro-signal contacts or twin contacts to prevent a contact faults when using contact inputs since the control circuit input signals are micro-currents.



Micro signal contacts



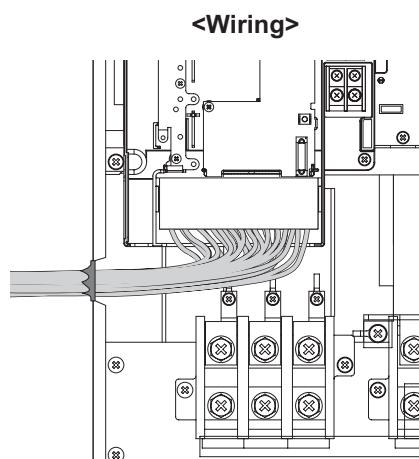
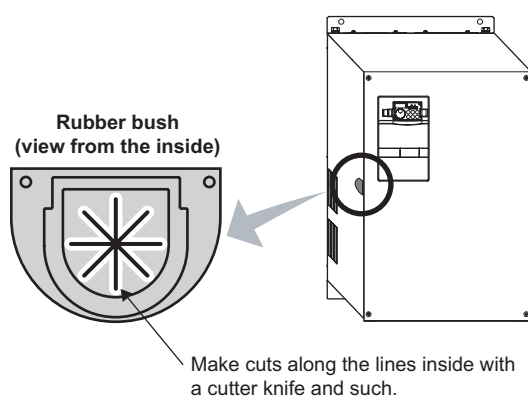
Twin contacts

- 3) Do not apply a voltage to the contact input terminals (e.g. STF) of the control circuit.
- 4) Always apply a voltage to the alarm output terminals (A, B, C) via a relay coil, lamp, etc.
- 5) It is recommended to use the cables of 0.75mm<sup>2</sup> gauge for connection to the control circuit terminals.  
If the cable gauge used is 1.25mm<sup>2</sup> or more, the front cover may be lifted when there are many cables running or the cables are run improperly, resulting in an operation panel contact fault.
- 6) The wiring length should be 30m (98.43feet) maximum.

#### ● Wiring of the control circuit of the FR-F720-03160 (FR-F740-01800) or more

For wiring of the control circuit of the FR-F720-03160 (FR-F740-01800) or more, separate away from wiring of the main circuit.

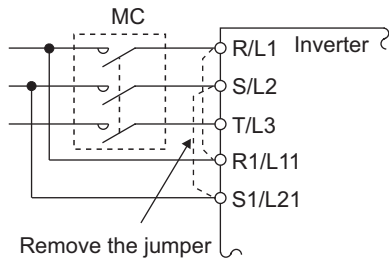
Make cuts in rubber bush of the inverter side and lead wires.





#### 1.4.4 When connecting the control circuit and the main circuit separately to the power supply (separate power)

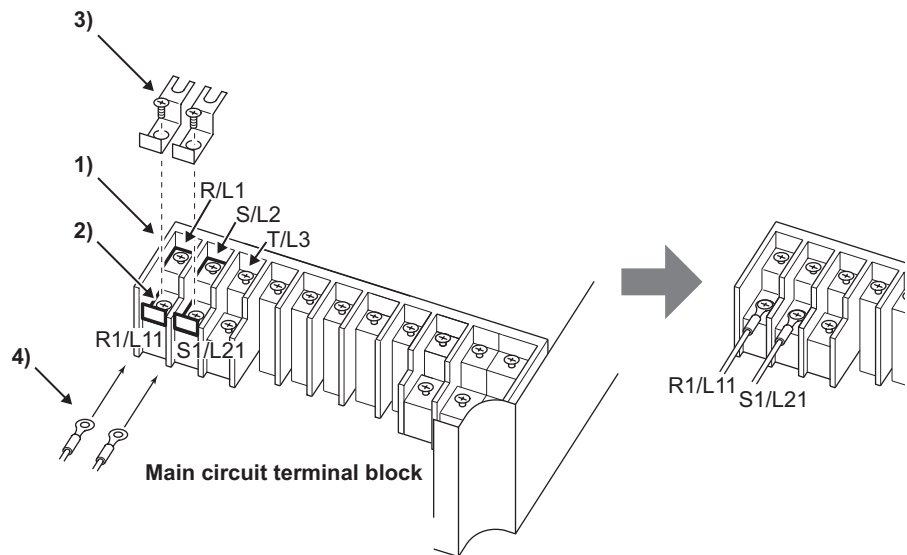
<Connection diagram>



When the protected circuit is activated, opening of the electromagnetic contactor (MC) on the inverter power supply side results in power loss in the control circuit, disabling the alarm output signal retention. Terminals R1/L11 and S1/L21 are provided to hold an alarm signal. In this case, connect the power supply terminals R1/L11 and S1/L21 of the control circuit to the primary side of the MC.

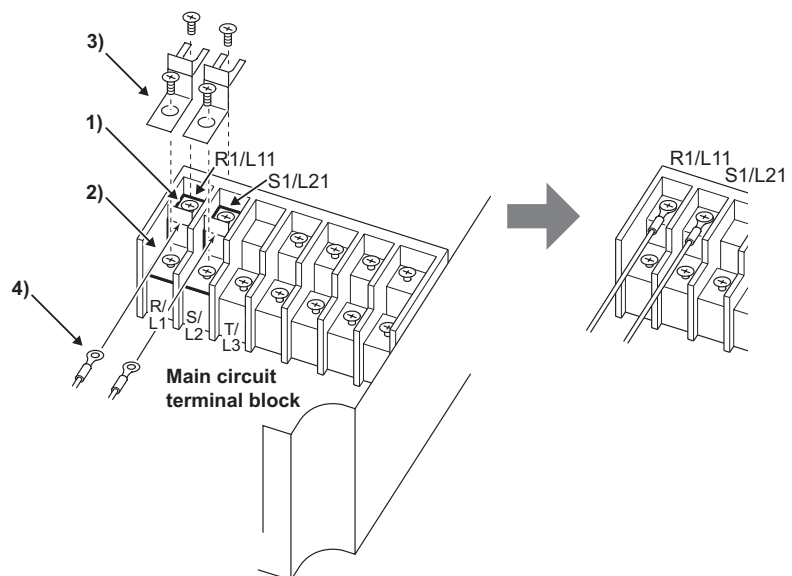
##### • FR-F720-00046 to 00250, FR-F740-00023 to 00126

- 1) Loosen the upper screws.
- 2) Remove the lower screws.
- 3) Remove the jumper
- 4) Connect the separate power supply cable for the control circuit to the lower terminals (R1/L11, S1/L21).



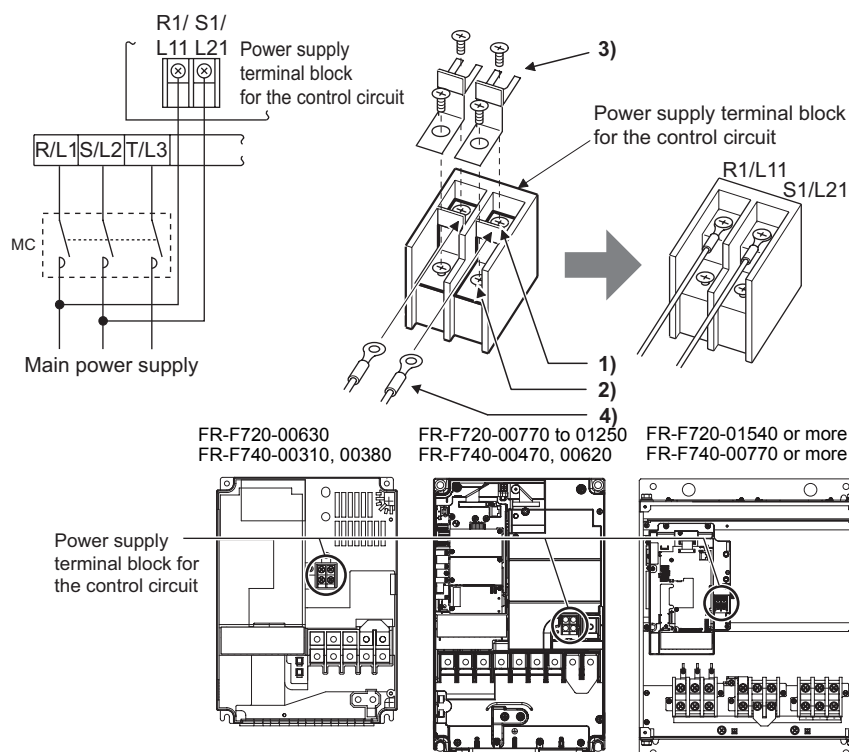
##### • FR-F720-00340, 00490, FR-F740-00170, 00250

- 1) Remove the upper screws.
- 2) Remove the lower screws.
- 3) Remove the jumper.
- 4) Connect the separate power supply cable for the control circuit to the upper terminals (R1/L11, S1/L21).



### • FR-F720-00630 (FR-F740-00310) or more

- 1) Remove the upper screws.
- 2) Remove the lower screws.
- 3) Pull the jumper toward you to remove.
- 4) Connect the separate power supply cable for the control circuit to the upper terminals (R1/L11, S1/L21).  
Never connect the power cable to the terminals in the lower stand.  
Doing so will damage the inverter.



### CAUTION

1. Do not turn off the control power (terminals R1/L11 and S1/L21) with the main circuit power (R/L1, S/L2, T/L3) on. Doing so may damage the inverter.
2. Be sure to use the inverter with the jumpers across terminals R/L1-R1/L11 and S/L2-S1/L21 removed when supplying power from other sources. The inverter may be damaged if you do not remove the jumper.
3. The voltage should be the same as that of the main control circuit when the control circuit power is supplied from other than the primary side of the MC.
4. The power capacity is 60VA or more for FR-F720-00770 (FR-F740-00380) or less, 80VA or more for FR-F720-00930 (FR-F740-00470) or more when separate power is supplied from R1/L11, S1/L21.
5. When the power supply used with the control circuit is different from the one used with the main circuit, make up a circuit which will switch off the main circuit power supply terminals R/L1, S/L2, T/L3 when the control circuit power supply terminals R1/L11, S1/L21 are switched off.



### 1.4.5 Changing the control logic

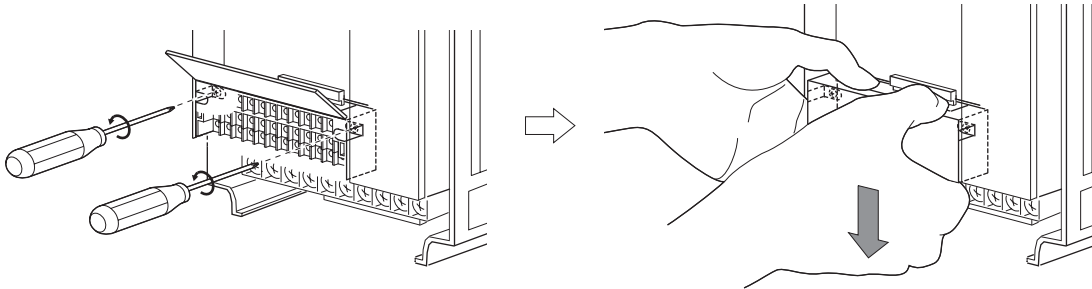
The input signals are set to sink logic (SINK) when shipped from the factory.

To change the control logic, the jumper connector on the back of the control circuit terminal block must be moved to the other position.

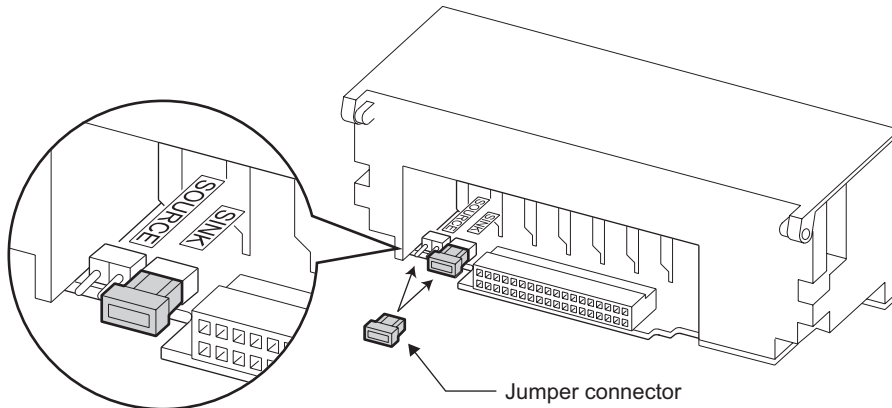
(The output signals may be used in either the sink or source logic independently of the jumper connector position.)

1) Loosen the two installation screws in both ends of the control circuit terminal block. (These screws cannot be removed.)

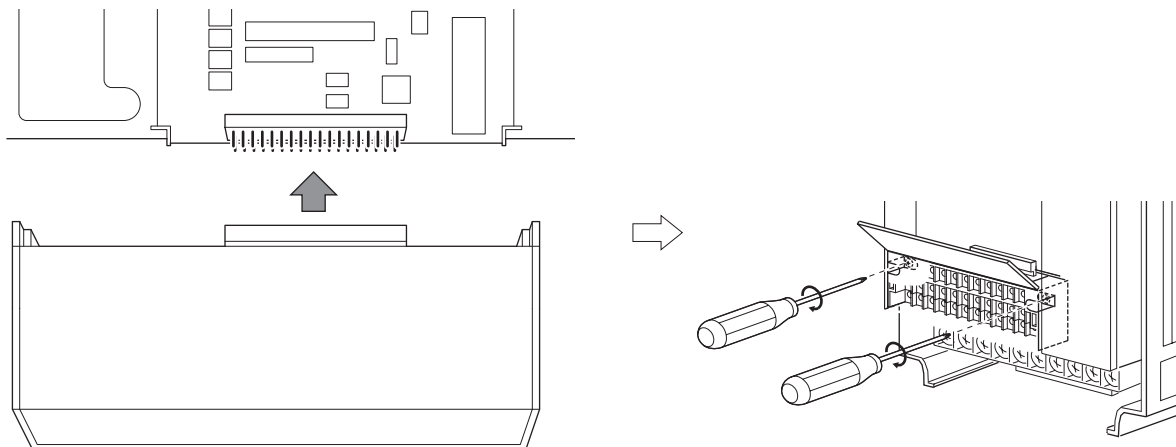
Pull down the terminal block from behind the control circuit terminals.



2) Change the jumper connector set to the sink logic (SINK) on the rear panel of the control circuit terminal block to source logic (SOURCE).



3) Using care not to bend the pins of the inverter's control circuit connector, reinstall the control circuit terminal block and fix it with the mounting screws.



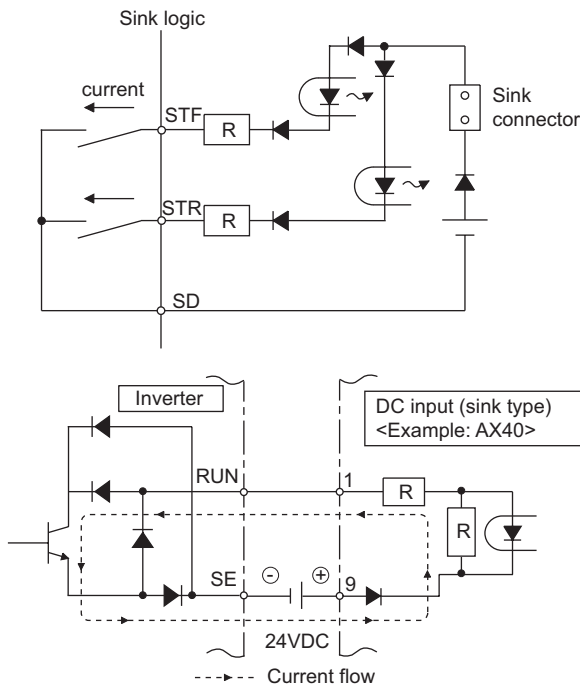
#### CAUTION

1. Make sure that the control circuit connector is fitted correctly.
2. While power is on, never disconnect the control circuit terminal block.

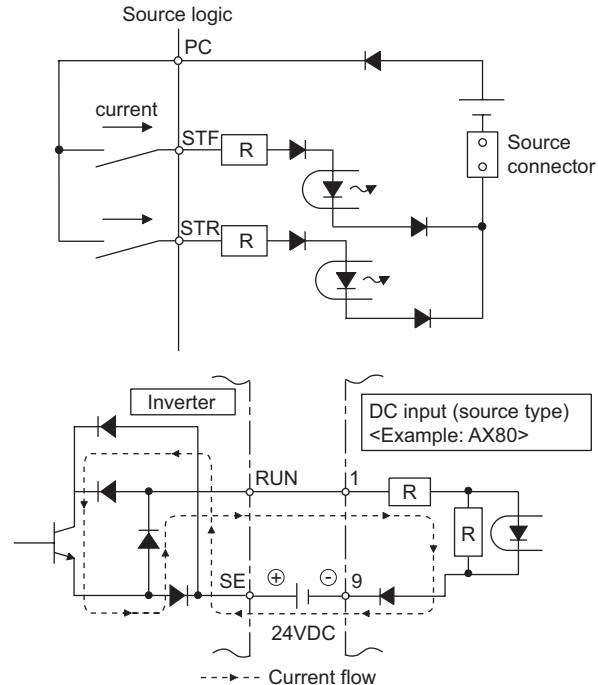
#### 4) Sink logic and source logic

- In sink logic, a signal switches on when a current flows from the corresponding signal input terminal. Terminal SD is common to the contact input signals. Terminal SE is common to the open collector output signals.
- In source logic, a signal switches on when a current flows into the corresponding signal input terminal. Terminal PC is common to the contact input signals. Terminal SE is common to the open collector output signals.

##### ● Current flow concerning the input/output signal when sink logic is selected



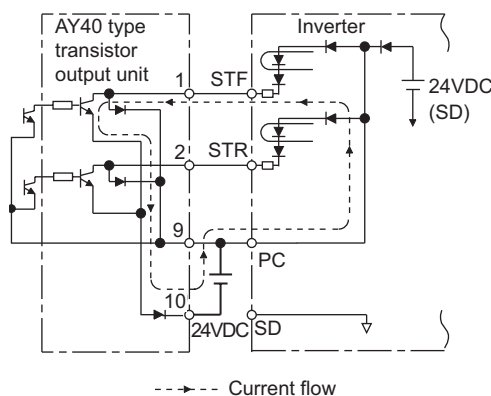
##### ● Current flow concerning the input/output signal when source logic is selected



##### ● When using an external power supply for transistor output

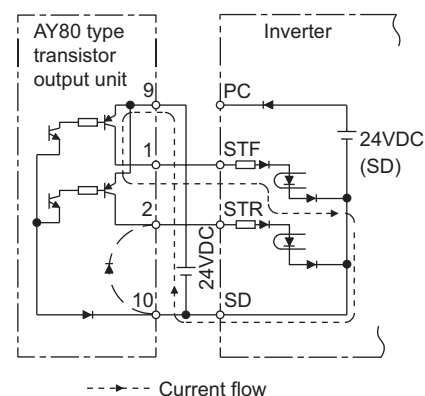
###### · Sink logic type

Use terminal PC as a common terminal to prevent a malfunction caused by undesirable current. (Do not connect terminal SD of the inverter with terminal 0V of the external power supply. When using terminals PC-SD as a 24VDC power supply, do not install a power supply in parallel in the outside of the inverter. Doing so may cause a malfunction due to undesirable current.)



###### · Source logic type

When using a transistor power supply for transistor output, use terminal SD as a common to prevent misoperation caused by undesirable current.



## 1.5 Connection of stand-alone option units

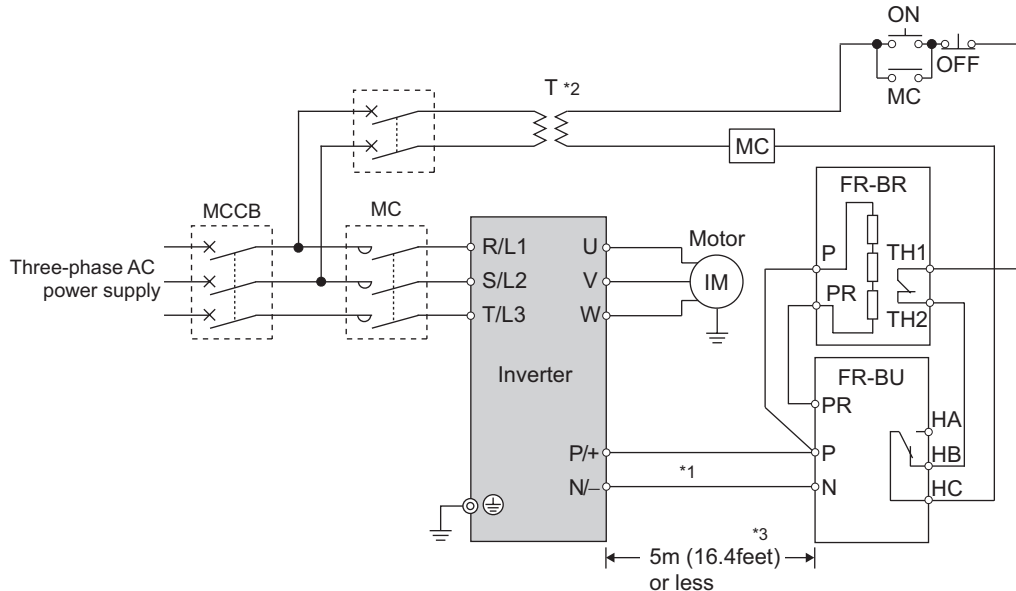
The inverter accepts a variety of stand-alone option units as required.

Incorrect connection will cause inverter damage or accident. Connect and operate the option unit carefully in accordance with the corresponding option unit manual.

### 1.5.1 Connection of the brake unit (FR-BU/MT-BU5)

When connecting the brake unit (FR-BU(H)/MT-BU5) to improve the brake capability at deceleration, make connection as shown below.

(1) Connection with the FR-BU (FR-F720-02330 (FR-F740-01160) or less)



\*1 Connect the inverter terminals (P/+, N/-) and brake unit (FR-BU (H)) terminals so that their terminal signals match with each other. (Incorrect connection will damage the inverter.)

\*2 When the power supply is 400V class, install a step-down transformer.

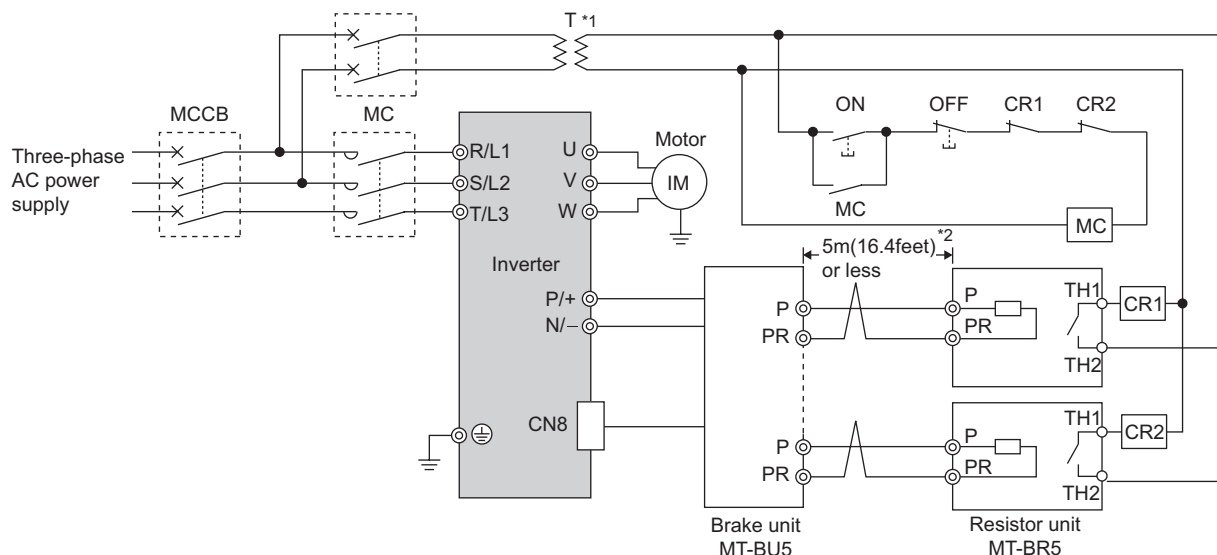
\*3 The wiring distance between the inverter, brake unit (FR-BU) and resistor unit (FR-BR) should be within 5m(16.4 feet). If twisted wires are used, the distance should be within 10m(32.8feet).

### CAUTION

- If the transistors in the brake unit should become faulty, the resistor can be unusually hot, causing a fire. Therefore, install a magnetic contactor on the inverter's input side to configure a circuit so that a current is shut off in case of fault.

## **(2) Connection with the MT-BU5 (FR-F720-03160 (FR-F740-01800) or more)**

After making sure that the wiring is correct, set "1" in *Pr.30 Regenerative function selection*. (Refer to page 88)



\*1 When the power supply is 400V class, install a step-down transformer.

\*2 The wiring length between the resistor unit and brake resistor should be 10m(32.8feet) maximum when wires are twisted and 5m(16.4feet) maximum when wires are not twisted.

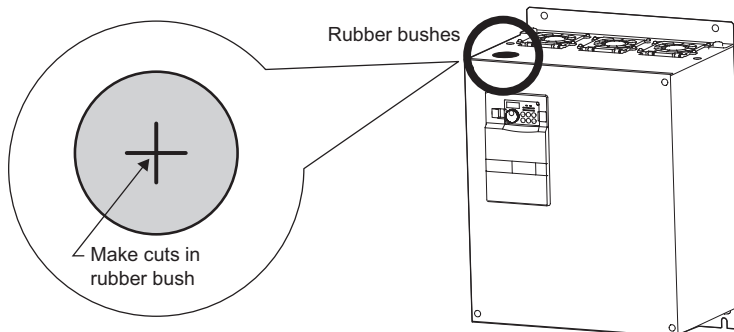
### **CAUTION**

- Install the brake unit in a place where a cooling air reaches the brake unit heatsink and within a distance of the cable supplied with the brake unit reaches the inverter.
- For wiring of the brake unit and inverter, use an accessory cable supplied with the brake unit. Connect the main circuit cable to the inverter terminals P/+ and N/- and connect the control circuit cable to the CN8 connector inside by making cuts in the rubber bush at the top of the inverter for leading the cable.
- The brake unit which uses multiple resistor units has terminals equal to the number of resistor units. Connect one resistor unit to one pair of terminal (P, PR).

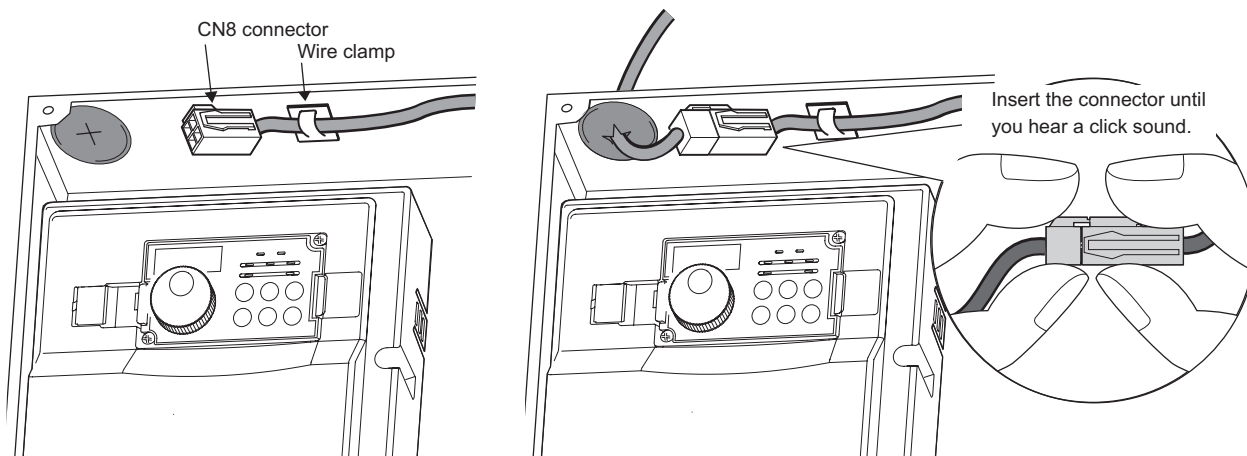
### **<Inserting the CN8 connector>**

Make cuts in rubber bush of the upper portion of the inverter and lead a cable.

- Make cuts in the rubber bush for leading the CN8 connector cable with a nipper or cutter knife.



- Insert a connector on the MT-BU5 side through a rubber bush to connect to a connector on the inverter side.

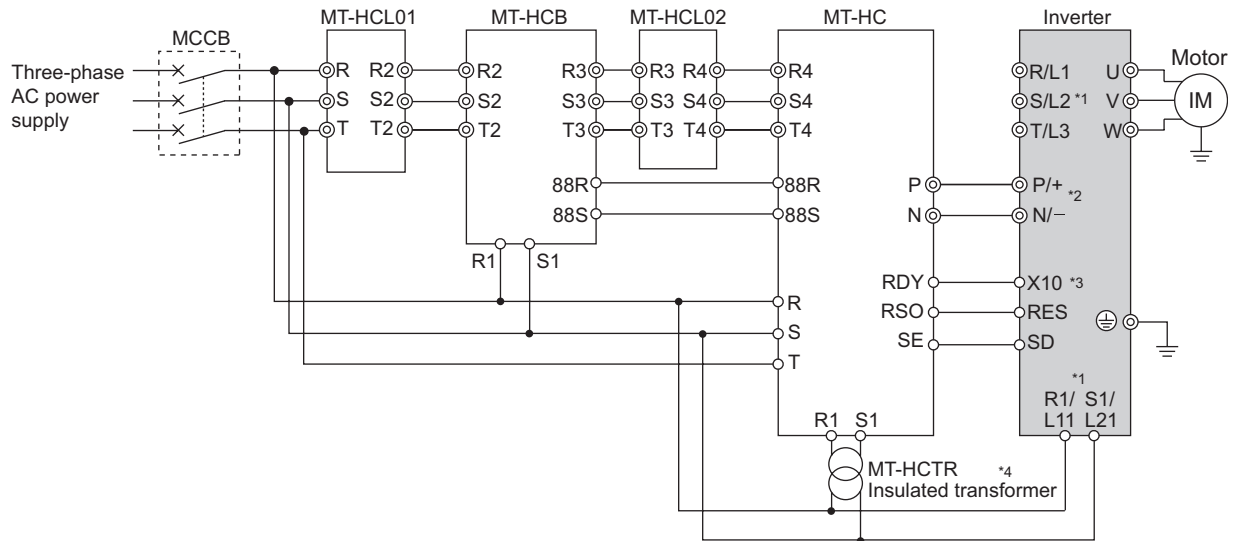


### **CAUTION**

Clamp the CN8 connector cable on the inverter side with a wire clamp securely.

**24**

## **(2) Connection with the MT-HC (FR-F720-03160 (FR-F740-01800) or more)**



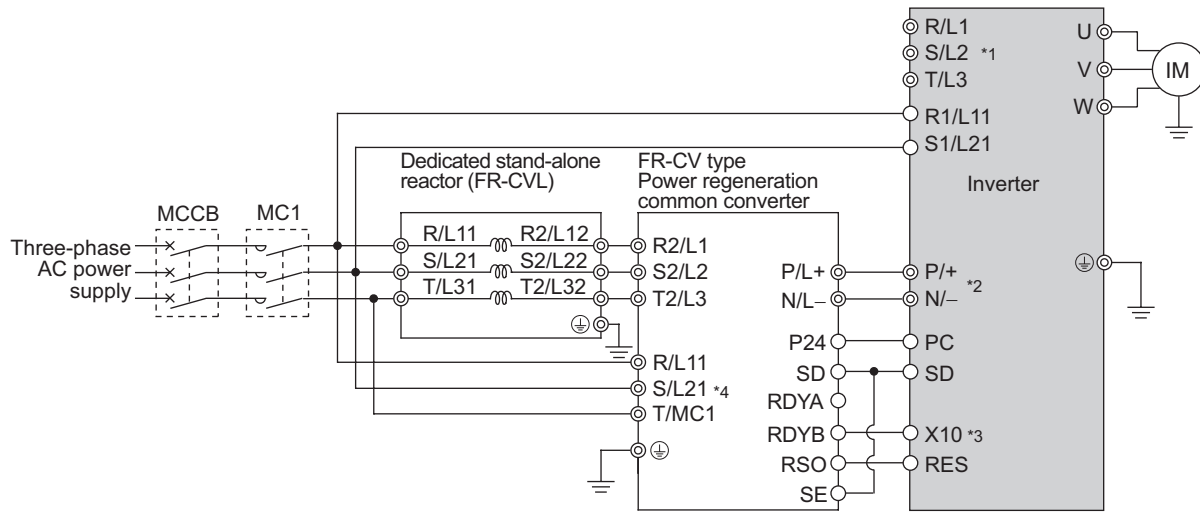
- \*1 Remove the jumper across terminals R-R1, S-S1 of the inverter, and connect the control circuit power supply to the R1 and S1 terminals. The power input terminals R/L1, S/L2, T/L3 must be open. Incorrect connection will damage the inverter. (E.OPT (option alarm) will occur. (Refer to page 238.)
- \*2 Do not insert the MCCB between terminals P/+ – N/- (P/+ – P/+, N/- – N/-). Opposite polarity of terminals N, P will damage the inverter.
- \*3 Use Pr. 178 to Pr. 189 (input terminal function selection) to assign the terminals used for the X10 (X11) signal. (Refer to page 90.) For communication where the start command is sent only once, e.g. RS-485 communication operation, use the X11 signal when making setting to hold the mode at occurrence of an instantaneous power failure. (Refer to page 88.)
- \*4 Connect the power supply to terminals R1 and S1 of the MT-HC via an insulated transformer.

### **CAUTION**

- Use sink logic (factory setting) when the MT-HC is connected. The MT-HC cannot be connected when source logic is selected.
- The voltage phases of terminals R/L1, S/L2, T/L3 and terminals R4, S4, T4 must be matched.
- When connecting the inverter to the MT-HC, do not connect the DC reactor provided to the inverter.

### 1.5.4 Connection of the power regeneration common converter (FR-CV)

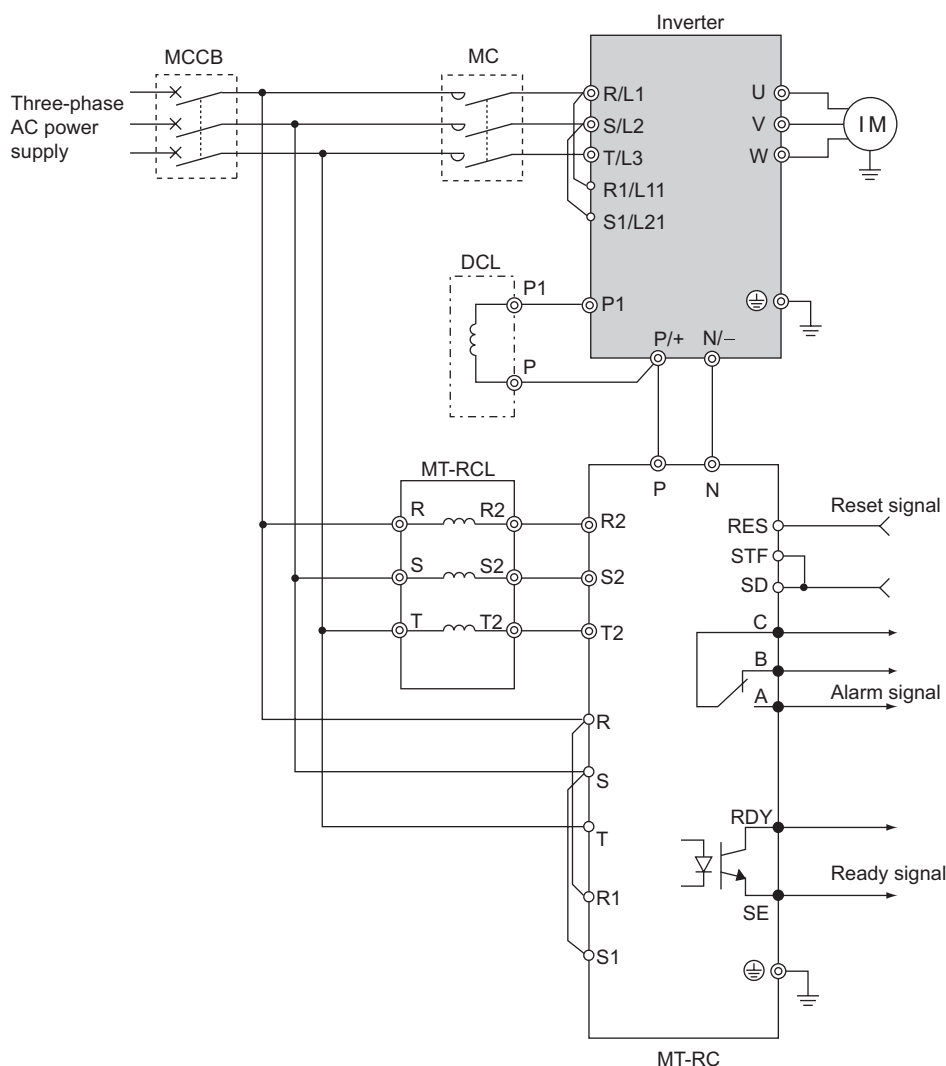
When connecting the power regeneration common converter (FR-CV), make connection so that the inverter terminals (P/+, N/-) and the terminal symbols of the power regeneration common converter (FR-CV) are the same. After making sure that the wiring is correct, set "2" in Pr. 30 Regenerative function selection. (Refer to page 88.)



- \*1 Remove the jumpers across terminals R/L1-R1/L11 and S/L2-S1/L21 of the inverter, and connect the control circuit power supply across terminals R1/L11-S1/L21. Always keep the power input terminals R/L1, S/L2, T/L3 open. Incorrect connection will damage the inverter. (E.OPT (option alarm) will occur. (Refer to page 238.)) Opposite polarity of terminals N/-, P/+ will damage the inverter.
- \*2 Do not insert an MCCB between the terminals P/+ – N/- (between P/L+ – P/+, between N/L- – N/-).
- \*3 Assign the terminal for X10 signal using any of Pr. 178 to Pr. 189 (input terminal function selection). (Refer to page 90)
- \*4 Be sure to connect the power supply and terminals R/L11, S/L21, T/MC1. Operating the inverter without connecting them will damage the power regeneration common converter.

#### CAUTION

1. Use sink logic (factory setting) when the FR-CV is connected. The FR-CV cannot be connected when source logic is selected.
2. The voltage phases of terminals R/L11, S/L21, T/MC1 and terminals R2/L1, S2/L2, T2/L3 must be matched.



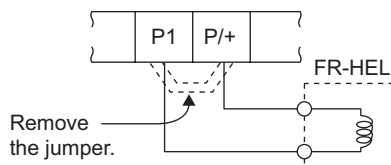
### CAUTION

- Refer to the MT-RC manual for precautions for connecting the power coordination reactor and others.

### 1.5.6 Connection of the power factor improving DC reactor (FR-HEL)

When using the DC reactor (FR-HEL), connect it between terminals P1-P/+.

For the FR-F720-02330 (FR-F740-01160) or less, the jumper connected across terminals P1-P/+ must be removed. Otherwise, the reactor will not exhibit its performance.

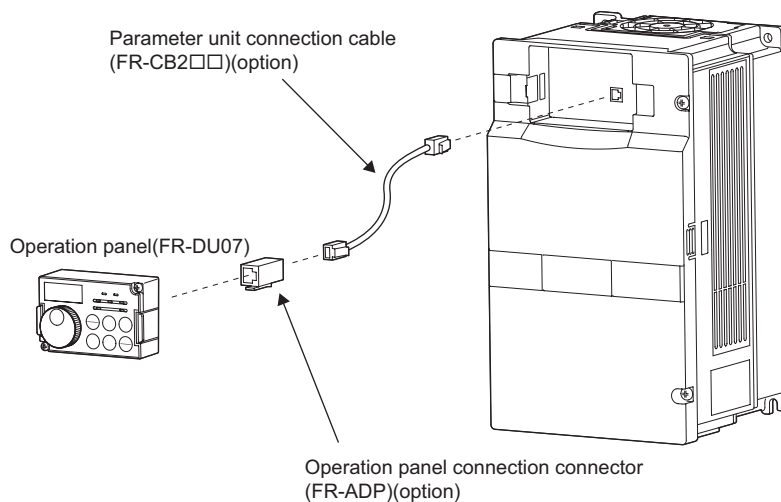


### CAUTION

1. The wiring distance should be within 5m(16.4feet).
2. The size of the cables used should be equal to or larger than that of the power supply cables (R/L1, S/L2, T/L3).

### 1.5.7 When connecting the operation panel using a connection cable

Using the optional parameter unit connection cable (FR-CB2□□), you can mount the operation panel (FR-DU07) on the enclosure surface, for example, to perform remote operation or monitoring.



#### REMARKS

- Overall wiring length when the operation panel is connected: 20m(65.6 feet)
- Refer to the following when fabricating the cable on the user side.  
Commercially available product examples  
(as of Apr, 2004)

|    | Product         | Type                  | Maker                             |
|----|-----------------|-----------------------|-----------------------------------|
| 1) | 10BASE-T cable  | SGLPEV-T 0.5mm × 4P * | Mitsubishi Cable Industries, Ltd. |
| 2) | RJ-45 connector | 5-554720-3            | Tyco Electronics Corporation      |

\* Do not use pins No. 2, 8 of the 10BASE-T cable.

☞ Refer to page 166 for RS-485 communication.

# 2 PRECAUTIONS FOR USE OF THE INVERTER

This chapter explains the "PRECAUTIONS FOR USE OF THE INVERTER" for use of this product.

Always read the instructions before using the equipment

|     |                                           |    |
|-----|-------------------------------------------|----|
| 2.1 | Enclosure design.....                     | 30 |
| 2.2 | Precautions for use of the inverter ..... | 34 |
| 2.3 | Others .....                              | 35 |

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## 2.1 Enclosure design

When an inverter enclosure is to be designed and manufactured, heat generated by contained equipment, etc., the environment of an operating place, and others must be fully considered to determine the enclosure structure, size and equipment layout. The inverter unit uses many semiconductor devices. To ensure higher reliability and long period of operation, operate the inverter in the ambient environment that completely satisfies the equipment specifications.

### 2.1.1 Inverter installation environment

As the inverter installation environment should satisfy the standard specifications indicated in the following table, operation in any place that does not meet these conditions not only deteriorates the performance and life of the inverter, but also causes a failure. Refer to the following points and take adequate measures.

**Environmental standard specifications of inverter**

| Item                | Description                                                |                                             |
|---------------------|------------------------------------------------------------|---------------------------------------------|
| Ambient temperature | LD                                                         | -10 to +50°C (14°F to 122°F) (non-freezing) |
|                     | SLD(Initial setting)                                       | -10 to +40°C (14°F to 104°F) (non-freezing) |
| Ambient humidity    | 90% RH maximum (non-condensing)                            |                                             |
| Atmosphere          | Free from corrosive and explosive gases, dust and dirt     |                                             |
| Maximum Altitude    | 1,000m (3280.80 feet) or less                              |                                             |
| Vibration           | 5.9m/s <sup>2</sup> or less *1 (JIS C 60068-2-6 compliant) |                                             |

\*1 2.9m/s<sup>2</sup> or less for the FR-F740-04320 or more.

#### (1) Temperature

The permissible ambient temperature of the inverter is -10°C (14°F) to +50°C (122°F) (when LD is set) or -10°C (14°F) to +40°C (104°F) (when SLD is set). Always operate the inverter within this temperature range. Operation outside this range will considerably shorten the service lives of the semiconductors, parts, capacitors and others. Take the following measures so that the ambient temperature of the inverter falls within the specified range.

##### 1) Measures against high temperature

- Use a forced ventilation system or similar cooling system. (Refer to page 32.)
- Install the enclosure in an air-conditioned electrical chamber.
- Block direct sunlight.
- Provide a shield or similar plate to avoid direct exposure to the radiated heat and wind of a heat source.
- Ventilate the area around the enclosure well.

##### 2) Measures against low temperature

- Provide a space heater in the enclosure.
- Do not power off the inverter. (Keep the start signal of the inverter off.)

##### 3) Sudden temperature changes

- Select an installation place where temperature does not change suddenly.
- Avoid installing the inverter near the air outlet of an air conditioner.
- If temperature changes are caused by opening/closing of a door, install the inverter away from the door.

#### (2) Humidity

Normally operate the inverter within the 45 to 90% range of the ambient humidity. Too high humidity will pose problems of reduced insulation and metal corrosion. On the other hand, too low humidity may produce a spatial electrical breakdown. The insulation distance specified in JEM1103 "Control Equipment Insulator" is defined as humidity 45 to 85%.

##### 1) Measures against high humidity

- Make the enclosure enclosed, and provide it with a hygroscopic agent.
- Take dry air into the enclosure from outside.
- Provide a space heater in the enclosure.

##### 2) Measures against low humidity

What is important in fitting or inspection of the unit in this status is to discharge your body (static electricity) beforehand and keep your body from contact with the parts and patterns, besides blowing air of proper humidity into the enclosure from outside.

##### 3) Measures against condensation

Condensation may occur if frequent operation stops change the in-enclosure temperature suddenly or if the outside-air temperature changes suddenly.

Condensation causes such faults as reduced insulation and corrosion.

- Take the measures against high humidity in 1).
- Do not power off the inverter. (Keep the start signal of the inverter off.)

### (3) Dust, dirt, oil mist

Dust and dirt will cause such faults as poor contact of contact points, reduced insulation or reduced cooling effect due to moisture absorption of accumulated dust and dirt, and in-enclosure temperature rise due to clogged filter.

In the atmosphere where conductive powder floats, dust and dirt will cause such faults as malfunction, deteriorated insulation and short circuit in a short time.

Since oil mist will cause similar conditions, it is necessary to take adequate measures.

#### Countermeasures

- Place in a totally enclosed enclosure.  
Take measures if the in-enclosure temperature rises. (*Refer to page 32.*)
- Purge air.  
Pump clean air from outside to make the in-enclosure pressure higher than the outside-air pressure.

### (4) Corrosive gas, salt damage

If the inverter is exposed to corrosive gas or to salt near a beach, the printed board patterns and parts will corrode or the relays and switches will result in poor contact.

In such places, take the measures given in Section (3).

### (5) Explosive, flammable gases

As the inverter is non-explosion proof, it must be contained in an explosion proof enclosure.

In places where explosion may be caused by explosive gas, dust or dirt, an enclosure cannot be used unless it structurally complies with the guidelines and has passed the specified tests. This makes the enclosure itself expensive (including the test charges).

The best way is to avoid installation in such places and install the inverter in a non-hazardous place.

### (6) Highland

Use the inverter at the altitude of within 1000m (3280.80 feet).

If it is used at a higher place, it is likely that thin air will reduce the cooling effect and low air pressure will deteriorate dielectric strength.

### (7) Vibration, impact

The vibration resistance of the inverter is up to  $5.9\text{m/s}^2$  ( $2.9\text{m/s}^2$  for the FR-F740-04320 or more) at 10 to 55Hz frequency and 1mm (0.04 inches) amplitude as specified in JIS C 60068-2-6.

Vibration or impact, if less than the specified value, applied for a long time may make the mechanism loose or cause poor contact to the connectors.

Especially when impact is imposed repeatedly, caution must be taken as the part pins are likely to break.

#### Countermeasures

- Provide the enclosure with rubber vibration isolators.
- Strengthen the structure to prevent the enclosure from resonance.
- Install the enclosure away from sources of vibration.

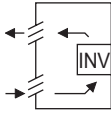
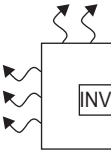
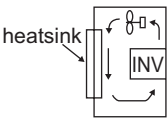
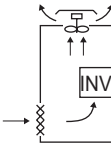
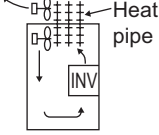


### 2.1.2 Cooling system types for inverter enclosure

From the enclosure that contains the inverter, the heat of the inverter and other equipment (transformers, lamps, resistors, etc.) and the incoming heat such as direct sunlight must be dissipated to keep the in-enclosure temperature lower than the permissible temperatures of the in-enclosure equipment including the inverter.

The cooling systems are classified as follows in terms of the cooling calculation method.

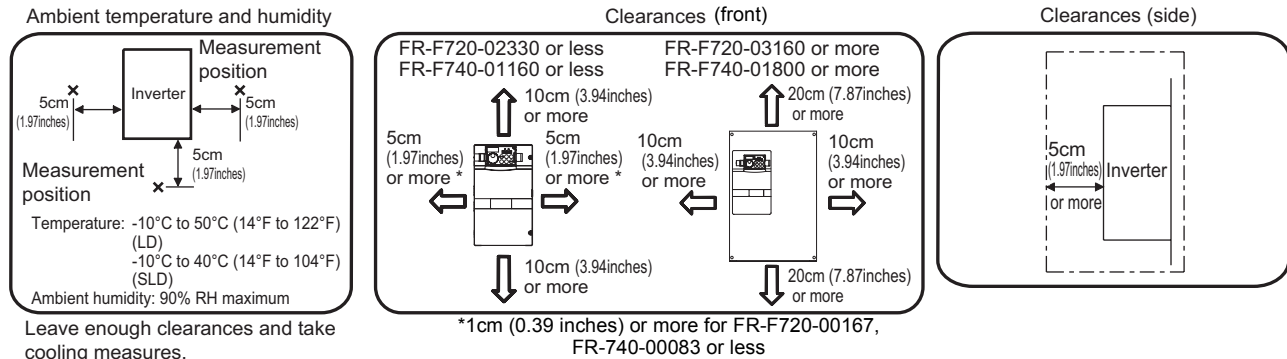
- 1) Cooling by natural heat dissipation from the enclosure surface (Totally enclosed type)
- 2) Cooling by heat sink (Aluminum fin, etc.)
- 3) Cooling by ventilation (Forced ventilation type, pipe ventilation type)
- 4) Cooling by heat exchanger or cooler (Heat pipe, cooler, etc.)

| Cooling System         | Enclosure Structure                                                                                                              | Comment                                                                                                                                                                        |
|------------------------|----------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Natural cooling</b> | Natural ventilation (Enclosed, open type)<br>   | Low in cost and generally used, but the enclosure size increases as the inverter capacity increases. For relatively small capacities.                                          |
|                        | Natural ventilation (Totally enclosed type)<br> | Being a totally enclosed type, the most appropriate for hostile environment having dust, dirt, oil mist, etc. The enclosure size increases depending on the inverter capacity. |
| <b>Forced cooling</b>  | Heatsink cooling<br>                           | Having restrictions on the heatsink mounting position and area, and designed for relative small capacities.                                                                    |
|                        | Forced ventilation<br>                        | For general indoor installation. Appropriate for enclosure downsizing and cost reduction, and often used.                                                                      |
|                        | Heat pipe<br>                                 | Totally enclosed type for enclosure downsizing.                                                                                                                                |

## 2.1.3 Inverter placement

### (1) Clearances around the inverter

To ensure ease of heat dissipation and maintenance, leave at least the shown clearances around the inverter. At least the following clearances are required under the inverter as a wiring space, and above the inverter as a heat dissipation space.



#### REMARKS

For replacing the cooling fan of the FR-F740-04320 or more, 30cm(11.8 inches) of space is necessary in front of the inverter. Refer to the *Instruction Manual (basic)* for fan replacement.

### (2) Inverter mounting orientation

Mount the inverter on a wall as specified. Do not mount it horizontally or any other way.

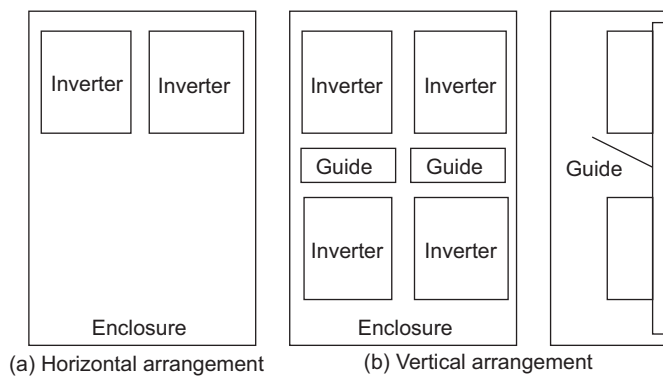
### (3) Above the inverter

Heat is blown up from inside the inverter by the small fan built in the unit. Any equipment placed above the inverter should be heat resistant.

### (4) Arrangement of multiple inverters

When multiple inverters are placed in the same enclosure, generally arrange them horizontally as shown in the right figure (a). When it is inevitable to arrange them vertically to minimize space, take such measures as to provide guides since heat from the bottom inverters can increase the temperatures in the top inverters, causing inverter failures.

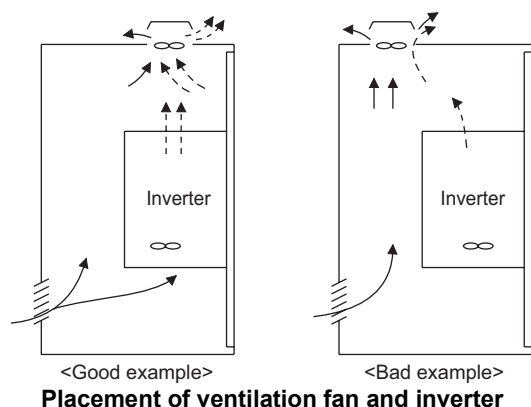
When mounting multiple inverters, fully take caution not to make the ambient temperature of the inverter higher than the permissible value by providing ventilation and increasing the enclosure size.



Arrangement of multiple inverters

### (5) Placement of ventilation fan and inverter

Heat generated in the inverter is blown up from the bottom of the unit as warm air by the cooling fan. When installing a ventilation fan for that heat, determine the place of ventilation fan installation after fully considering an air flow. (Air passes through areas of low resistance. Make an airway and airflow plates to expose the inverter to cool air.)



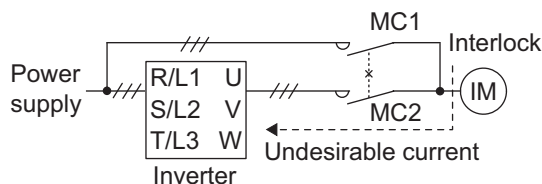


## 2.2 Precautions for use of the inverter

The FR-F700 series is a highly reliable product, but incorrect peripheral circuit making or operation/handling method may shorten the product life or damage the product.

Before starting operation, always recheck the following items.

- (1) Use crimping terminals with insulation sleeve to wire the power supply and motor.
- (2) Application of power to the output terminals (U, V, W) of the inverter will damage the inverter. Never perform such wiring.
- (3) After wiring, wire offcuts must not be left in the inverter.  
Wire offcuts can cause an alarm, failure or malfunction. Always keep the inverter clean. When drilling mounting holes in an enclosure etc., take care not to allow chips and other foreign matter to enter the inverter.
- (4) Use cables of the size to make a voltage drop 2% maximum.  
If the wiring distance is long between the inverter and motor, a main circuit cable voltage drop will cause the motor torque to decrease especially at the output of a low frequency.  
Refer to *page 10* for the recommended cable sizes.
- (5) The overall wiring length should be 500m (1640.4 feet) maximum.  
Especially for long distance wiring, the fast-response current limit function may be reduced or the equipment connected to the inverter output side may malfunction or become faulty under the influence of a charging current due to the stray capacity of the wiring. Therefore, note the overall wiring length. (*Refer to page 13.*)
- (6) Electromagnetic wave interference  
The input/output (main circuit) of the inverter includes high frequency components, which may interfere with the communication devices (such as AM radios) used near the inverter. In this case, set the EMC filter valid to minimize interference. (*Refer to page 40*)
- (7) Do not install a power factor correction capacitor, varistor or arrester on the inverter output side.  
This will cause the inverter to trip or the capacitor, varistor, or arrester to be damaged. If any of the above devices is installed, immediately remove it.
- (8) Before starting wiring or other work after the inverter is operated, wait for at least 10 minutes after the power supply has been switched off, and check that there are no residual voltage using a tester or the like. The capacitor is charged with high voltage for some time after power off and it is dangerous.
- (9) A short circuit or ground fault on the inverter output side may damage the inverter modules.
  - Fully check the insulation resistance of the circuit prior to inverter operation since repeated short circuits caused by peripheral circuit inadequacy or a ground fault caused by wiring inadequacy or reduced motor insulation resistance may damage the inverter modules.
  - Fully check the to-ground insulation and inter-phase insulation of the inverter output side before power-on.  
Especially for an old motor or use in hostile atmosphere, securely check the motor insulation resistance etc.
- (10) Do not use the inverter input side magnetic contactor to start/stop the inverter.  
Always use the start signal (ON/OFF of STF and STR signals) to start/stop the inverter. (*Refer to page 37*)
- (11) Do not apply a voltage higher than the permissible voltage to the inverter I/O signal circuits.  
Contact to the inverter I/O signal circuits or opposite polarity may damage the I/O devices. Especially check the wiring to prevent the speed setting potentiometer from being connected incorrectly to short terminals 10E-5.
- (12) Provide electrical and mechanical interlocks for MC1 and MC2 which are used for commercial power supply-inverter switch-over.  
When the wiring is incorrect or if there is a commercial power supply-inverter switch-over circuit as shown below, the inverter will be damaged by leakage current from the power supply due to arcs generated at the time of switch-over or chattering caused by a sequence error.



- (13) If the machine must not be restarted when power is restored after a power failure, provide a magnetic contactor in the inverter's input side and also make up a sequence which will not switch on the start signal.  
If the start signal (start switch) remains on after a power failure, the inverter will automatically restart as soon as the power is restored.
- (14) Instructions for overload operation  
When performing operation of frequent start/stop of the inverter, increase/decrease in the temperature of the transistor element of the inverter may repeat due to a continuous flow of large current, shortening the life from thermal fatigue. Since thermal fatigue is related to the amount of current, the life can be increased by reducing bound current, starting current, etc. Decreasing current may increase the life. However, decreasing current will result in insufficient torque and the inverter may not start. Therefore, increase the inverter capacity to have enough allowance for current.
- (15) Make sure that the specifications and rating match the system requirements.

## 2.3 Others

### 2.3.1 Leakage currents and countermeasures

Capacitances exist between the inverter I/O cables, other cables and earth and in the motor, through which a leakage current flows. Since its value depends on the capacitances, carrier frequency, etc., low acoustic noise operation at the increased carrier frequency of the inverter will increase the leakage current. Therefore, take the following measures. Select the earth leakage breaker according to its rated sensitivity current, independently of the carrier frequency setting.

#### (1) To-ground leakage currents

Leakage currents may flow not only into the inverter's own line but also into the other lines through the ground cable, etc. These leakage currents may operate ground leakage circuit breakers and earth leakage relays unnecessarily.

##### ● Countermeasures

- If the carrier frequency setting is high, decrease the *Pr. 72 PWM frequency selection* setting. Note that motor noise increases. Selecting *Pr. 240 Soft-PWM operation selection* makes the sound inoffensive.
- By using earth leakage circuit breakers designed for harmonic and surge suppression in the inverter's own line and other line, operation can be performed with the carrier frequency kept high (with low noise).

##### ● To-ground leakage currents

- Take caution as long wiring will increase the leakage current. Decreasing the carrier frequency of the inverter reduces the leakage current.
- Increasing the motor capacity increases the leakage current. The leakage current of the 400V class is larger than that of the 200V class.

#### (2) Line-to-line leakage currents

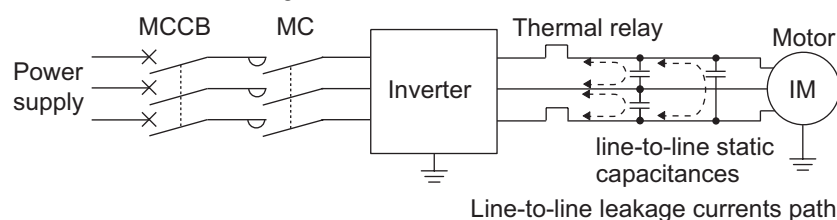
Harmonics of leakage currents flowing in static capacities between the inverter output cables may operate the external thermal relay unnecessarily. When the wiring length is long (50m(164.04feet) or more) for the 400V class small-capacity model (FR-F740-00170 or less), the external thermal relay is likely to operate unnecessarily because the ratio of the leakage current to the rated motor current increases.

##### ● Line-to-line leakage current data example(200V class)

| Motor Capacity (kW(HP)) | Rated Motor Current(A) | Leakage Currents(mA)          |                                |
|-------------------------|------------------------|-------------------------------|--------------------------------|
|                         |                        | Wiring length 50m(164.04feet) | Wiring length 100m(328.08feet) |
| 0.4(1/2)                | 1.8                    | 310                           | 500                            |
| 0.75(1)                 | 3.2                    | 340                           | 530                            |
| 1.5(2)                  | 5.8                    | 370                           | 560                            |
| 2.2(3)                  | 8.1                    | 400                           | 590                            |
| 3.7(5)                  | 12.8                   | 440                           | 630                            |
| 5.5(7.5)                | 19.4                   | 490                           | 680                            |
| 7.5(10)                 | 25.6                   | 535                           | 725                            |

- Dedicated motor SF-JR 4P
- Carrier frequency: 14.5kHz
- Used wire: 2mm<sup>2</sup>, 4cores Cabtyre cable

\*The leakage currents of the 400V class are about twice as large.



##### ● Countermeasures

- Use *Pr. 9 Electronic thermal O/L relay*.
- If the carrier frequency setting is high, decrease the *Pr. 72 PWM frequency selection* setting. Note that motor noise increases. Selecting *Pr. 240 Soft-PWM operation selection* makes the sound inoffensive. To ensure that the motor is protected against line-to-line leakage currents, it is recommended to use a temperature sensor to directly detect motor temperature.

##### ● Installation and selection of moulded case circuit breaker

Install a moulded case circuit breaker (MCCB) on the power receiving side to protect the wiring of the inverter input side. Select the MCCB according to the inverter input side power factor (which depends on the power supply voltage, output frequency and load). Especially for a completely electromagnetic MCCB, one of a slightly large capacity must be selected since its operation characteristic varies with harmonic currents. (Check it in the data of the corresponding breaker.) As a ground leakage breaker, use the Mitsubishi ground leakage breaker designed for harmonics and surge suppression.



### (3) Selection of rated sensitivity current of ground leakage breaker

When using the ground leakage circuit breaker with the inverter circuit, select its rated sensitivity current as follows, independently of the PWM carrier frequency:

- Breaker designed for harmonic and surge suppression

Rated sensitivity current:

$$I\Delta n \geq 10 \times (I_{g1} + I_{gn} + I_{gi} + I_{g2} + I_{gm})$$

- Standard breaker

Rated sensitivity current:

$$I\Delta n \geq 10 \times \{I_{g1} + I_{gn} + I_{gi} + 3 \times (I_{g2} + I_{gm})\}$$

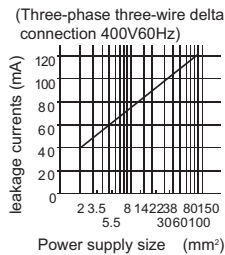
$I_{g1}$ ,  $I_{g2}$ : Leakage currents in wire path during commercial power supply operation

$I_{gn}$ : Leakage current of inverter input side noise filter

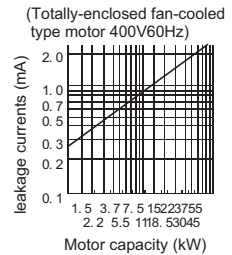
$I_{gm}$ : Leakage current of motor during commercial power supply operation

$I_{gi}$ : Leakage current of inverter unit

Example of leakage current per 1km during the commercial power supply operation when the CV cable is routed in metal conduit

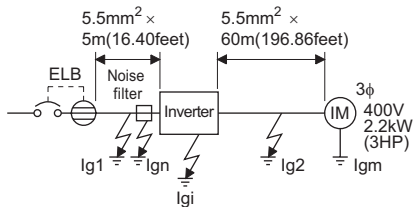


Leakage current example of Three-phase induction motor during the commercial power supply operation



For "Δ" connection, the amount of leakage current is 1/3

Example



|                                     | Breaker Designed for Harmonic and Surge Suppression                                                      | Standard Breaker |
|-------------------------------------|----------------------------------------------------------------------------------------------------------|------------------|
| Leakage current $I_{g1}$ (mA)       | $\frac{1}{3} \times 66 \times \frac{5m(16.40\text{feet})}{1000m} = 0.11$<br>(3280.80feet)                |                  |
| Leakage current $I_{gn}$ (mA)       | 0 (without noise filter)                                                                                 |                  |
| Leakage current $I_{gi}$ (mA)       | 1 (When there is no EMC filter)<br>Refer to the following table for the leakage current of the inverter* |                  |
| Leakage current $I_{g2}$ (mA)       | $\frac{1}{3} \times 66 \times \frac{60m(196.86\text{feet})}{1000m} = 1.32$<br>(3280.80feet)              |                  |
| Motor leakage current $I_{gm}$ (mA) | 0.36                                                                                                     |                  |
| Total leakage current (mA)          | 2.79                                                                                                     | 6.15             |
| Rated sensitivity current (mA)      | 30                                                                                                       | 100              |

\* Refer to page 40 for the presence/absence of the EMC filter.

#### ● Inverter leakage current (with and without EMC filter)

|                        | Voltage (V) | EMC Filter |          |
|------------------------|-------------|------------|----------|
|                        |             | ON (mA)    | OFF (mA) |
| Phase grounding        | 200         | 22(1)*     | 1        |
|                        | 400         | 30         | 1        |
| Earthed-neutral system | 400         | 1          | 1        |

Input power conditions  
(200V class: 220V/60Hz, 400V class: 440V/60Hz, power supply unbalance within 3%)

\*For the FR-F720-00046 and FR-F720-00077, the EMC filter is always valid.  
The leakage current is 1mA.

#### CAUTION

- Install the earth leakage breaker (ELB) on the input side of the inverter.
- In the Δ connection earthed-neutral system, the sensitivity current is purified against an ground fault in the inverter output side. Grounding must conform to the requirements of national and local safety regulations and electrical codes. (JIS, NEC section 250, IEC 536 class 1 and other applicable standards)
- When the breaker is installed on the output side of the inverter, it may be unnecessarily operated by harmonics even if the effective value is less than the rating. In this case, do not install the breaker since the eddy current and hysteresis loss will increase, leading to temperature rise.
- The following models are standard breakers....BV-C1, BC-V, NVB, NV-L, NV-G2N, NV-G3NA and NV-2F earth leakage relay (except NV-ZHA), NV with AA neutral wire open-phase protection  
The other models are designed for harmonic and surge suppression....NV-C/NV-S/MN series, NV30-FA, NV50-FA, BV-C2, earth leakage alarm breaker (NF-Z), NV-ZHA, NV-H

## 2.3.2 Power-off and magnetic contactor (MC)

### (1) Inverter input side magnetic contactor (MC)

On the inverter input side, it is recommended to provide an MC for the following purposes.

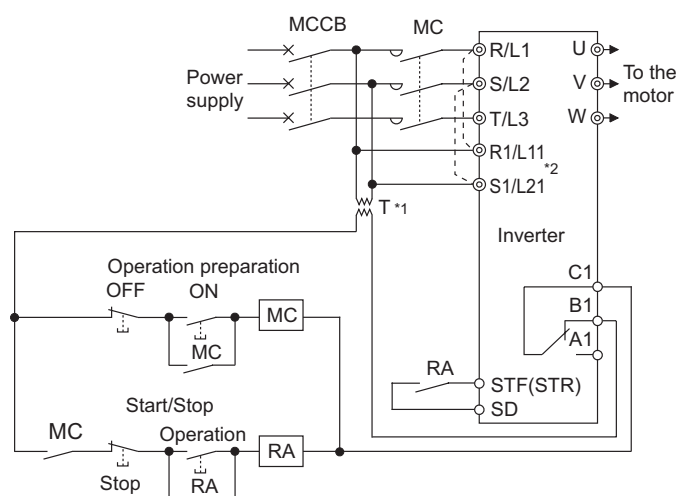
(Refer to page 3 for selection.)

- 1) To release the inverter from the power supply when the inverter's protective function is activated or when the drive is not functioning (e.g. emergency stop operation).
- 2) To prevent any accident due to an automatic restart at restoration of power after an inverter stop made by a power failure
- 3) The control power supply for inverter is always running and consumes a little power. When stopping the inverter for an extended period of time, powering off the inverter will save power slightly.
- 4) To separate the inverter from the power supply to ensure safe maintenance and inspection work

The inverter's input side MC is used for the above purpose, select class JEM1038-AC3MC for the inverter input side current when making an emergency stop during normal operation.

#### REMARKS

The MC may be switched on/off to start/stop the inverter. However, since repeated inrush currents at power on will shorten the life of the converter circuit (switching life is about 1,000,000 times (FR-F720-01540 or more, switching life is about 500,000)), frequent starts and stops must be avoided. Turn on/off the inverter start controlling terminals (STF, STR) to run/stop the inverter.



#### • Inverter start/stop circuit example

As shown on the left, always use the start signal (ON or OFF across terminals STF or STR-SD) to make a start or stop. (Refer to page 94)

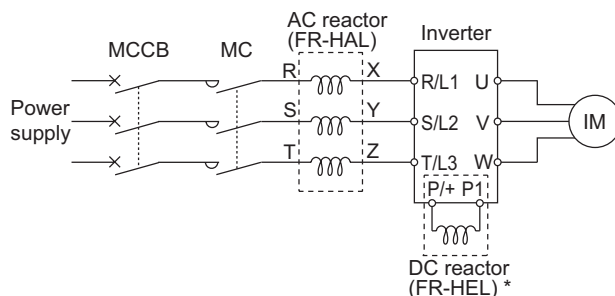
- \*1 When the power supply is 400V class, install a step-down transformer.
- \*2 Connect the power supply terminals R1/L11, S1/L21 of the control circuit to the primary side of the MC to hold an alarm signal when the inverter's protective circuit is activated. At this time, remove jumpers across terminals R/L1-R1/L11 and S/L2-S1/L21. (Refer to page 18 for removal of the jumper.)

### (2) Handling of the inverter output side magnetic contactor

Switch the magnetic contactor between the inverter and motor only when both the inverter and motor are at a stop. When the magnetic contactor is turned on while the inverter is operating, overcurrent protection of the inverter and such will activate. When an MC is provided to switch to a commercial power supply, for example, it is recommended to use commercial power supply-inverter switchover operation Pr. 135 to Pr. 139 (Refer to page 197).

### 2.3.3 Installation of a reactor

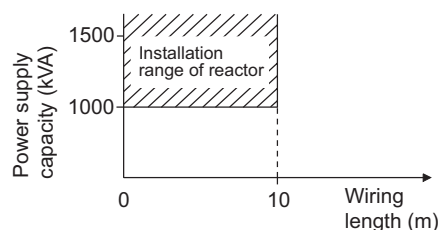
When the inverter is connected near a large-capacity power transformer (1000kVA or more and wiring length 10m(32.81feet) max.) or when a power capacitor is to be switched over, an excessive peak current may flow in the power input circuit, damaging the converter circuit. To prevent this, always install the optional DC reactor (FR-HEL) or AC reactor (FR-HAL)



- \* When connecting the FR-HEL to the FR-F720-02330 (FR-F740-01160) or less, remove the jumper across terminals P-P1. For the FR-F720-03160 (FR-F740-01800) or more, a DC reactor is supplied. Always install the reactor.

#### REMARKS

The wiring length between the FR-HEL and inverter should be 5m maximum and minimized. Use the same wire size as that of the power supply wire (R/L1, S/L2, T/L3). (Refer to page 10)





### 2.3.4 Inverter-generated noises and their reduction techniques

Some noises enter the inverter to malfunction it and others are radiated by the inverter to malfunction peripheral devices. Though the inverter is designed to be insusceptible to noises, it handles low-level signals, so it requires the following basic techniques. Also, since the inverter chops outputs at high carrier frequency, that could generate noises. If these noises cause peripheral devices to malfunction, measures should be taken to suppress noises. These techniques differ slightly depending on noise propagation paths.

#### 1) Basic techniques

- Do not run the power cables (I/O cables) and signal cables of the inverter in parallel with each other and do not bundle them.
- Use twisted pair shielded cables for the detector connection and control signal cables, and connect the sheathes of the shield cables to terminal SD.
- Ground the inverter, motor, etc. at one point.

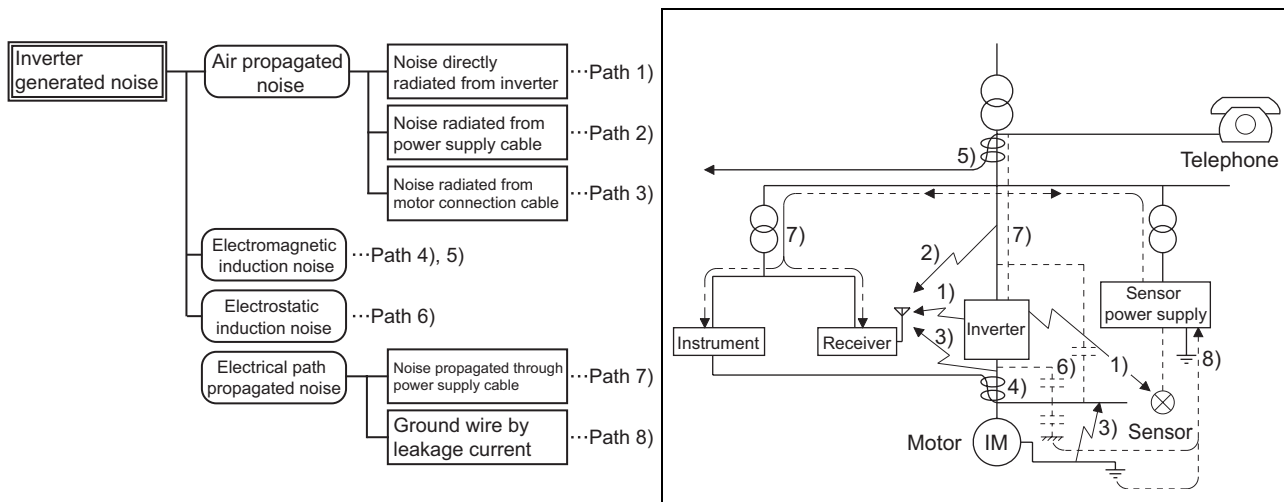
#### 2) Techniques to reduce noises that enter and malfunction the inverter

When devices that generate many noises (which use magnetic contactors, magnetic brakes, many relays, for example) are installed near the inverter and the inverter may be malfunctioned by noises, the following measures must be taken:

- Provide surge suppressors for devices that generate many noises to suppress noises.
- Fit data line filters to signal cables.
- Ground the shields of the detector connection and control signal cables with cable clamp metal.

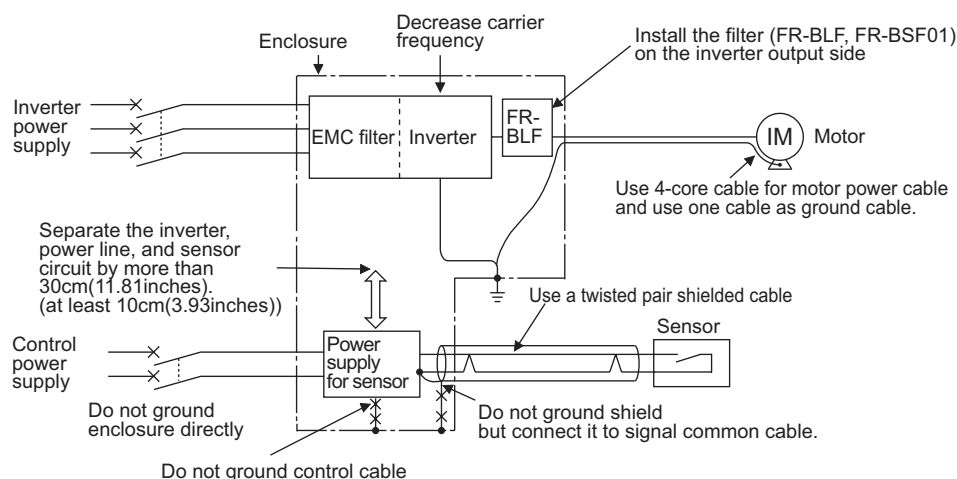
#### 3) Techniques to reduce noises that are radiated by the inverter to malfunction peripheral devices

Inverter-generated noises are largely classified into those radiated by the cables connected to the inverter and inverter main circuits (I/O), those electromagnetically and electrostatically induced to the signal cables of the peripheral devices close to the main circuit power supply, and those transmitted through the power supply cables.



| Noise Propagation Path | Measures                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
|------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1) 2) 3)               | <p>When devices that handle low-level signals and are liable to malfunction due to noises, e.g. instruments, receivers and sensors, are contained in the enclosure that contains the inverter or when their signal cables are run near the inverter, the devices may be malfunctioned by air-propagated noises. The following measures must be taken:</p> <ol style="list-style-type: none"> <li>(1) Install easily affected devices as far away as possible from the inverter.</li> <li>(2) Run easily affected signal cables as far away as possible from the inverter and its I/O cables.</li> <li>(3) Do not run the signal cables and power cables (inverter I/O cables) in parallel with each other and do not bundle them.</li> <li>(4) Set the EMC filter ON/OFF switch of the inverter to the ON position. <i>(Refer to page 40)</i></li> <li>(5) Inserting a line noise filter into the output suppresses the radiation noise from the cables.</li> <li>(6) Use shield cables as signal cables and power cables and run them in individual metal conduits to produce further effects.</li> </ol> |
| 4) 5) 6)               | <p>When the signal cables are run in parallel with or bundled with the power cables, magnetic and static induction noises may be propagated to the signal cables to malfunction the devices and the following measures must be taken:</p> <ol style="list-style-type: none"> <li>(1) Install easily affected devices as far away as possible from the inverter.</li> <li>(2) Run easily affected signal cables as far away as possible from the I/O cables of the inverter.</li> <li>(3) Do not run the signal cables and power cables (inverter I/O cables) in parallel with each other and do not bundle them.</li> <li>(4) Use shield cables as signal cables and power cables and run them in individual metal conduits to produce further effects.</li> </ol>                                                                                                                                                                                                                                                                                                                                         |
| 7)                     | <p>When the power supplies of the peripheral devices are connected to the power supply of the inverter in the same line, inverter-generated noises may flow back through the power supply cables to malfunction the devices and the following measures must be taken:</p> <ol style="list-style-type: none"> <li>(1) Set the EMC filter ON/OFF switch of the inverter to the ON position. <i>(Refer to page 40)</i></li> <li>(2) Install the line noise filter (FR-BLF, FR-BSF01) to the power cables (I/O cables) of the inverter.</li> </ol>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |
| 8)                     | <p>When a closed loop circuit is formed by connecting the peripheral device wiring to the inverter, leakage currents may flow through the ground cable of the inverter to malfunction the device. In such a case, disconnection of the ground cable of the device may cause the device to operate properly.</p>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |

### ●Noise reduction examples





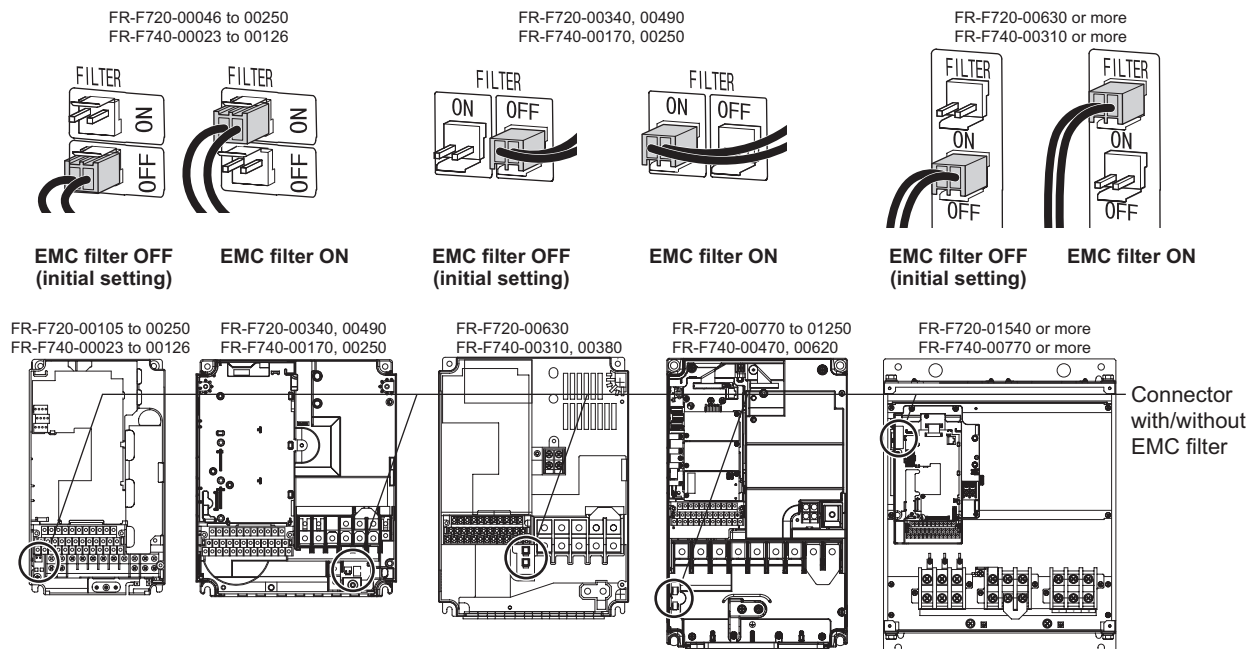
### 2.3.5 EMC filter

The inverter is equipped with a built-in EMC filter.

Effective for reduction of air-propagated noise on the input side of the inverter.

The EMC filter is factory-set to disable (OFF).

To enable it, fit the EMC filter ON/OFF connector to the ON position.

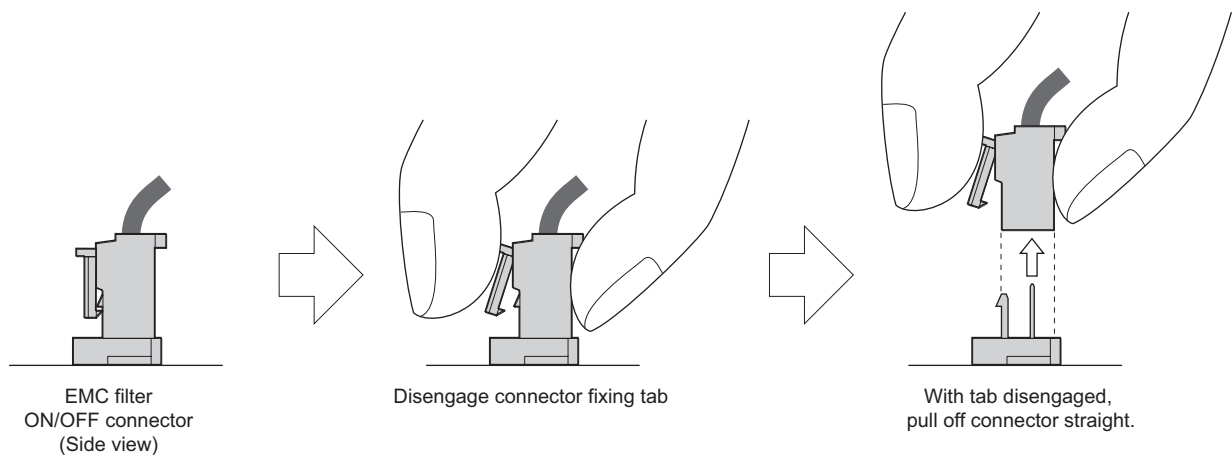


The FR-F720-00046 and 00077 are not provided with the ON/OFF connector of the EMC filter. (The EMC filter is always valid.)

#### <How to disconnect the connector>

- (1) After confirming that the power supply is off, remove the front cover. (For the front cover removal method, refer to the *Instruction Manual (basic)*.)
- (2) When disconnecting the connector, push the fixing tab and pull the connector straight without pulling the cable or forcibly pulling the connector with the tab fixed. When installing the connector, also engage the fixing tab securely.

If it is difficult to disconnect the connector, use a pair of long-nose pliers, etc.



#### CAUTION

- Fit the connector to either ON or OFF.
- Enabling (turning on) the EMC filter increase leakage current. (Refer to page 36)



## WARNING

While power is on or when the inverter is running, do not open the front cover. Otherwise you may get an electric shock.

### 2.3.6 Power supply harmonics

The inverter may generate power supply harmonics from its converter circuit to affect the power generator, power capacitor etc. Power supply harmonics are different from noise and leakage currents in source, frequency band and transmission path. Take the following countermeasure suppression techniques.

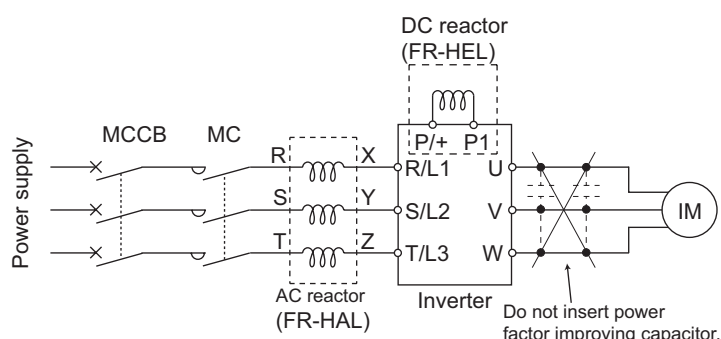
●The differences between harmonics and noises are indicated below:

| Item                        | Harmonics                                       | Noise                                                                      |
|-----------------------------|-------------------------------------------------|----------------------------------------------------------------------------|
| Frequency                   | Normally number 40 to 50 max.<br>(3kHz or less) | High frequency (several 10kHz to 1GHz order)                               |
| Environment                 | To-electric channel, power impedance            | To-space, distance, wiring path                                            |
| Quantitative understanding  | Theoretical calculation possible                | Random occurrence, quantitative grasping difficult                         |
| Generated amount            | Nearly proportional to load capacity            | Depending on the current fluctuation ratio (larger as switching is faster) |
| Affected equipment immunity | Specified in standard per equipment             | Different depending on maker's equipment specifications                    |
| Suppression example         | Provide reactor.                                | Increase distance.                                                         |

#### ●Measures

The harmonic current generated from the inverter to the input side differs according to various conditions such as the wiring impedance, whether a reactor is used or not, and output frequency and output current on the load side.

For the output frequency and output current, we understand that they should be calculated in the conditions under the rated load at the maximum operating frequency.



#### CAUTION

The power factor improving capacitor and surge suppressor on the inverter output side may be overheated or damaged by the harmonic components of the inverter output. Also, since an excessive current flows in the inverter to activate overcurrent protection, do not provide a capacitor and surge suppressor on the inverter output side when the motor is driven by the inverter. For power factor improvement, install a reactor on the inverter input side or in the DC circuit.



### 2.3.7 Inverter-driven 400V class motor

In the PWM type inverter, a surge voltage attributable to wiring constants is generated at the motor terminals. Especially for a 400V class motor, the surge voltage may deteriorate the insulation. When the 400V class motor is driven by the inverter, consider the following measures:

#### ●Measures

It is recommended to take either of the following measures:

- (1) Rectifying the motor insulation and limiting the PWM carrier frequency according to the wiring length  
For the 400V class motor, use an insulation-enhanced motor.  
Specifically,
  - 1) Specify the "400V class inverter-driven insulation-enhanced motor".
  - 2) For the dedicated motor such as the constant-torque motor and low-vibration motor, use the "inverter-driven, dedicated motor".
  - 3) Set *Pr. 72 PWM frequency selection* as indicated below according to the wiring length

|                                       | Wiring Length               |                                              |                                |
|---------------------------------------|-----------------------------|----------------------------------------------|--------------------------------|
|                                       | 50m (164.04feet)<br>or less | 50m to 100m<br>(164.04feet to<br>328.09feet) | exceeding 100m<br>(328.09feet) |
| <i>Pr. 72 PWM frequency selection</i> | 15(14.5kHz) or less         | 9(9kHz) or less                              | 4(4kHz) or less                |

- (2) Suppressing the surge voltage on the inverter side  
Connect the surge voltage suppression filter (FR-ASF-H) to the FR-F720-02330 (FR-F740-01160) or less and the sine wave filter (MT-BSL/BSC) to the FR-F720-03160 (FR-F740-01800) or more on the inverter output side.

#### CAUTION

- For details of *Pr. 72 PWM frequency selection*, refer to page 129.
- For explanation of surge voltage suppression filter (FR-ASF-H) and sine wave filter (MT-BSL/BSC), refer to the manual of each option.

# **3 PARAMETERS**

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This chapter explains the "PARAMETERS" for use of this product.

Always read this instructions before use.

---

1

2

3

4

5



## 3.1 Parameter List

### 3.1.1 Parameter list

In the initial setting, only the simple mode parameters are displayed.

Set Pr. 160 User group read selection as required.

| Parameter | Name                      | Initial Value | Setting Range | Remarks                                                            |
|-----------|---------------------------|---------------|---------------|--------------------------------------------------------------------|
| 160       | User group read selection | 0             | 9999          | Only the simple mode parameters can be displayed.                  |
|           |                           |               | 0             | Simple mode and extended mode parameters can be displayed.         |
|           |                           |               | 1             | Only the parameters registered in the user group can be displayed. |

#### REMARKS

- The parameters marked Ⓢ are the simple mode parameters.
- The parameters marked with   in the table allow its setting to be changed during operation even if "0" (initial value) is set in Pr. 77 Parameter write selection.
- Parameters for the option are displayed only when the option unit is installed.
- The instruction codes (hexadecimal) for "read" and "write" on the right of the parameter number are those used to set the parameter via communication. "Extended" indicates the setting of the extended link parameter. (Refer to page 161 for communication)

| Function           | Parameters | Instruction Code |       | Name                                   | Setting Range       | Minimum Setting Increments | Initial Value                 | Refer to Page | Customer Setting |
|--------------------|------------|------------------|-------|----------------------------------------|---------------------|----------------------------|-------------------------------|---------------|------------------|
|                    |            | Read             | Write |                                        |                     |                            |                               |               |                  |
| Basic functions    | Ⓢ 0        | 00<br>80         | 0     | Torque boost                           | 0 to 30%            | 0.1%                       | 6/4/3/2/<br>1.5/1%            | 58            |                  |
|                    | Ⓢ 1        | 01<br>81         | 0     | Maximum frequency                      | 0 to 120Hz          | 0.01Hz                     | 120/60Hz                      | 67            |                  |
|                    | Ⓢ 2        | 02<br>82         | 0     | Minimum frequency                      | 0 to 120Hz          | 0.01Hz                     | 0Hz                           | 67            |                  |
|                    | Ⓢ 3        | 03<br>83         | 0     | Base frequency                         | 0 to 400Hz          | 0.01Hz                     | 60Hz                          | 69            |                  |
|                    | Ⓢ 4        | 04<br>84         | 0     | Multi-speed setting (high speed)       | 0 to 400Hz          | 0.01Hz                     | 60Hz                          | 72            |                  |
|                    | Ⓢ 5        | 05<br>85         | 0     | Multi-speed setting (middle speed)     | 0 to 400Hz          | 0.01Hz                     | 30Hz                          | 72            |                  |
|                    | Ⓢ 6        | 06<br>86         | 0     | Multi-speed setting (low speed)        | 0 to 400Hz          | 0.01Hz                     | 10Hz                          | 72            |                  |
|                    | Ⓢ 7        | 07<br>87         | 0     | Acceleration time                      | 0 to 3600/ 360s     | 0.1/0.01s                  | 5s/15s                        | 79            |                  |
|                    | Ⓢ 8        | 08<br>88         | 0     | Deceleration time                      | 0 to 3600/ 360s     | 0.1/0.01s                  | 10s/30s                       | 79            |                  |
|                    | Ⓢ 9        | 09<br>89         | 0     | Electronic thermal O/L relay           | 0 to 500/0 to 3600A | 0.01/0.1A                  | Rated inverter output current | 83            |                  |
| DC injection brake | 10         | 0A<br>8A         | 0     | DC injection brake operation frequency | 0 to 120Hz, 9999    | 0.01Hz                     | 3Hz                           | 86            |                  |
|                    | 11         | 0B<br>8B         | 0     | DC injection brake operation time      | 0 to 10s, 8888      | 0.1s                       | 0.5s                          | 86            |                  |
|                    | 12         | 0C<br>8C         | 0     | DC injection brake operation voltage   | 0 to 30%            | 0.1%                       | 4/2/1%                        | 86            |                  |
| —                  | 13         | 0D<br>8D         | 0     | Starting frequency                     | 0 to 60Hz           | 0.01Hz                     | 0.5Hz                         | 81            |                  |
| —                  | 14         | 0E<br>8E         | 0     | Load pattern selection                 | 0, 1                | 1                          | 1                             | 65            |                  |
| Jog operation      | 15         | 0F<br>8F         | 0     | Jog frequency                          | 0 to 400Hz          | 0.01Hz                     | 5Hz                           | 74            |                  |
|                    | 16         | 10<br>90         | 0     | Jog acceleration/deceleration time     | 0 to 3600/360s      | 0.1/0.01s                  | 0.5s                          | 74            |                  |
| —                  | 17         | 11<br>91         | 0     | MRS input selection                    | 0, 2                | 1                          | 0                             | 92            |                  |

| Function                            | Parameters      | Instruction Code    |       |          | Name                                                                        | Setting Range                        | Minimum Setting Increments | Initial Value | Refer to Page | Customer Setting |
|-------------------------------------|-----------------|---------------------|-------|----------|-----------------------------------------------------------------------------|--------------------------------------|----------------------------|---------------|---------------|------------------|
|                                     |                 | Read                | Write | Extended |                                                                             |                                      |                            |               |               |                  |
| —                                   | <b>18</b>       | 12<br>92            |       | 0        | <b>High speed maximum frequency</b>                                         | 120 to 400Hz                         | 0.01Hz                     | 120/60Hz      | 67            |                  |
| —                                   | <b>19</b>       | 13<br>93            |       | 0        | <b>Base frequency voltage</b>                                               | 0 to 1000V, 8888, 9999               | 0.1V                       | 9999          | 69            |                  |
| Acceleration/<br>deceleration times | <b>20</b>       | 14<br>94            |       | 0        | <b>Acceleration/deceleration reference frequency</b>                        | 1 to 400Hz                           | 0.01Hz                     | 60Hz          | 79            |                  |
|                                     | <b>21</b>       | 15<br>95            |       | 0        | <b>Acceleration/deceleration time increments</b>                            | 0, 1                                 | 1                          | 0             | 79            |                  |
| Stall prevention                    | <b>22</b>       | 16<br>96            |       | 0        | <b>Stall prevention operation level</b>                                     | 0 to 120%, 9999                      | 0.1%                       | 110%          | 61            |                  |
|                                     | <b>23</b>       | 17<br>97            |       | 0        | <b>Stall prevention operation level compensation factor at double speed</b> | 0 to 150%, 9999                      | 0.1%                       | 9999          | 61            |                  |
| Multi-speed setting                 | <b>24 to 27</b> | 18 to B<br>98 to 9B |       | 0        | <b>Multi-speed setting 4 speed to 7 speed</b>                               | 0 to 400Hz, 9999                     | 0.01Hz                     | 9999          | 72            |                  |
| —                                   | <b>28</b>       | 1C<br>9C            |       | 0        | <b>Multi-speed input compensation selection</b>                             | 0, 1                                 | 1                          | 0             | 76            |                  |
| —                                   | <b>29</b>       | 1D<br>9D            |       | 0        | <b>Acceleration/deceleration pattern selection</b>                          | 0, 1, 2, 3                           | 1                          | 0             | 82            |                  |
| —                                   | <b>30</b>       | 1E<br>9E            |       | 0        | <b>Regenerative function selection</b>                                      | 0, 2/0, 1, 2                         | 1                          | 0             | 88            |                  |
| Frequency jump                      | <b>31</b>       | 1F<br>9F            |       | 0        | <b>Frequency jump 1A</b>                                                    | 0 to 400Hz, 9999                     | 0.01Hz                     | 9999          | 68            |                  |
|                                     | <b>32</b>       | 20<br>A0            |       | 0        | <b>Frequency jump 1B</b>                                                    | 0 to 400Hz, 9999                     | 0.01Hz                     | 9999          | 68            |                  |
|                                     | <b>33</b>       | 21<br>A1            |       | 0        | <b>Frequency jump 2A</b>                                                    | 0 to 400Hz, 9999                     | 0.01Hz                     | 9999          | 68            |                  |
|                                     | <b>34</b>       | 22<br>A2            |       | 0        | <b>Frequency jump 2B</b>                                                    | 0 to 400Hz, 9999                     | 0.01Hz                     | 9999          | 68            |                  |
|                                     | <b>35</b>       | 23<br>A3            |       | 0        | <b>Frequency jump 3A</b>                                                    | 0 to 400Hz, 9999                     | 0.01Hz                     | 9999          | 68            |                  |
|                                     | <b>36</b>       | 24<br>A4            |       | 0        | <b>Frequency jump 3B</b>                                                    | 0 to 400Hz, 9999                     | 0.01Hz                     | 9999          | 68            |                  |
| —                                   | <b>37</b>       | 25<br>A5            |       | 0        | <b>Speed display</b>                                                        | 0, 1 to 9998                         | 1                          | 0             | 104           |                  |
| Frequency detection                 | <b>41</b>       | 29<br>A9            |       | 0        | <b>Up-to-frequency sensitivity</b>                                          | 0 to 100%                            | 0.1%                       | 10%           | 100           |                  |
|                                     | <b>42</b>       | 2A<br>AA            |       | 0        | <b>Output frequency detection</b>                                           | 0 to 400Hz                           | 0.01Hz                     | 6Hz           | 100           |                  |
|                                     | <b>43</b>       | 2B<br>AB            |       | 0        | <b>Output frequency detection for reverse rotation</b>                      | 0 to 400Hz, 9999                     | 0.01Hz                     | 9999          | 100           |                  |
| Second functions                    | <b>44</b>       | 2C<br>AC            |       | 0        | <b>Second acceleration/deceleration time</b>                                | 0 to 3600/360s                       | 0.1/0.01s                  | 5s            | 79            |                  |
|                                     | <b>45</b>       | 2D<br>AD            |       | 0        | <b>Second deceleration time</b>                                             | 0 to 3600/360s, 9999                 | 0.1/0.01s                  | 9999          | 79            |                  |
|                                     | <b>46</b>       | 2E<br>AE            |       | 0        | <b>Second torque boost</b>                                                  | 0 to 30%, 9999                       | 0.1%                       | 9999          | 58            |                  |
|                                     | <b>47</b>       | 2F<br>AF            |       | 0        | <b>Second V/F (base frequency)</b>                                          | 0 to 400Hz, 9999                     | 0.01Hz                     | 9999          | 69            |                  |
|                                     | <b>48</b>       | 30<br>B0            |       | 0        | <b>Second stall prevention operation current</b>                            | 0 to 120%                            | 0.1%                       | 110%          | 61            |                  |
|                                     | <b>49</b>       | 31<br>B1            |       | 0        | <b>Second stall prevention operation frequency</b>                          | 0 to 400Hz, 9999                     | 0.01Hz                     | 0Hz           | 61            |                  |
|                                     | <b>50</b>       | 32<br>B2            |       | 0        | <b>Second output frequency detection</b>                                    | 0 to 400Hz                           | 0.01Hz                     | 30Hz          | 100           |                  |
|                                     | <b>51</b>       | 33<br>B3            |       | 0        | <b>Second electronic thermal O/L relay</b>                                  | 0 to 500A, 9999/<br>0 to 3600A, 9999 | 0.01/0.1A                  | 9999          | 83            |                  |



| Function                            | Parameters | Instruction Code |       |          | Name                                                        | Setting Range                                     | Minimum Setting Increments | Initial Value                 | Refer to Page | Customer Setting |
|-------------------------------------|------------|------------------|-------|----------|-------------------------------------------------------------|---------------------------------------------------|----------------------------|-------------------------------|---------------|------------------|
|                                     |            | Read             | Write | Extended |                                                             |                                                   |                            |                               |               |                  |
| Monitor functions                   | 52         | 34               | B4    | 0        | DU/PU main display data selection                           | 0, 5, 6, 8 to 14, 17, 20, 23 to 25, 50 to 57, 100 | 1                          | 0                             | 105           |                  |
|                                     |            |                  |       |          |                                                             |                                                   |                            |                               |               |                  |
|                                     | 54         | 36               | B6    | 0        | CA terminal function selection                              | 1 to 3, 5, 6, 8 to 14, 17, 21, 24, 50, 52, 53     | 1                          | 1                             | 109           |                  |
|                                     |            |                  |       |          |                                                             |                                                   |                            |                               |               |                  |
| Automatic restart functions         | 55         | 37               | B7    | 0        | Frequency monitoring reference                              | 0 to 400Hz                                        | 0.01Hz                     | 60Hz                          | 109           |                  |
|                                     |            |                  |       |          |                                                             |                                                   |                            |                               |               |                  |
|                                     | 56         | 38               | B8    | 0        | Current monitoring reference                                | 0 to 500A/0 to 3600A                              | 0.01/0.1A                  | Rated inverter output current | 109           |                  |
|                                     |            |                  |       |          |                                                             |                                                   |                            |                               |               |                  |
| Automatic restart functions         | 57         | 39               | B9    | 0        | Restart coasting time                                       | 0, 0.1 to 5s, 9999/0, 0.1 to 30s, 9999            | 0.1s                       | 9999                          | 114           |                  |
|                                     |            |                  |       |          |                                                             |                                                   |                            |                               |               |                  |
| Automatic restart functions         | 58         | 3A               | BA    | 0        | Restart cushion time                                        | 0 to 60s                                          | 0.1s                       | 1s                            | 114           |                  |
|                                     |            |                  |       |          |                                                             |                                                   |                            |                               |               |                  |
| —                                   | 59         | 3B               | BB    | 0        | Remote function selection                                   | 0, 1, 2, 3                                        | 1                          | 0                             | 77            |                  |
| —                                   | Ⓢ 60       | 3C               | BC    | 0        | Energy saving control selection                             | 0, 4, 9                                           | 1                          | 0                             | 123           |                  |
| —                                   | 65         | 41               | C1    | 0        | Retry selection                                             | 0 to 5                                            | 1                          | 0                             | 119           |                  |
| —                                   | 66         | 42               | C2    | 0        | Stall prevention operation reduction starting frequency     | 0 to 400Hz                                        | 0.01Hz                     | 60Hz                          | 61            |                  |
| Retry                               | 67         | 43               | C3    | 0        | Number of retries at alarm occurrence                       | 0 to 10, 101 to 110                               | 1                          | 0                             | 119           |                  |
|                                     |            |                  |       |          |                                                             |                                                   |                            |                               |               |                  |
|                                     |            |                  |       |          |                                                             |                                                   |                            |                               |               |                  |
| Retry                               | 68         | 44               | C4    | 0        | Retry waiting time                                          | 0 to 10s                                          | 0.1s                       | 1s                            | 119           |                  |
|                                     |            |                  |       |          |                                                             |                                                   |                            |                               |               |                  |
|                                     |            |                  |       |          |                                                             |                                                   |                            |                               |               |                  |
| Retry                               | 69         | 45               | C5    | 0        | Retry count display erase                                   | 0                                                 | 1                          | 0                             | 119           |                  |
|                                     |            |                  |       |          |                                                             |                                                   |                            |                               |               |                  |
|                                     |            |                  |       |          |                                                             |                                                   |                            |                               |               |                  |
| —                                   | 70         | 46               | C6    | 0        | Special regenerative brake duty                             | 0 to 10%                                          | 0.1%                       | 0%                            | 88            |                  |
| —                                   | 71         | 47               | C7    | 0        | Applied motor                                               | 0, 1, 2, 20                                       | 1                          | 0                             | 85            |                  |
| —                                   | 72         | 48               | C8    | 0        | PWM frequency selection                                     | 0 to 15/0 to 6, 25                                | 1                          | 2                             | 129           |                  |
| —                                   | 73         | 49               | C9    | 0        | Analog input selection                                      | 0 to 7, 10 to 17                                  | 1                          | 1                             | 132           |                  |
| —                                   | 74         | 4A               | CA    | 0        | Input filter time constant                                  | 0 to 8                                            | 1                          | 1                             | 133           |                  |
| —                                   | 75         | 4B               | CB    | 0        | Reset selection/disconnected PU detection/PU stop selection | 0 to 3, 14 to 17, 100 to 103, 114 to 117          | 1                          | 14                            | 141           |                  |
| —                                   | 76         | 4C               | CC    | 0        | Alarm code output selection                                 | 0, 1, 2                                           | 1                          | 0                             | 121           |                  |
| —                                   | 77         | 4D               | CD    | 0        | Parameter write selection                                   | 0, 1, 2                                           | 1                          | 0                             | 144           |                  |
| —                                   | 78         | 4E               | CE    | 0        | Reverse rotation prevention selection                       | 0, 1, 2                                           | 1                          | 0                             | 145           |                  |
| —                                   | Ⓢ 79       | 4F               | CF    | 0        | Operation mode selection                                    | 0, 1, 2, 3, 4, 6, 7                               | 1                          | 0                             | 147           |                  |
| Simple magnetic flux vector control | 80         | 50               | D0    | 0        | Motor capacity (simple magnetic flux vector control)        | 0.4 to 55kW, 9999/0 to 3600kW, 9999               | 0.01/0.1kW                 | 9999                          | 59            |                  |
|                                     |            |                  |       |          |                                                             |                                                   |                            |                               |               |                  |
| Simple magnetic flux vector control | 90         | 5A               | DA    | 0        | Motor constant (R1)                                         | 0 to 50Ω, 9999/0 to 400mΩ, 9999                   | 0.001Ω/0.01mΩ              | 9999                          | 59            |                  |
|                                     |            |                  |       |          |                                                             |                                                   |                            |                               |               |                  |

\* Can be written by only communication from the PU connector.

| Function                   | Parameters   | Instruction Code |       | Name                                              | Setting Range                  | Minimum Setting Increments | Initial Value | Refer to Page | Customer Setting |
|----------------------------|--------------|------------------|-------|---------------------------------------------------|--------------------------------|----------------------------|---------------|---------------|------------------|
|                            |              | Read             | Write |                                                   |                                |                            |               |               |                  |
| Adjustable 5 points V/F    | <b>100</b>   | 00<br>80         | 1     | V/F1 (first frequency)                            | 0 to 400Hz, 9999               | 0.01Hz                     | 9999          | 71            |                  |
|                            | <b>101</b>   | 01<br>81         | 1     | V/F1 (first frequency voltage)                    | 0 to 1000V                     | 0.1V                       | 0V            | 71            |                  |
|                            | <b>102</b>   | 02<br>82         | 1     | V/F2 (second frequency)                           | 0 to 400Hz, 9999               | 0.01Hz                     | 9999          | 71            |                  |
|                            | <b>103</b>   | 03<br>83         | 1     | V/F1 (first frequency)                            | 0 to 1000V                     | 0.1V                       | 0V            | 71            |                  |
|                            | <b>104</b>   | 04<br>84         | 1     | V/F3 (third frequency)                            | 0 to 400Hz, 9999               | 0.01Hz                     | 9999          | 71            |                  |
|                            | <b>105</b>   | 05<br>85         | 1     | V/F3 (third frequency voltage)                    | 0 to 1000V                     | 0.1V                       | 0V            | 71            |                  |
|                            | <b>106</b>   | 06<br>86         | 1     | V/F4 (fourth frequency)                           | 0 to 400Hz, 9999               | 0.01Hz                     | 9999          | 71            |                  |
|                            | <b>107</b>   | 07<br>87         | 1     | V/F4 (fourth frequency voltage)                   | 0 to 1000V                     | 0.1V                       | 0V            | 71            |                  |
|                            | <b>108</b>   | 08<br>88         | 1     | V/F5 (fifth frequency)                            | 0 to 400Hz, 9999               | 0.01Hz                     | 9999          | 71            |                  |
|                            | <b>109</b>   | 09<br>89         | 1     | V/F5 (fifth frequency voltage)                    | 0 to 1000V                     | 0.1V                       | 0V            | 71            |                  |
| PU connector communication | <b>117</b>   | 11<br>91         | 1     | PU communication station                          | 0 to 31                        | 1                          | 0             | 166           |                  |
|                            | <b>118</b>   | 12<br>92         | 1     | PU communication speed                            | 48, 96, 192, 384               | 1                          | 192           | 166           |                  |
|                            | <b>119</b>   | 13<br>93         | 1     | PU communication stop bit length.                 | 0, 1, 10, 11                   | 1                          | 1             | 166           |                  |
|                            | <b>120</b>   | 14<br>94         | 1     | PU communication parity check                     | 0, 1, 2                        | 1                          | 2             | 166           |                  |
|                            | <b>121</b>   | 15<br>95         | 1     | Number of PU communication retries                | 0 to 10, 9999                  | 1                          | 1             | 166           |                  |
|                            | <b>122</b>   | 16<br>96         | 1     | PU communication check time interval              | 0, 0.1 to 999.8s, 9999         | 0.1s                       | 9999          | 166           |                  |
|                            | <b>123</b>   | 17<br>97         | 1     | PU communication waiting time setting             | 0 to 150ms, 9999               | 1                          | 9999          | 166           |                  |
|                            | <b>124</b>   | 18<br>98         | 1     | PU communication CR/LF presence/absence selection | 0, 1, 2                        | 1                          | 1             | 166           |                  |
| —                          | Ⓒ <b>125</b> | 19<br>99         | 1     | Terminal 2 frequency setting gain frequency       | 0 to 400Hz                     | 0.01Hz                     | 60Hz          | 134           |                  |
| —                          | Ⓒ <b>126</b> | 1A<br>9A         | 1     | Terminal 4 frequency setting gain frequency       | 0 to 400Hz                     | 0.01Hz                     | 60Hz          | 134           |                  |
| PID operation              | <b>127</b>   | 1B<br>9B         | 1     | PID control automatic switchover frequency        | 0 to 400Hz, 9999               | 0.01Hz                     | 9999          | 189           |                  |
|                            | <b>128</b>   | 1C<br>9C         | 1     | PID action selection                              | 10, 11, 20, 21, 50, 51, 60, 61 | 1                          | 10            | 189           |                  |
|                            | <b>129</b>   | 1D<br>9D         | 1     | PID proportional band                             | 0.1 to 1000%, 9999             | 0.1%                       | 100%          | 189           |                  |
|                            | <b>130</b>   | 1E<br>9E         | 1     | PID integral time                                 | 0.1 to 3600s, 9999             | 0.1s                       | 1s            | 189           |                  |
|                            | <b>131</b>   | 1F<br>9F         | 1     | PID upper limit                                   | 0 to 100%, 9999                | 0.1%                       | 9999          | 189           |                  |
|                            | <b>132</b>   | 20<br>A0         | 1     | PID lower limit                                   | 0 to 100%, 9999                | 0.1%                       | 9999          | 189           |                  |
|                            | <b>133</b>   | 21<br>A1         | 1     | PID action set point                              | 0 to 100%, 9999                | 0.01%                      | 9999          | 189           |                  |
|                            | <b>134</b>   | 22<br>A2         | 1     | PID differential time                             | 0.01 to 10.00s, 9999           | 0.01s                      | 9999          | 189           |                  |



| Function                                     | Parameters | Instruction Code |       | Name                                                                                  | Setting Range                                 | Minimum Setting Increments | Initial Value | Refer to Page | Customer Setting |
|----------------------------------------------|------------|------------------|-------|---------------------------------------------------------------------------------------|-----------------------------------------------|----------------------------|---------------|---------------|------------------|
|                                              |            | Read             | Write |                                                                                       |                                               |                            |               |               |                  |
| Commercial power supply-inverter switch-over | 135        | 23               | 1     | Commercial power-supply switchover sequence output terminal selection                 | 0, 1                                          | 1                          | 0             | 197           |                  |
|                                              |            | A3               |       |                                                                                       |                                               |                            |               |               |                  |
|                                              | 136        | 24               | 1     | MC switchover interlock time                                                          | 0 to 100s                                     | 0.1s                       | 1s            | 197           |                  |
|                                              |            | A4               |       |                                                                                       |                                               |                            |               |               |                  |
|                                              | 137        | 25               | 1     | Waiting time at a start                                                               | 0 to 100s                                     | 0.1s                       | 0.5s          | 197           |                  |
|                                              |            | A5               |       |                                                                                       |                                               |                            |               |               |                  |
|                                              | 138        | 26               | 1     | Commercial power-supply operation switchover selection at an alarm                    | 0, 1                                          | 1                          | 0             | 197           |                  |
|                                              |            | A6               |       |                                                                                       |                                               |                            |               |               |                  |
|                                              | 139        | 27               | 1     | Automatic switchover frequency between inverter and commercial power-supply operation | 0 to 60Hz, 9999                               | 0.01Hz                     | 9999          | 197           |                  |
|                                              |            | A7               |       |                                                                                       |                                               |                            |               |               |                  |
| Backlash measures                            | 140        | 28               | 1     | Backlash acceleration stopping frequency                                              | 0 to 400Hz                                    | 0.01Hz                     | 1Hz           | 82            |                  |
|                                              |            | A8               |       |                                                                                       |                                               |                            |               |               |                  |
|                                              | 141        | 29               | 1     | Backlash acceleration stopping time                                                   | 0 to 360s                                     | 0.1s                       | 0.5s          | 82            |                  |
|                                              |            | A9               |       |                                                                                       |                                               |                            |               |               |                  |
|                                              | 142        | 2A               | 1     | Backlash deceleration stopping frequency                                              | 0 to 400Hz                                    | 0.01Hz                     | 1Hz           | 82            |                  |
|                                              |            | AA               |       |                                                                                       |                                               |                            |               |               |                  |
|                                              | 143        | 2B               | 1     | Backlash deceleration stopping time                                                   | 0 to 360s                                     | 0.1s                       | 0.5s          | 82            |                  |
|                                              |            | AB               |       |                                                                                       |                                               |                            |               |               |                  |
| —                                            | 144        | 2C               | 1     | Speed setting switchover                                                              | 0, 2, 4, 6, 8, 10, 102, 104, 106, 108, 110    | 1                          | 4             | 104           |                  |
|                                              |            | AC               |       |                                                                                       |                                               |                            |               |               |                  |
| PU                                           | 145        | 2D               | 1     | PU display language selection                                                         | 0 to 7                                        | 1                          | 1             | 220           |                  |
|                                              |            | AD               |       |                                                                                       |                                               |                            |               |               |                  |
| Current detection                            | 148        | 30               | 1     | Stall prevention level at 0V input.                                                   | 0 to 120%                                     | 0.1%                       | 110%          | 61            |                  |
|                                              |            | B0               |       |                                                                                       |                                               |                            |               |               |                  |
|                                              | 149        | 31               | 1     | Stall prevention level at 10V input.                                                  | 0 to 120%                                     | 0.1%                       | 120%          | 61            |                  |
|                                              |            | B1               |       |                                                                                       |                                               |                            |               |               |                  |
|                                              | 150        | 32               | 1     | Output current detection level                                                        | 0 to 120%                                     | 0.1%                       | 110%          | 101           |                  |
|                                              |            | B2               |       |                                                                                       |                                               |                            |               |               |                  |
|                                              | 151        | 33               | 1     | Output current detection signal delay time                                            | 0 to 10s                                      | 0.1s                       | 0s            | 101           |                  |
|                                              |            | B3               |       |                                                                                       |                                               |                            |               |               |                  |
|                                              | 152        | 34               | 1     | Zero current detection level                                                          | 0 to 150%                                     | 0.1%                       | 5%            | 101           |                  |
|                                              |            | B4               |       |                                                                                       |                                               |                            |               |               |                  |
|                                              | 153        | 35               | 1     | Zero current detection time                                                           | 0 to 1s                                       | 0.01s                      | 0.5s          | 101           |                  |
|                                              |            | B5               |       |                                                                                       |                                               |                            |               |               |                  |
| —                                            | 154        | 36               | 1     | Voltage reduction selection during stall prevention operation                         | 0, 1                                          | 1                          | 1             | 61            |                  |
|                                              |            | B6               |       |                                                                                       |                                               |                            |               |               |                  |
| —                                            | 155        | 37               | 1     | RT signal reflection time selection                                                   | 0, 10                                         | 1                          | 0             | 93            |                  |
|                                              |            | B7               |       |                                                                                       |                                               |                            |               |               |                  |
| —                                            | 156        | 38               | 1     | Stall prevention operation selection                                                  | 0 to 31, 100, 101                             | 1                          | 0             | 61            |                  |
|                                              |            | B8               |       |                                                                                       |                                               |                            |               |               |                  |
| —                                            | 157        | 39               | 1     | OL signal output timer                                                                | 0 to 25s, 9999                                | 0.1s                       | 0s            | 61            |                  |
|                                              |            | B9               |       |                                                                                       |                                               |                            |               |               |                  |
| —                                            | 158        | 3A               | 1     | AM terminal function selection                                                        | 1 to 3, 5, 6, 8 to 14, 17, 21, 24, 50, 52, 53 | 1                          | 1             | 109           |                  |
|                                              |            | BA               |       |                                                                                       |                                               |                            |               |               |                  |
| —                                            | 159        | 3B               | 1     | Automatic switchover ON range between commercial power-supply and inverter operation  | 0 to 10Hz, 9999                               | 0.01Hz                     | 9999          | 197           |                  |
|                                              |            | BB               |       |                                                                                       |                                               |                            |               |               |                  |
| —                                            | © 160      | 00               | 2     | User group read selection                                                             | 0, 1, 9999                                    | 1                          | 0             | 145           |                  |
|                                              |            | 80               |       |                                                                                       |                                               |                            |               |               |                  |
| —                                            | 161        | 01               | 2     | Frequency setting/key lock operation selection                                        | 0, 1, 10, 11                                  | 1                          | 0             | 220           |                  |
|                                              |            | 81               |       |                                                                                       |                                               |                            |               |               |                  |

| Function                           | Parameters | Instruction Code                    |                                              | Name                                                          | Setting Range                                            | Minimum Setting Increments | Initial Value | Refer to Page | Customer Setting |
|------------------------------------|------------|-------------------------------------|----------------------------------------------|---------------------------------------------------------------|----------------------------------------------------------|----------------------------|---------------|---------------|------------------|
|                                    |            | Read                                | Extended                                     |                                                               |                                                          |                            |               |               |                  |
|                                    |            | Write                               |                                              |                                                               |                                                          |                            |               |               |                  |
| Automatic restart functions        | 162        | 02                                  | 2                                            | Automatic restart after instantaneous power failure selection | 0, 1, 10, 11                                             | 1                          | 0             | 114           |                  |
|                                    |            | 82                                  |                                              |                                                               |                                                          |                            |               |               |                  |
|                                    | 163        | 03                                  | 2                                            | First cushion time for restart                                | 0 to 20s                                                 | 0.1s                       | 0s            | 114           |                  |
|                                    |            | 83                                  |                                              |                                                               |                                                          |                            |               |               |                  |
|                                    | 164        | 04                                  | 2                                            | First cushion voltage for restart                             | 0 to 100%                                                | 0.1%                       | 0%            | 114           |                  |
| 84                                 |            |                                     |                                              |                                                               |                                                          |                            |               |               |                  |
| 165                                | 05         | 2                                   | Stall prevention operation level for restart | 0 to 120%                                                     | 0.1%                                                     | 110%                       | 114           |               |                  |
|                                    | 85         |                                     |                                              |                                                               |                                                          |                            |               |               |                  |
| Current detection                  | 166        | 06                                  | 2                                            | Output current detection signal retention time                | 0 to 10s, 9999                                           | 0.1s                       | 0.1s          | 101           |                  |
|                                    |            | 86                                  |                                              |                                                               |                                                          |                            |               |               |                  |
| —                                  | 167        | 07                                  | 2                                            | Output current detection operation selection                  | 0, 1                                                     | 1                          | 0             | 101           |                  |
|                                    |            | 87                                  |                                              |                                                               |                                                          |                            |               |               |                  |
| —                                  | 168        | Parameter for manufacturer setting. |                                              |                                                               |                                                          |                            |               |               |                  |
| —                                  | 169        | Do not make setting.                |                                              |                                                               |                                                          |                            |               |               |                  |
| Cumulative monitor clear           | 170        | 0A                                  | 2                                            | Cumulative power meter clear                                  | 0, 10, 9999                                              | 1                          | 9999          | 105           |                  |
|                                    |            | 8A                                  |                                              |                                                               |                                                          |                            |               |               |                  |
| 171                                | 0B         | 2                                   | Operation hour meter clear                   | 0, 9999                                                       | 1                                                        | 9999                       | 105           |               |                  |
|                                    |            |                                     |                                              |                                                               |                                                          |                            |               |               | 8B               |
| User group                         | 172        | 0C                                  | 2                                            | User group registered display/batch clear                     | 9999, (0 to 16)                                          | 1                          | 0             | 145           |                  |
|                                    |            | 8C                                  |                                              |                                                               |                                                          |                            |               |               |                  |
|                                    | 173        | 0D                                  | 2                                            | User group registration                                       | 0 to 999, 9999                                           | 1                          | 9999          | 145           |                  |
|                                    |            | 8D                                  |                                              |                                                               |                                                          |                            |               |               |                  |
| 174                                | 0E         | 2                                   | User group clear                             | 0 to 999, 9999                                                | 1                                                        | 9999                       | 145           |               |                  |
|                                    | 8E         |                                     |                                              |                                                               |                                                          |                            |               |               |                  |
| Input terminal function assignment | 178        | 12                                  | 2                                            | STF terminal function selection                               | 0 to 8, 10 to 12, 14, 16, 24, 25, 60, 62, 64 to 67, 9999 | 1                          | 60            | 90            |                  |
|                                    |            | 92                                  |                                              |                                                               |                                                          |                            |               |               |                  |
|                                    | 179        | 13                                  | 2                                            | STR terminal function selection                               | 0 to 8, 10 to 12, 14, 16, 24, 25, 61, 62, 64 to 67, 9999 | 1                          | 61            | 90            |                  |
|                                    |            | 93                                  |                                              |                                                               |                                                          |                            |               |               |                  |
|                                    | 180        | 14                                  | 2                                            | RL terminal function selection                                | 0 to 8, 10 to 14, 16, 24, 25, 62, 64 to 67, 9999         | 1                          | 0             | 90            |                  |
|                                    |            | 94                                  |                                              |                                                               |                                                          |                            |               |               |                  |
|                                    | 181        | 15                                  | 2                                            | RM terminal function selection                                |                                                          | 1                          | 1             | 90            |                  |
|                                    |            | 95                                  |                                              |                                                               |                                                          |                            |               |               |                  |
|                                    | 182        | 16                                  | 2                                            | RH terminal function selection                                | 1                                                        | 2                          | 90            |               |                  |
|                                    |            | 96                                  |                                              |                                                               |                                                          |                            |               |               |                  |
|                                    | 183        | 17                                  | 2                                            | RT terminal function selection                                | 1                                                        | 3                          | 90            |               |                  |
|                                    |            | 97                                  |                                              |                                                               |                                                          |                            |               |               |                  |
|                                    | 184        | 18                                  | 2                                            | AU terminal function selection                                | 0 to 8, 10 to 14, 16, 24, 25, 62 to 67, 9999             | 1                          | 4             | 90            |                  |
|                                    |            | 98                                  |                                              |                                                               |                                                          |                            |               |               |                  |
|                                    | 185        | 19                                  | 2                                            | JOG terminal function selection                               | 0 to 8, 10 to 14, 16, 24, 25, 62, 64 to 67, 9999         | 1                          | 5             | 90            |                  |
|                                    |            | 99                                  |                                              |                                                               |                                                          |                            |               |               |                  |
| 186                                | 1A         | 2                                   | CS terminal function selection               | 1                                                             |                                                          | 6                          | 90            |               |                  |
|                                    | 9A         |                                     |                                              |                                                               |                                                          |                            |               |               |                  |
| 187                                | 1B         | 2                                   | MRS terminal function selection              | 1                                                             |                                                          | 24                         | 90            |               |                  |
|                                    | 9B         |                                     |                                              |                                                               |                                                          |                            |               |               |                  |
| 188                                | 1C         | 2                                   | STOP terminal function selection             | 1                                                             | 25                                                       | 90                         |               |               |                  |
|                                    | 9C         |                                     |                                              |                                                               |                                                          |                            |               |               |                  |
| 189                                | 1D         | 2                                   | RES terminal function selection              | 1                                                             | 62                                                       | 90                         |               |               |                  |
|                                    | 9D         |                                     |                                              |                                                               |                                                          |                            |               |               |                  |



| Function                            | Parameters | Instruction Code     |          | Name                                               | Setting Range                                                                                                                                                                            | Minimum Setting Increments | Initial Value | Refer to Page | Customer Setting |
|-------------------------------------|------------|----------------------|----------|----------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------|---------------|---------------|------------------|
|                                     |            | Read                 | Extended |                                                    |                                                                                                                                                                                          |                            |               |               |                  |
|                                     |            | Write                |          |                                                    |                                                                                                                                                                                          |                            |               |               |                  |
| Output terminal function assignment | 190        | 1E                   | 2        | RUN terminal function selection                    | 0 to 5, 7, 8, 10 to 19, 25, 26, 45 to 47, 64, 70 to 78, 90 to 96, 98, 99, 100 to 105, 107, 108, 110 to 116, 125, 126, 145 to 147, 164, 170, 190 to 196, 198, 199, 9999                   | 1                          | 0             | 96            |                  |
|                                     |            | 9E                   |          |                                                    |                                                                                                                                                                                          |                            |               |               |                  |
|                                     | 191        | 1F                   | 2        | SU terminal function selection                     |                                                                                                                                                                                          | 1                          | 1             | 96            |                  |
|                                     |            | 9F                   |          |                                                    |                                                                                                                                                                                          |                            |               |               |                  |
|                                     | 192        | 20                   | 2        | IPF terminal function selection                    |                                                                                                                                                                                          | 1                          | 2             | 96            |                  |
|                                     |            | A0                   |          |                                                    |                                                                                                                                                                                          |                            |               |               |                  |
|                                     | 193        | 21                   | 2        | OL terminal function selection                     | 1                                                                                                                                                                                        | 3                          | 96            |               |                  |
|                                     |            | A1                   |          |                                                    |                                                                                                                                                                                          |                            |               |               |                  |
|                                     | 194        | 22                   | 2        | FU terminal function selection                     | 1                                                                                                                                                                                        | 4                          | 96            |               |                  |
|                                     |            | A2                   |          |                                                    |                                                                                                                                                                                          |                            |               |               |                  |
|                                     | 195        | 23                   | 2        | ABC1 terminal function selection                   | 0 to 5, 7, 8, 10 to 19, 25, 26, 45 to 47, 64, 70 to 78, 90, 91, 94 to 96, 98, 99, 100 to 105, 107, 108, 110 to 116, 125, 126, 145 to 147, 164, 170, 190, 191, 194 to 196, 198, 199, 9999 | 1                          | 99            | 96            |                  |
|                                     |            | A3                   |          |                                                    |                                                                                                                                                                                          |                            |               |               |                  |
|                                     | 196        | 24                   | 2        | ABC2 terminal function selection                   |                                                                                                                                                                                          | 1                          | 9999          | 96            |                  |
|                                     |            | A4                   |          |                                                    |                                                                                                                                                                                          |                            |               |               |                  |
| Multi-speed setting                 | 232 to 239 | 28 to 2F<br>A8 to AF | 2        | Multi-speed setting (speeds 8 to 15)               |                                                                                                                                                                                          | 0 to 400Hz, 9999           | 0.01Hz        | 9999          | 72               |
| —                                   | 240        | 30<br>B0             | 2        | Soft-PWM operation selection                       | 0, 1                                                                                                                                                                                     | 1                          | 1             | 129           |                  |
| —                                   | 241        | 31<br>B1             | 2        | Analog input display unit switchover               | 0, 1                                                                                                                                                                                     | 1                          | 0             | 134           |                  |
| —                                   | 242        | 32<br>B2             | 2        | Terminal 1 added compensation amount (terminal 2)  | 0 to 100%                                                                                                                                                                                | 0.1%                       | 100%          | 132           |                  |
| —                                   | 243        | 33<br>B3             | 2        | Terminal 1 added compensation amount (terminal 4)  | 0 to 100%                                                                                                                                                                                | 0.1%                       | 75%           | 132           |                  |
| —                                   | 244        | 34<br>B4             | 2        | Cooling fan operation selection                    | 0, 1                                                                                                                                                                                     | 1                          | 1             | 213           |                  |
| Slip compensation                   | 245        | 35<br>B5             | 2        | Rated slip                                         | 0 to 50%, 9999                                                                                                                                                                           | 0.01%                      | 9999          | 60            |                  |
|                                     |            |                      |          |                                                    |                                                                                                                                                                                          |                            |               |               |                  |
|                                     | 246        | 36<br>B6             | 2        | Slip compensation time constant                    | 0.01 to 10s                                                                                                                                                                              | 0.01s                      | 0.5s          | 60            |                  |
|                                     |            |                      |          |                                                    |                                                                                                                                                                                          |                            |               |               |                  |
|                                     | 247        | 37<br>B7             | 2        | Constant-output region slip compensation selection | 0, 9999                                                                                                                                                                                  | 1                          | 9999          | 60            |                  |
|                                     |            |                      |          |                                                    |                                                                                                                                                                                          |                            |               |               |                  |
| —                                   | 250        | 3A<br>BA             | 2        | Stop selection                                     | 0 to 100s, 1000 to 1100s, 8888, 9999                                                                                                                                                     | 0.1s                       | 9999          | 89            |                  |
| —                                   | 251        | 3B<br>BB             | 2        | Output phase failure protection selection          | 0, 1                                                                                                                                                                                     | 1                          | 1             | 122           |                  |
| Frequency compensation function     | 252        | 3C<br>BC             | 2        | Override bias                                      | 0 to 200%                                                                                                                                                                                | 0.1%                       | 50%           | 132           |                  |
|                                     | 253        | 3D                   | 2        | Override gain                                      | 0 to 200%                                                                                                                                                                                | 0.1%                       | 150%          | 132           |                  |
|                                     |            | BD                   |          |                                                    |                                                                                                                                                                                          |                            |               |               |                  |

| Function           | Parameters | Instruction Code                                            |       | Name                                                                 | Setting Range                                                            | Minimum Setting Increments | Initial Value | Refer to Page | Customer Setting |
|--------------------|------------|-------------------------------------------------------------|-------|----------------------------------------------------------------------|--------------------------------------------------------------------------|----------------------------|---------------|---------------|------------------|
|                    |            | Read                                                        | Write |                                                                      |                                                                          |                            |               |               |                  |
| Life check         | 255        | 3F<br>BF                                                    | 2     | Life alarm status display                                            | (0 to 15)                                                                | 1                          | 0             | 214           |                  |
|                    | 256        | 40<br>C0                                                    | 2     | Inrush current limit circuit life display                            | (0 to 100%)                                                              | 1%                         | 100%          | 214           |                  |
|                    | 257        | 41<br>C1                                                    | 2     | Control circuit capacitor life display                               | (0 to 100%)                                                              | 1%                         | 100%          | 214           |                  |
|                    | 258        | 42<br>C2                                                    | 2     | Main circuit capacitor life display                                  | (0 to 100%)                                                              | 1%                         | 100%          | 214           |                  |
|                    | 259        | 43<br>C3                                                    | 2     | Main circuit capacitor life measuring                                | 0, 1                                                                     | 1                          | 0             | 214           |                  |
| —                  | 260        | 44<br>C4                                                    | 2     | PWM frequency automatic switchover                                   | 0, 1                                                                     | 1                          | 1             | 129           |                  |
| Power failure stop | 261        | 45<br>C5                                                    | 2     | Power failure stop selection                                         | 0, 1, 2                                                                  | 1                          | 0             | 117           |                  |
|                    | 262        | 46<br>C6                                                    | 2     | Subtracted frequency at deceleration start                           | 0 to 20Hz                                                                | 0.01Hz                     | 3Hz           | 117           |                  |
|                    | 263        | 47<br>C7                                                    | 2     | Subtraction starting frequency                                       | 0 to 120Hz, 9999                                                         | 0.01Hz                     | 60Hz          | 117           |                  |
|                    | 264        | 48<br>C8                                                    | 2     | Power-failure deceleration time 1                                    | 0 to 3600/ 360s                                                          | 0.1/0.01s                  | 5s            | 117           |                  |
|                    | 265        | 49<br>C9                                                    | 2     | Power-failure deceleration time 2                                    | 0 to 3600/ 360s, 9999                                                    | 0.1/0.01s                  | 9999          | 117           |                  |
|                    | 266        | 4A<br>CA                                                    | 2     | Power failure deceleration time switchover frequency                 | 0 to 400Hz                                                               | 0.01Hz                     | 60Hz          | 117           |                  |
| —                  | 267        | 4B<br>CB                                                    | 2     | Terminal 4 input selection                                           | 0, 1, 2                                                                  | 1                          | 0             | 130           |                  |
| —                  | 268        | 4C<br>CC                                                    | 2     | Monitor decimal digits selection                                     | 0, 1, 9999                                                               | 1                          | 9999          | 105           |                  |
| —                  | 269        | Parameter for manufacturer setting.<br>Do not make setting. |       |                                                                      |                                                                          |                            |               |               |                  |
| —                  | 299        | 6B<br>EB                                                    | 2     | Rotation direction detection selection at restarting                 | 0, 1, 9999                                                               | 1                          | 9999          | 114           |                  |
| Digital input      | 300        | 00<br>80                                                    | 3     | BCD input bias                                                       | Parameter for digital input option (FR-A7AX)                             |                            |               |               |                  |
|                    | 301        | 01<br>81                                                    | 3     | BCD input gain                                                       |                                                                          |                            |               |               |                  |
|                    | 302        | 02<br>82                                                    | 3     | BIN input bias                                                       |                                                                          |                            |               |               |                  |
|                    | 303        | 03<br>83                                                    | 3     | BIN input gain                                                       |                                                                          |                            |               |               |                  |
|                    | 304        | 04<br>84                                                    | 3     | Digital input and analog input compensation enable/disable selection |                                                                          |                            |               |               |                  |
|                    | 305        | 05<br>85                                                    | 3     | Read timing operation selection                                      |                                                                          |                            |               |               |                  |
| Analog output      | 306        | 06<br>86                                                    | 3     | Analog output signal selection                                       | Extension analog output/digital output option<br>Parameter for (FR-A7AY) |                            |               |               |                  |
|                    | 307        | 07<br>87                                                    | 3     | Setting for zero analog output                                       |                                                                          |                            |               |               |                  |
|                    | 308        | 08<br>88                                                    | 3     | Setting for maximum analog output                                    |                                                                          |                            |               |               |                  |
|                    | 309        | 09<br>89                                                    | 3     | Analog output signal voltage/current switchover                      |                                                                          |                            |               |               |                  |
|                    | 310        | 0A<br>8A                                                    | 3     | Analog meter voltage output selection                                |                                                                          |                            |               |               |                  |
|                    | 311        | 0B<br>8B                                                    | 3     | Setting for zero analog meter voltage output                         |                                                                          |                            |               |               |                  |
|                    | 312        | 0C<br>8C                                                    | 3     | Setting for maximum analog meter voltage output                      |                                                                          |                            |               |               |                  |



| Function             | Parameters | Instruction Code |          | Name                                        | Setting Range                                                                 | Minimum Setting Increments | Initial Value | Refer to Page | Customer Setting |
|----------------------|------------|------------------|----------|---------------------------------------------|-------------------------------------------------------------------------------|----------------------------|---------------|---------------|------------------|
|                      |            | Read             | Extended |                                             |                                                                               |                            |               |               |                  |
|                      |            | Write            |          |                                             |                                                                               |                            |               |               |                  |
| Digital output       | 313        | 0D<br>8D         | 3        | DO0 output selection                        | Parameter for extension analog output/digital output option (FR-A7AY)         |                            |               |               |                  |
|                      | 314        | 0E<br>8E         | 3        | DO1 output selection                        |                                                                               |                            |               |               |                  |
|                      | 315        | 0F<br>8F         | 3        | DO2 output selection                        |                                                                               |                            |               |               |                  |
|                      | 316        | 10<br>90         | 3        | DO3 output selection                        |                                                                               |                            |               |               |                  |
|                      | 317        | 11<br>91         | 3        | DO4 output selection                        |                                                                               |                            |               |               |                  |
|                      | 318        | 12<br>92         | 3        | DO5 output selection                        |                                                                               |                            |               |               |                  |
|                      | 319        | 13<br>93         | 3        | DO6 output selection                        |                                                                               |                            |               |               |                  |
| Relay output         | 320        | 14<br>94         | 3        | RA1 output selection                        | Parameter for relay output option (FR-A7AR)                                   |                            |               |               |                  |
|                      | 321        | 15<br>95         | 3        | RA2 output selection                        |                                                                               |                            |               |               |                  |
|                      | 322        | 16<br>96         | 3        | RA3 output selection                        |                                                                               |                            |               |               |                  |
| Analog output        | 323        | 17<br>97         | 3        | AM0 0V adjustment                           | Parameter for extension analog output/digital output option (FR-A7AY)         |                            |               |               |                  |
|                      | 324        | 18<br>98         | 3        | AM1 0mA adjustment                          |                                                                               |                            |               |               |                  |
| —                    | 329        | 1D<br>9D         | 3        | Digital input unit selection                | Parameter for digital input option (FR-A7AX)                                  |                            |               |               |                  |
| RS-485 communication | 331        | 1F<br>9F         | 3        | RS-485 communication station                | 0 to 31(0 to 247)                                                             | 1                          | 0             | 166           |                  |
|                      | 332        | 20<br>A0         | 3        | RS-485 communication speed                  | 3, 6, 12, 24, 48, 96, 192, 384                                                | 1                          | 96            | 166           |                  |
|                      | 333        | 21<br>A1         | 3        | RS-485 communication stop bit length        | 0, 1, 10, 11                                                                  | 1                          | 1             | 166           |                  |
|                      | 334        | 22<br>A2         | 3        | RS-485 communication parity check selection | 0, 1, 2                                                                       | 1                          | 2             | 166           |                  |
|                      | 335        | 23<br>A3         | 3        | RS-485 communication number of retries      | 0 to 10, 9999                                                                 | 1                          | 1             | 166           |                  |
|                      | 336        | 24<br>A4         | 3        | RS-485 communication check time interval    | 0 to 999.8s, 9999                                                             | 0.1s                       | 0s            | 166           |                  |
|                      | 337        | 25<br>A5         | 3        | RS-485 communication waiting time setting   | 0 to 150ms, 9999                                                              | 1                          | 9999          | 166           |                  |
|                      | 338        | 26<br>A6         | 3        | Communication operation command source      | 0, 1                                                                          | 1                          | 0             | 156           |                  |
|                      | 339        | 27<br>A7         | 3        | Communication speed command source          | 0, 1, 2                                                                       | 1                          | 0             | 156           |                  |
|                      | 340        | 28<br>A8         | 3        | Communication startup mode selection        | 0, 1, 2, 10, 12                                                               | 1                          | 0             | 155           |                  |
|                      | 341        | 29<br>A9         | 3        | RS-485 communication CR/LF selection        | 0, 1, 2                                                                       | 1                          | 1             | 166           |                  |
|                      | 342        | 2A<br>AA         | 3        | Communication EEPROM write selection        | 0, 1                                                                          | 1                          | 0             | 167           |                  |
|                      | 343        | 2B<br>AB         | 3        | Communication error count                   | —                                                                             | 1                          | 0             | 178           |                  |
| DeviceNet            | 345        | 2D<br>AD         | 3        | DeviceNet address                           | Parameter for DeviceNet communication option (FR-A7ND)                        |                            |               |               |                  |
|                      | 346        | 2E<br>AE         | 3        | DeviceNet baud rate                         |                                                                               |                            |               |               |                  |
| CC-Link, PROFIBUS-DP | 349        | 31<br><br>B1     | 3        | Communication reset selection               | Parameter for CC-Link and PROFIBUS-DP communication option (FR-A7NC, FR-A7NP) |                            |               |               |                  |

| Function                | Parameters | Instruction Code |          | Name                                                          | Setting Range                                         | Minimum Setting Increments | Initial Value          | Refer to Page | Customer Setting |
|-------------------------|------------|------------------|----------|---------------------------------------------------------------|-------------------------------------------------------|----------------------------|------------------------|---------------|------------------|
|                         |            | Read             | Extended |                                                               |                                                       |                            |                        |               |                  |
|                         |            | Write            |          |                                                               |                                                       |                            |                        |               |                  |
| LONWORKS                | 387        | 57<br>D7         | 3        | Initial communication delay time                              | Parameter for LONWORKS communication option (FR-A7NL) |                            |                        |               |                  |
|                         | 388        | 58<br>D8         | 3        | Send time interval at hart beat                               |                                                       |                            |                        |               |                  |
|                         | 389        | 59<br>D9         | 3        | Minimum sending time at hart beat                             |                                                       |                            |                        |               |                  |
|                         | 390        | 5A<br>DA         | 3        | % setting reference frequency                                 |                                                       |                            |                        |               |                  |
|                         | 391        | 5B<br>DB         | 3        | Receive time interval at hart beat                            |                                                       |                            |                        |               |                  |
|                         | 392        | 5C<br>DC         | 3        | Event driven detection width                                  |                                                       |                            |                        |               |                  |
| Remote output           | 495        | 5F<br>DF         | 4        | Remote output selection                                       | 0, 1                                                  | 1                          | 0                      | 103           |                  |
|                         | 496        | 60<br>E0         | 4        | Remote output data 1                                          | 0 to 4095                                             | 1                          | 0                      | 103           |                  |
|                         | 497        | 61<br>E1         | 4        | Remote output data 2                                          | 0 to 4095                                             | 1                          | 0                      | 103           |                  |
| Communication error     | 500        | 00<br>80         | 5        | Communication error execution waiting time                    | Parameter for communication option                    |                            |                        |               |                  |
|                         | 501        | 01<br>81         | 5        | Communication error occurrence count display                  |                                                       |                            |                        |               |                  |
|                         | 502        | 02<br>82         | 5        | Stop mode selection at communication error                    |                                                       |                            |                        |               |                  |
| Maintenance             | 503        | 03<br>83         | 5        | Maintenance timer                                             | 0 (1 to 9998)                                         | 1                          | 0                      | 216           |                  |
|                         | 504        | 04<br>84         | 5        | Maintenance timer alarm output set time                       | 0 to 9998, 9999                                       | 1                          | 9999                   | 216           |                  |
| CC-Link                 | 542        | 2A<br>AA         | 5        | Communication station number (CC-Link)                        | Parameter for CC-Link communication option (FR-A7NC)  |                            |                        |               |                  |
|                         | 543        | 2B<br>AB         | 5        | Baud rate (CC-Link)                                           |                                                       |                            |                        |               |                  |
|                         | 544        | 2C<br>AC         | 5        | CC-Link extended setting                                      |                                                       |                            |                        |               |                  |
| Communication           | 549        | 31<br>B1         | 5        | Protocol selection                                            | 0, 1                                                  | 1                          | 1                      | 178           |                  |
|                         | 550        | 32<br>B2         | 5        | NET mode operation command source selection                   | 0, 1, 9999                                            | 1                          | 9999                   | 156           |                  |
|                         | 551        | 33<br>B3         | 5        | PU mode operation command source selection                    | 1, 2                                                  | 1                          | 2                      | 156           |                  |
| Current average monitor | 555        | 37<br>B7         | 5        | Current average time                                          | 0.1 to 1.0s                                           | 0.1s                       | 1s                     | 217           |                  |
|                         | 556        | 38<br>B8         | 5        | Data output mask time                                         | 0.0 to 20.0s                                          | 0.1s                       | 0s                     | 217           |                  |
|                         | 557        | 39<br>B9         | 5        | Current average value monitor signal output reference current | 0 to 500A/0 to 3600A                                  | 0.01/0.1A                  | Rated inverter current | 217           |                  |
| —                       | 563        | 3F<br>BF         | 5        | Energization time carrying-over times                         | (0 to 65535)                                          | 1                          | 0                      | 105           |                  |
| —                       | 564        | 40<br>C0         | 5        | Operating time carrying-over times                            | (0 to 65535)                                          | 1                          | 0                      | 105           |                  |
| Multiple rating         | 570        | 46<br>C6         | 5        | Multiple rating setting                                       | 0, 1                                                  | 1                          | 0                      | 66            |                  |
| —                       | 571        | 47<br>C7         | 5        | Holding time at a start                                       | 0.0 to 10.0s, 9999                                    | 0.1s                       | 9999                   | 81            |                  |
| —                       | 573        | 49<br>C9         | 6        | 4mA input check selection                                     | 1, 9999                                               | 1                          | 9999                   | 139           |                  |



| Function                        | Parameters | Instruction Code |       | Name | Setting Range                                                | Minimum Setting Increments | Initial Value | Refer to Page | Customer Setting |
|---------------------------------|------------|------------------|-------|------|--------------------------------------------------------------|----------------------------|---------------|---------------|------------------|
|                                 |            | Read             | Write |      |                                                              |                            |               |               |                  |
| PID control                     | 575        | 4B               | CB    | 5    | Output interruption detection time                           | 0 to 3600s, 9999           | 0.1s          | 1s            | 189              |
|                                 |            | 4C               |       |      |                                                              |                            |               |               |                  |
|                                 | 576        | 4D               | CC    | 5    | Output interruption detection level                          | 0 to 400Hz                 | 0.01Hz        | 0Hz           | 189              |
| Pump function                   | 577        | 4D               | CD    | 5    | Output interruption release level                            | 900 to 1100%               | 0.1%          | 1000%         | 189              |
|                                 |            | 4E               |       |      |                                                              |                            |               |               |                  |
|                                 | 578        | 4F               | CE    | 5    | Auxiliary motor operation selection                          | 0 to 3                     | 1             | 0             | 202              |
|                                 | 579        | 4F               | CF    | 5    | Motor connection function selection                          | 0 to 3                     | 1             | 0             | 202              |
|                                 | 580        | 50               | DO    | 6    | MC switching interlock time                                  | 0 to 100s                  | 0.1s          | 1s            | 202              |
|                                 | 581        | 51               | D1    | 6    | Start waiting time                                           | 0 to 100s                  | 0.1s          | 1s            | 202              |
|                                 | 582        | 52               | D2    | 6    | Auxiliary motor connection-time deceleration time            | 0 to 3600s, 9999           | 0.1s          | 1s            | 202              |
|                                 | 583        | 53               | D3    | 6    | Auxiliary motor disconnection-time acceleration time         | 0 to 3600s, 9999           | 0.1s          | 1s            | 202              |
|                                 | 584        | 54               | D4    | 6    | Auxiliary motor 1 starting frequency                         | 0 to 400Hz                 | 0.01Hz        | 60Hz          | 202              |
|                                 | 585        | 55               | D5    | 6    | Auxiliary motor 2 starting frequency                         | 0 to 400Hz                 | 0.01Hz        | 60Hz          | 202              |
|                                 | 586        | 56               | D6    | 6    | Auxiliary motor 3 starting frequency                         | 0 to 400Hz                 | 0.01Hz        | 60Hz          | 202              |
|                                 | 587        | 57               | D7    | 6    | Auxiliary motor 1 stopping frequency                         | 0 to 400Hz                 | 0.01Hz        | 0Hz           | 202              |
|                                 | 588        | 58               | D8    | 6    | Auxiliary motor 2 stopping frequency                         | 0 to 400Hz                 | 0.01Hz        | 0Hz           | 202              |
|                                 | 589        | 59               | D9    | 6    | Auxiliary motor 3 stopping frequency                         | 0 to 400Hz                 | 0.01Hz        | 0Hz           | 202              |
|                                 | 590        | 5A               | DA    | 6    | Auxiliary motor start detection time                         | 0 to 3600s                 | 0.1s          | 5s            | 202              |
|                                 | 591        | 5B               | DB    | 6    | Auxiliary motor stop detection time                          | 0 to 3600s                 | 0.1s          | 5s            | 202              |
| —                               | 611        | 0B               | 8B    | 6    | Acceleration time at a restart                               | 0 to 3600s, 9999           | 0.1s          | 5/15s         | 114              |
| —                               | 867        | 43               | C3    | 8    | AM output filter                                             | 0 to 5s                    | 0.01s         | 0.01s         | 109              |
| —                               | 869        | 45               | C5    | 8    | Current output filter                                        | 0 to 5s                    | 0.01s         | 0.02s         | 109              |
| —                               | 872        | 48               | C8    | 8    | Input phase failure protection selection                     | 0, 1                       | 1             | 0             | 122              |
| Regeneration avoidance function | 882        | 52               | D2    | 8    | Regeneration avoidance operation selection                   | 0, 1                       | 1             | 0             | 211              |
|                                 | 883        | 53               | D3    | 8    | Regeneration avoidance operation level                       | 300 to 800V                | 0.1V          | DC380V/760V   | 211              |
|                                 | 884        | 54               | D4    | 8    | Regeneration avoidance at deceleration detection sensitivity | 0 to 5                     | 1             | 0             | 211              |
|                                 | 885        | 55               | D5    | 8    | Regeneration avoidance compensation frequency limit value    | 0 to 10Hz, 9999            | 0.01Hz        | 6Hz           | 211              |
|                                 | 886        | 56               | D6    | 8    | Regeneration avoidance voltage gain                          | 0 to 200%                  | 0.1%          | 100%          | 211              |
| Free parameter                  | 888        | 58               | D8    | 8    | Free parameter 1                                             | 0 to 9999                  | 1             | 9999          | 219              |
|                                 | 889        | 59               | D9    | 8    | Free parameter 2                                             | 0 to 9999                  | 1             | 9999          | 219              |

| Function                          | Parameters | Instruction Code |       | Name                                                       | Setting Range               | Minimum Setting Increments | Initial Value                          | Refer to Page | Customer Setting |
|-----------------------------------|------------|------------------|-------|------------------------------------------------------------|-----------------------------|----------------------------|----------------------------------------|---------------|------------------|
|                                   |            | Read             | Write |                                                            |                             |                            |                                        |               |                  |
| Energy saving monitor             | 891        | 5B<br>DB         | 8     | Cumulative power monitor digit shifted times               | 0 to 4, 9999                | 1                          | 9999                                   | 124           |                  |
|                                   | 892        | 5C<br>DC         | 8     | Load factor                                                | 30 to 150%                  | 0.1%                       | 100%                                   | 124           |                  |
|                                   | 893        | 5D<br>DD         | 8     | Energy saving monitor reference (motor capacity)           | 0.1 to 55kW/<br>0 to 3600kW | 0.01/0.1kW                 | SLD/LD value of Applied moter Capacity | 124           |                  |
|                                   | 894        | 5E<br>DE         | 8     | Control selection during commercial power-supply operation | 0, 1, 2, 3                  | 1                          | 0                                      | 124           |                  |
|                                   | 895        | 5F<br>DF         | 8     | Power saving rate reference value                          | 0, 1, 9999                  | 1                          | 9999                                   | 124           |                  |
|                                   | 896        | 60<br>E0         | 8     | Power unit cost                                            | 0 to 500, 9999              | 0.01                       | 9999                                   | 124           |                  |
|                                   | 897        | 61<br>E1         | 8     | Power saving monitor average time                          | 0, 1 to 1000h, 9999         | 1                          | 9999                                   | 124           |                  |
|                                   | 898        | 62<br>E2         | 8     | Power saving cumulative monitor clear                      | 0, 1, 10, 9999              | 1                          | 9999                                   | 124           |                  |
|                                   | 899        | 63<br>E3         | 8     | Operation time rate (estimated value)                      | 0 to 100%, 9999             | 0.1%                       | 9999                                   | 124           |                  |
| Calibration parameters            | C0 (900)   | 5C<br>DC         | 1     | CA terminal calibration                                    | —                           | —                          | —                                      | 111           |                  |
|                                   | C1 (901)   | 5D<br>DD         | 1     | AM terminal calibration                                    | —                           | —                          | —                                      | 111           |                  |
|                                   | C2 (902)   | 5E<br>DE         | 1     | Terminal 2 frequency setting bias frequency                | 0 to 400Hz                  | 0.01Hz                     | 0Hz                                    | 134           |                  |
|                                   | C3 (902)   | 5E<br>DE         | 1     | Terminal 2 frequency setting bias                          | 0 to 300%                   | 0.1%                       | 0%                                     | 134           |                  |
|                                   | 125 (903)  | 5F<br>DF         | 1     | Terminal 2 frequency setting gain frequency                | 0 to 400Hz                  | 0.01Hz                     | 60Hz                                   | 134           |                  |
|                                   | C4 (903)   | 5F<br>DF         | 1     | Terminal 2 frequency setting gain                          | 0 to 300%                   | 0.1%                       | 100%                                   | 134           |                  |
|                                   | C5 (904)   | 60<br>E0         | 1     | Terminal 4 frequency setting bias frequency                | 0 to 400Hz                  | 0.01Hz                     | 0Hz                                    | 134           |                  |
|                                   | C6 (904)   | 60<br>E0         | 1     | Terminal 4 frequency setting bias                          | 0 to 300%                   | 0.1%                       | 20%                                    | 134           |                  |
|                                   | 126 (905)  | 61<br>E1         | 1     | Terminal 4 frequency setting gain frequency                | 0 to 400Hz                  | 0.01Hz                     | 60Hz                                   | 134           |                  |
|                                   | C7 (905)   | 61<br>E1         | 1     | Terminal 4 frequency setting gain                          | 0 to 300%                   | 0.1%                       | 100%                                   | 134           |                  |
| Analog output current calibration | C8 (930)   | 7A<br>FA         | 1     | Current output bias signal                                 | 0 to 100%                   | 0.1%                       | 0%                                     | 111           |                  |
|                                   | C9 (930)   | 7A<br>FA         | 1     | Current output bias current                                | 0 to 100%                   | 0.1%                       | 0%                                     | 111           |                  |
|                                   | C10 (931)  | 7B<br>FB         | 1     | Current output gain signal                                 | 0 to 100%                   | 0.1%                       | 100%                                   | 111           |                  |
|                                   | C11 (931)  | 7B<br>FB         | 1     | Current output gain current                                | 0 to 100%                   | 0.1%                       | 100%                                   | 111           |                  |
| —                                 | 989        | 59<br>D9         | 9     | Parameter copy alarm release                               | 10, 100                     | 1                          | 10/100                                 | —             |                  |
| PU                                | 990        | 5A<br>DA         | 9     | PU buzzer control                                          | 0, 1                        | 1                          | 1                                      | 222           |                  |
|                                   | © 991      | 5B<br>DB         | 9     | PU contrast adjustment                                     | 0 to 63                     | 1                          | 58                                     | 222           |                  |
| Clear parameter                   | Pr.CL      | —                | —     | Parameter clear                                            | 0, 1                        | 1                          | 0                                      | 223           |                  |
|                                   | ALLC       | —                | —     | All parameter clear                                        | 0, 1                        | 1                          | 0                                      | 224           |                  |
|                                   | Er.CL      | —                | —     | Alarm history clear                                        | 0, 1                        | 1                          | 0                                      | 227           |                  |
|                                   | PCPY       | —                | —     | Parameter copy                                             | 0, 1, 2, 3                  | 1                          | 0                                      | 225           |                  |

|             |                                                                                                                                   |            |
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| <b>3.23</b> | <b>All parameter clear</b>                                                                                                     | <b>224</b> |
| <b>3.24</b> | <b>Parameter copy</b>                                                                                                          | <b>225</b> |
| <b>3.25</b> | <b>Parameter verification</b>                                                                                                  | <b>226</b> |
| <b>3.26</b> | <b>Check and clear of the alarm history</b>                                                                                    | <b>227</b> |

## 3.2 Adjust the output torque of the motor (current)

| Purpose                                              | Parameter that must be set          |                                             | Refer to page |
|------------------------------------------------------|-------------------------------------|---------------------------------------------|---------------|
| Set starting torque manually                         | Manual torque boost                 | Pr.0, Pr.46                                 | 58            |
| Automatically control output power according to load | Simple magnetic flux vector control | Pr.80, Pr.90                                | 59            |
| Compensate for motor slip to secure low-speed torque | Slip compensation                   | Pr.245 to Pr.247                            | 60            |
| Limit output power to prevent inverter trip          | Stall prevention operation          | Pr.22, Pr.23, Pr.66, Pr.154, Pr.156, Pr.157 | 61            |
| Select overload according to application             | Load pattern selection              | Pr.14                                       | 65            |
| Change the overload current rating specifications    | Multiple rating setting             | Pr.570                                      | 66            |

### 3.2.1 Manual torque boost (Pr.0, Pr.46)

You can compensate for a voltage drop in the low-frequency region to improve motor torque reduction in the low-speed range.

- Motor torque in the low-frequency range can be adjusted to the load to increase the starting motor torque.
- The starting torque boost can be changed by switching between terminals.

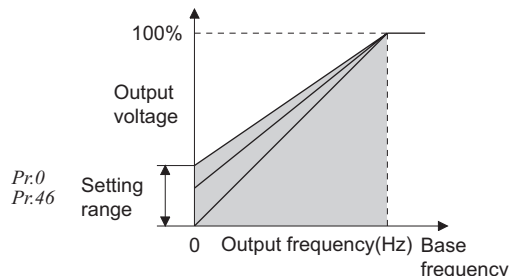
Pr. 1  
page 67

Pr.45  
page 79

Pr.47  
page 69

| Parameter Number | Name                | Initial Value<br>200V class (400V class) |      | Setting Range | Description                                          |
|------------------|---------------------|------------------------------------------|------|---------------|------------------------------------------------------|
| 0                | Torque boost        | 00048 (00023)                            | 6%   | 0 to 30%      | Set the output voltage at 0Hz as %.                  |
|                  |                     | 00077 to 00167 (00038 to 00083)          | 4%   |               |                                                      |
|                  |                     | 00250, 00340 (00126, 00170)              | 3%   |               |                                                      |
|                  |                     | 00490 to 01540 (00250 to 00770)          | 2%   |               |                                                      |
|                  |                     | 01870, 02330 (00930, 01160)              | 1.5% |               |                                                      |
|                  |                     | 03160 (01800) or more                    | 1%   |               |                                                      |
| 46 *1            | Second torque boost | 9999                                     |      | 0 to 30%      | Set the torque boost value when the RT signal is on. |
|                  |                     |                                          |      | 9999          | Without second torque boost                          |

\*1 They can be set when Pr. 160 User group read selection = "0". (Refer to page 145.)



#### (1) Starting torque adjustment

- On the assumption that Pr. 19 Base frequency voltage is 100%, set the output voltage at 0Hz in % in Pr. 0 (Pr. 46).
- Adjust the parameter little by little (about 0.5%), and check the motor status each time. If the setting is too large, the motor will overheat. The guideline is about 10% at the greatest.

#### (2) Set multiple base frequencies (RT signal, Pr. 46)

- Use the second torque boost when changing the torque boost according to application or when using multiple motors by switching between them by one inverter.
- Pr. 46 Second torque boost is made valid when the RT signal turns on.

#### REMARKS

- The RT signal acts as the second function selection signal and makes the other second functions valid. (Refer to page 92)
- The RT signal is assigned to the RT terminal in the default setting. By setting "3" to any of Pr. 178 to Pr. 189 (Input terminal function selection), you can assign the RT signal to the other terminal.

#### CAUTION

- Increase the setting when the distance between the inverter and motor is long or when motor torque is insufficient in the low-speed range. If the setting is too large, an overcurrent trip may occur.
- When simple magnetic flux vector control is selected in Pr. 80, the settings of Pr. 0 and Pr. 46 are invalid.
- When using the inverter dedicated motor (constant torque motor) with the FR-F720-00250 or 00340 and FR-F740-00126 or 00170, set the torque boost value to 2%. If the initial set Pr. 71 value is changed to the setting for use with a constant-torque motor, the Pr. 0 setting changes to the corresponding value in above.
- Changing the terminal assignment using Pr. 178 to Pr. 189 (Input terminal function selection) may affect the other functions. Please make setting after confirming the function of each terminal.

#### ◆ Parameters referred to ◆

Pr. 3 Base frequency, Pr. 19 Base frequency voltage Refer to page 69  
 Pr. 71 Applied motor Refer to page 85  
 Pr. 80 Motor capacity (simple magnetic flux vector control) Refer to page 59  
 Pr. 178 to Pr.189 (Input terminal function selection) Refer to page 90

### 3.2.2 Simple magnetic flux vector control (Pr.80, Pr.90)

Providing optimum excitation to the motor can also produce high torque in a low-speed range.  
(Simple magnetic flux vector control)

Pr. 79  
page 147  
Pr.100  
page 71

| Parameter Number | Name                                                 | Initial Value | Setting Range<br>200V class (400V class) |             | Description                                                                             |
|------------------|------------------------------------------------------|---------------|------------------------------------------|-------------|-----------------------------------------------------------------------------------------|
| 80               | Motor capacity (simple magnetic flux vector control) | 9999          | 02330 (01160) or less                    | 0.4 to 55kW | Set the capacity of the motor used to select simple magnetic flux vector control.       |
|                  |                                                      |               | 03160 (01800) or more                    | 0 to 3600kW |                                                                                         |
|                  |                                                      |               | 9999                                     |             | V/F control is performed                                                                |
| 90               | Motor constant (R1)                                  | 9999          | 02330 (01160) or less                    | 0 to 50Ω    | Used to set the motor primary resistance value.<br>(Normally setting is not necessary.) |
|                  |                                                      |               | 03160 (01800) or more                    | 0 to 400mΩ  |                                                                                         |
|                  |                                                      |               | 9999                                     |             | Use the Mitsubishi motor (SF-JR, SF-HRCA) constants                                     |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

#### POINT

- The number of motor poles should be any of 2, 4 and 6 poles.
- Single-motor operation (One motor for one inverter)
- The wiring length from inverter to motor should be within 30m

#### (1) Automatically control optimum torque (Pr.80)

- When simple magnetic flux vector control is not used, set "9999" (initial value) in Pr.80.
- Set the used motor capacity (equal to or one rank higher than the inverter capacity).

#### REMARKS

When using a constant-torque motor, set Pr. 71 Applied motor to "1" (constant-torque motor).

#### CAUTION

- When simple magnetic flux vector control is selected, the rated motor frequency is set in Pr. 3 and the rated motor voltage is set in Pr. 19. The base frequency voltage is handled as 400V when "9999" or "8888" is set in Pr. 19.
- Adjustable 5 points V/F, energy saving operation mode, optimum excitation control function only under V/F control. They do not function for simple magnetic flux vector control.

#### (2) Set the motor constant (Pr.90)

- Normally setting is not necessary. When you need more torque under simple magnetic flux vector control for other manufacturer's motor, set the motor primary resistance value (R1) for Δ connection. When the setting value is "9999" (initial value), the motor constant is based on the Mitsubishi motor constant (SF-JR, SF-HRCA).

#### ◆ Parameters referred to ◆

Pr. 3 Base frequency, Pr. 19 Base frequency voltage Refer to page 69

Pr. 60 Energy saving control selection Refer to page 123

Pr. 71 Applied motor Refer to page 85

Pr. 77 Parameter write selection Refer to page 144

### 3.2.3 Slip compensation (Pr. 245 to Pr. 247)

Pr. 244  
page 213

The inverter output current may be used to assume motor slip to keep the motor speed constant.

Pr. 250  
page 89

| Parameter Number | Name                                               | Initial Value | Setting Range | Description                                                                                                                                                                                                      |
|------------------|----------------------------------------------------|---------------|---------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 245              | Rated slip                                         | 9999          | 0.01 to 50%   | Used to set the rated motor slip.                                                                                                                                                                                |
|                  |                                                    |               | 0, 9999       | No slip compensation                                                                                                                                                                                             |
| 246              | Slip compensation time constant                    | 0.5s          | 0.01 to 10s   | Used to set the slip compensation response time. When the value is made smaller, response will be faster. However, as load inertia is greater, a regenerative overvoltage (E.OV□) error is more liable to occur. |
| 247              | Constant-output region slip compensation selection | 9999          | 0             | Slip compensation is not made in the constant output range (frequency range above the frequency set in Pr.3)                                                                                                     |
|                  |                                                    |               | 9999          | Slip compensation is made in the constant output range.                                                                                                                                                          |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

- Slip compensation is validated when the motor rated slip calculated by the following formula is set to Pr. 245. Slip compensation is not made when Pr. 245 = "0" or "9999".

$$\text{Rated slip} = \frac{\text{Synchronous speed at base frequency} - \text{rated speed}}{\text{Synchronous speed at base frequency}} \times 100[\%]$$

#### REMARKS

When performing slip compensation, the output frequency may become greater than the set frequency. Set the Pr. 1 Maximum frequency value a little higher than the set frequency.

#### ◆ Parameters referred to ◆

Pr. 1 Maximum frequency  Refer to page 67

Pr. 3 Base frequency  Refer to page 69

### 3.2.4 Stall prevention operation

(Pr.22, Pr.23, Pr.48, Pr.49, Pr.66, Pr.148, Pr.149, Pr.154, Pr.156, Pr.157)

This function monitors the output current and automatically changes the output frequency to prevent the inverter from coming to an alarm stop due to overcurrent, overvoltage, etc. It can also limit stall prevention and fast-response current limit operation during acceleration/deceleration, driving or regeneration.

- Stall prevention

If the output current exceeds the stall prevention operation level, the output frequency of the inverter is automatically varied to reduce the output current.

Also the second stall prevention function can restrict the output frequency range in which the stall prevention function is valid. (Pr.49)

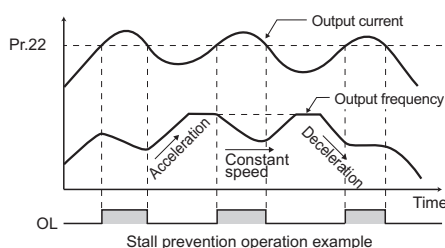
- Fast-response current limit

If the current exceeds the limit value, the output of the inverter is shut off to prevent an overcurrent.

| Parameter Number | Name                                                                 | Initial Value | Setting Range     | Description                                                                                                           |
|------------------|----------------------------------------------------------------------|---------------|-------------------|-----------------------------------------------------------------------------------------------------------------------|
| 22               | Stall prevention operation level                                     | 110% *        | 0                 | Stall prevention operation selection becomes invalid.                                                                 |
|                  |                                                                      |               | 0.1 to 120% *     | Set the current value at which stall prevention operation will be started.                                            |
|                  |                                                                      |               | 9999              | Analog variable                                                                                                       |
| 23               | Stall prevention operation level compensation factor at double speed | 9999          | 0 to 150% *       | The stall operation level can be reduced when operating at a high speed above the rated frequency.                    |
|                  |                                                                      |               | 9999              | Constant according to Pr. 22                                                                                          |
| 48               | Second stall prevention operation current                            | 110% *        | 0                 | Second stall prevention operation invalid                                                                             |
|                  |                                                                      |               | 0.1 to 120% *     | The second stall prevention operation level can be set.                                                               |
| 49               | Second stall prevention operation frequency                          | 0Hz           | 0                 | Second stall prevention operation invalid                                                                             |
|                  |                                                                      |               | 0.01 to 400Hz     | Set the frequency at which stall prevention operation of Pr. 48 is started.                                           |
|                  |                                                                      |               | 9999              | Pr. 48 is valid when the RT signal is on.                                                                             |
| 66               | Stall prevention operation reduction starting frequency              | 60Hz          | 0 to 400Hz        | Set the frequency at which the stall operation level is started to reduce.                                            |
| 148              | Stall prevention level at 0V input.                                  | 110% *        | 0 to 120% *       | Stall prevention operation level can be changed by the analog signal input to terminal 1.                             |
| 149              | Stall prevention level at 10V input.                                 | 120% *        | 0 to 120% *       |                                                                                                                       |
| 154              | Voltage reduction selection during stall prevention operation        | 1             | 0                 | With voltage reduction                                                                                                |
|                  |                                                                      |               | 1                 | Without voltage reduction                                                                                             |
| 156              | Stall prevention operation selection                                 | 0             | 0 to 31, 100, 101 | You can select whether stall prevention operation and fast-response current limit operation will be performed or not. |
| 157              | OL signal output timer                                               | 0s            | 0 to 25s          | Set the output start time of the OL signal output when stall prevention is activated.                                 |
|                  |                                                                      |               | 9999              | Without the OL signal output                                                                                          |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

\* When Pr. 570 Multiple rating setting = "1", performing parameter clear changes the initial value and setting range. (Refer to page 66)



#### (1) Setting of stall prevention operation level (Pr.22)

- Set in Pr. 22 the ratio of the output current to the rated inverter current at which stall prevention operation will be performed. Normally set 110% (initial value).
- Stall prevention operation stops acceleration (makes deceleration) during acceleration, makes deceleration during constant speed, and stops deceleration during deceleration.
- When stall prevention operation is performed, the OL signal is output.

#### CAUTION

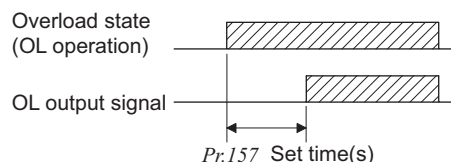
- If an overload status lasts long, an inverter trip (e.g. electronic thermal relay function (E.THM)) may occur.
- When Pr. 156 has been set to activate the fast-response current limit (initial setting), the Pr. 22 setting should not be higher than 140%. The torque will not be developed by doing so. (When Pr. 570 = "1")

|         |          |
|---------|----------|
| Pr.21   | page 79  |
| Pr.24   | page 72  |
| Pr.47   | page 69  |
| Pr.50   | page 100 |
| Pr. 65  | page 119 |
| Pr.67   | page 119 |
| Pr. 144 | page 104 |
| Pr.150  | page 101 |
| Pr.153  | page 101 |
| Pr.155  | page 93  |
| Pr. 158 | page 109 |

## (2) Stall prevention operation signal output and output timing adjustment (OL signal, Pr. 157)

- When the output power exceeds the stall prevention operation level and stall prevention is activated, the stall prevention operation signal (OL signal) turns on for longer than 100ms. When the output power falls to or below the stall prevention operation level, the output signal turns off.
- Use Pr. 157 "OL signal output timer" to set whether the OL signal is output immediately or after a preset period of time.
- This operation is also performed when the regeneration avoidance function  $\phi L$  (overvoltage stall) is executed.

| Pr. 157 Setting      | Description                                |
|----------------------|--------------------------------------------|
| 0<br>(initial value) | Output immediately.                        |
| 0.1 to 25            | Output after the set time (s) has elapsed. |
| 9999                 | Not output.                                |



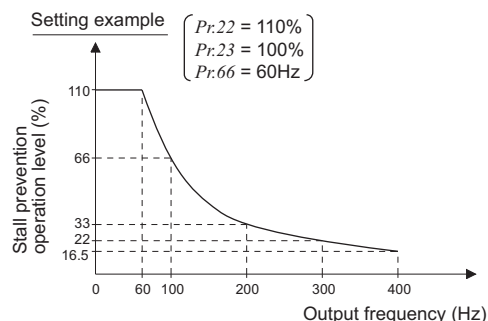
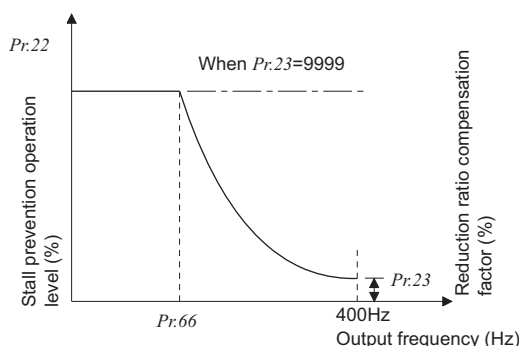
### REMARKS

- The OL signal is assigned to the terminal OL in the initial setting. The OL signal can also be assigned to the other terminal by setting "3 (positive logic) or 103 (negative logic)" to any of Pr. 190 to Pr. 196 (output terminal function selection).

### CAUTION

- If the frequency has fallen to 0.5Hz by stall prevention operation and remains for 3s, an alarm (E.OLT) appears to shutoff the inverter output.
- When terminal assignment is changed using Pr. 190 to Pr. 196 (output terminal function selection), the other functions may be affected. Please make setting after confirming the function of each terminal.

## (3) Setting of stall prevention operation in high frequency region (Pr.22, Pr.23, Pr.66)



- During high-speed operation above the rated motor frequency, acceleration may not be made because the motor current does not increase. If operation is performed in a high frequency range, the current at motor lockup becomes smaller than the rated output current of the inverter, and the protective function (OL) is not executed if the motor is at a stop.

To improve the operating characteristics of the motor in this case, the stall prevention level can be reduced in the high frequency region. This function is effective for performing operation up to the high-speed range on a centrifugal separator etc. Normally, set 60Hz to Pr. 66 and 100% to Pr. 23.

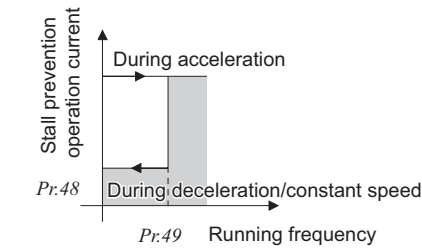
- Formula for stall prevention operation level

$$\text{Stall prevention operation level (\%)} = A + B \times \left[ \frac{\text{Pr.22} - A}{\text{Pr.22} - B} \right] \times \left[ \frac{\text{Pr.23} - 100}{100} \right]$$

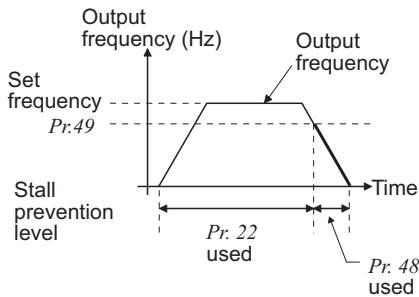
$$\text{However, } A = \frac{\text{Pr.66(Hz)} \times \text{Pr.22(\%)}}{\text{Output frequency (H)}}, \quad B = \frac{\text{Pr.66(Hz)} \times \text{Pr.22(\%)}}{400\text{Hz}}$$

- When Pr. 23 Stall prevention operation level compensation factor at double speed = "9999" (initial value), the stall prevention operation level is kept constant at the Pr. 22 setting up to 400Hz.

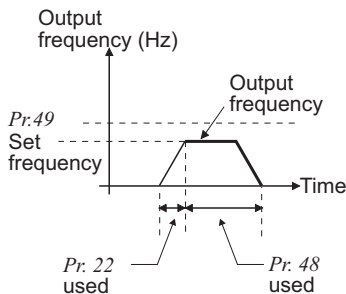
#### (4) Set multiple stall prevention operation levels (Pr.48, Pr.49)



Set frequency exceeds Pr. 49



Set frequency is Pr. 49 or less



- Setting "9999" in Pr. 49 Second stall prevention operation frequency and turning the RT signal on make Pr. 48 Second stall prevention operation current valid.
- In Pr. 48, you can set the stall prevention operation level at the output frequency from 0Hz to that set in Pr. 49. During acceleration, however, the operation level is as set in Pr. 22.
- This function can also be used for stop-on-contact or similar operation by decreasing the Pr. 48 setting to weaken the deceleration torque (stopping torque).

| Pr. 49 Setting       | Operation                                                                                                                                                               |
|----------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 0<br>(initial value) | The second stall prevention operation is not performed.                                                                                                                 |
| 0.01Hz to 400Hz      | If the output frequency is equal to or less than the frequency set in Pr. 49, the second stall prevention function activates. (during constant speed or deceleration)*1 |
| 9999*2               | The second stall prevention function is performed according to the RT signal.<br>RT signal ON ... Stall level Pr. 48<br>RT signal OFF ... Stall level Pr.22             |

- \*1 The smaller setting of the stall prevention operation levels set in Pr. 22 and Pr. 48 has a higher priority.
- \*2 When Pr. 22 = "9999" (Stall prevention operation level analog input), the stall prevention operation level also switches from the analog input (terminal 1 input) to the stall prevention operation level of Pr. 48 when the RT signal turns on. (The second stall prevention operation level cannot be input in an analog form.)

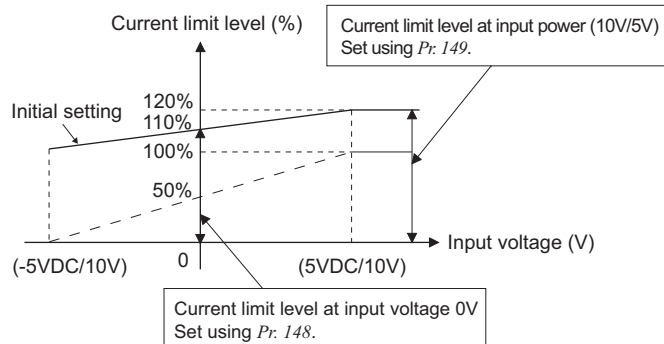
#### REMARKS

- When Pr. 49 ≠ "9999" (level changed according to frequency) and Pr. 48 = "0%" The stall prevention operation level is 0% at or higher than the frequency set in Pr. 49.
- In the initial setting, the RT signal is assigned to the RT terminal. By setting "3" to any of Pr. 178 to Pr. 189 (input terminal function selection), you can assign the RT signal to the other terminal.

#### CAUTION

- Changing the terminal assignment using Pr. 178 to Pr. 189 (input terminal function selection) may affect the other functions. Please make setting after confirming the function of each terminal.
- The RT signal acts as the second function selection signal and makes the other second functions valid. (Refer to page 93)

#### (5) Stall prevention operation level setting by terminal 1 (analog variable)



- Set Pr. 22 to "9999".
- Input 0 to 5V (or 0 to 10V) to terminal 1. Select 5V or 10V using Pr. 73 Analog input selection. When Pr. 73 = "1" (initial value), 0 to ±10V is input.
- Set the current limit level at the input voltage of 0V in Pr. 148 Stall prevention level at 0V input.
- Set the current limit level at the input voltage of 10V or 5V in Pr. 149 Stall prevention level at 10V input.

#### REMARKS

- The fast-response current limit level cannot be set.
- When Pr. 22 = 9999 (analog variable), functions other than the terminal 1 (auxiliary input, override function, PID control) are not executed.

**(6) To further prevent an alarm stop (Pr.154)**

- When Pr. 154 is set to "0", the output voltage reduces during stall prevention operation. By making setting to reduce the output voltage, an overcurrent trip can further become difficult to occur.
- Use this function where a torque decrease will not pose a problem.

| Pr.154 Setting       | Description                |
|----------------------|----------------------------|
| 0                    | Output voltage reduced     |
| 1<br>(initial value) | Output voltage not reduced |

**(7) Limit the stall prevention operation and fast-response current limit operation according to the operating status (Pr.156)**

- Refer to the following table and select whether fast-response current limit operation will be performed or not and the operation to be performed at OL signal output.

| Pr. 156 Setting      | Fast-response current limit<br>○: Activated<br>●: Not activated | Stall prevention operation selection<br>○:Activated<br>●:Not activated |                |              | OL Signal Output<br>○:Operation continued<br>●:Operation not continued <sup>*1</sup> |
|----------------------|-----------------------------------------------------------------|------------------------------------------------------------------------|----------------|--------------|--------------------------------------------------------------------------------------|
|                      |                                                                 | Acceleration                                                           | Constant speed | Deceleration |                                                                                      |
| 0<br>(initial value) | ○                                                               | ○                                                                      | ○              | ○            | ○                                                                                    |
| 1                    | ●                                                               | ○                                                                      | ○              | ○            | ○                                                                                    |
| 2                    | ○                                                               | ●                                                                      | ○              | ○            | ○                                                                                    |
| 3                    | ●                                                               | ●                                                                      | ○              | ○            | ○                                                                                    |
| 4                    | ○                                                               | ○                                                                      | ●              | ○            | ○                                                                                    |
| 5                    | ●                                                               | ○                                                                      | ●              | ○            | ○                                                                                    |
| 6                    | ○                                                               | ●                                                                      | ●              | ○            | ○                                                                                    |
| 7                    | ●                                                               | ●                                                                      | ●              | ○            | ○                                                                                    |
| 8                    | ○                                                               | ○                                                                      | ○              | ●            | ○                                                                                    |
| 9                    | ●                                                               | ○                                                                      | ○              | ●            | ○                                                                                    |
| 10                   | ○                                                               | ●                                                                      | ○              | ●            | ○                                                                                    |
| 11                   | ●                                                               | ●                                                                      | ○              | ●            | ○                                                                                    |
| 12                   | ○                                                               | ○                                                                      | ●              | ●            | ○                                                                                    |
| 13                   | ●                                                               | ○                                                                      | ●              | ●            | ○                                                                                    |
| 14                   | ○                                                               | ●                                                                      | ●              | ●            | ○                                                                                    |
| 15                   | ●                                                               | ●                                                                      | ●              | ●            | ○                                                                                    |

| Pr. 156 Setting | Fast-response current limit<br>○:Activated<br>●: Not activated | Stall prevention operation selection<br>○:Activated<br>●:Not activated |                |              | OL Signal Output<br>○:Operation continued<br>●:Operation not continued <sup>*1</sup> |
|-----------------|----------------------------------------------------------------|------------------------------------------------------------------------|----------------|--------------|--------------------------------------------------------------------------------------|
|                 |                                                                | Acceleration                                                           | Constant speed | Deceleration |                                                                                      |
| 16              | ○                                                              | ○                                                                      | ○              | ○            | ●                                                                                    |
| 17              | ●                                                              | ○                                                                      | ○              | ○            | ●                                                                                    |
| 18              | ○                                                              | ●                                                                      | ○              | ○            | ●                                                                                    |
| 19              | ●                                                              | ●                                                                      | ○              | ○            | ●                                                                                    |
| 20              | ○                                                              | ○                                                                      | ●              | ○            | ●                                                                                    |
| 21              | ●                                                              | ○                                                                      | ●              | ○            | ●                                                                                    |
| 22              | ○                                                              | ●                                                                      | ●              | ○            | ●                                                                                    |
| 23              | ●                                                              | ●                                                                      | ●              | ○            | ●                                                                                    |
| 24              | ○                                                              | ○                                                                      | ○              | ○            | ●                                                                                    |
| 25              | ●                                                              | ○                                                                      | ○              | ●            | ●                                                                                    |
| 26              | ○                                                              | ●                                                                      | ○              | ●            | ●                                                                                    |
| 27              | ●                                                              | ●                                                                      | ○              | ●            | ●                                                                                    |
| 28              | ○                                                              | ○                                                                      | ●              | ●            | ●                                                                                    |
| 29              | ●                                                              | ○                                                                      | ●              | ●            | ●                                                                                    |
| 30              | ○                                                              | ●                                                                      | ●              | ●            | ●                                                                                    |
| 31              | ●                                                              | ●                                                                      | ●              | ●            | ●                                                                                    |

|                   |              |   |   |   |   |   |
|-------------------|--------------|---|---|---|---|---|
| 100 <sup>*2</sup> | Driving      | ○ | ○ | ○ | ○ | ○ |
|                   | Regeneration | ● | ● | ● | ● | ○ |

|                   |              |   |   |   |   |   |
|-------------------|--------------|---|---|---|---|---|
| 101 <sup>*2</sup> | Driving      | ● | ○ | ○ | ○ | ○ |
|                   | Regeneration | ● | ● | ● | ● | ○ |

<sup>\*1</sup> When "Operation not continued for OL signal output" is selected, the "EOL" alarm code (stopped by stall prevention) is displayed and operation stopped.

<sup>\*2</sup> The settings "100" and "101" allow operations to be performed in the driving and regeneration modes, respectively. The setting "101" disables the fast-response current limit in the driving mode.

**CAUTION**

- When the load is heavy, when the lift is predetermined, or when the acceleration/deceleration time is short, stall prevention is activated and acceleration/deceleration may not be made according to the preset acceleration/deceleration time. Set Pr. 156 and stall prevention operation level to the optimum values.
- In vertical lift applications, make setting so that the fast-response current limit is not activated. Torque may not be produced, causing a drop due to gravity.

## CAUTION

- ⚠ Do not set a small value as the stall prevention operation current. Otherwise, torque generated will reduce.
- ⚠ Always perform test operation.
  - Stall prevention operation during acceleration may increase the acceleration time.
  - Stall prevention operation performed during constant speed may cause sudden speed changes.
  - Stall prevention operation during deceleration may increase the deceleration time, increasing the deceleration distance.

### ◆ Parameters referred to ◆

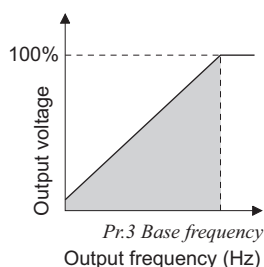
- Pr.73 Analog input selection Refer to page 130
- Pr. 178 to Pr.189 (Input terminal function selection) Refer to page 90
- Pr. 190 to Pr. 196 (output terminal function selection) Refer to page 96
- Pr. 570 Multiple rating setting Refer to page 66

### 3.2.5 Load pattern selection (Pr.14)

You can select the optimum output characteristic (V/F characteristic) for the application and load characteristics.

| Parameter Number | Name                   | Initial Value | Setting Range | Description               |
|------------------|------------------------|---------------|---------------|---------------------------|
| 14               | Load pattern selection | 1             | 0             | For constant torque load  |
|                  |                        |               | 1             | For variable-torque loads |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)



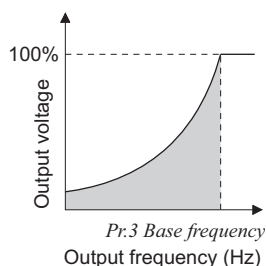
#### (1) For constant-torque load (setting "0")

- At or less than the base frequency voltage, the output voltage varies linearly with the output frequency.
- Set this value when driving the load whose load torque is constant if the speed varies, e.g. conveyor, cart or roll drive.

#### POINT

If the load is a fan or pump, select "For rated torque load (setting "0")" in any of the following cases.

- When a blower of large moment of inertia (J) is accelerated in a short time
- For constant-torque load such as rotary pump or gear pump
- When load torque increases at low speed, e.g. screw pump



#### (2) For variable-torque load (setting "1", initial value)

- At or less than the base frequency voltage, the output voltage varies with the output frequency in a square curve.
- Set this value when driving the load whose load torque varies in proportion to the square of the speed, e.g. fan or pump.

### ◆ Parameters referred to ◆

- Pr. 0 Torque boost Refer to page 58
- Pr.1 Maximum frequency Refer to page 67
- Pr.3 Base frequency Refer to page 69
- Pr.60 Energy saving control selection Refer to page 123
- Pr.80 Motor capacity (simple magnetic flux vector control) Refer to page 59
- Pr. 178 to Pr.189 (Input terminal function selection) Refer to page 90

Pr. 13  
page 81

Pr.15  
page 74

### 3.2.6 Multiple rating (Pr.570)

You can use the inverter by changing the overload current rating specifications according to load applications. Note that the control rating of each function changes.

Pr.564  
page 105

Pr.571  
page 81

| Parameter Number | Name                    | Initial Value | Setting Range | Description                                                                                                             |
|------------------|-------------------------|---------------|---------------|-------------------------------------------------------------------------------------------------------------------------|
| 570              | Multiple rating setting | 0             | 0             | SLD<br>Ambient temperature 40°C (104°F),<br>Overload current rating 110% 60s, 120% 3s<br>(Inverse time characteristics) |
|                  |                         |               | 1             | LD<br>Ambient temperature 50°C (122°F),<br>Overload current rating 120% 60s, 150% 3s<br>(Inverse time characteristics)  |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

- The initial value and setting range of the following parameters are changed by performing parameter clear and reset after changing this parameter setting.

| Parameter Number | Name                                                                 |               | Pr. 570 Setting                        |                                       | Refer to Page |
|------------------|----------------------------------------------------------------------|---------------|----------------------------------------|---------------------------------------|---------------|
|                  |                                                                      |               | 0<br>(initial value)                   | 1                                     |               |
| 9                | Electronic thermal O/L relay                                         | Initial Value | SLD rated current *1                   | LD rated current *1                   | 83            |
| 22               | Stall prevention operation level                                     | Setting Range | 0, 0.1 to 120%, 9999                   | 0, 0.1 to 150%, 9999                  | 61            |
|                  |                                                                      | Initial Value | 110%                                   | 120%                                  |               |
| 23               | Stall prevention operation level compensation factor at double speed | Setting Range | 0 to 150%, 9999                        | 0 to 200%, 9999                       | 61            |
|                  |                                                                      | Initial Value | 9999                                   | 9999                                  |               |
| 48               | Second stall prevention operation current                            | Setting Range | 0, 0.1 to 120%                         | 0, 0.1 to 150%                        | 61            |
|                  |                                                                      | Initial Value | 110%                                   | 120%                                  |               |
| 56               | Current monitoring reference                                         | Initial Value | SLD rated current *1                   | LD rated current *1                   | 109           |
| 148              | Stall prevention level at 0V input.                                  | Setting Range | 0 to 120%                              | 0 to 150%                             | 61            |
|                  |                                                                      | Initial Value | 110%                                   | 120%                                  |               |
| 149              | Stall prevention level at 10V input.                                 | Setting Range | 0 to 120%                              | 0 to 150%                             | 61            |
|                  |                                                                      | Initial Value | 120%                                   | 150%                                  |               |
| 150              | Output current detection level                                       | Setting Range | 0 to 120%                              | 0 to 150%                             | 101           |
|                  |                                                                      | Initial Value | 110%                                   | 120%                                  |               |
| 165              | Stall prevention operation level for restart                         | Setting Range | 0 to 120%                              | 0 to 150%                             | 114           |
|                  |                                                                      | Initial Value | 110%                                   | 120%                                  |               |
| 557              | Current average value monitor signal output reference current        | Initial Value | SLD rated current *1                   | LD rated current *1                   | 217           |
| 893              | Energy saving monitor reference (motor capacity)                     | Initial Value | SLD value of Applied moter Capacity *2 | LD value of Applied moter Capacity *2 | 124           |

\*1 The rated current differs according to the inverter capacity. Refer to rated specifications (page 250).

\*2 For the FR-F720-02330(FR-F740-01160) or less, SLD/LD value of Applied moter Capacity is the same. Refer to rated specifications (page 250).

#### CAUTION

When Pr. 570 = "0" (initial value), Pr.260 PWM frequency automatic switchover becomes invalid. (Refer to page 129.)

### 3.3 Limit the output frequency

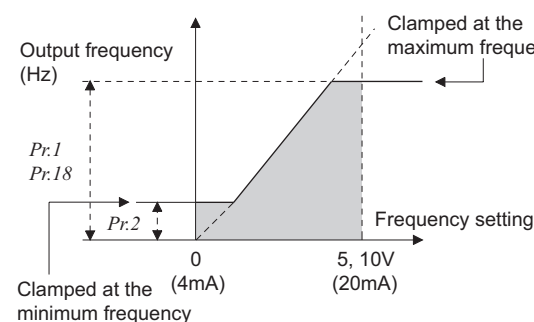
| Purpose                                                | Parameter that must be set |                      | Refer to Page |
|--------------------------------------------------------|----------------------------|----------------------|---------------|
| Set upper limit and lower limit of output frequency    | Maximum/minimum frequency  | Pr. 1, Pr. 2, Pr. 18 | 67            |
| Perform operation by avoiding machine resonance points | Frequency jump             | Pr. 31 to Pr. 36     | 68            |

#### 3.3.1 Maximum/minimum frequency (Pr. 1, Pr. 2, Pr. 18)

You can limit the motor speed. Clamp the upper and lower limits of the output frequency.

| Parameter Number | Name                         | Initial Value<br>200V class (400V class) |       | Setting Range | Description                                         |
|------------------|------------------------------|------------------------------------------|-------|---------------|-----------------------------------------------------|
| 1                | Maximum frequency            | 02330 (01160) or less                    | 120Hz | 0 to 120Hz    | Set the upper limit of the output frequency.        |
|                  |                              | 03160 (01800) or more                    | 60Hz  |               |                                                     |
| 2                | Minimum frequency            | 0Hz                                      |       | 0 to 120Hz    | Set the lower limit of the output frequency.        |
| 18 *             | High speed maximum frequency | 02330 (01160) or less                    | 120Hz | 120 to 400Hz  | Set when performing the operation at 120Hz or more. |
|                  |                              | 03160 (01800) or more                    | 60Hz  |               |                                                     |

\* The parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)



#### (1) Set maximum frequency

- Set the upper limit of the output frequency in *Pr. 1 Maximum frequency*. If the frequency of the frequency command entered is higher than the setting, the output frequency is clamped at the maximum frequency.
- When you want to perform operation above 120Hz, set the upper limit of the output frequency to *Pr. 18 High speed maximum frequency*. (When *Pr. 18* is set, *Pr. 1* automatically switches to the frequency of *Pr. 18*. When *Pr. 18* is set, *Pr. 18* automatically switches to the frequency of *Pr. 1*.)

#### REMARKS

- When performing operation above 60Hz using the frequency setting analog signal, change *Pr. 125 (Pr. 126) (frequency setting gain)*. If only *Pr. 1* or *Pr. 18* is changed, operation above 60Hz cannot be performed

#### (2) Set minimum frequency

- Use *Pr. 2 Minimum frequency* to set the lower limit of the output frequency.
- The output frequency is clamped by the *Pr. 2* setting even the set frequency is lower than the *Pr. 2* setting (The frequency will not decrease to the *Pr. 2* setting.)

#### REMARKS

- When *Pr. 15 Jog frequency* is equal to or less than *Pr. 2*, the *Pr. 15* setting has precedence over the *Pr. 2* setting.
- When stall prevention is activated to decrease the output frequency, the output frequency may drop to *Pr. 2* or below.

## CAUTION

- If the *Pr. 2* setting is higher than the *Pr. 13 Starting frequency* value, note that the motor will run at the set frequency according to the acceleration time setting by merely switching the start signal on, without entry of the command frequency.

#### ◆ Parameters referred to ◆

*Pr. 13 Starting frequency* Refer to page 81

*Pr. 15 Jog frequency* Refer to page 74

*Pr. 125 Terminal 2 frequency setting gain frequency, Pr. 126 Terminal 4 frequency setting gain frequency* Refer to page 134

Pr. 0  
page 58

Pr. 3  
page 69

Pr. 17  
page 92

Pr. 19  
page 69



### 3.3.2 Avoid mechanical resonance points (Frequency jump) (Pr. 31 to Pr. 36)

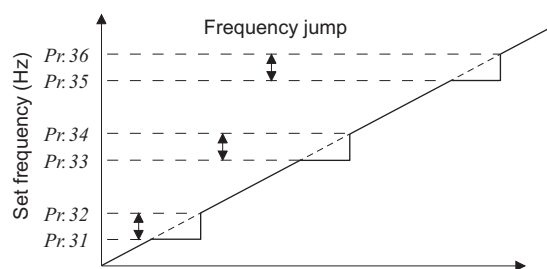
When it is desired to avoid resonance attributable to the natural frequency of a mechanical system, these parameters allow resonant frequencies to be jumped.

Pr. 30  
page 88

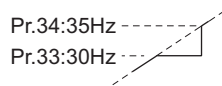
Pr. 37  
page 104

| Parameter Number | Name              | Initial Value | Setting Range    | Description                                                               |
|------------------|-------------------|---------------|------------------|---------------------------------------------------------------------------|
| 31               | Frequency jump 1A | 9999          | 0 to 400Hz, 9999 | 1A to 1B, 2A to 2B, 3A to 3B is frequency jumps<br>9999: Function invalid |
| 32               | Frequency jump 1B | 9999          | 0 to 400Hz, 9999 |                                                                           |
| 33               | Frequency jump 2A | 9999          | 0 to 400Hz, 9999 |                                                                           |
| 34               | Frequency jump 2B | 9999          | 0 to 400Hz, 9999 |                                                                           |
| 35               | Frequency jump 3A | 9999          | 0 to 400Hz, 9999 |                                                                           |
| 36               | Frequency jump 3B | 9999          | 0 to 400Hz, 9999 |                                                                           |

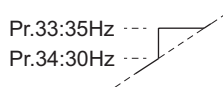
The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)



- Up to three areas may be set, with the jump frequencies set to either the top or bottom point of each area.
- The settings of frequency jumps 1A, 2A, 3A are jump points, and operation is performed at these frequencies in the jump areas.



**Example 1** To fix the frequency to 30Hz in the range 30Hz to 35Hz, set 35Hz in Pr. 34 and 30Hz in Pr. 33.



**Example 2** To jump the frequency to 35Hz in the range 30Hz to 35Hz, set 35Hz in Pr. 33 and 30Hz in Pr. 34.

#### CAUTION

- During acceleration/deceleration, the running frequency within the set area is valid.

## 3.4 Set V/F pattern

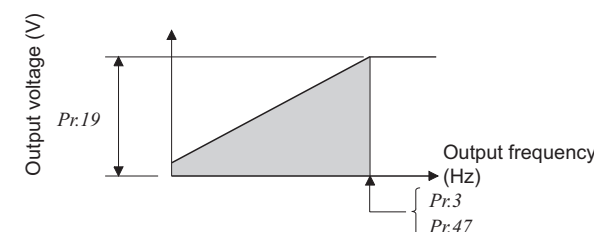
| Purpose           | Parameter that must be set             |                         | Refer to page |
|-------------------|----------------------------------------|-------------------------|---------------|
| Set motor ratings | Base frequency, Base frequency voltage | Pr.3, Pr.19, Pr.47      | 69            |
| Use special motor | Adjustable 5 points V/F                | Pr.71, Pr.100 to Pr.109 | 71            |

### 3.4.1 Base frequency, voltage (Pr.3, Pr.19, Pr.47)

Used to adjust the inverter outputs (voltage, frequency) to the motor rating.

| Parameter Number | Name                        | Initial Value | Setting Range | Description                                                             |
|------------------|-----------------------------|---------------|---------------|-------------------------------------------------------------------------|
| 3                | Base frequency              | 60Hz          | 0 to 400Hz    | Set the frequency when the motor rated torque is generated. (50Hz/60Hz) |
| 19 *             | Base frequency voltage      | 9999          | 0 to 1000V    | Set the base voltage.                                                   |
|                  |                             |               | 8888          | 95% of power supply voltage                                             |
|                  |                             |               | 9999          | Same as power supply voltage                                            |
| 47 *             | Second V/F (base frequency) | 9999          | 0 to 400Hz    | Set the base frequency when the RT signal is on.                        |
|                  |                             |               | 9999          | Second V/F invalid                                                      |

\* The parameters can be set when Pr. 160 User group read selection = "0" (Refer to page 145)



#### (1) Setting of base frequency (Pr.3)

- When operating a standard motor, generally set the rated frequency of the motor to Pr. 3 Base frequency. When running the motor using commercial power supply-inverter switch-over operation, set Pr. 3 to the same value as the power supply frequency.
- If the frequency given on the motor rating plate is "50Hz" only, always set to "50Hz". Leaving the base frequency unchanged from "60Hz" may make the voltage too low and the torque insufficient.
- When using the Mitsubishi constant-torque motor, set Pr. 3 to 60Hz.

#### (2) Set multiple base frequencies (Pr.47)

- When you want to change the base frequency when switching multiple motors with one inverter, use the Pr. 47 Second V/F (base frequency).
- Pr. 47 Second V/F (base frequency) is valid when the RT signal is on.

#### REMARKS

- The RT signal acts as the second function selection signal and makes the other second functions valid. (Refer to page 93)
- In the initial setting, the RT signal is assigned to the RT terminal. By setting "3" to any of Pr. 178 to Pr. 189 (Input terminal function selection), you can assign the RT signal to the other terminal.

Pr. 2  
page 67

Pr.4  
page 72

Pr.18  
page 67

Pr.20  
page 79

Pr.46  
page 58

Pr.48  
page 61



### (3) Base frequency voltage setting (*Pr. 19*)

- Use *Pr. 19 Base frequency voltage* to set the base voltage (e.g. rated motor voltage).
- If the setting is less than the power supply voltage, the maximum output voltage of the inverter is as set in *Pr. 19*.
- *Pr. 19* can be utilized in the following cases.
  - (a) When regeneration frequency is high (e.g. continuous regeneration)  
During regeneration, the output voltage becomes higher than the reference and may cause an overcurrent trip (E.OC□) due to an increased motor current.
  - (b) When power supply voltage variation is large  
When the power supply voltage exceeds the rated voltage of the motor, speed variation or motor overheat may be caused by excessive torque or increased motor current.
  - (c) When you want to expand constant-output characteristic range  
To expand the constant-output characteristic range at the base frequency or less, set a value greater than the power supply voltage to *Pr. 19*.

---

#### CAUTION

---

- When *Pr. 71 Applied motor* is set to "2" (adjustable 5 points V/F characteristic), the *Pr. 47* setting becomes invalid. In addition, you cannot set "8888" or "9999" in *Pr. 19*.
- 

#### ◆ Parameters referred to ◆

*Pr. 14 Load pattern selection* Refer to page 65  
*Pr. 29 Acceleration/deceleration pattern selection* Refer to page 82  
*Pr. 71 Applied motor* Refer to page 85  
*Pr. 80 Motor capacity (simple magnetic flux vector control)*, Refer to page 59.  
*Pr. 178 to Pr. 189 (input terminal function selection)* Refer to page 90.

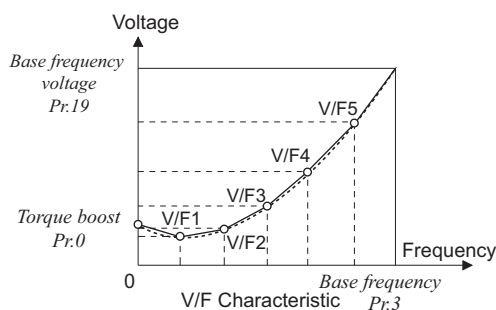
### 3.4.2 Adjustable 5 points V/F (Pr. 71, Pr. 100 to 109)

A dedicated V/F pattern can be made by freely setting the V/F characteristic between a startup and the base frequency and base voltage under V/F control (frequency voltage/frequency).

The torque pattern that is optimum for the machine's characteristic can be set.

| Parameter Number | Name                            | Initial Value | Setting Range    | Description                                                                  |
|------------------|---------------------------------|---------------|------------------|------------------------------------------------------------------------------|
| 71               | Applied motor                   | 0             | 0, 1, 2, 20      | Set "2" for adjustable 5 points V/F control.                                 |
| 100              | V/F1 (first frequency)          | 9999          | 0 to 400Hz, 9999 | Set each points (frequency, voltage) of V/F pattern.<br>9999: No V/F setting |
| 101              | V/F1 (first frequency voltage)  | 0V            | 0 to 1000V       |                                                                              |
| 102              | V/F2 (second frequency)         | 9999          | 0 to 400Hz, 9999 |                                                                              |
| 103              | V/F2 (second frequency voltage) | 0V            | 0 to 1000V       |                                                                              |
| 104              | V/F3 (third frequency)          | 9999          | 0 to 400Hz, 9999 |                                                                              |
| 105              | V/F3 (third frequency voltage)  | 0V            | 0 to 1000V       |                                                                              |
| 106              | V/F4 (fourth frequency)         | 9999          | 0 to 400Hz, 9999 |                                                                              |
| 107              | V/F4 (fourth frequency voltage) | 0V            | 0 to 1000V       |                                                                              |
| 108              | V/F5 (fifth frequency)          | 9999          | 0 to 400Hz, 9999 |                                                                              |
| 109              | V/F5 (fifth frequency voltage)  | 0V            | 0 to 1000V       |                                                                              |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)



- Any V/F characteristic can be provided by presetting the parameters of V/F1 (first frequency voltage/first frequency) to V/F5.
- For a machine of large static friction coefficient and small dynamic static friction coefficient, for example, set a V/F pattern that will increase the voltage only in a low-speed range since such a machine requires large torque at a start.

#### (Setting procedure)

- Set the rated motor current in Pr. 19 Base frequency voltage. (No function at the setting of "9999" (initial value) or "8888".)
- Set Pr. 71 Applied motor to "2" (Adjustable 5 points V/F characteristic).
- Set the frequency and voltage you want to set in Pr. 100 to Pr. 109.

## CAUTION

- ⚠ Set this parameter correctly according to the motor used.  
Incorrect setting may cause the motor to overheat and burn.

### CAUTION

- Adjustable 5 points V/F characteristics function only under V/F control or optimum excitation control. They do not function for simple magnetic flux vector control.
- When Pr. 19 Base frequency voltage = "8888" or "9999", Pr. 71 cannot be set to "2". To set Pr. 71 to "2", set the rated voltage value in Pr. 19.
- When the frequency values at each point are the same, a write disable error (Err 1) appears.
- Set the points (frequencies, voltages) of Pr. 100 to Pr. 109 within the ranges of Pr. 3 Base frequency and Pr. 19 Base frequency voltage.
- When "2" is set in Pr. 71, Pr. 47 Second V/F (base frequency) will not function.
- When Pr. 71 is set to "2", the electronic thermal relay function makes calculation as a standard motor.

### REMARKS

- A greater energy saving effect can be expected by combining Pr. 60 Energy saving control selection and adjustable 5 points V/F.
- For the FR-F720-00250 and 00340 and the FR-F740-00126 and 00170, the Pr. 0 and Pr. 12 settings are automatically changed according to the Pr. 71 setting.

|        |          |    |
|--------|----------|----|
| Pr. 71 | 0, 2, 20 | 1  |
| Pr. 0  | 3%       | 2% |
| Pr. 12 | 4%       | 2% |

#### ◆ Parameters referred to ◆

- Pr. 3 Base frequency, Pr. 19 Base frequency voltage Refer to page 69
- Pr. 47 Second V/F (base frequency) Refer to page 69
- Pr. 60 Energy saving control selection Refer to page 123
- Pr. 71 Applied motor Refer to page 85
- Pr. 60 Motor capacity (simple magnetic flux vector control), Pr. 90 Motor constant (R1) Refer to page 59

|         |          |
|---------|----------|
| Pr. 69  | page 119 |
| Pr. 72  | page 129 |
| Pr. 90  | page 59  |
| Pr. 117 | page 166 |

### 3.5 Frequency setting by external terminals

| Purpose                                                       | Parameter that must be set               |                                                      | Refer to Page |
|---------------------------------------------------------------|------------------------------------------|------------------------------------------------------|---------------|
| Make frequency setting by combination of terminals            | Multi-speed operation                    | Pr. 4 to Pr. 6, Pr. 24 to Pr. 27, Pr. 232 to Pr. 239 | 72            |
| Perform jog operation                                         | Jog operation                            | Pr. 15, Pr. 16                                       | 74            |
| Added compensation for multi-speed setting and remote setting | Multi-speed input compensation selection | Pr. 28                                               | 76            |
| Infinitely variable speed setting by terminals                | Remote setting function                  | Pr. 59                                               | 77            |

#### 3.5.1 Multi-speed setting operation (Pr. 4 to Pr. 6, Pr. 24 to Pr. 27, Pr. 232 to Pr. 239)

Can be used to change the preset speed in the parameter with the contact terminals.  
Any speed can be selected by merely turning on-off the contact signals (RH, RM, RL, REX signals).

Pr. 3  
page 69

Pr. 7  
page 79

Pr. 23  
page 61

Pr. 28  
page 76

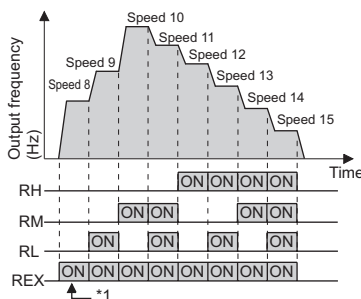
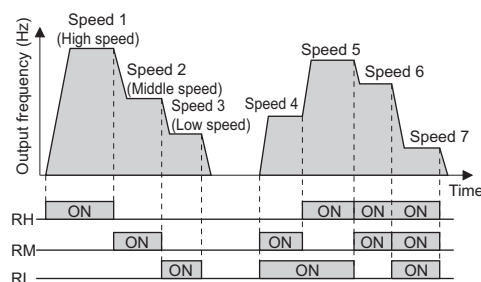
Pr. 196  
page 96

Pr. 240  
page 129

| Parameter Number | Name                               | Initial Value | Setting Range    | Description                                                                                                                         |
|------------------|------------------------------------|---------------|------------------|-------------------------------------------------------------------------------------------------------------------------------------|
| 4                | Multi-speed setting (high speed)   | 60Hz          | 0 to 400Hz       | Set the frequency when RH turns on.                                                                                                 |
| 5                | Multi-speed setting (middle speed) | 30Hz          | 0 to 400Hz       | Set the frequency when RM turns on.                                                                                                 |
| 6                | Multi-speed setting (low speed)    | 10Hz          | 0 to 400Hz       | Set the frequency when RL turns on.                                                                                                 |
| 24 *             | Multi-speed setting (speed4)       | 9999          | 0 to 400Hz, 9999 | Frequency from speed 4 to speed 15 can be set according to the combination of the RH, RM, RL and REX signals.<br>9999: not selected |
| 25 *             | Multi-speed setting (speed 5)      | 9999          | 0 to 400Hz, 9999 |                                                                                                                                     |
| 26 *             | Multi-speed setting (speed 6)      | 9999          | 0 to 400Hz, 9999 |                                                                                                                                     |
| 27 *             | Multi-speed setting (speed 7)      | 9999          | 0 to 400Hz, 9999 |                                                                                                                                     |
| 232 *            | Multi-speed setting (speed 8)      | 9999          | 0 to 400Hz, 9999 |                                                                                                                                     |
| 233 *            | Multi-speed setting (speed 9)      | 9999          | 0 to 400Hz, 9999 |                                                                                                                                     |
| 234 *            | Multi-speed setting (speed 10)     | 9999          | 0 to 400Hz, 9999 |                                                                                                                                     |
| 235 *            | Multi-speed setting (speed 11)     | 9999          | 0 to 400Hz, 9999 |                                                                                                                                     |
| 236 *            | Multi-speed setting (speed 12)     | 9999          | 0 to 400Hz, 9999 |                                                                                                                                     |
| 237 *            | Multi-speed setting (speed 13)     | 9999          | 0 to 400Hz, 9999 |                                                                                                                                     |
| 238 *            | Multi-speed setting (speed 14)     | 9999          | 0 to 400Hz, 9999 |                                                                                                                                     |
| 239 *            | Multi-speed setting (speed 15)     | 9999          | 0 to 400Hz, 9999 |                                                                                                                                     |

The above parameters allow its setting to be changed during operation in any operation mode even if "0" (initial value) is set in Pr. 77 Parameter write selection.

\* The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)



#### (1) Multi-speed setting (Pr. 4 to Pr. 6)

- Operation is performed at the frequency set in Pr. 4 when the RH signal turns on, Pr. 5 when the RM signal turns on, and Pr. 6 when the RL signal turns on.

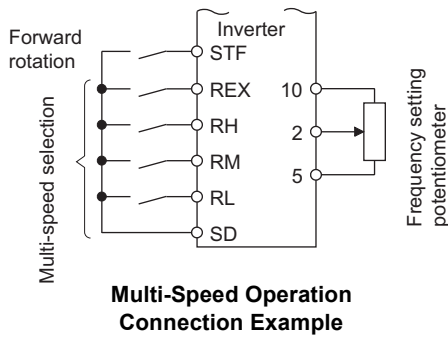
##### REMARKS

In the initial setting, if two or three speeds are simultaneously selected, priority is given to the set frequency of the lower signal. For example, when the RH and RM signals turn on, the RM signal (Pr. 5) has a higher priority.

#### (2) Multi-speed setting higher than speed 4 (Pr. 24 to Pr. 27, Pr. 232 to Pr. 239)

- Frequency from speed 4 to speed 15 can be set according to the combination of the RH, RM, RL and REX signals. Set the running frequencies in Pr. 24 to Pr. 27, Pr. 232 to Pr. 239. (In the initial value setting, speed 4 to speed 15 are unavailable.)
- For the terminal used for REX signal input, set "8" in any of Pr. 178 to Pr. 186 to assign the function.

\*1 When only the REX signal turns on with Pr. 232 Multi-speed setting (speed 8) set to "9999", the set frequency becomes the low speed running frequency (Pr. 6).



## REMARKS

- The priorities of the frequency commands by the external signals are "jog operation > multi-speed operation > terminal 4 analog input > terminal 2 analog input". (Refer to *page 130* for the frequency command by analog input)
- Valid in external operation mode or PU/external combined operation mode (*Pr. 79* = "3" or "4").
- Multi-speed parameters can also be set in the PU or external operation mode.
- *Pr. 24 to Pr. 27* and *Pr. 232 to Pr. 239* settings have no priority between them.
- When a value other than "0" is set in *Pr. 59 Remote function selection*, the RH, RM and RL signals are used as the remote setting signals and the multi-speed setting becomes invalid
- When making analog input compensation, set "1" in *Pr. 28 Multi-speed input compensation selection*.

## CAUTION

- The RH, RM, RL, REX signals can be assigned to the input terminal using any of *Pr. 178 to Pr. 189 (input terminal function selection)*. When terminal assignment is changed, the other functions may be affected. Please make setting after confirming the function of each terminal.

## ◆ Parameters referred to ◆

*Pr. 1 Maximum frequency, Pr. 2 Minimum frequency* Refer to *page 67*

*Pr. 15 Jog frequency* Refer to *page 74*

*Pr. 28 Multi-speed input compensation selection* Refer to *page 76*

*Pr. 59 Remote function selection* Refer to *page 77*

*Pr. 178 to Pr. 189 (input terminal function selection)* Refer to *page 90*

## 3.5.2 Jog operation (Pr. 15, Pr. 16)

You can set the frequency and acceleration/deceleration time for jog operation. Jog operation can be performed from either the outside or PU.

Can be used for conveyor positioning, test operation, etc.

Pr. 14  
page 65  
Pr. 17  
page 92

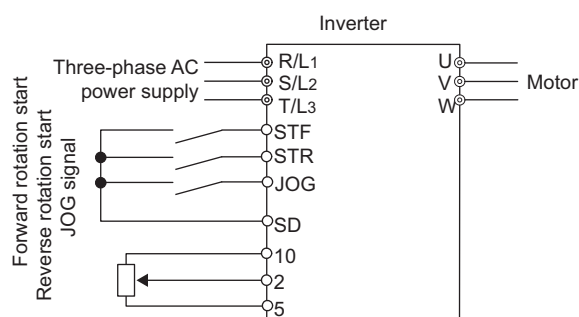
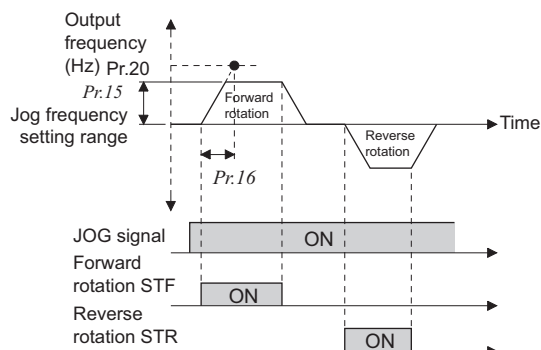
| Parameter Number | Name                               | Initial Value | Setting Range   | Description                                                                                                                                                                                                                                                                                         |
|------------------|------------------------------------|---------------|-----------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 15               | Jog frequency                      | 5Hz           | 0 to 400Hz      | Set the frequency for jog operation.                                                                                                                                                                                                                                                                |
| 16               | Jog acceleration/deceleration time | 0.5s          | 0 to 3600/360s* | Set the acceleration/deceleration time for jog operation. As the acceleration/deceleration time set the time taken to reach the frequency set in Pr. 20 Acceleration/deceleration reference frequency. (Initial value is 60Hz)<br>The acceleration and deceleration times cannot be set separately. |

The above parameters are displayed as simple mode parameters only when the parameter unit (FR-PU04) is connected. When the operation panel (FR-DU07) is connected, the above parameters can be set only when Pr. 160 User group read selection = "0". (Refer to page 145)

\* When the setting of Pr. 21 Acceleration/deceleration time increments is "0" (initial value), the setting range is "0 to 3600s" and the setting increments are "0.1s", and when the setting is "1", the setting range is "0 to 360s" and the setting increments are "0.01s"

### (1) Jog operation from outside

- When the jog signal is on, a start and stop can be made by the start signal (STF, STR). (The jog signal is assigned to the terminal JOG in the initial setting)

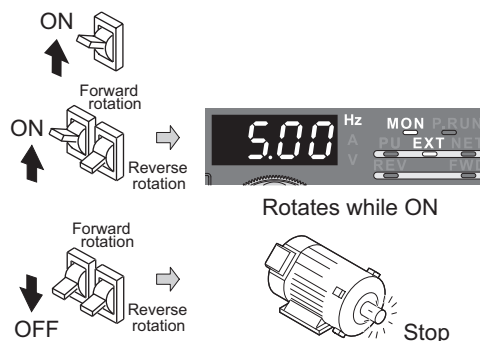


Connection diagram for external jog operation

### Operation

- Screen at powering on
  - Confirm that the external operation mode is selected. ([EXT] lit)  
If not displayed, press  $\text{PU/EXT}$  to change to the external [EXT] operation mode.  
If the operation mode still does not change, set Pr. 79 to change to the external operation mode.
- Turn the JOG switch on.
- Turn the start switch (STF or STR) on.
  - The motor rotates while start switch (STF or STR) is ON.
  - Rotates at 5Hz. (Initial value of Pr. 15)
- Turn the start switch (STF or STR) off.

### Indication

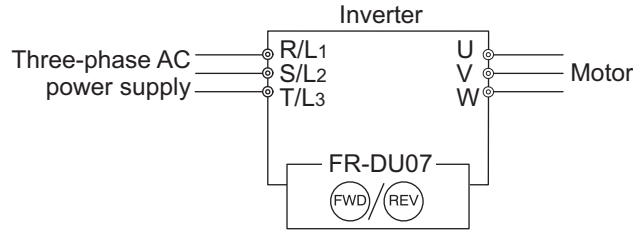


### REMARKS

- When you want to change the running frequency, change Pr. 15 Jog frequency. (initial value "5Hz")
- When you want to change the running frequency, change Pr. 16 Jog acceleration/deceleration time. (initial value "0.5s")

## (2) Jog operation from PU

- Set the PU (FR-DU07/FR-PU04) to the jog operation mode. Operation is performed only while the start button is pressed.



### Operation Indication

- Confirmation of the RUN indication and operation mode indication

- The monitor mode should have been selected.
- The inverter should be at a stop.



- Press **PU/EXT** to choose the PU JOG operation mode.



- Press **FWD** (or **REV**).

- While **FWD** (or **REV**) is pressed, the motor rotates.
- Rotates at 5Hz. (initial value of Pr. 15)



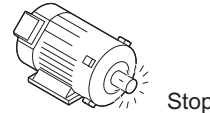
Hold down.



- Release **FWD** (or **REV**).



Release



#### [When changing the frequency of PU JOG operation]

- Press **MODE** to choose the parameter setting mode.



(The parameter number read previously appears.)

- Turn **▲** until Pr. 15 JOG frequency appears.



- Press **SET** to show the currently set value. (5Hz)



- Turn **▲** to set the value to "10.00". (10Hz)



- Press **SET** to set.



- Perform the operations in steps 1 to 4. Flicker... Parameter setting complete!!  
The motor rotates at 10Hz.

### CAUTION

- Pr. 29 Acceleration/deceleration pattern selection = "1" (S-pattern acceleration/deceleration A), the acceleration/deceleration reference frequency applies until Pr. 3 Base frequency is reached.
- The Pr. 15 setting should be equal to or higher than the Pr. 13 Starting frequency setting.
- The JOG signal can be assigned to the input terminal using any of Pr. 178 to Pr. 189 (input terminal function selection). When terminal assignment is changed, the other functions may be affected. Please make setting after confirming the function of each terminal.
- During jog operation, the second acceleration/deceleration via the RT signal cannot be selected. (The other second functions are valid. (Refer to page 92))
- When Pr. 79 Operation mode selection = "4", push **FWD** / **REV** of the PU (FR-DU07/FR-PU04) to make a start or push **STOP/RESET** to make a stop.
- This function is invalid when Pr. 79 = "3" or "6".

#### ◆ Parameters referred to ◆

- Pr. 13 Starting frequency Refer to page 81
- Pr. 29 Acceleration/deceleration pattern selection Refer to page 82
- Pr. 20 Acceleration/deceleration reference frequency, Pr. 21 Acceleration/deceleration time increments Refer to page 79
- Pr. 79 Operation mode selection Refer to page 147
- Pr. 178 to Pr. 189 (input terminal function selection) Refer to page 90

## 3.5.3 Input compensation of multi-speed and remote setting (Pr. 28)

Pr.27  
page 72

Pr. 29  
page 82

By inputting the frequency setting compensation signal (terminal 1, 2), the speed (frequency) can be compensated for relative to the multi-speed setting or the speed setting by remote setting function.

| Parameter Number | Name                                     | Initial Value | Setting Range | Description          |
|------------------|------------------------------------------|---------------|---------------|----------------------|
| 28               | Multi-speed input compensation selection | 0             | 0             | Without compensation |
|                  |                                          |               | 1             | With compensation    |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

### REMARKS

- Select the compensation input voltage (0 to  $\pm 5V$ , 0 to  $\pm 10$ ) and used terminal (terminal 1, 2) using Pr. 73 Analog input selection.

### ◆ Parameters referred to ◆

Pr. 4 to Pr. 6, Pr. 24 to Pr. 27, Pr. 232 to Pr. 239 (multi-speed operation) Refer to page 72  
 Pr. 73 Analog input selection Refer to page 130  
 Pr. 59 Remote function selection Refer to page 77

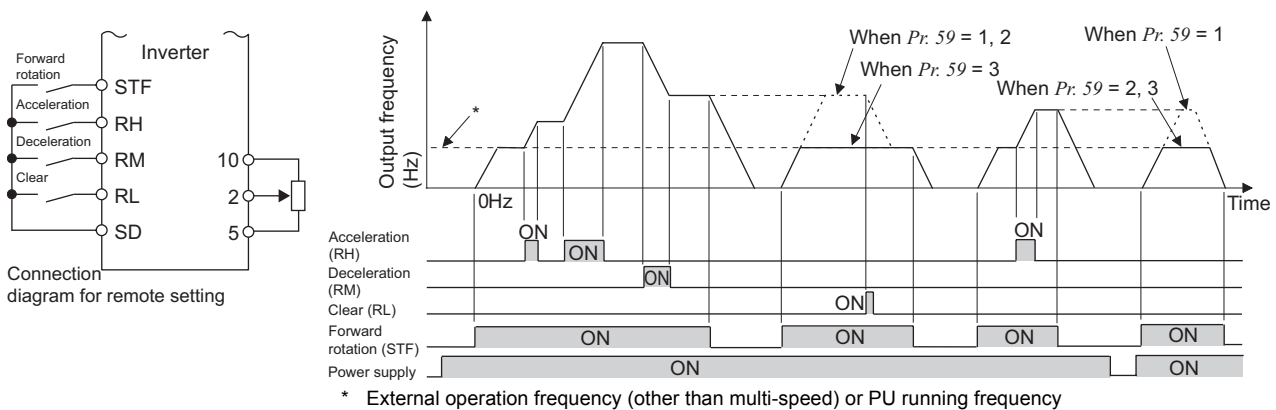
### 3.5.4 Remote setting function (Pr. 59)

- Even if the operation panel is located away from the enclosure, you can use contact signals to perform continuous variable-speed operation, without using analog signals.

Pr. 58  
page 114  
Pr. 60  
page 123

| Parameter Number | Name                      | Initial Value | Setting Range | Description                |                                                              |
|------------------|---------------------------|---------------|---------------|----------------------------|--------------------------------------------------------------|
|                  |                           |               |               | RH, RM, RL signal function | Frequency Setting storage function                           |
| 59               | Remote function selection | 0             | 0             | Multi-speed setting        | —                                                            |
|                  |                           |               | 1             | Remote setting             | Yes                                                          |
|                  |                           |               | 2             | Remote setting             | No                                                           |
|                  |                           |               | 3             | Remote setting             | No<br>(Turning STF/STR off clears remote setting frequency.) |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)



#### (1) Remote setting function

- Use Pr. 59 to select whether the remote setting function is used or not and whether the frequency setting storage function in the remote setting mode is used or not.  
When Pr. 59 is set to any of "1 to 3" (remote setting function valid), the functions of the RH, RM and RL signals are changed to acceleration (RH), deceleration (RM) and clear (RL).
- When the remote function is used, the output frequency of the inverter can be compensated for as follows:  
External operation ...Frequency set by RH/RM operation + external running frequency or PU running frequency (other than multi-speed).  
(When making analog input compensation, set "1" to Pr. 28 Multi-speed input compensation selection.)  
When Pr. 28 is set to "0" and acceleration/deceleration is made to reach the set frequency of the analog voltage input (terminal 2 or terminal 4) by RH/RM, the auxiliary input by terminal 1 becomes invalid.)

PU operation .....Frequency set by RH/RM operation + PU running frequency

#### (2) Frequency setting storage

- The frequency setting storage function stores the remote setting frequency (frequency set by RH/RM operation) into the memory (EEPROM). When power is switched off once, then on, operation is resumed with that output frequency value. (Pr. 59 = 1)

##### <Frequency setting storage conditions>

- Frequency at the point when the start signal (STF or STR) turns off
- The remotely-set frequency is stored every one minute after one minute has elapsed since turn off (on) of both the RH (acceleration) and RM (deceleration) signals. (The frequency is written if the present frequency setting compared with the past frequency setting every one minute is different. The state of the RL signal does not affect writing.)

### CAUTION

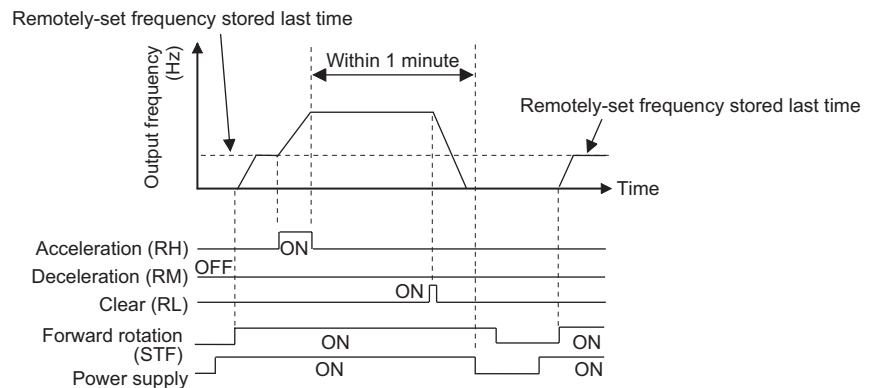
- The range where the frequency can be varied by RH (acceleration) or RM (deceleration) is 0 to the maximum frequency (*Pr. 1* or *Pr. 18* setting).
- When the acceleration or deceleration signal switches on, acceleration/deceleration time is as set in *Pr. 44* and *Pr. 45*. Note that when long time has been set in *Pr. 7* or *Pr. 8*, the acceleration/deceleration time is as set in *Pr. 7* or *Pr. 8*. (when RT signal is off)  
When the RT signal is on, acceleration/deceleration is made in the time set to *Pr. 44* and *Pr. 45*, regardless of the *Pr. 7* or *Pr. 8* setting.
- Even if the start signal (STF or STR) is off, turning on the acceleration (RH) or deceleration (RM) signal varies the preset frequency.
- When switching the start signal from ON to OFF, or changing frequency by the RH or RM signal frequently, set the frequency setting value storage function (write to EEPROM) invalid (*Pr. 59* = "2, 3"). If set valid (*Pr. 59* = "1"), frequency is written to EEPROM frequently, this will shorten the life of the EEPROM.
- The RH, RM, RL signals can be assigned to the input terminal using any *Pr. 178* to *Pr. 189* (input terminal function selection). When terminal assignment is changed, the other functions may be affected. Please make setting after confirming the function of each terminal.
- Also available for the network operation mode.

### REMARKS

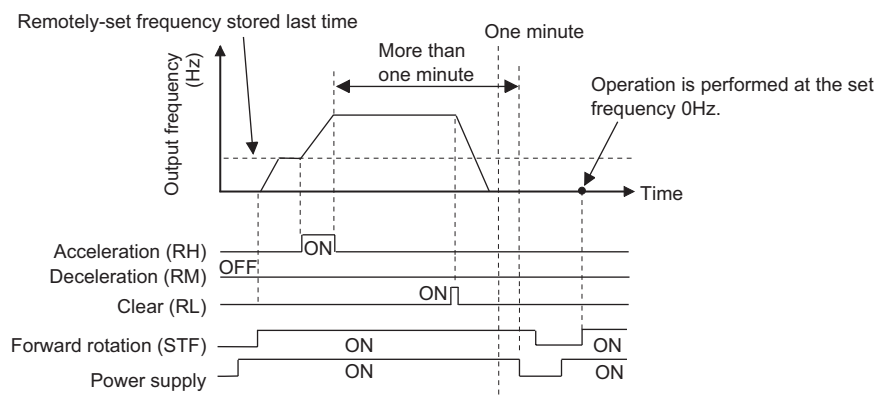
During jog operation or PID control operation, the remote setting function is invalid.

#### Setting frequency is "0"

- Even when the remotely-set frequency is cleared by turning on the RL (clear) signal after turn off (on) of both the RH and RM signals, the inverter operates at the remotely-set frequency stored in the last operation if power is reapplied before one minute has elapsed since turn off (on) of both the RH and RM signals.



- When the remotely-set frequency is cleared by turning on the RL (clear) signal after turn off (on) of both the RH and RM signals, the inverter operates at the frequency in the remotely-set frequency cleared state if power is reapplied after one minute has elapsed since turn off (on) of both the RH and RM signals.



## CAUTION

⚠ When selecting this function, re-set the maximum frequency according to the machine.

#### ◆ Parameters referred to ◆

*Pr. 1* Maximum frequency, *Pr. 18* High speed maximum frequency Refer to page 67

*Pr. 7* Acceleration time, *Pr. 8* Deceleration time, *Pr. 44* Second acceleration/deceleration time, *Pr. 45* Second deceleration time. Refer to page 79

*Pr. 28* Multi-speed input compensation selection Refer to page 76

*Pr. 178* to *Pr. 189* (input terminal function selection) Refer to page 90

## 3.6 Setting of acceleration/deceleration time and acceleration/deceleration pattern

| Purpose                                                        | Parameter that must be set                               |                                        | Refer to page |
|----------------------------------------------------------------|----------------------------------------------------------|----------------------------------------|---------------|
| Motor acceleration/deceleration time setting                   | Acceleration/deceleration times                          | Pr.7, Pr.8, Pr.20, Pr.21, Pr.44, Pr.45 | 79            |
| Starting frequency                                             | Starting frequency and start-time hold                   | Pr.13, Pr.571                          | 81            |
| Set acceleration/deceleration pattern suitable for application | Acceleration/deceleration pattern and back lash measures | Pr.29, Pr.140 to Pr.143                | 82            |

### 3.6.1 Setting of the acceleration and deceleration time (Pr.7, Pr.8, Pr.20, Pr.21, Pr.44, Pr.45)

Used to set motor acceleration/deceleration time.

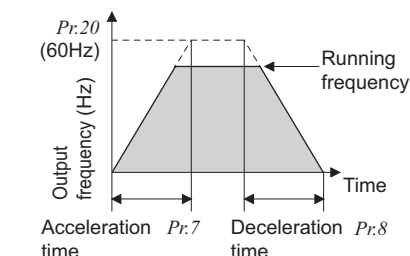
Set a larger value for a slower speed increase/decrease or a smaller value for a faster speed increase/decrease.

For the acceleration time at automatic restart after instantaneous power failure, refer to *Pr. 611 Acceleration time at a restart (page 114)*.

| Parameter Number | Name                                                 | Initial Value<br>200V class (400V class) |     | Setting Range      | Description                                                                                                                                                                  |
|------------------|------------------------------------------------------|------------------------------------------|-----|--------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 7                | Acceleration time                                    | 00340 (00170)<br>or less                 | 5s  | 0 to 3600/ 360s *2 | Set the motor acceleration time.                                                                                                                                             |
|                  |                                                      | 00490 (00250)<br>or more                 | 15s |                    |                                                                                                                                                                              |
| 8                | Deceleration time                                    | 00340 (00170)<br>or less                 | 10s | 0 to 3600/ 360s *2 | Set the motor deceleration time.                                                                                                                                             |
|                  |                                                      | 00490 (00250)<br>or more                 | 30s |                    |                                                                                                                                                                              |
| 20 *1            | Acceleration/<br>deceleration<br>reference frequency | 60Hz                                     |     | 1 to 400Hz         | Set the frequency that will be the basis of acceleration/deceleration time.<br>As acceleration/deceleration time, set the frequency change time from stop to <i>Pr. 20</i> . |
| 21 *1            | Acceleration/<br>deceleration time<br>increments     | 0                                        |     | 0                  | Increments: 0.1s<br>Range: 0 to 3600s                                                                                                                                        |
|                  |                                                      |                                          |     | 1                  | Increments: 0.01s<br>Range: 0 to 360s                                                                                                                                        |
| 44 *1            | Second<br>acceleration/<br>deceleration time         | 5s                                       |     | 0 to 3600/360s *2  | Set the acceleration/deceleration time when the RT signal is on.                                                                                                             |
| 45 *1            | Second<br>deceleration time                          | 9999                                     |     | 0 to 3600/360s *2  | Set the deceleration time when the RT signal is on.                                                                                                                          |
|                  |                                                      |                                          |     | 9999               | Acceleration time = deceleration time                                                                                                                                        |

\*1 The parameters can be set when *Pr. 160 User group read selection* = "0" (Refer to page 145)

\*2 Depends on the *Pr. 21 Acceleration/deceleration time increments* setting. The initial value for the setting range is "0 to 3600s" and the setting increments is "0.1s".



#### (1) Acceleration time setting (Pr.7, Pr.20)

- Use *Pr. 7 Acceleration time* to set the acceleration time required to reach *Pr. 20 Acceleration/deceleration reference frequency* from 0Hz.
- Set the acceleration time according to the following formula.

$$\text{Acceleration time setting} = \frac{\text{Pr.20}}{\text{Maximum operating frequency} - \text{Pr. 13}} \times \text{Acceleration time from stop to maximum operating frequency}$$

Example) When *Pr. 20* = 60Hz (initial value), *Pr. 13* = 0.5Hz, and acceleration can be made up to the maximum operating frequency of 50Hz in 10s

$$\text{Pr. 7} = \frac{60\text{Hz}}{50\text{Hz} - 0.5\text{Hz}} \times 10\text{s} \doteq 12.1\text{s}$$

Pr.6  
page 72

Pr. 9  
page 83

Pr.19  
page 69

Pr.22  
page 61

Pr.43  
page 100

Pr.46  
page 58



## (2) Deceleration time setting (Pr.8, Pr.20)

- Use Pr. 8 Deceleration time to set the deceleration time required to reach 0Hz from Pr. 20 Acceleration/deceleration reference frequency.
- Set the deceleration time according to the following formula.

$$\text{Deceleration time setting} = \frac{\text{Pr.20}}{\text{Maximum operating frequency - Pr. 10}} \times \text{Deceleration time from maximum operating frequency to stop.}$$

Example) When Pr. 20 = 120Hz, Pr. 10 = 3Hz, and deceleration can be made up to the maximum operating frequency of 50Hz in 10s

$$\text{Pr.8} = \frac{120\text{Hz}}{50\text{Hz} - 3\text{Hz}} \times 10\text{s} \doteq 25.5\text{s}$$

## (3) Change the setting range and increments of the acceleration/deceleration time (Pr.21)

- Use Pr. 21 to set the acceleration/deceleration time and minimum setting range.  
Setting "0" (initial value).....0 to 3600s (minimum setting increments 0.1s)  
Setting "1" .....0 to 360s (minimum setting increments 0.01s)

### CAUTION

- Changing the Pr. 21 setting changes the acceleration/deceleration setting (Pr. 7, Pr. 8, Pr. 16, Pr. 44, Pr. 45).  
(The Pr. 611 Acceleration time at a restart setting is not affected.)

<Example>

When Pr. 21 = "0", setting "5.0" s in Pr. 7 and "1" in Pr. 21 automatically changes the Pr. 7 setting to "0.5" s.

## (4) Set multiple acceleration/deceleration time (RT signal, Pr.44, Pr.45)

- Pr. 44 and Pr. 45 are valid when the RT signal is on. (When the RT signal is on, the other second functions such as the second torque boost are also selected.) (Refer to page 93)
- When "9999" is set in Pr. 45, the deceleration time becomes equal to the acceleration time (Pr. 44).

### CAUTION

- In S-shaped acceleration/deceleration pattern A (refer to page 82), the set time is the period required to reach the base frequency set in Pr.3 Base frequency.
- Acceleration/deceleration time formula when the set frequency is the base frequency or higher

$$t = \frac{4}{9} \times \frac{T}{(\text{Pr.3})^2} \times f^2 + \frac{5}{9} T$$

T: Acceleration/deceleration time setting value(s)

f : Set frequency(Hz)

- Guideline for acceleration/deceleration time when Pr. 3 Base frequency = 60Hz (0Hz to set frequency)

| Frequency setting (Hz)                 | 60 | 120 | 200 | 400 |
|----------------------------------------|----|-----|-----|-----|
| Acceleration/<br>deceleration time (s) |    |     |     |     |
| 5                                      | 5  | 12  | 27  | 102 |
| 15                                     | 15 | 35  | 82  | 305 |

- The RT signal can be assigned to the input terminal using any of Pr. 178 to Pr. 189 (Input terminal function selection). When terminal assignment is changed, the other functions may be affected. Please make setting after confirming the function of each terminal.

### REMARKS

- The RT signal is assigned to the RT terminal in the default setting. By setting "3" to any of Pr. 178 to Pr. 189 (Input terminal function selection), you can assign the RT signal to the other terminal.
- If the Pr. 20 setting is changed, the Pr. 125 and Pr. 126 (frequency setting signal gain frequency) settings do not change. Set Pr. 125 and Pr. 126 to adjust the gains.
- When the Pr. 7, Pr. 8, Pr. 44 and Pr. 45 settings are 0.03s or less, the acceleration/deceleration time is 0.04s. At that time, set Pr. 20 to "120Hz" or less.
- If the acceleration/deceleration time is set, the actual motor acceleration/deceleration time cannot be made shorter than the shortest acceleration/deceleration time determined by the mechanical system J (inertia moment) and motor torque.

### ◆ Parameters referred to ◆

Pr. 3 Base frequency Refer to page 69

Pr. 29 Acceleration/deceleration pattern selection Refer to page 82

Pr. 125, Pr. 126 (Frequency setting gain frequency) Refer to page 134

Pr. 178 to Pr.189 (Input terminal function selection) Refer to page 90

### 3.6.2 Starting frequency and start-time hold function (Pr.13, Pr.571)

You can set the starting frequency and hold the set starting frequency for a certain period of time. Set these functions when you need the starting torque or want to smooth motor drive at a start.

| Parameter Number | Name                    | Initial Value | Setting Range | Description                                                                                                                      |
|------------------|-------------------------|---------------|---------------|----------------------------------------------------------------------------------------------------------------------------------|
| 13               | Starting frequency      | 0.5Hz         | 0 to 60Hz     | Frequency at start can be set in the range 0 to 60Hz. You can set the starting frequency at which the start signal is turned on. |
| 571              | Holding time at a start | 9999          | 0.0 to 10.0s  | Set the holding time of Pr. 13 Starting frequency.                                                                               |
|                  |                         |               | 9999          | Holding function at a start is invalid                                                                                           |

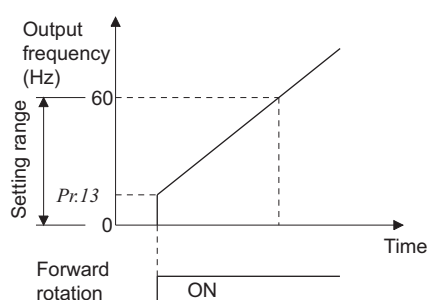
The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

Pr.12  
page 86

Pr.14  
page 65

Pr.570  
page 66

Pr.575  
page 189

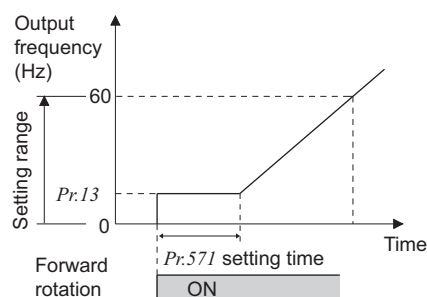


#### (1) Starting frequency setting (Pr.13)

- Frequency at start can be set in the range 0 to 60Hz.
- You can set the starting frequency at which the start signal is turned on.

#### CAUTION

The inverter will not start if the frequency setting signal is less than the value set in Pr. 13. For example, when 5Hz is set in Pr. 13, the motor will not start running until the frequency setting signal reaches 5Hz.



#### (2) Start-time hold function (Pr.571)

- This function holds the time set in Pr. 571 and the output frequency set in Pr. 13 Starting frequency.
- This function performs initial excitation to smooth the motor drive at a start.

#### REMARKS

When Pr. 13 = "0Hz", the starting frequency is held at 0.01Hz.

#### CAUTION

- When the start signal was turned off during start-time hold, deceleration is started at that point.
- At switching between forward rotation and reverse rotation, the starting frequency is valid but the start-time hold function is invalid.

## ⚠ CAUTION

⚠ Note that when Pr. 13 is set to any value lower than Pr. 2 Minimum frequency, simply turning on the start signal will run the motor at the preset frequency even if the command frequency is not input.

#### ◆ Parameters referred to ◆

Pr.2 Minimum frequency Refer to page 67



### 3.6.3 Acceleration/deceleration pattern (Pr.29, Pr.140 to Pr.143)

You can set the acceleration/deceleration pattern suitable for application.

You can also set the backlash measures that stop acceleration/deceleration once at the parameter-set frequency and time during acceleration/deceleration.

Pr.28

page 76

Pr.30

page 88

Pr.139

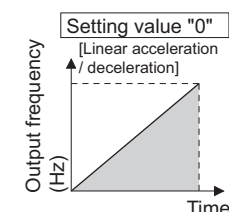
page 197

Pr. 144

page 104

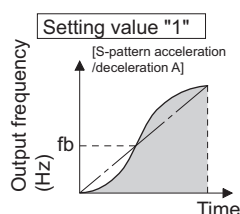
| Parameter Number | Name                                        | Initial Value | Setting Range | Description                                                                         |
|------------------|---------------------------------------------|---------------|---------------|-------------------------------------------------------------------------------------|
| 29               | Acceleration/deceleration pattern selection | 0             | 0             | Linear acceleration/ deceleration                                                   |
|                  |                                             |               | 1             | S-pattern acceleration/deceleration A                                               |
|                  |                                             |               | 2             | S-pattern acceleration/deceleration B                                               |
|                  |                                             |               | 3             | Backlash measures                                                                   |
| 140              | Backlash acceleration stopping frequency    | 1Hz           | 0 to 400Hz    | Set the stopping frequency and time for backlash measures.<br>Valid when Pr. 29 = 3 |
| 141              | Backlash acceleration stopping time         | 0.5s          | 0 to 360s     |                                                                                     |
| 142              | Backlash deceleration stopping frequency    | 1Hz           | 0 to 400Hz    |                                                                                     |
| 143              | Backlash deceleration stopping time         | 0.5s          | 0 to 360s     |                                                                                     |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)



#### (1) Linear acceleration/ deceleration (setting value "0", initial value)

- When the frequency is changed for acceleration, deceleration, etc. in inverter operation, the output frequency is changed linearly (linear acceleration/ deceleration) to reach the set frequency without straining the motor and inverter. Linear acceleration/deceleration has a uniform frequency/time slope.

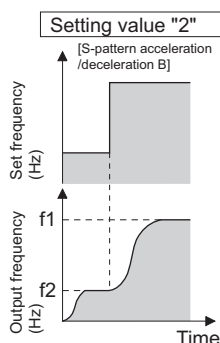


#### (2) S-pattern acceleration/deceleration A (setting value "1")

- For machine tool spindle applications, etc.  
Used when acceleration/deceleration must be made in a short time to a high-speed range of not lower than the 60Hz. In this acceleration/deceleration pattern, Pr. 3 Base frequency (fb) is the inflection point of the S pattern and you can set the acceleration/deceleration time appropriate for motor torque reduction in a constant-output operation region of 60Hz or higher.

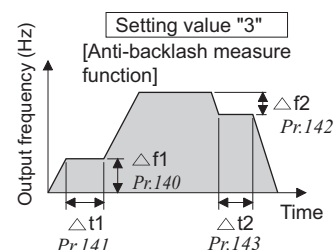
#### CAUTION

- As the acceleration/deceleration time of S-pattern acceleration/deceleration A, set the time taken until Pr. 3 Base frequency is reached, not Pr. 20 Acceleration/deceleration reference frequency.



#### (3) S-pattern acceleration/deceleration B (setting value "2")

- For prevention of load shifting in conveyor and other applications. Since acceleration/deceleration is always made in an S shape from current frequency (f2) to target frequency (f1), this function eases shock produced at acceleration/deceleration and is effective for load collapse prevention, etc.



#### (4) Backlash measures (setting value "3", Pr. 140 to Pr. 143)

- What is backlash?  
Reduction gears have an engagement gap and have a dead zone between forward rotation and reverse rotation. This dead zone is called backlash, and this gap disables a mechanical system from following motor rotation.  
More specifically, a motor shaft develops excessive torque when the direction of rotation changes or when constant-speed operation shifts to deceleration, resulting in a sudden motor current increase or regenerative status.
- To avoid backlash, acceleration/deceleration is temporarily stopped.  
Set the acceleration/deceleration stopping frequency and time in Pr. 140 to Pr. 143.

#### CAUTION

Setting the backlash measures increases the acceleration/deceleration time by the stopping time.

#### ◆ Parameters referred to ◆

Pr. 3 Base frequency Refer to page 69

Pr. 7 Acceleration time, Pr. 8 Deceleration time, Pr. 20 Acceleration/deceleration reference frequency Refer to page 79

## 3.7 Selection and protection of a motor

| Purpose                        | Parameter that must be set   |             | Refer to page |
|--------------------------------|------------------------------|-------------|---------------|
| Motor protection from overheat | Electronic thermal O/L relay | Pr.9, Pr.51 | 83            |
| Use the constant torque motor  | Applied motor                | Pr. 71      | 85            |

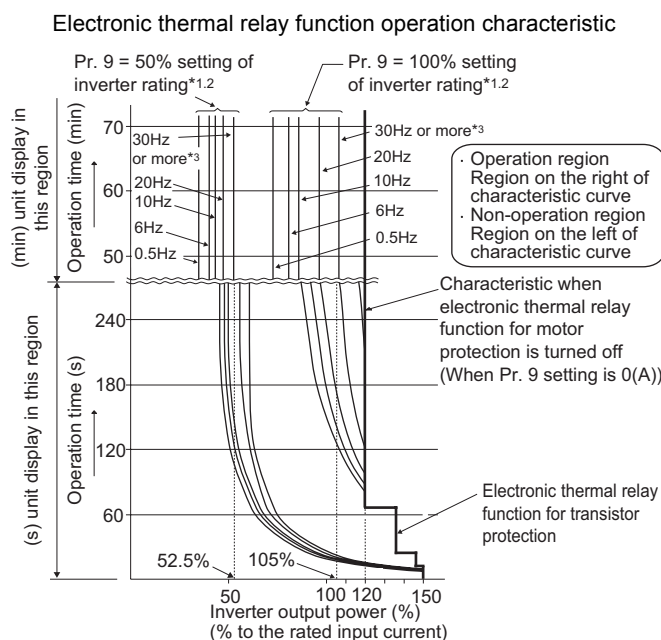
### 3.7.1 Motor protection from overheat (Electronic thermal relay function) (Pr.9)

Set the current of the electronic thermal O/L relay to protect the motor from overheat. This feature provides the optimum protective characteristics, including reduced motor cooling capability, at low speed.

| Parameter Number | Name                                | Initial Value                 | Setting Range<br>200V class (400V class)               | Description                                                                                                         |
|------------------|-------------------------------------|-------------------------------|--------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------|
| 9                | Electronic thermal O/L relay        | Rated inverter output current | 02330 (01160) or less<br>03160 (01800) or more         | Set the rated motor current.                                                                                        |
| 51*              | Second electronic thermal O/L relay | 9999                          | 02330 (01160) or less<br>03160 (01800) or more<br>9999 | Made valid when the RT signal is on.<br>Set the rated motor current.<br>Second electronic thermal O/L relay invalid |

\* The parameters can be set when Pr. 160 User group read selection = "0" (Refer to page 145)

#### (1) Electronic thermal O/L relay (Pr.9)



This function detects the overload (overheat) of the motor, stops the operation of the inverter's output transistor, and stops the output. (The operation characteristic is shown on the left)

- Set the rated current [A] of the motor in Pr.9. (When the power supply specification is 200V/220V(400V/440V) 60Hz, set the 1.1 times the rated motor current.)
- Set "0" in Pr. 9 when you do not want to activate the electronic thermal relay function, e.g. when using an external thermal relay with the motor. (The output transistor protection of the inverter functions (E.THT).)
- When using the Mitsubishi constant-torque motor
  - Set "1" in Pr. 71. (This provides a 100% continuous torque characteristic in the low-speed range.)
  - Set the rated current of the motor in Pr. 9.

- \*1 When a value 50% of the inverter rated output current (current value) is set in Pr. 9
- \*2 The % value denotes the percentage to the inverter rated output current. It is not the percentage to the motor rated current.
- \*3 When you set the electronic thermal relay function dedicated to the Mitsubishi constant-torque motor, this characteristic curve applies to operation at 6Hz or higher.

#### CAUTION

- Protective function by electronic thermal relay function is reset by inverter power reset and reset signal input. Avoid unnecessary reset and power-off.
- When multiple motors are operated by a single inverter, protection cannot be provided by the electronic thermal relay function. Install an external thermal relay to each motor.
- When the difference between the inverter and motor capacities is large and the setting is small, the protective characteristics of the electronic overcurrent protection will be deteriorated. In this case, use an external thermal relay.
- A special motor cannot be protected by the electronic thermal relay function. Use the external thermal relay.
- The operation time of the transistor protection thermal relay shortens when the Pr. 72 PWM frequency selection Setting increases.

Pr.8  
page 79

Pr.10  
page 86

Pr.50  
page 100

Pr.52  
page 105



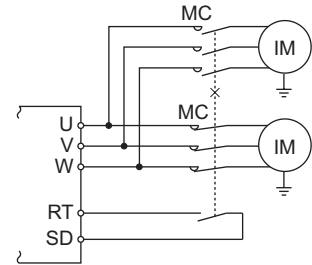
## (2) Set multiple electronic thermal relay functions (Pr.51)

Use this function when rotating two motors of different rated currents individually by a single inverter. (When rotating two motors together, use external thermal relays.)

- Set the rated current of the second motor in Pr. 51.
- When the RT signal is on, thermal protection is provided based on the Pr. 51 setting.

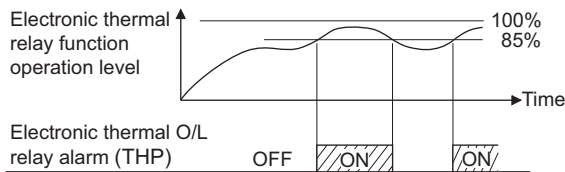
### REMARKS

- The RT signal acts as the second function selection signal and makes the other second functions valid. (Refer to page 92)
- The RT signal is assigned to the RT terminal in the initial setting. By setting "3" in any of Pr. 178 to Pr. 189 (input terminal function selection), you can assign the RT signal to the other terminal.



## (3) Electronic thermal relay function alarm output and alarm signal (THP signal)

100%: Electronic thermal relay function alarm operation value

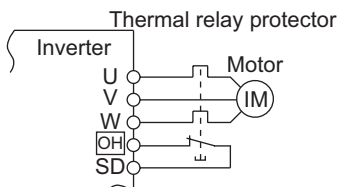


- The alarm signal (THP) is output when the electronic thermal relay function cumulative value reaches 85% of the level set in Pr. 9 or Pr. 51. If it reaches 100% of the Pr. 9 Electronic thermal O/L relay setting, electronic thermal relay function protection (E. THM/E.THT) occurs.
- The inverter does not shut off the output if the alarm signal is output.
- For the terminal used for the THP signal output, assign the function by setting "8" (positive logic) or "108" (negative logic) in any of Pr. 190 to Pr. 196 (output terminal function selection).

### CAUTION

- The signal can be assigned to the input terminal using any of Pr. 190 to Pr. 196 (output terminal function selection). When terminal assignment is changed, the other functions may be affected. Please make setting after confirming the function of each terminal. (Refer to page 96)

## (4) External thermal relay input (OH signal)



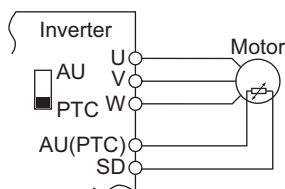
External thermal relay input connection example

- To protect the motor against overheat, use the OH signal when using an external thermal relay or the built-in thermal protector of the motor.
- When the thermal relay operates, the inverter shuts off the output and outputs the alarm signal (E.OHT).
- For the terminal used for OH signal input, assign the function by setting "7" to any of Pr. 178 to Pr. 189 (input terminal function selection)

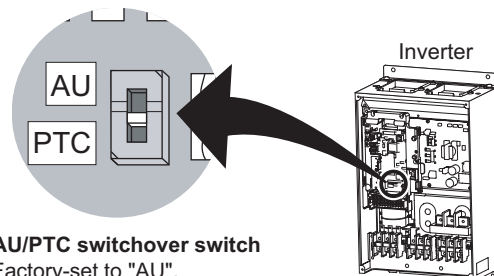
### CAUTION

- The signal can be assigned to the input terminal using any of Pr. 178 to Pr. 189 (input terminal function selection). When terminal assignment is changed, the other functions may be affected. Please make setting after confirming the function of each terminal. (Refer to page 90)

## (5) PTC thermistor input (PTC signal)



PTC thermistor input connection example



**AU/PTC switchover switch**  
Factory-set to "AU".  
Set to the "PTC" position to validate the PTC signal input.

Built-in PTC thermistor of the motor can be input to the PTC signal (AU terminal).

- For the terminal used for PTC signal input, assign the function by setting "63" to Pr. 184 AU terminal function selection and also set the AU/PTC switchover switch to the PTC terminal function. (The initial setting is the AU terminal function.)
- If a motor overheat state is detected for more than 10s according to the input from the PTC thermistor, the inverter shuts off the output and outputs the PTC thermal alarm signal (E.PTC).

- The input specifications of the PTC thermistor are shown on the right.

| Motor Temperature | PTC Thermistor Resistance Value ( $\Omega$ ) |
|-------------------|----------------------------------------------|
| Normal            | 0 to 500                                     |
| Boundary          | 500 to 4k                                    |
| Overheat          | 4k or higher                                 |

## CAUTION

- When the PTC signal was not assigned to *Pr. 184* and the AU/PTC switchover switch was set to the PTC terminal function, the function assigned to the AU terminal is always off. Reversely, when the PTC signal was assigned to *Pr. 184* and the AU/PTC switchover switch was set to the AU terminal function, a PTC thermal error (E.PTC) occurs since the function is always in a motor overheat state.
- When you want to input a current, assign the AU signal to the other signal.
- When terminal assignment is changed, the other functions may be affected. Please make setting after confirming the function of the AU terminal.

### ◆ Parameters referred to ◆

*Pr. 71 Applied motor* Refer to page 85  
*Pr. 72 PWM frequency selection* Refer to page 129  
*Pr.178 to Pr.189 (Input terminal function selection)* Refer to page 90  
*Pr. 190 to Pr. 196 (Output terminal function selection)* Refer to page 96  
*Specifications of the AU terminal* Refer to page 14

## 3.7.2 Applied motor (Pr.71)

Setting of the used motor selects the thermal characteristic appropriate for the motor. Setting is necessary when using a constant-torque motor. Thermal characteristic of the electronic thermal relay function suitable for the motor is set.

**Pr.69**  
 page 119  
**Pr. 72**  
 page 129

| Parameter Number | Name          | Initial Value | Setting Range | Description                                                                                                |
|------------------|---------------|---------------|---------------|------------------------------------------------------------------------------------------------------------|
| 71               | Applied motor | 0             | 0, 1, 2, 20   | Selecting the standard motor or constant-torque motor sets the corresponding motor thermal characteristic. |

The above parameters can be set when *Pr. 160 User group read selection* = "0". (Refer to page 145)

Refer to the following list and set this parameter according to the motor used.

| Pr. 71 Setting    | Thermal Characteristic of the Electronic Thermal Relay Function                           | Motor (O : used motor) |                                 |
|-------------------|-------------------------------------------------------------------------------------------|------------------------|---------------------------------|
|                   |                                                                                           | Standard (SF-JR, etc.) | Constant torque (SF-HRCA, etc.) |
| 0 (initial value) | Thermal characteristics of a standard motor                                               | ○                      |                                 |
| 1                 | Thermal characteristics of the Mitsubishi constant-torque motor                           |                        | ○                               |
| 2                 | Thermal characteristics of a standard motor<br>Adjustable 5 points V/F (Refer to page 71) | ○                      |                                 |
| 20                | Mitsubishi standard motor SF-JR 4P(1.5kW(2HP) or less)                                    | ○                      |                                 |

## REMARKS

- For the FR-F720-00250 and 00490 and the FR-F740-00126 and 00170, the *Pr. 0 Torque boost* and *Pr. 12 DC injection brake operation voltage* settings are automatically changed according to the *Pr. 71* setting as follows.

| Pr. 71 | Standard Motor Setting<br>0, 2, 20 | Constant Torque Motor Setting<br>1 |
|--------|------------------------------------|------------------------------------|
| Pr. 0  | 3%                                 | 2%                                 |
| Pr. 12 | 4%                                 | 2%                                 |

## ⚠ CAUTION

- ⚠ Set this parameter correctly according to the motor used. Incorrect setting may cause the motor to overheat and burn.

### ◆ Parameters referred to ◆

*Pr. 0 Torque boost* Refer to page 58  
*Pr.12 DC injection brake operation voltage* Refer to page 86  
*Pr. 100 to Pr. 109 (Adjustable 5 points V/F)* Refer to page 71



### 3.8 Motor brake and stop operation

| Purpose                                         | Parameter that must be set         |                | Refer to Page |
|-------------------------------------------------|------------------------------------|----------------|---------------|
| Motor braking torque adjustment                 | DC injection brake                 | Pr.10 to Pr.12 | 86            |
| Improve the motor braking torque with an option | Selection of a regenerative brake  | Pr.30          | 88            |
| Coast the motor to a stop                       | Selection of motor stopping method | Pr. 250        | 89            |

#### 3.8.1 DC injection brake (Pr. 10 to Pr. 12)

The DC injection brake can be operated at a motor stop to adjust the stop timing and braking torque.

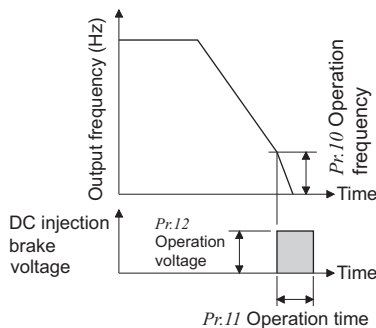
Pr. 9  
page 83

Pr. 13  
page 81

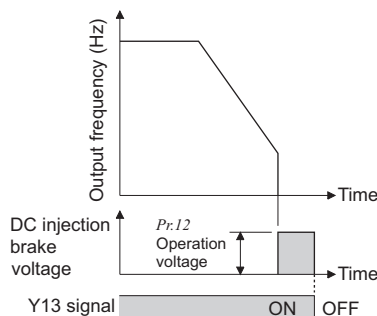
| Parameter Number | Name                                   | Initial Value<br>200V class (400V class) |    | Setting Range | Description                                            |                                              |
|------------------|----------------------------------------|------------------------------------------|----|---------------|--------------------------------------------------------|----------------------------------------------|
| 10               | DC injection brake operation frequency | 3Hz                                      |    | 0 to 120Hz    | Set the operation frequency of the DC injection brake. |                                              |
|                  |                                        |                                          |    | 9999          | Operated at <i>Pr. 13</i> or less.                     |                                              |
| 11               | DC injection brake operation time      | 0.5s                                     |    | 0             | DC injection brake disabled                            |                                              |
|                  |                                        |                                          |    | 0.1 to 10s    | Set the operation time of the DC injection brake.      |                                              |
|                  |                                        |                                          |    | 8888          | Operate when X13 signal is on                          |                                              |
| 12               | DC injection brake operation voltage   | 00340 (00170) or less                    | 4% | 0 to 30%      | 0                                                      | DC injection brake disabled                  |
|                  |                                        | 00490 to 02330 (00250 to 01160)          | 2% |               | 0.1 to 30%                                             | Set the DC injection brake voltage (torque). |
|                  |                                        | 03160 (01800) or more                    | 1% |               |                                                        |                                              |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

When Pr. 11="0.1 to 10s"



When Pr. 11="8888"



#### (1) Operation frequency setting (Pr. 10)

- When the frequency at which the DC injection brake operates is set in Pr. 10, the DC injection brake is operated when this frequency is reached during deceleration.
- At the Pr. 10 setting of "9999", the DC injection brake is operated when deceleration is made to the frequency set in Pr. 13 Starting frequency.

#### (2) Operation time setting (Pr. 11)

- Use Pr. 11 to set the duration period the DC injection brake is applied.
- When Pr. 11 = "0s", the DC injection brake is not operated. (At a stop, the motor coasts.)
- When Pr. 11="8888", the DC injection brake is applied while X13 signal is on.
- For the terminal used for X13 signal input, set "13" in any of Pr. 178 to Pr. 189 to assign the function. (Refer to page 90.)
- When the motor does not stop due to large load moment (J), increasing the setting produces an effect.

**(3) Operation voltage (torque) setting (Pr.12)**

- Use *Pr. 12* to set the percentage to the power supply voltage.
- When *Pr. 12* = "0%", the DC injection brake is not operated. (At a stop, the motor coasts.)
- When using the constant-torque motor (SF-JRCA) and energy saving motor (SF-HR, SF-HRCA), change the *Pr. 12* setting as follows.
  - SF-JRCA: FR-F720-00167 (FR-F740-00083) or less ...4%,  
FR-F720-00250 to 02330 (FR-F740-00126 to 01160)...2%
  - SF-HR, SF-HRCA: FR-F720-00167 (FR-F740-00083) or less...4%,  
FR-F720-00250 and 00340 (FR-F740-00126 and 00170)...3%,  
FR-F720-00490 to 02330 (FR-F740-00250 to 01160)...2% (FR-F740-00620...1.5%)

**REMARKS**

- For the 00126 and 00170, when the *Pr. 12* setting is as below, changing the *Pr. 71 Applied motor* setting changes the *Pr. 12* setting automatically, it is not necessary to change the *Pr. 12* setting.
  - (a) When *Pr. 12* is 4% (initial value)  
The *Pr. 12* setting is automatically changed to 2% if the *Pr. 71* value is changed from the value selecting the standard motor (0, 2) to the value selecting the constant motor (1).
  - (b) When *Pr. 12* is 2%  
The *Pr. 12* setting is automatically changed to 4% if the *Pr. 71* value is changed from the value selecting the constant motor (1) to the value selecting the standard motor (0, 2).

**CAUTION**

As stop holding torque is not produced, install a mechanical brake.

**◆ Parameters referred to ◆**

*Pr. 13 Starting frequency* Refer to page 81

*Pr. 71 Applied motor* Refer to page 85



### 3.8.2 Selection of a regenerative brake (Pr. 30, Pr.70)

- Use the "high power factor converter (FR-HC, MT-HC) to reduce harmonics, improve the power factor, or continuously use the regenerative mode.

Pr. 29  
page 82

Pr. 31  
page 68

Pr. 69  
page 119

Pr. 71  
page 85

| Parameter Number | Name                            | Initial Value | Setting Range | Description                                                                                                                                              |
|------------------|---------------------------------|---------------|---------------|----------------------------------------------------------------------------------------------------------------------------------------------------------|
| 30               | Regenerative function selection | 0             | 0             | Without regenerative function, brake unit (FR-BU, BU type)                                                                                               |
|                  |                                 |               | 1             | Brake unit (MT-BU5), power regeneration converter (MT-RC) (Setting can be made only for the FR-F720-03160 (FR-F740-01800) or more)                       |
|                  |                                 |               | 2             | High power factor converter (FR-HC, MT-HC), power regeneration common converter (FR-CV)                                                                  |
| 70               | Special regenerative brake duty | 0%            | 0 to 10%      | Set the %ED of the brake transistor operation when using a brake unit (MT-BU5). (Setting can be made only for the FR-F720-03160 (FR-F740-01800) or more) |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

#### (1) When the brake unit (BU, FR-BU) is used

- Set "0" (initial value) in Pr. 30. The Pr. 70 setting is made invalid.

#### (2) When using a brake unit (MT-BU5) and power regeneration converter (MT-RC) (FR-F720-03160 (FR-F740-01800) or more)

- Set "1" in Pr. 30.
- Set "10%" in Pr. 70 when using a brake unit (MT-BU5).
- Set "0%" in Pr. 70 when using a power regeneration converter (MT-RC).

#### (3) When using the high power factor converter (FR-HC, MT-HC) or power regeneration common converter (FR-CV)

- Set "2" in Pr. 30. The Pr. 70 setting is made invalid.
- Use any of Pr. 178 to Pr. 189 (Input terminal function assignment) to assign the following signals to the contact input terminals.
  - (a) X10 signal: FR-HC, MT-HC connection, FR-CV connection (inverter operation enable signal)  
To make protective coordination with the FR-HC, MT-HC or FR-CV, use the inverter operation enable signal to shut off the inverter output. Input the RDY signal of the FR-HC, MT-HC (RDYB signal of the FR-CV).
  - (b) X11 signal: FR-HC, MT-HC connection (instantaneous power failure detection signal)  
When the setting has been made to hold the mode at occurrence of an instantaneous power failure for RS-485 communication operation, use this signal to hold the mode. Input the Y1 or Y2 signal (instantaneous power failure detection signal) of the FR-HC, MT-HC.
- For the terminal used for X10 or X11 signal input, assign its function by setting "10" (X10) or "11" (X11) to any of Pr. 178 to Pr. 189.

#### REMARKS

- The MRS signal can also be used instead of the X10 signal. (Refer to page 90.)
- Refer to pages 22 to 26 for the connection of the brake unit, high power factor converter (FR-HC, MT-HC) and power regeneration common converter (FR-CV).

#### CAUTION

- Changing the terminal assignment using Pr. 178 to Pr. 189 (input terminal function selection) may affect the other functions. Please make setting after confirming the function of each terminal.

#### ◆ Parameters referred to ◆

Pr. 178 to Pr.189 (input terminal function selection)  Refer to page 90

### 3.8.3 Stop selection (Pr.250)

Used to select the stopping method (deceleration to a stop or coasting) when the start signal turns off. Used to stop the motor with a mechanical brake, etc. together with switching off of the start signal.

You can also select the operations of the start signals (STF/STR). (Refer to page 94 for start signal selection)

Pr.247

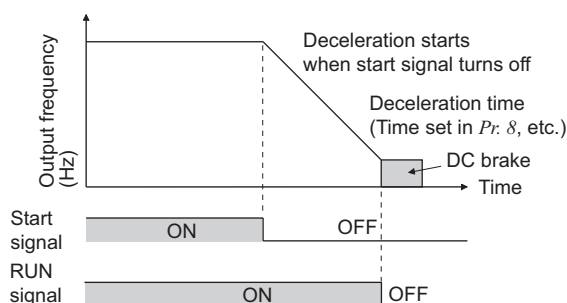
page 60

Pr. 251

page 122

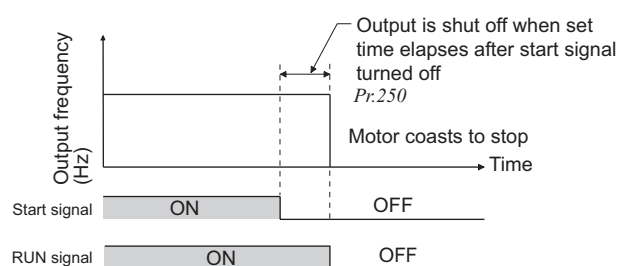
| Parameter Number | Name           | Initial Value | Setting Range  | Description                                                              |                                                                                                       |
|------------------|----------------|---------------|----------------|--------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------|
|                  |                |               |                | Start Signal (STF/STR)<br>(Refer to page 94)                             | Stop Operation                                                                                        |
| 250              | Stop selection | 9999          | 0 to 100s      | STF signal: Forward rotation start<br>STR signal: Reverse rotation start | The motor is coasted to a stop when the preset time elapses after the start signal is turned off. The |
|                  |                |               | 1000s to 1100s | STF signal: Start signal<br>STR signal: Forward/reverse signal           | motor is coasted to a stop (Pr. 250 - 1000)s after the start signal is turned off.                    |
|                  |                |               | 9999           | STF signal: Forward rotation start<br>STR signal: Reverse rotation start | When the start signal is turned off, the motor decelerates to stop.                                   |
|                  |                |               | 8888           | STF signal: Start signal<br>STR signal: Forward/reverse signal           |                                                                                                       |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)



#### (1) Decelerate the motor to a stop

- Set Pr. 250 to "9999" (initial value) or "8888".
- The motor decelerates to a stop when the start signal (STF/STR) turns off.



#### (2) Coast the motor to a stop.

- Use Pr. 250 to set the time from when the start signal turns off until the output is shut off. When any of "1000" to "1100" is set, the output is shut off after (Pr. 250 - 1000)s.
- The output is shut off when the time set in Pr. 250 has elapsed after the start signal had turned off. The motor coasts to a stop.
- The RUN signal turns off when the output stops.

#### CAUTION

- When the start signal is turned on again during motor coasting, the motor starts at Pr. 13 Starting frequency.

#### ◆ Parameters referred to ◆

Pr. 7 Acceleration time, Pr. 8 Deceleration time Refer to page 79



### 3.9 Function assignment of external terminal and control

| Purpose                                                                             | Parameter that must be set                                |                                  | Refer to Page |
|-------------------------------------------------------------------------------------|-----------------------------------------------------------|----------------------------------|---------------|
| Assign function to input terminal                                                   | Input terminal function selection                         | Pr.178 to Pr.189                 | 90            |
| Set MRS signal (output shutoff) to normally closed contact specification            | MRS input selection                                       | Pr.17                            | 92            |
| Make RT signal (second function selection) invalid during acceleration/deceleration | RT refection time selection                               | Pr.155                           | 93            |
| Assign start signal and forward/reverse command to other signals                    | Start signal (STF/STR) operation selection                | Pr.250                           | 94            |
| Assign function to output terminal                                                  | Output terminal function assignment                       | Pr.190 to Pr.196                 | 96            |
| Detect output frequency.                                                            | Up-to-frequency sensitivity<br>Output frequency detection | Pr.41 to Pr.43, Pr.50            | 100           |
| Detect output current.                                                              | Output current detection<br>Zero current detection        | Pr.150 to Pr.153, Pr.166, Pr.167 | 101           |
| Remote output function                                                              | Remote output                                             | Pr.495 to Pr.497                 | 103           |

#### 3.9.1 Input terminal function selection (Pr.178 to Pr.189)

Use these parameters to select/change the input terminal functions.

Pr.174  
page 145

Pr.190  
page 96

| Parameters No. | Name                             | Initial Value | Initial Signal                                                        | Setting Range                                            |
|----------------|----------------------------------|---------------|-----------------------------------------------------------------------|----------------------------------------------------------|
| 178            | STF terminal function selection  | 60            | STF (forward rotation command)                                        | 0 to 8, 10 to 12, 14, 16, 24, 25, 60, 62, 64 to 67, 9999 |
| 179            | STR terminal function selection  | 61            | STR (reverse rotation command)                                        | 0 to 8, 10 to 12, 14, 16, 24, 25, 61, 62, 64 to 67, 9999 |
| 180            | RL terminal function selection   | 0             | RL (low-speed operation command)                                      | 0 to 8, 10 to 14, 16, 24, 25, 62, 64 to 67, 9999         |
| 181            | RM terminal function selection   | 1             | RM (middle-speed operation command)                                   |                                                          |
| 182            | RH terminal function selection   | 2             | RH (high speed operation command)                                     |                                                          |
| 183            | RT terminal function selection   | 3             | RT (second function selection)                                        |                                                          |
| 184            | AU terminal function selection   | 4             | AU (terminal 4 input selection)                                       | 0 to 8, 10 to 14, 16, 24, 25, 62 to 67, 9999             |
| 185            | JOG terminal function selection  | 5             | JOG (Jog operation selection)                                         | 0 to 8, 10 to 14, 16, 24, 25, 62, 64 to 67, 9999         |
| 186            | CS terminal function selection   | 6             | CS (selection of automatic restart after instantaneous power failure) |                                                          |
| 187            | MRS terminal function selection  | 24            | MRS (output stop)                                                     |                                                          |
| 188            | STOP terminal function selection | 25            | STOP (start self-holding selection)                                   |                                                          |
| 189            | RES terminal function selection  | 62            | RES (inverter reset)                                                  |                                                          |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

#### (1) Input terminal function assignment

- Use Pr. 178 to Pr. 189 to set the functions of the input terminals.
- Refer to the following table and set the parameters:

| Setting | Signal Name | Function                  |                                | Related Parameters                                   | Refer to Page |
|---------|-------------|---------------------------|--------------------------------|------------------------------------------------------|---------------|
| 0       | RL          | Pr.59 = 0 (initial value) | Low-speed operation command    | Pr. 4 to Pr. 6, Pr. 24 to Pr. 27, Pr. 232 to Pr. 239 | 72            |
|         |             | Pr.59 = 1, 2, 4           | Remote setting (setting clear) | Pr. 59                                               | 77            |
| 1       | RM          | Pr.59 = 0 (initial value) | Middle-speed operation command | Pr. 4 to Pr. 6, Pr. 24 to Pr. 27, Pr. 232 to Pr. 239 | 72            |
|         |             | Pr.59 = 1, 2, 4           | Remote setting (deceleration)  | Pr. 59                                               | 77            |

| Setting | Signal Name | Function                                                                       |                               | Related Parameters                                   | Refer to Page           |
|---------|-------------|--------------------------------------------------------------------------------|-------------------------------|------------------------------------------------------|-------------------------|
| 2       | RH          | Pr.59 = 0 (initial value)                                                      | High-speed operation command  | Pr. 4 to Pr. 6, Pr. 24 to Pr. 27, Pr. 232 to Pr. 239 | 72                      |
|         |             | Pr.59 = 1, 2 *1                                                                | Remote setting (acceleration) | Pr. 59                                               | 77                      |
| 3       | RT          | Second function selection                                                      |                               | Pr.44 to Pr.51                                       | 58, 61, 69, 79, 83, 100 |
| 4       | AU          | Terminal 4 input selection                                                     |                               | Pr.267                                               | 130                     |
| 5       | JOG         | Jog operation selection                                                        |                               | Pr. 15, Pr. 16                                       | 74                      |
| 6       | CS          | Selection of automatic restart after instantaneous power failure, flying start |                               | Pr.57, Pr.58, Pr.162 to Pr.165, Pr.611               | 114                     |
| 7       | OH          | External thermal relay input *2                                                |                               | Pr. 9                                                | 83                      |
| 8       | REX         | 15 speed selection (combination with three speeds RL, RM, RH)                  |                               | Pr. 4 to Pr. 6, Pr. 24 to Pr. 27, Pr.232 to Pr.239   | 72                      |
| 10      | X10         | Inverter operation enable signal (FR-HC, MT-HC, FR-CV connection)              |                               | Pr.30                                                | 88                      |
| 11      | X11         | FR-HC or MT-HC connection, instantaneous power failure detection               |                               | Pr.30                                                | 88                      |
| 12      | X12         | PU operation external interlock                                                |                               | Pr. 79                                               | 147                     |
| 13      | X13         | External DC injection brake operation start                                    |                               | Pr.11, Pr.12                                         | 86                      |
| 14      | X14         | PID control valid terminal                                                     |                               | Pr.127 to Pr.134, Pr.575 to Pr.577                   | 189                     |
| 16      | X16         | PU-external operation switchover                                               |                               | Pr.79, Pr.340                                        | 153                     |
| 24      | MRS         | Output stop                                                                    |                               | Pr. 17                                               | 92                      |
| 25      | STOP        | Start self-holding selection                                                   |                               | —                                                    | 94                      |
| 60      | STF         | Forward rotation command (assigned to STF terminal (Pr. 178) only)             |                               | —                                                    | 94                      |
| 61      | STR         | Reverse rotation command (assigned to STR terminal (Pr. 179) only)             |                               | —                                                    | 94                      |
| 62      | RES         | Inverter reset                                                                 |                               | —                                                    | —                       |
| 63      | PTC         | PTC thermistor input (assigned to AU terminal (Pr. 184) only)                  |                               | Pr. 9                                                | 83                      |
| 64      | X64         | PID forward/reverse action switchover                                          |                               | Pr.127 to Pr.134, Pr.5                               | 189                     |
| 65      | X65         | PU-NET operation switchover                                                    |                               | Pr.79, Pr.340                                        | 155                     |
| 66      | X66         | External-NET operation switchover                                              |                               | Pr.79, Pr.340                                        | 155                     |
| 67      | X67         | Command source switchover                                                      |                               | Pr.338, Pr.339                                       | 156                     |
| 9999    | —           | No function                                                                    |                               | —                                                    | —                       |

\*1 When Pr. 59 Remote function selection = "1 or 2", the functions of the RL, RM and RH signals change as listed above.

\*2 The OH signal turns on when the relay contact "opens".

### CAUTION

- Changing the terminal assignment using Pr. 178 to Pr. 189 (input terminal function selection) may affect the other functions. Please make setting after confirming the function of each terminal.
- One function can be assigned to two or more terminals. In this case, the terminal inputs are ORed.
- The priorities of the speed commands are in order of jog, multi-speed setting (RH, RM, RL, REX) and PID (X14).
- When the X10 signal (FR-HC, MT-HC, FR-CV connection - inverter operation enable signal) is not set or when the PU operation external interlock (X12) signal is not assigned at the Pr. 79 Operation mode selection setting of "7", the MRS signal shares this function.
- Use common terminals to assign multi-speeds (speed 7) and remote setting. They cannot be set individually. (Common terminals are used since these functions are designed for speed setting and need not be set at the same time.)

## (2) Response time of each signal

- The response time of the X10 signal is within 2ms. However, when the X10 signal is not assigned at the Pr. 30 Regenerative function selection setting of "2" (FR-HC/MT-HC/FR-CV connection), the response time of the MRS signal is within 2ms.
- Pr. 17 MRS input selection is made invalid.

| Pr.30 Setting | MRS Assignment | X10 Assignment | Response Time |            | Pr. 17  |
|---------------|----------------|----------------|---------------|------------|---------|
|               |                |                | MRS           | X10        |         |
| 2             | ○              | ×              | Within 2ms    | —          | Invalid |
|               | ×              | ○              | —             | Within 2ms | —       |
|               | ○              | ○              | Within 20ms   | Within 2ms | Valid   |
| Other than 2  | ○              | ×              | Within 20ms   | —          | Valid   |
|               | ×              | ○              | —             | —          | —       |
|               | ○              | ○              | Within 20ms   | —          | Valid   |



### 3.9.2 Inverter output shutoff signal (MRS signal, Pr. 17)

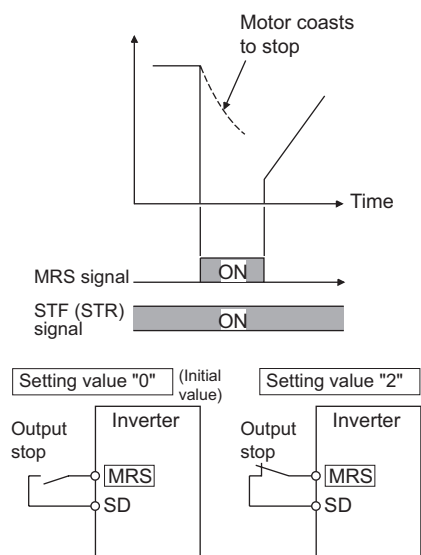
The inverter output can be shut off from the MRS signal. The logic of the MRS signal can also be selected.

Pr.16  
page 74

Pr.18  
page 67

| Parameter Number | Name                | Initial Value | Setting Range | Description                                          |
|------------------|---------------------|---------------|---------------|------------------------------------------------------|
| 17               | MRS input selection | 0             | 0             | Open input always                                    |
|                  |                     |               | 2             | Close input always (NC contact input specifications) |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)



#### (1) Output shutoff signal (terminal MRS)

- Turning on the output shutoff signal (MRS) during inverter running shuts off the output immediately.
- Terminal MRS may be used as described below.
  - When mechanical brake (e.g. electromagnetic brake) is used to stop motor  
The inverter output is shut off when the mechanical brake operates.
  - To provide interlock to disable operation by the inverter  
With the MRS signal on, the inverter cannot be operated if the start signal is entered into the inverter.
  - Coast the motor to a stop.  
When the start signal is turned off, the inverter decelerates the motor to a stop in the preset deceleration time, but when the MRS signal is turned on, the motor coasts to a stop.

#### (2) MRS signal logic inversion (Pr.17)

- When Pr. 17 is set to "2", the MRS signal (output stop) can be changed to the normally closed (NC contact) input specification. When the MRS signal turns on (opens), the inverter shuts off the output.

#### REMARKS

- The MRS signal is assigned to the terminal MRS in the initial setting. By setting "24" in any of Pr. 178 to Pr. 189 (input terminal function selection), the RT signal can be assigned to the other terminal.
- The MRS signal can shut off the output, independently of the PU, external or network operation mode.

#### CAUTION

- Changing the terminal assignment using Pr. 178 to Pr. 189 (input terminal function selection) may affect the other functions. Please make setting after confirming the function of each terminal.

#### ◆ Parameters referred to ◆

Pr. 178 to Pr.189 (Input terminal function selection) Refer to page 90

### 3.9.3 Second function RT signal reflection time selection (Terminal RT, Pr. 155)

You can select the second function using the external terminal (RT signal).  
You can also set the RT signal operation condition (reflection time).

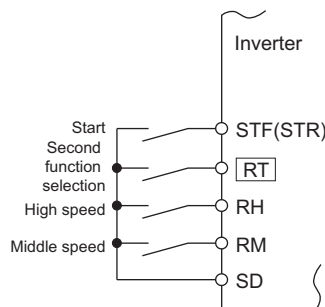
Pr.154  
page 61  
Pr.156  
page 61

| Parameter Number | Name                                | Initial Value | Setting Range | Description                                                                                                                      |
|------------------|-------------------------------------|---------------|---------------|----------------------------------------------------------------------------------------------------------------------------------|
| 155              | RT signal reflection time selection | 0             | 0             | This function is immediately made valid with on/off of the RT signal.                                                            |
|                  |                                     |               | 10            | The on/off of the RT signal is valid only during a stop and constant speed operation.(invalid during acceleration/ deceleration) |

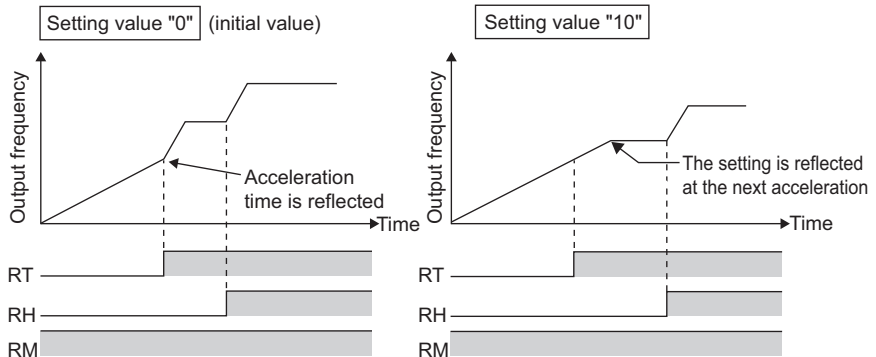
The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

- When the RT signal turns on, the second function becomes valid.
- The second function has the following applications.
  - (a)Switching between normal use and emergency use
  - (b)Switching between heavy load and light load
  - (c)Changing of acceleration/deceleration time by broken line acceleration/deceleration
  - (d)Switching of characteristic between main motor and sub motor

#### Second function connection diagram



#### Second acceleration/deceleration time example



- Functions that can be set as second functions

| Function                          | First Function Parameter Number | Second Function Parameter Number | Refer to Page |
|-----------------------------------|---------------------------------|----------------------------------|---------------|
| Torque boost                      | Pr.0                            | Pr.46                            | 58            |
| Base Frequency                    | Pr.3                            | Pr.47                            | 69            |
| Acceleration time                 | Pr.7                            | Pr.44                            | 79            |
| Deceleration time                 | Pr.8                            | Pr.44, Pr.45                     | 79            |
| Electronic thermal relay function | Pr. 9                           | Pr.51                            | 83            |
| Stall prevention                  | Pr.22                           | Pr.48, Pr.49                     | 61            |

#### REMARKS

- The RT signal is assigned to the RT terminal in the initial setting. By setting "3" to any of Pr. 178 to Pr. 189 (input terminal function selection), the RT signal can be assigned to the other terminal.

#### CAUTION

- When the RT signal is on, the other functions such as the second acceleration/deceleration time are also selected.
- Changing the terminal assignment using Pr. 178 to Pr. 189 (input terminal function selection) may affect the other functions. Please make setting after confirming the function of each terminal.

#### ◆ Parameters referred to ◆

Pr.0, Pr.46 Torque boost Refer to page 58  
 Pr. 3, Pr. 47 Base frequency Refer to page 69  
 Pr. 7, Pr. 8, Pr. 44, Pr. 45 Acceleration and deceleration times Refer to page 79  
 Pr. 9, Pr. 51 Electronic thermal O/L relay Refer to page 83  
 Pr. 22, Pr. 48 Stall prevention operation level Refer to page 61  
 Pr. 178 to Pr.189 (input terminal function selection) Refer to page 90



### 3.9.4 Start signal selection (Terminal STF, STR, STOP, Pr. 250)

Pr.247  
page 60  
Pr. 251  
page 122

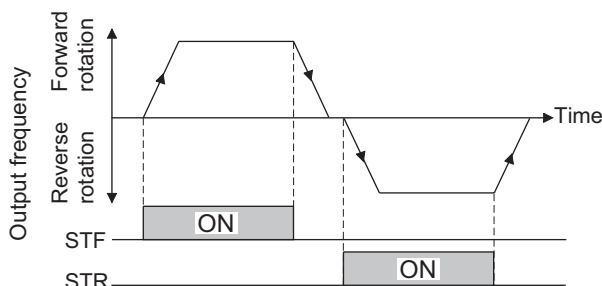
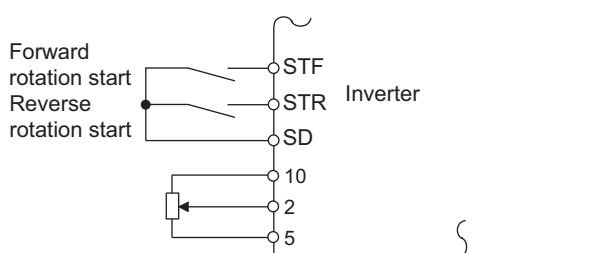
You can select the operation of the start signal (STF/STR).  
Used to select the stopping method (deceleration to a stop or coasting) when the start signal turns off.  
Used to stop the motor with a mechanical brake, etc. together with switching off of the start signal.  
(Refer to page 89 for stop selection)

| Parameter Number | Name           | Initial Value | Setting Range  | Description                                                              |                                                                                                                                                                                                  |
|------------------|----------------|---------------|----------------|--------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
|                  |                |               |                | Start Signal (STF/STR)                                                   | Stop Operation                                                                                                                                                                                   |
| 250              | Stop selection | 9999          | 0 to 100s      | STF signal: Forward rotation start<br>STR signal: Reverse rotation start | The motor is coasted to a stop when the preset time elapses after the start signal is turned off. When the setting is any of 1000s to 1100s, the inverter coasts to a stop in (Pr. 250 - 1000)s. |
|                  |                |               | 1000s to 1100s | STF signal: Start signal<br>STR signal: Forward/reverse rotation signal  |                                                                                                                                                                                                  |
|                  |                |               | 9999           | STF signal: Forward rotation start<br>STR signal: Reverse rotation start | When the start signal is turned off, the motor decelerates to stop.                                                                                                                              |
|                  |                |               | 8888           | STF signal: Start signal<br>STR signal: Forward/reverse rotation signal  |                                                                                                                                                                                                  |

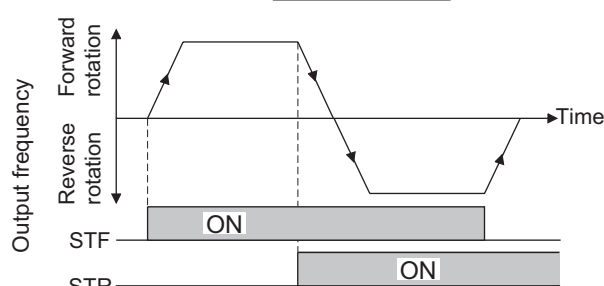
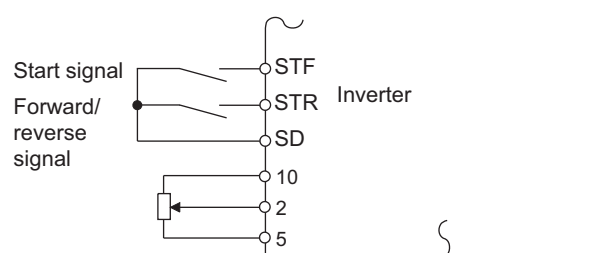
The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

#### (1) 2-wire type (terminal STF, STR)

- A two-wire type connection is shown below.
- In the initial setting, the forward/reverse rotation signals (STF/STR) are used as start and stop signals. Turn on either of the forward and reverse rotation signals to start the motor in the corresponding direction. If both are turned off (or on) during operation, the inverter decelerates to a stop.
- The speed setting signal may either be given by entering 0 to 10VDC across the speed setting input terminal 2-5, by setting the required values in Pr. 4 to Pr. 6 Multi-speed setting (high, middle, low speeds), etc. (For multi-speed operation, refer to page 72)
- When Pr. 250 is set to any of "1000 to 1100, 8888", the STF signal becomes a start command and the STR signal a forward/reverse command.



2-wire connection example (Pr. 250 = "9999")



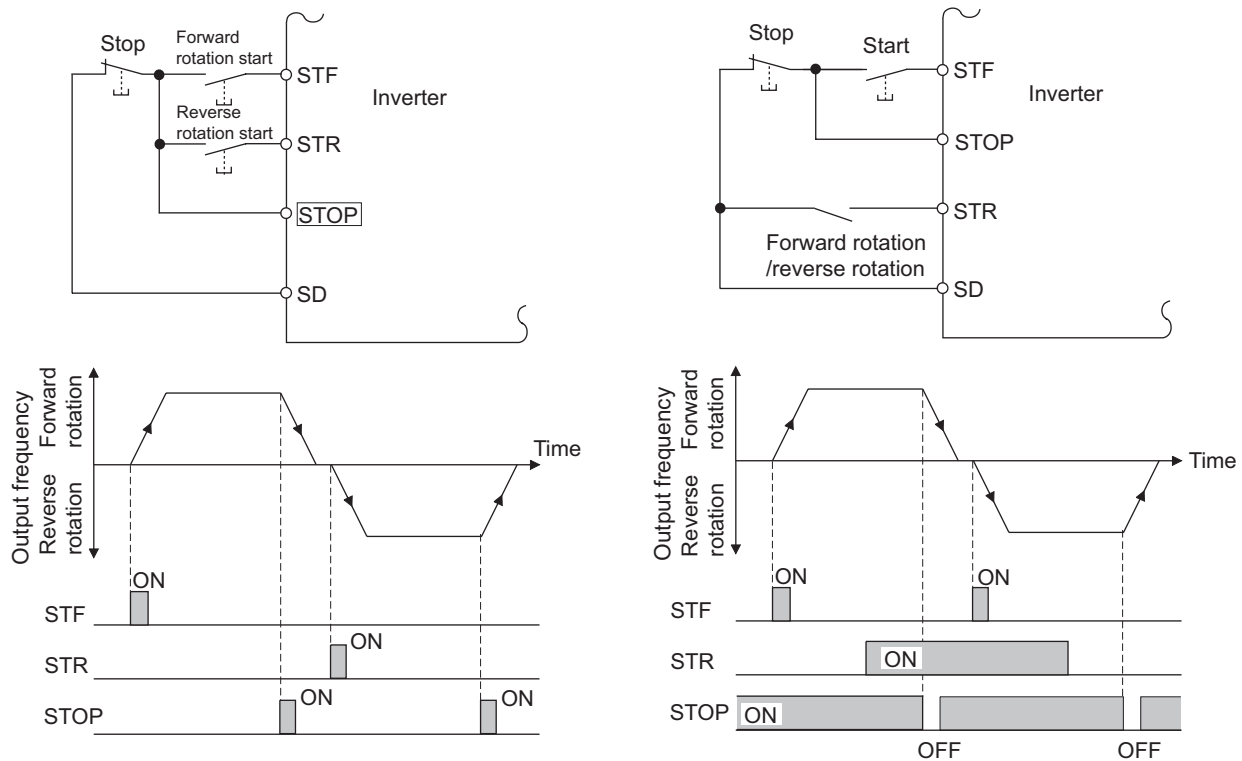
2-wire connection example (Pr. 250 = "8888")

#### REMARKS

- When Pr. 250 is set to any of "0 to 100, 1000 to 1100", the motor coasts to a stop if the start command is turned off. (Refer to page 89)
- The STF and STR signals are assigned to the STF and STR terminals in the initial setting. The STF signal can be assigned to Pr. 178 STF terminal function selection and the STR signal to Pr. 179 STR terminal function selection only.

## (2) 3-wire type (terminal STF, STR, STOP)

- A three-wire type connection is shown below.
- The start self-holding selection becomes valid when the STOP signal is turned on. In this case, the forward/reverse rotation signal functions only as a start signal.
- If the start signal (STF or STR) is turned on and then off, the start signal is held and makes a start. When changing the direction of rotation, turn STR (STF) on once and then off.
- To stop the inverter, turning off the STOP signal once decelerates it to a stop.



Three-Wire Type Connection Example (Pr.250 = "9999")

Three-Wire Type Connection Example (Pr.250 = "8888")

### REMARKS

- The STOP signal is assigned to the terminal STOP in the initial setting. By setting "25" in Pr. 178 to Pr. 189, the STOP signal can also be assigned to the other terminal.
- When the JOG signal is turned on to enable jog operation, the STOP signal becomes invalid.
- If the MRS signal is turned on to stop the output, the self-holding function is not canceled.

## (3) Start signal selection

| STF | STR | Pr. 250 Setting Inverter Status |                      |
|-----|-----|---------------------------------|----------------------|
|     |     | 0 to 100s, 9999                 | 1000s to 1100s, 8888 |
| OFF | OFF | Stop                            | Stop                 |
| OFF | ON  | Reverse rotation                |                      |
| ON  | OFF | Forward rotation                | Forward rotation     |
| ON  | ON  | Stop                            | Reverse rotation     |



### 3.9.5 Output terminal function selection (Pr. 190 to Pr. 196)

You can change the functions of the open collector output terminal and relay output terminal.

Pr. 189  
page 90  
Pr. 232  
page 72

| Parameter Number | Name                             |                                | Initial Value | Initial Signal                                  | Setting Range                                                                                                                                                                            |
|------------------|----------------------------------|--------------------------------|---------------|-------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 190              | RUN terminal function selection  | Open collector output terminal | 0             | RUN (inverter running)                          | 0 to 5, 7, 8, 10 to 19, 25, 26, 45 to 47, 64, 70 to 78, 90 to 96, 98, 99, 100 to 105, 107, 108, 110 to 116, 125, 126, 145 to 147, 164, 170, 190 to 196, 198, 199, 9999                   |
| 191              | SU terminal function selection   |                                | 1             | SU (up to frequency)                            |                                                                                                                                                                                          |
| 192              | IPF terminal function selection  |                                | 2             | IPF (instantaneous power failure, undervoltage) |                                                                                                                                                                                          |
| 193              | OL terminal function selection   |                                | 3             | OL (overload alarm)                             |                                                                                                                                                                                          |
| 194              | FU terminal function selection   |                                | 4             | FU (output frequency detection)                 |                                                                                                                                                                                          |
| 195              | ABC1 terminal function selection | Relay output terminal          | 99            | ALM (alarm output)                              | 0 to 5, 7, 8, 10 to 19, 25, 26, 45 to 47, 64, 70 to 78, 90, 91, 94 to 96, 98, 99, 100 to 105, 107, 108, 110 to 116, 125, 126, 145 to 147, 164, 170, 190, 191, 194 to 196, 198, 199, 9999 |
| 196              | ABC2 terminal function selection |                                | 9999          | No function                                     |                                                                                                                                                                                          |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

#### (1) Output signal list

- You can set the functions of the output terminals.
- Refer to the following table and set the parameters: (0 to 99: Positive logic, 100 to 199: Negative logic)

| Setting        |                | Signal Name | Function                                   | Operation                                                                                                                                                                            | Related Parameters                                | Refer to Page |
|----------------|----------------|-------------|--------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------|---------------|
| Positive Logic | Negative Logic |             |                                            |                                                                                                                                                                                      |                                                   |               |
| 0              | 100            | RUN         | Inverter running                           | Output during operation when the inverter output frequency rises to or above Pr. 13 Starting frequency.                                                                              | —                                                 | 98            |
| 1              | 101            | SU          | Up to frequency *1, 2                      | Output when the output frequency is reached to the set frequency.                                                                                                                    | Pr. 41                                            | 100           |
| 2              | 102            | IPF         | Instantaneous power failure/undervoltage   | Output at occurrence of an instantaneous power failure or when undervoltage protection is activated.                                                                                 | Pr. 57                                            | 114           |
| 3              | 103            | OL          | Overload alarm                             | Output while stall prevention function is activated.                                                                                                                                 | Pr. 22, Pr. 23, Pr. 66, Pr. 148, Pr. 149, Pr. 154 | 61            |
| 4              | 104            | FU          | Output frequency detection *2              | Output when the output frequency reaches the frequency setting in Pr. 42 (Pr. 43 for reverse rotation).                                                                              | Pr. 42, Pr. 43                                    | 100           |
| 5              | 105            | FU2         | Second output frequency detection *2       | Output when the output frequency reaches the frequency setting in Pr. 50.                                                                                                            | Pr. 50                                            | 100           |
| 7              | 107            | RBP         | Regenerative brake prealarm                | Output when 85% of the regenerative brake duty set in Pr. 70 is reached. Setting can be made for the FR-F720-03160 (FR-F740-01800) or more.                                          | Pr. 70                                            | 88            |
| 8              | 108            | THP         | Electronic thermal relay function prealarm | Output when the electronic thermal relay function cumulative value reaches 85%. (Electronic thermal relay function protection (E.THT/E.THM) activates, when the value reached 100%.) | Pr. 9                                             | 84            |
| 10             | 110            | PU          | PU operation mode                          | Output when the PU operation mode is selected.                                                                                                                                       | Pr. 79                                            | 147           |
| 11             | 111            | RY          | Inverter operation ready                   | Output when the inverter can be started by switching the start signal on or while it is running.                                                                                     | —                                                 | 98            |
| 12             | 112            | Y12         | Output current detection                   | Output when the output current is higher than the Pr. 150 setting for longer than the time set in Pr. 151.                                                                           | Pr. 150, Pr. 151                                  | 101           |
| 13             | 113            | Y13         | Zero current detection                     | Output when the output power is lower than the Pr. 152 setting for longer than the time set in Pr. 153.                                                                              | Pr. 152, Pr. 153                                  | 101           |



| Setting        |                | Signal Name | Function                                                                    | Operation                                                                                                                                                            | Related Parameters                          | Refer to Page |
|----------------|----------------|-------------|-----------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------|---------------|
| Positive Logic | Negative Logic |             |                                                                             |                                                                                                                                                                      |                                             |               |
| 14             | 114            | FDN         | PID lower limit                                                             | Output when the feedback value falls below the lower limit of PID control.                                                                                           | Pr. 127 to Pr. 134, Pr. 575 to Pr. 577      | 189           |
| 15             | 115            | FUP         | PID upper limit                                                             | Output when the feedback value rises above the upper limit of PID control                                                                                            |                                             |               |
| 16             | 116            | RL          | PID forward/reverse rotation output                                         | Output when forward rotation is performed in PID control.                                                                                                            |                                             |               |
| 17             | —              | MC1         | Commercial power-supply switchover MC1                                      | Used when the commercial power supply-inverter switchover function is used.                                                                                          | Pr. 135 to Pr. 139, Pr. 159                 | 197           |
| 18             | —              | MC2         | Commercial power-supply switchover MC2                                      |                                                                                                                                                                      |                                             |               |
| 19             | —              | MC3         | Commercial power-supply switchover MC3                                      |                                                                                                                                                                      |                                             |               |
| 25             | 125            | FAN         | Fan fault output                                                            | Output at the time of a fan fault.                                                                                                                                   | Pr. 244                                     | 213           |
| 26             | 126            | FIN         | Heatsink overheat pre-alarm                                                 | Output when the heatsink temperature reaches about 85% of the heatsink overheat protection providing temperature.                                                    | —                                           | 237           |
| 45             | 145            | RUN3        | During inverter running and start command is on                             | Output when the inverter running and start commands are on.                                                                                                          | —                                           | 98            |
| 46             | 146            | Y46         | During deceleration at occurrence of power failure (retained until release) | Output when the power failure-time deceleration function is executed.                                                                                                | Pr. 261 to Pr. 266                          | 117           |
| 47             | 147            | PID         | During PID control activated                                                | Output during PID control.                                                                                                                                           | Pr. 127 to Pr. 134, Pr. 575 to Pr. 577      | 189           |
| 64             | 164            | Y64         | During retry                                                                | Output during retry processing.                                                                                                                                      | Pr. 65 to Pr. 69                            | 119           |
| 70             | 170            | SLEEP       | PID output interruption                                                     | Output when the PID output interruption function is executed.                                                                                                        | Pr. 127 to Pr. 134, Pr. 575 to Pr. 577      | 189           |
| 71             | —              | RO1         | Commercial-power supply side motor 1 connection RO1                         | Used when using advanced PID control (pump function).                                                                                                                | Pr. 575 to Pr. 591                          | 202           |
| 72             | —              | RO2         | Commercial-power supply side motor 2 connection RO2                         |                                                                                                                                                                      |                                             |               |
| 73             | —              | RO3         | Commercial-power supply side motor 3 connection RO3                         |                                                                                                                                                                      |                                             |               |
| 74             | —              | RO4         | Commercial-power supply side motor 4 connection RO4                         |                                                                                                                                                                      |                                             |               |
| 75             | —              | RIO1        | Inverter side motor 1 connection RIO1                                       |                                                                                                                                                                      |                                             |               |
| 76             | —              | RIO2        | Inverter side motor 2 connection RIO2                                       |                                                                                                                                                                      |                                             |               |
| 77             | —              | RIO3        | Inverter side motor 3 connection RIO3                                       |                                                                                                                                                                      |                                             |               |
| 78             | —              | RIO4        | Inverter side motor 4 connection RIO4                                       |                                                                                                                                                                      |                                             |               |
| 90             | 190            | Y90         | Life alarm                                                                  | Output when any of the control circuit capacitor, main circuit capacitor and inrush current limit circuit or the cooling fan approaches the end of its service life. | Pr. 255 to Pr. 259                          | 214           |
| 91             | 191            | Y91         | Alarm output 3 (power-off signal)                                           | Output when an error occurs due to the circuit failure or connection alarm of the inverter.                                                                          | —                                           | 99            |
| 92             | 192            | Y92         | Energy saving average value updated timing                                  | Turned on and off alternately every time the power saving average value is updated when the power saving monitor is used.                                            | Pr. 52, Pr. 54, Pr. 158, Pr. 891 to Pr. 899 | 124           |
| 93             | 193            | Y93         | Current average value monitor signal                                        | Average current value and maintenance timer value are output as pulses. Cannot be set to <i>Pr. 195 and Pr. 196</i> (relay output terminal).                         | Pr. 555 to Pr. 557                          | 217           |



| Setting        |                | Signal Name | Function                 | Operation                                                                                                                                                                                           | Related Parameters               | Refer to Page |
|----------------|----------------|-------------|--------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------|---------------|
| Positive Logic | Negative Logic |             |                          |                                                                                                                                                                                                     |                                  |               |
| 94             | 194            | ALM2        | Alarm output 2           | Output when the inverter's protective function is activated to stop the output (major fault). Continue outputting the signal during inverter reset and stop outputting after reset is cancelled. *2 | —                                | 99            |
| 95             | 195            | Y95         | Maintenance timer signal | Output when <i>Pr. 503</i> rises to or above the <i>Pr. 504</i> setting.                                                                                                                            | <i>Pr. 503</i> , <i>Pr. 504</i>  | 216           |
| 96             | 196            | REM         | Remote output            | Output to the terminal when a value is set to the parameter.                                                                                                                                        | <i>Pr. 495</i> to <i>Pr. 497</i> | 103           |
| 98             | 198            | LF          | Minor fault output       | Output when a minor fault (fan failure or communication error warning) occurs.                                                                                                                      | <i>Pr. 121</i> , <i>Pr. 244</i>  | 166, 213      |
| 99             | 199            | ALM         | Alarm output             | Output when the inverter's protective function is activated to stop the output (major fault). The signal output is stopped when a reset turns on.                                                   | —                                | 99            |
| 9999           |                | —           | No function              | —                                                                                                                                                                                                   | —                                | —             |

\*1 Note that when the frequency setting is varied using an analog signal or  of the operation panel (FR-DU07), the output of the SU (up to frequency) signal may alternate on and off depending on that varying speed and the timing of the varying speed due to acceleration/deceleration time setting. (The output will not alternate on and off when the acceleration/deceleration time setting is "0s".)

\*2 When a power supply reset is performed, the alarm output 2 signal (ALM2) turns off as soon as the power supply switches off.

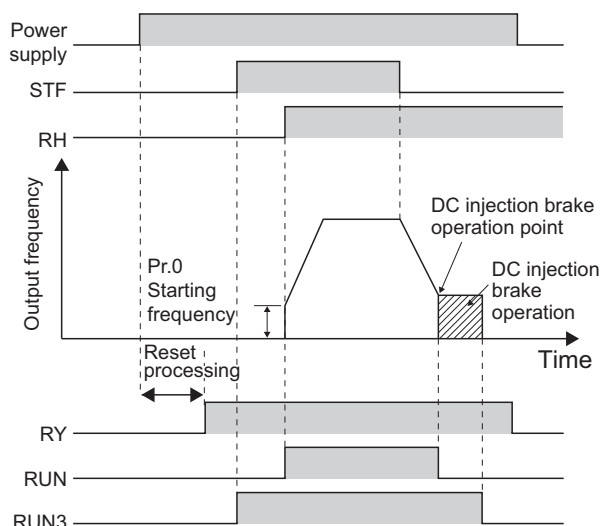
#### REMARKS

- The same function may be set to more than one terminal.
- When the function is executed, the terminal conducts at the setting of any of "0" to "99", and does not conduct at the setting of any of "100" to "199".
- The signal will not function if a value other than the above is set to any of *Pr. 190* to *Pr. 196*.
- When *Pr. 76 Alarm code output selection* = "1", the output signals of the terminals SU, IPF, OL and FU are switched as set in *Pr. 76*. (When an inverter alarm occurs, the signal output is switched to the alarm output.)
- The output assignment of the terminal RUN and alarm output relay are as set above regardless of *Pr. 76*.

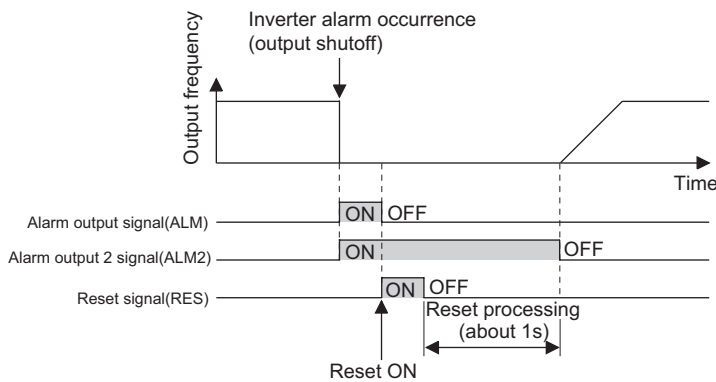
#### CAUTION

- When terminal assignment is changed using *Pr. 190* to *Pr. 196* (output terminal function selection), the other functions may be affected. Please make setting after confirming the function of each terminal.

## (2) Inverter operation ready signal (RY signal) and inverter running signal (RUN, RUN3 signal)



- When the inverter is ready to operate, the output of the operation ready signal (RY) is on. It is also on during inverter running.
- When the output frequency of the inverter rises to or above *Pr. 13 Starting frequency*, the output of the inverter running signal (RUN) is turned on. During an inverter stop or DC injection brake operation, the output is off.
- The output of the RUN3 signal is on when the inverter running and start signals are on.
- When using the RY or RUN3 signal, set "11 (positive logic)" or "111 (negative logic)" (RY) or "45 (positive logic)" or "145 (negative logic)" (RUN3) to any of *Pr. 190* to *Pr. 196* (output terminal function selection) to assign the function to the output terminal.
- The RUN signal is assigned to the terminal RUN in the default setting.

**(3) Alarm output signal (ALM, ALM2 signal)**

- If the inverter comes to an alarm stop, the ALM and ALM2 signals are output. (Refer to *page 231* for the alarm description.)
- The ALM2 signal remains on during a reset period after alarm occurrence.
- When using the ALM2 signal, set "94 (positive logic)" or "194 (negative logic)" to any of *Pr. 190 to Pr. 196 (output terminal function selection)* to assign the function to the output terminal.
- The ALM signal is assigned to the A1B1C1 contact in the initial setting.

**REMARKS**

Refer to *page 231* for the inverter alarm description.

**(4) Input MC shutoff signal (Y91 signal)**

- The Y91 signal is output at occurrence of an alarm attributable to the failure of the inverter circuit or an alarm caused by a wiring mistake.
- When using the Y91 signal, set "91 (positive logic)" or "191 (negative logic)" to any of *Pr. 190 to Pr. 196 (output terminal function selection)* to assign the function to the output terminal.
- The following table indicates the alarms that will output the Y91 signal. (Refer to *page 231* for the alarm description.)

| No. | Alarm Definition                                                                                 |
|-----|--------------------------------------------------------------------------------------------------|
| 1   | Inrush resistor overheat (E.IOH)                                                                 |
| 2   | CPU error (E.CPU)                                                                                |
| 3   | CPU error (E.E6)                                                                                 |
| 4   | CPU error (E.E7)                                                                                 |
| 5   | Parameter storage device alarm (E.PE)                                                            |
| 6   | Parameter storage device alarm (E.PE2)                                                           |
| 7   | 24VDC power output short circuit (E.P24)                                                         |
| 8   | Operation panel power supply short circuit<br>RS-485 terminals power supply short circuit(E.CTE) |
| 9   | Output side ground fault overcurrent protection(E.GF)                                            |
| 10  | Output phase failure protection (E.LF)                                                           |
| 11  | Brake transistor alarm detection/internal circuit error (E.BE)                                   |

## ◆ Parameters referred to ◆

*Pr. 13 Starting frequency* Refer to *page 81* .

*Pr. 76 Alarm code output selection* Refer to *page 121*



### 3.9.6 Detection of output frequency (SU, FU, FU2 signal, Pr. 41 to Pr. 43, Pr. 50)

The inverter output frequency is detected and output to the output signal.

Pr. 37  
page 104

Pr. 44  
page 79

Pr. 49  
page 61

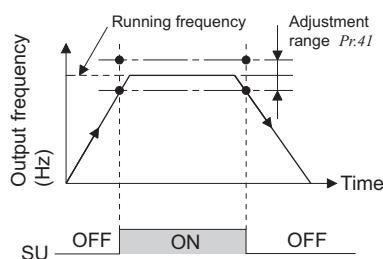
Pr. 51  
page 83

| Parameter Number | Name                                            | Initial Value | Setting Range | Description                                                         |
|------------------|-------------------------------------------------|---------------|---------------|---------------------------------------------------------------------|
| 41               | Up-to-frequency sensitivity                     | 10%           | 0 to 100%     | Set the level where the SU signal turns on.                         |
| 42               | Output frequency detection                      | 6Hz           | 0 to 400Hz    | Set the frequency where the FU signal turns on.                     |
| 43               | Output frequency detection for reverse rotation | 9999          | 0 to 400Hz    | Set the frequency where the FU signal turns on in reverse rotation. |
|                  |                                                 |               | 9999          | Same as Pr. 42 setting                                              |
| 50               | Second output frequency detection               | 30Hz          | 0 to 400Hz    | Set the frequency where the FU2 signal turns on.                    |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

#### (1) Up-to-frequency sensitivity (SU signal, Pr. 41)

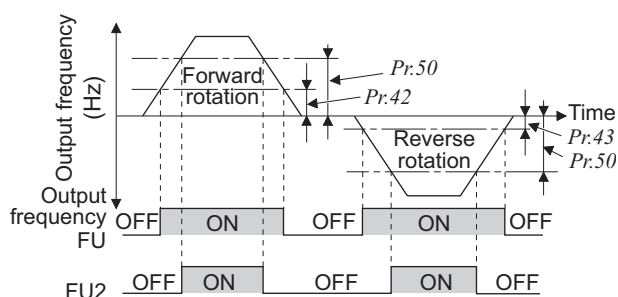
- When the output frequency reaches the running frequency, the up-to-frequency signal (SU) is output.
- The Pr. 41 value can be adjusted within the range  $\pm 1\%$  to  $\pm 100\%$  on the assumption that the set frequency is 100%.
- This parameter can be used to ensure that the running frequency has been reached to provide the operation start signal etc. for related equipment.



#### REMARKS

The output frequency compared with the set frequency changes depending on the control system.

| Control system                      | Compared output frequency                 |
|-------------------------------------|-------------------------------------------|
| V/F control                         | Output frequency                          |
| Simple magnetic flux vector control | Output frequency before slip compensation |



| Parameter Number | Output Signals |
|------------------|----------------|
| 42               | FU             |
| 43               |                |
| 50               | FU2            |

#### (2) Output frequency detection (FU signal, FU2 signal, Pr. 42, Pr. 43, Pr. 50)

- When the output frequency rises to or above the Pr. 42 setting, the output frequency detection signal (FU) is output.
- This function can be used for electromagnetic brake operation, open signal, etc.
- When the detection frequency is set in Pr. 43, frequency detection for reverse operation use only can also be set. This function is effective for switching the timing of electromagnetic brake operation between forward rotation (rise) and reverse rotation (fall) during vertical lift operation, etc.
- When Pr. 43  $\neq$  "9999", the Pr. 42 setting applies to forward rotation and the Pr. 43 setting applies to reverse rotation.
- When outputting a frequency detection signal besides the FU signal, set the detection frequency in Pr. 50. The FU2 signal is output when the output frequency reaches or exceeds the Pr. 50 setting.
- When using the FU2 signal, set "5 (positive logic)" or "105 (negative logic)" in any of Pr. 190 to Pr. 196 (output terminal function selection) to assign the function to the output terminal.

#### CAUTION

- When terminal assignment is changed using Pr. 190 to Pr. 196 (output terminal function selection), the other functions may be affected. Please make setting after confirming the function of each terminal.

#### ◆ Parameters referred to ◆

Pr. 190 to Pr. 196 (output terminal function selection) Refer to page 96



### 3.9.7 Output current detection function (Y12 signal, Y13 signal, Pr. 150 to Pr. 153, Pr. 166, Pr. 167)

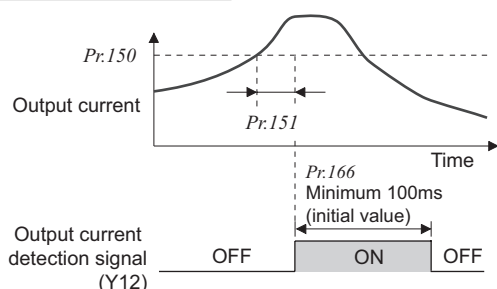
The output power during inverter running can be detected and output to the output terminal.

| Parameter Number | Name                                           | Initial Value | Setting Range | Description                                                                                                                                                               |
|------------------|------------------------------------------------|---------------|---------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 150              | Output current detection level                 | 110%*         | 0 to 120%*    | Set the output current detection level. 100% is the rated inverter current.                                                                                               |
| 151              | Output current detection signal delay time     | 0s            | 0 to 10s      | Set the output current detection period. Set the time from when the output current has risen above the setting until the output current detection signal (Y12) is output. |
| 152              | Zero current detection level                   | 5%            | 0 to 150%     | Set the zero current detection level. The rated inverter current is assumed to be 100%.                                                                                   |
| 153              | Zero current detection time                    | 0.5s          | 0 to 1s       | Set this parameter to define the period from when the output current drops below the Pr. 152 value until the zero current detection signal (Y13) is output.               |
| 166              | Output current detection signal retention time | 0.1s          | 0 to 10s      | Set the retention time when the Y12 signal is on.                                                                                                                         |
|                  |                                                |               | 9999          | The Y12 signal on status is retained. The signal is turned off at the next start.                                                                                         |
| 167              | Output current detection operation selection   | 0             | 0             | Operation continues when the Y12 signal is on                                                                                                                             |
|                  |                                                |               | 1             | The inverter is brought to an alarm stop when the Y12 signal is on. (E.CDO)                                                                                               |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

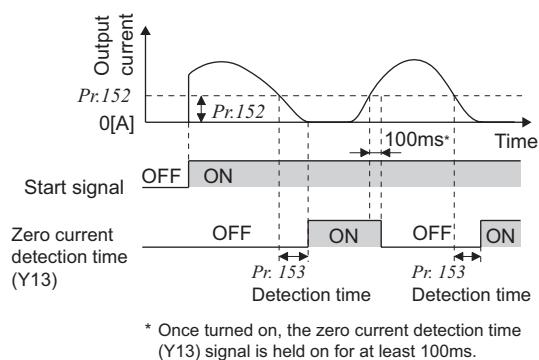
\* When Pr. 570 Multiple rating setting = "1", performing parameter clear changes the initial value and setting range. (Refer to page 66.)

Pr.166 ≠ 9999, Pr.167 = 0



#### (1) Output current detection (Y12 signal, Pr. 150, Pr. 151, Pr. 166, Pr. 167)

- The output power detection function can be used for excessive torque detection, etc.
- If the output current remains higher than the Pr. 150 setting during inverter operation for longer than the time set in Pr. 151, the output current detection signal (Y12) is output from the inverter's open collector or relay output terminal.
- When the Y12 signal turns on, the ON state is held for the time set in Pr. 166.
- When Pr. 166 = "9999", the ON state is held until a next start.
- At the Pr. 167 setting of "1", the inverter output is stopped and the output current detection alarm (E.CDO) is displayed when the Y12 signal turns on. When an alarm stop occurs, the Y12 signal is on for the time set in Pr. 166 at the Pr. 166 setting of other than 9999, and remains on until a reset is made at the Pr. 166 setting of 9999.
- Set "12 (positive logic)" or "112 (negative logic)" to any of Pr. 190 to Pr. 196 (output terminal function selection) to assign the function of the Y12 signal to the output terminal.



## (2) Zero current detection (Y13 signal, Pr. 152, Pr. 153)

- If the output current remains lower than the Pr. 152 setting during inverter operation for longer than the time set in Pr. 153, the zero current detection (Y13) signal is output from the inverter's open collector or relay output terminal.
- When the inverter's output current falls to "0", torque will not be generated. This may cause a drop due to gravity when the inverter is used in vertical lift application. To prevent this, the output current zero signal (Y13) can be output from the inverter to close the mechanical brake when the output current has fallen to "zero".
- Set "13 (positive logic)" or "113 (negative logic)" to any of Pr. 190 to Pr. 196 (output terminal function selection) to assign the function of the output power detection signal (Y13) to the output terminal.

### CAUTION

- When terminal assignment is changed using Pr. 190 to Pr. 196 (output terminal function selection), the other functions may be affected. Please make setting after confirming the function of each terminal.



## CAUTION

- ⚠ The zero current detection level setting should not be too high, and the zero current detection time setting not too long. Otherwise, the detection signal may not be output when torque is not generated at a low output current.
- ⚠ To prevent the machine and equipment from resulting in hazardous conditions by use of the zero current detection signal, install a safety backup such as an emergency brake.

### ◆ Parameters referred to ◆

Pr. 190 to Pr. 196 (output terminal function selection) Refer to page 96

3.9.8 Remote output function (REM signal, Pr. 495 to Pr. 497)

You can utilize the on/off of the inverter's output signals instead of the remote output terminal of the programmable logic controller.

Pr.343  
page 178  
Pr.503  
page 216

| Parameter Number | Name                    | Initial Value | Setting Range | Description                                       |
|------------------|-------------------------|---------------|---------------|---------------------------------------------------|
| 495              | Remote output selection | 0             | 0             | Remote output data clear at powering off          |
|                  |                         |               | 1             | Remote output data retention even at powering off |
| 496 *            | Remote output data 1    | 0             | 0 to 4095     | Refer to the following diagram.                   |
| 497 *            | Remote output data 2    | 0             | 0 to 4095     |                                                   |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

\* The above parameters allow its setting to be changed during operation in any operation mode even if "0" (initial value) is set in Pr. 77 Parameter write selection.

<Remote output data>

Pr.496

|     |   |   |   |   |      |      |    |    |     |    |     |
|-----|---|---|---|---|------|------|----|----|-----|----|-----|
| b11 |   |   |   |   |      |      |    |    |     |    | b0  |
| *   | * | * | * | * | ABC2 | ABC1 | FU | OL | IPF | SU | RUN |

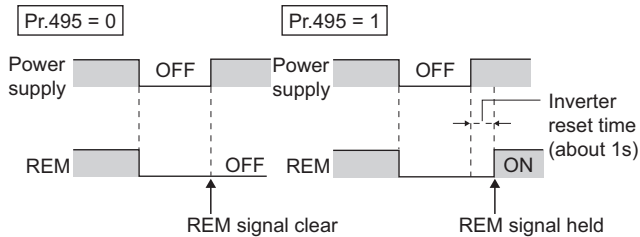
Pr.497

|     |   |        |        |        |       |       |       |       |       |       |       |
|-----|---|--------|--------|--------|-------|-------|-------|-------|-------|-------|-------|
| b11 |   |        |        |        |       |       |       |       |       |       | b0    |
| *   | * | RA3 *3 | RA2 *3 | RA1 *3 | Y6 *2 | Y5 *2 | Y4 *2 | Y3 *2 | Y2 *2 | Y1 *2 | Y0 *2 |

- \*1 As desired (always 0 when read)
- \*2 Y0 to Y6 are available only when the extension output option (FR-A7AY) is fitted
- \*3 RA1 to RA3 are available only when the relay output option (FR-A7AR) is fitted

Example)When "96" (positive logic) is set to Pr. 190 RUN terminal function selection and "1" (H01) is set to Pr. 496, the terminal RUN turns on.

ON/OFF example for positive logic



- When Pr. 495 = "0" (initial value), performing a power supply reset (including a power failure) clears the REM signal output. (The ON/OFF states of the terminals are as set in Pr. 190 to Pr. 196.) The Pr. 496 and Pr. 497 settings are also "0". When Pr. 495 = "1", the remote output data before power supply-off is stored into the EEPROM, so the signal output at power recovery is the same as before power supply-off. However, it is not stored when the inverter is reset (terminal reset, reset request through communication). (See the chart on the left)

REMARKS

- The output terminal where the REM signal is not assigned using any of Pr. 190 to Pr. 196 does not turn on/off if 0/1 is set to the terminal bit of Pr. 496 or Pr. 497 . (It turns on/off with the assigned function.)
- When the inverter is reset (terminal reset, reset request through communication), Pr. 496 and Pr. 497 values turn to "0". When Pr. 495 = "1", however, they are the settings at power supply-off. (The settings are stored at power supply-off.)

CAUTION

- When Pr. 495 = "1", take such a step as to connect R1/L11, S1/L21 and P/+, N/- to ensure that control power will be retained to some degree. If you do not take such a step, the output signals provided after power-on are not guaranteed.

◆ Parameters referred to ◆

- Pr. 190 to Pr. 196 (output terminal function selection) Refer to page 96

### 3.10 Monitor display and monitor output signal

| Purpose                                              | Parameter that must be set                                    |                                        | Refer to Page |
|------------------------------------------------------|---------------------------------------------------------------|----------------------------------------|---------------|
| Display motor speed<br>Set speed                     | Speed display and speed setting                               | Pr.37, Pr.144                          | 104           |
| Change PU monitor display data                       | DU/PU main display data selection<br>Cumulative monitor clear | Pr.52, Pr.170, Pr.171, Pr.268, Pr.891  | 105           |
| Change of the monitor output from terminal CA and AM | Terminal CA, AM function selection                            | Pr.54 to Pr.56, Pr.158, Pr.867, Pr.869 | 109           |
| Adjust terminal CA, AM outputs                       | Terminal CA, AM calibration                                   | Pr.900, Pr.901, Pr.930, Pr.931         | 111           |

#### 3.10.1 Speed display and speed setting (Pr.37, Pr.144)

You can change the PU (FR-DU07/FR-PU04) monitor display or frequency setting to motor speed or machine speed.

| Parameter Number | Name                     | Initial Value | Setting Range                              | Description                                                    |
|------------------|--------------------------|---------------|--------------------------------------------|----------------------------------------------------------------|
| 37               | Speed display            | 0             | 0                                          | Frequency display, setting                                     |
|                  |                          |               | 1 to 9998                                  | Set the machine speed at 60Hz.                                 |
| 144              | Speed setting switchover | 4             | 0, 2, 4, 6, 8, 10, 102, 104, 106, 108, 110 | Set the number of motor poles when displaying the motor speed. |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

- To display the machine speed, set in Pr. 37 the machine speed for 60Hz operation.
- When displaying the motor speed, set the number of motor poles (2, 4, 6, 8, 10) or number of motor poles + 100 (102, 104, 106, 108, 110) to Pr. 144.
- When both Pr. 37 and Pr. 144 have been set, their priorities are as given below.  
Pr.144, 102 to 110 > Pr.37, 1 to 9998 > Pr.144, 2 to 10
- When the running speed monitor is selected, each monitor and setting are determined by the combination of Pr. 37 and Pr. 144 as listed below. (The units within the thick frame are the initial values.)

| Pr. 37 Setting       | Pr. 144 Setting | Output Frequency Monitor | Set Frequency Monitor | Running Speed Monitor | Frequency Setting Parameter Setting |
|----------------------|-----------------|--------------------------|-----------------------|-----------------------|-------------------------------------|
| 0<br>(initial value) | 0               | Hz                       | Hz                    | r/min *1              | Hz                                  |
|                      | 2 to 10         | Hz                       | Hz                    | r/min *1              | Hz                                  |
|                      | 102 to 110      | r/min *1                 | r/min *1              | r/min *1              | r/min *1                            |
| 1 to 9998            | 0               | Hz                       | Hz                    | Machine speed *1      | Hz                                  |
|                      | 2 to 10         | Machine speed *1         | Machine speed *1      | Machine speed *1      | Machine speed *1                    |
|                      | 102 to 110      | Hz                       | Hz                    | r/min *1              | Hz                                  |

\*1 Motor speed r/min conversion formula ..... frequency  $\times$  120/number of motor poles (Pr. 144)

Machine speed conversion formula ..... Pr. 37  $\times$  frequency/60Hz

For Pr. 144 in the above formula, the value is "Pr. 144-100" when "102 to 110" is set in Pr. 144 and the value is "4" when Pr. 37 = 0 and Pr.144 = 0.

\*2 Hz is in 0.01Hz increments, machine speed is in 1m/min increments, and r/min is in 1r/min increments.

#### CAUTION

- In the V/F control mode, the output frequency of the inverter is displayed in terms of synchronous speed, and therefore, it is unequal to the actual speed by motor slip.
- When the running speed display is selected at the setting of Pr. 37 "0" and Pr. 144 "0", the monitor display is provided on the assumption that the number of motor poles is 4. (1800r/min is displayed at 60Hz)
- Refer to Pr. 52 when you want to change the PU main monitor (PU main display).
- Since the panel display of the operation panel (FR-DU07) is 4 digits in length, the monitor value of more than "9999" is displayed "----".

## CAUTION

Make sure that the settings of the running speed and number of motor poles are correct. Otherwise, the motor might run at extremely high speed, damaging the machine.

#### ◆ Parameters referred to ◆

Pr.52 DU/PU main display data selection  Refer to page 105

### 3.10.2 DU/PU monitor display selection (Pr.52, Pr.170, Pr.171, Pr.268, Pr.563, Pr.564, Pr.891)

The monitor to be displayed on the main screen of the operation panel (FR-DU07)/parameter unit (FR-PU04) can be selected.

| Parameter Number | Name                                         | Initial Value           | Setting Range                                     | Description                                                                                                                         |
|------------------|----------------------------------------------|-------------------------|---------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------|
| 52               | DU/PU main display data selection            | 0<br>(output frequency) | 0, 5, 6, 8 to 14, 17, 20, 23 to 25, 50 to 57, 100 | Select the monitor to be displayed on the operation panel and parameter unit. Refer to the following table for monitor description. |
| 170              | Cumulative power meter clear                 | 9999                    | 0                                                 | Set "0" to clear the watt-hour meter monitor.                                                                                       |
|                  |                                              |                         | 10                                                | Set the maximum value when monitoring from communication to 0 to 9999kWh.                                                           |
|                  |                                              |                         | 9999                                              | Set the maximum value when monitoring from communication to 0 to 65535kWh.                                                          |
| 171              | Operation hour meter clear                   | 9999                    | 0, 9999                                           | Set "0" in the parameter to clear the watt-hour monitor. Setting "9999" has no effect.                                              |
| 268 *            | Monitor decimal digits selection             | 9999                    | 0                                                 | Displays as integral value.                                                                                                         |
|                  |                                              |                         | 1                                                 | Displayed in 0.1 increments.                                                                                                        |
|                  |                                              |                         | 9999                                              | No function                                                                                                                         |
| 563              | Energization time carrying-over times        | 0                       | 0 to 65535<br>(reading only)                      | The numbers of cumulative energization time monitor exceeded 65535h is displayed. Reading only                                      |
| 564              | Operating time carrying-over times           | 0                       | 0 to 65535<br>(reading only)                      | The numbers of operation time monitor exceeded 65535h is displayed. Reading only                                                    |
| 891              | Cumulative power monitor digit shifted times | 9999                    | 0 to 4                                            | Set the number of times to shift the cumulative power monitor digit. Clamp the monitoring value at maximum.                         |
|                  |                                              |                         | 9999                                              | No shift<br>Clear the monitor value when it exceeds the maximum value.                                                              |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

\* The above parameters allow its setting to be changed during operation in any operation mode even if "0" (initial value) is set in Pr. 77 Parameter write selection.

#### (1) Monitor description list (Pr.52)

- In Pr. 52, set the monitor to be displayed on the operation panel (FR-DU07) or parameter unit (FR-PU04).
- Refer to the following table and set the monitor to be displayed. (The signals marked × cannot be selected for monitoring)

| Types of Monitor                              | Increments      | Pr.52 Parameter Setting Value |                 | Description                                                                                             |
|-----------------------------------------------|-----------------|-------------------------------|-----------------|---------------------------------------------------------------------------------------------------------|
|                                               |                 | DU LED                        | PU Main Monitor |                                                                                                         |
| Output frequency                              | 0.01Hz          | 0/100                         |                 | Displays the inverter output frequency.                                                                 |
| Output current                                | 0.01A/0.1A *5   | 0/100                         |                 | Displays the inverter output current effective value.                                                   |
| Output voltage                                | 0.1V            | 0/100                         |                 | Displays the inverter output voltage.                                                                   |
| Alarm display                                 | —               | 0/100                         |                 | Displays 8 past alarms individually.                                                                    |
| Frequency setting                             | 0.01Hz          | 5                             | *1              | Displays the set frequency.                                                                             |
| Running speed                                 | 1(r/min)        | 6                             | *1              | Displays the motor speed. (depending on Pr. 37 and Pr. 144 settings)                                    |
| Converter output voltage                      | 0.1V            | 8                             | *1              | Displays the DC bus voltage value.                                                                      |
| Regenerative brake duty                       | 0.1%            | 9                             | *1              | Brake duty set in Pr. 30, Pr. 70. (Setting can be made for the FR-F720-03160 (FR-F740-01800) or more.)  |
| Electronic thermal relay function load factor | 0.1%            | 10                            | *1              | Displays the motor thermal cumulative value on the assumption that the thermal operation level is 100%. |
| Output current peak value                     | 0.01A/0.1A *5   | 11                            | *1              | Holds and displays the peak value of the output power monitor (cleared at every start)                  |
| Converter output voltage peak value           | 0.1V            | 12                            | *1              | Holds and displays the peak value of the DC bus voltage value. (cleared at every start)                 |
| Input power                                   | 0.01kW/0.1kW *5 | 13                            | *1              | Displays the power on the inverter input side.                                                          |
| Output power                                  | 0.01kW/0.1kW *5 | 14                            | *1              | Displays the power on the inverter output side.                                                         |
| Input terminal status                         | —               | 55                            | *1              | Displays the input terminal ON/OFF states on the PU. (Refer to page 107 for the DU display)             |
| Output terminal status                        | —               |                               | *1              | Displays the output terminal ON/OFF states on the PU. (Refer to page 107 for the DU display)            |

|        |          |
|--------|----------|
| Pr.51  | page 83  |
| Pr.54  | page 109 |
| Pr.167 | page 101 |
| Pr.172 | page 145 |
| Pr.267 | page 130 |
| Pr.299 | page 114 |
| Pr.889 | page 219 |
| Pr.892 | page 124 |
| Pr.557 | page 217 |
| Pr.570 | page 66  |

| Types of Monitor                | Increments                       | Pr. 52 Parameter Setting Value |                 | Description                                                                                                                                                                        |
|---------------------------------|----------------------------------|--------------------------------|-----------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
|                                 |                                  | DU LED                         | PU Main Monitor |                                                                                                                                                                                    |
| Option input terminal states    | —                                | 56                             | ×               | Displays the input terminal ON/OFF states of the digital input option (FR-A7AX) on the DU. (Refer to <i>page 107</i> for details.)                                                 |
| Option output terminal states   | —                                | 57                             | ×               | Displays the output terminal ON/OFF states of the digital output option (FR-A7AY) or relay output option (FR-A7AR) on the DU. (Refer to <i>page 107</i> for details)               |
| Load meter                      | 0.1%                             | 17                             |                 | Displays the torque current in % on the assumption that the Pr. 56 setting is 100%.                                                                                                |
| Cumulative energization time *2 | 1h                               | 20                             |                 | Adds up and displays the energization time after inverter shipment. You can check the numbers of monitor value exceeded 65535h with Pr. 563.                                       |
| Actual operation time *2, 3     | 1h                               | 23                             |                 | Adds up and displays the inverter operation time. You can check the numbers of monitor value exceeded 65535h with Pr. 564. Can be cleared by Pr. 171. (Refer to <i>page 108</i> .) |
| Motor load factor               | 0.1%                             | 24                             |                 | Displays the output current value on the assumption that the inverter rated current value is 100%.                                                                                 |
| Cumulative power                | 0.01kWh/<br>0.1kWh *4*5          | 25                             |                 | Adds up and displays the power amount based on the output power monitor. Can be cleared by Pr. 170. (Refer to <i>page 108</i> .)                                                   |
| Power saving effect             | Variable according to parameters | 50                             |                 | Displays the energy-saving effect monitor. Can be converted into the charge display or % display by parameter setting. (Refer to <i>page 125</i> for details.)                     |
| Cumulative saving power         |                                  | 51                             |                 |                                                                                                                                                                                    |
| PID set point                   | 0.1%                             | 52                             |                 | Displays the set value for PID control. (Refer to <i>page 189</i> .)                                                                                                               |
| PID measured value              | 0.1%                             | 53                             |                 | Displays the measured value for PID control. (Refer to <i>page 189</i> .)                                                                                                          |
| PID deviation value             | 0.1%                             | 54                             |                 | Displays the deviation for PID control. (Refer to <i>page 189</i> .)                                                                                                               |

\*1 Frequency setting to output terminal status on the PU main monitor are selected by "other monitor selection" of the parameter unit (FR-PU04).

\*2 The cumulative energization time and actual operation time are accumulated from 0 to 65535 hours, then cleared, and accumulated again from 0. When the operation panel (FR-DU07) is used, the time is displayed up to 65.53 (65530h) on the assumption that 1h = 0.001, and thereafter, it is added up from 0.

\*3 The actual operation time is not added up if the cumulative operation time before power supply-off is less than 1h.

\*4 When using the parameter unit (FR-PU04), "kW" is displayed.

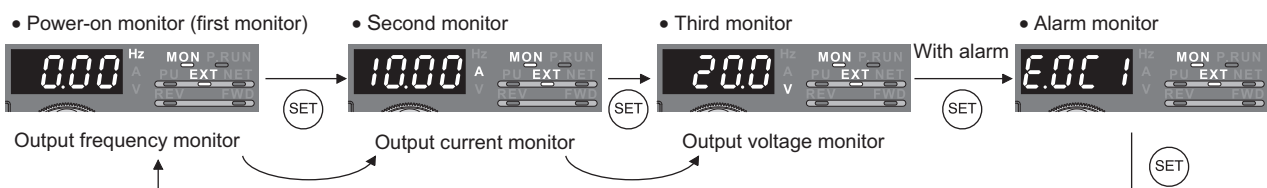
\*5 The setting depends on capacities. (FR-F720-02330 (FR-F740-01160) or less/FR-F720-03160 (FR-F740-01800) or more)

## REMARKS

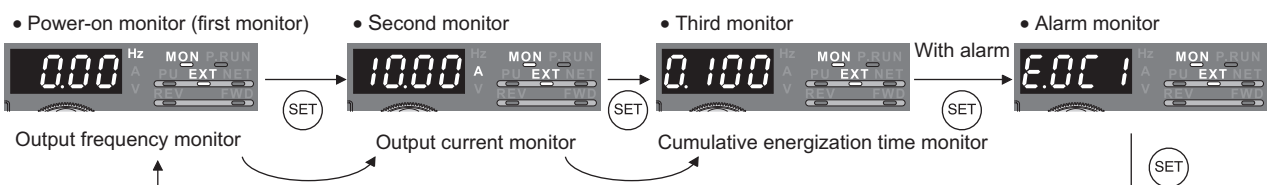
- By setting "0" in Pr. 52, the monitoring of output speed to alarm display can be selected in sequence by **SET**.
- When the operation panel (FR-DU07) is used, the displayed units are Hz, V and A only and the others are not displayed.
- The monitor set in Pr. 52 is displayed in the third monitor position. (The output voltage monitor is changed.)

## Initial value

- \* The monitor displayed at powering on is the first monitor. Display the monitor to be displayed on the first monitor and press **SET** for 1s. (To return to the output frequency monitor, hold down **SET** for 1s after displaying the output frequency monitor.)



Example) When Pr. 52 is set to "20" (cumulative energization time), the monitor is displayed on the operation panel as described below.



## (2) Display set frequency during stop (Pr.52)

- When Pr. 52 is set to "100", the set frequency monitor is displayed during a stop and the output frequency monitor is displayed during operation. (LED of Hz flickers during stop and is lit during running.)

|                  | Pr.52               |               |                  |
|------------------|---------------------|---------------|------------------|
|                  | 0                   | 100           |                  |
|                  | During running/stop | During stop   | During running   |
| Output frequency | Output frequency    | Set frequency | Output frequency |
| Output current   | Output current      |               |                  |
| Output voltage   | Output voltage      |               |                  |
| Alarm display    | Alarm display       |               |                  |

### REMARKS

- During an error, the output frequency at error occurrence appears.
- During MRS, the values displayed are the same as during a stop.

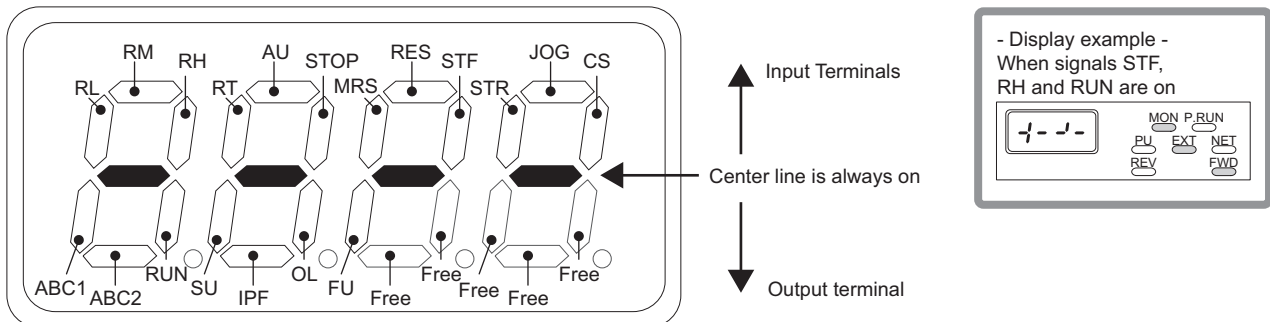
## (3) Operation panel (FR-DU07) I/O terminal monitor (Pr.52)

- When Pr. 52 is set to any of "55 to 57", the I/O terminal states can be monitored on the operation panel (FR-DU07).
- The I/O terminal monitor is displayed on the third monitor.
- The LED is on when the terminal is on, and the LED is off when the terminal is off. The center line of LED is always on.

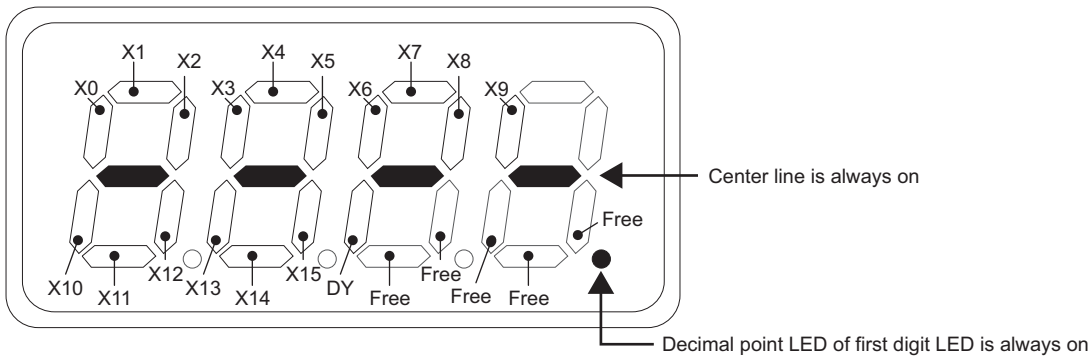
| Pr. 52 Setting | Monitor Description                                                                                                 |
|----------------|---------------------------------------------------------------------------------------------------------------------|
| 55             | Displays the I/O and output terminal ON/OFF states of the inverter unit.                                            |
| 56 *           | Displays the input terminal ON/OFF states of the digital input option (FR-A7AX).                                    |
| 57 *           | Displays the output terminal ON/OFF states of the digital output option (FR-A7AY) or relay output option (FR-A7AR). |

\* You can set "56" or "57" even if the option is not fitted. When the option is not fitted, the monitor displays are all off.

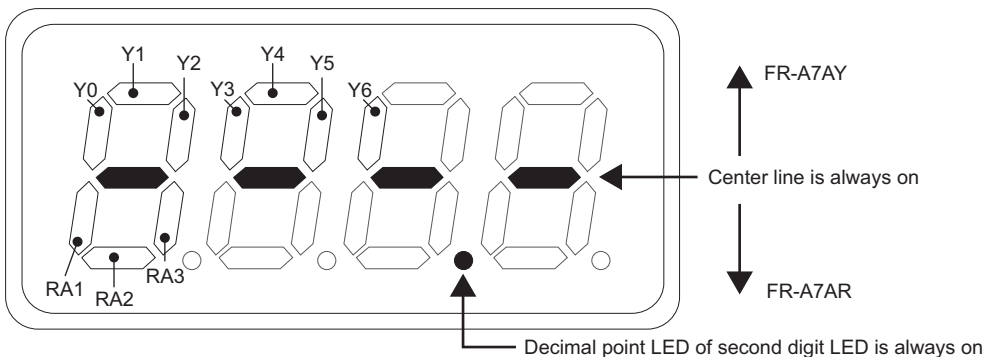
- On the unit I/O terminal monitor (Pr. 52 = "55"), the upper LEDs denote the input terminal states and the lower the output terminal states.



- On the input option terminal monitor (Pr. 52= "56"), the decimal point LED of the first digit LED is on.



- On the input option terminal monitor (Pr. 52= "57"), the decimal point LED of the second digit LED is on.



#### (4) Cumulative energization power monitor and clear (Pr.170, Pr.891)

- On the cumulative energization power monitor (Pr. 52 = "25"), the output power monitor value is added up and is updated in 1h increments.
- The operation panel (FR-DU07), parameter unit (FR-PU04) and communication (RS-485 communication, communication option) display units and display ranges are as indicated below.

| Operation panel *1 |         | Parameter unit *2   |         | Communication |                                  |      |
|--------------------|---------|---------------------|---------|---------------|----------------------------------|------|
| Range              | Unit    | Range               | Unit    | Range         |                                  | Unit |
|                    |         |                     |         | Pr.170 = 10   | Pr.170 = 9999                    |      |
| 0 to 99.99kWh      | 0.01kWh | 0 to 999.99kWh      | 0.01kWh | 0 to 9999kWh  | 0 to 65535kWh<br>(initial value) | 1kWh |
| 100.0 to 999.9kWh  | 0.1kWh  | 1000.0 to 9999.9kWh | 0.1kWh  |               |                                  |      |
| 1000 to 9999kWh    | 1kWh    | 10000 to 99999kWh   | 1kWh    |               |                                  |      |

\*1 Power is measured in the range 0 to 9999.99kWh, and displayed in 4 digits.

When the monitor value exceeds "99.99", a carry occurs, e.g. "100.0", so the value is displayed in 0.1kWh increments.

\*2 Power is measured in the range 0 to 99999.99.99kWh, and displayed in 5 digits.

When the monitor value exceeds "999.99", a carry occurs, e.g. "1000.0", so the value is displayed in 0.1kWh increments.

- The monitor data digit can be shifted to the right by the number set in Pr. 891.  
For example, if the cumulative power value is 1278.56kWh when Pr. 891 = "2", the PU/DU display is 12.78 (display in 100kWh increments) and the communication data is 12.
- If the maximum value is exceeded at Pr. 891 = "0 to 4", the power is clamped at the maximum value, indicating that a digit shift is necessary. If the maximum value is exceeded at Pr. 891 = "9999", the power returns to 0 and is recounted.
- If the maximum value is exceeded at Pr. 891 = "9999", the power returns to 0 and is recounted.
- Writing "0" in Pr. 170 clears the cumulative energization power monitor.

#### REMARKS

- If "0" is written in Pr. 170 and Pr. 170 is read again, "9999" or "10" is displayed.

#### (5) Cumulative energization time and actual operation time monitor (Pr.170, Pr.563, Pr.564)

- On the cumulative energization time monitor (Pr. 52 = "20"), the inverter running time is added up every hour.
- On the actual operation time monitor (Pr. 52 = "23"), the inverter running time is added up every hour. (Time is not added up during a stop.)
- If the numbers of monitor value exceeds 65535, it is added up from 0. You can check the numbers of cumulative energization time monitor exceeded 65535h with Pr. 563 and the numbers of actual operation time monitor exceeded 65535h with Pr. 564.
- Writing "0" in Pr. 171 clears the actual operation time monitor. (Energization time monitor can not be cleared.)

#### REMARKS

- The actual operation time is not added up unless the inverter is operated one or more hours continuously.
- If "0" is written in Pr. 171 and Pr. 171 is read again, "9999" is always displayed. Setting "9999" does not clear the actual operation time meter.

#### (6) You can select the decimal digits of the monitor (Pr.268)

- As the operation panel (FR-DU07) display is 4 digits long, the decimal places may vary at analog input, etc. The decimal places can be hidden by selecting the decimal digits.  
In such a case, the decimal digits can be selected by Pr. 268.

| Pr. 268 Setting      | Description                                                                                                                                                                                                                                                             |
|----------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 9999 (initial value) | No function                                                                                                                                                                                                                                                             |
| 0                    | When 1 or 2 decimal places (0.1 increments or 0.01 increments) are monitored, the decimal places are dropped and the monitor displays an integer value (1 increments).<br>The monitor value of 0.99 or less is displayed as 0.                                          |
| 1                    | When 2 decimal places (0.01 increments) are monitored, the 0.01 decimal place is dropped and the monitor displays the first decimal place (0.1 increments).<br>When the monitor display digit is originally in 1 increments, it is displayed unchanged in 1 increments. |

#### REMARKS

- The number of display digits on the cumulative energization time (Pr. 52 = "20"), actual operation time (Pr. 52 = "23"), cumulative energization power (Pr. 52 = "25") or cumulative saving power monitor (Pr. 52 = "51") does not change.

#### ◆ Parameters referred to ◆

Pr.37 Speed display, Pr. 144 speed setting switchover  Refer to page 104

Pr. 55 Frequency monitoring reference, Pr. 56 Current monitoring reference  Refer to page 109

### 3.10.3 CA, AM terminal function selection (Pr.54 to Pr.56, Pr.158, Pr.867, Pr.869)

For signal output, two different output terminals are available: analog current output terminal CA and analog output terminal AM.

You can select the signals output to the terminals CA, AM.

|        |          |
|--------|----------|
| Pr.52  | page 105 |
| Pr.57  | page 114 |
| Pr.157 | page 61  |
| Pr.159 | page 197 |
| Pr.611 | page 114 |
| Pr.872 | page 122 |

| Parameter Number | Name                           | Initial Value                 | Setting Range<br>200V class<br>(400V class)      | Description                                                                                  |
|------------------|--------------------------------|-------------------------------|--------------------------------------------------|----------------------------------------------------------------------------------------------|
| 54 *             | CA terminal function selection | 1<br>(output frequency)       | 1 to 3, 5, 6, 8 to 14,<br>17, 21, 24, 50, 52, 53 | Select the monitor output to terminal CA.                                                    |
| 158 *            | AM terminal function selection |                               |                                                  | Select the monitor output to terminal AM.                                                    |
| 55 *             | Frequency monitoring reference | 60Hz                          | 0 to 400Hz                                       | Set the full-scale value to output the output frequency monitor value to terminal CA and AM. |
| 56 *             | Current monitoring reference   | Rated inverter output current | 02330<br>(01160)<br>or less                      | Set the full-scale value to output the output current monitor value to terminal CA and AM.   |
|                  |                                |                               | 03160<br>(01800)<br>or more                      |                                                                                              |
| 867              | AM output filter               | 0.01s                         | 0 to 5s                                          | Set the output filter of terminal AM.                                                        |
| 869              | Current output filter          | 0.02s                         | 0 to 5s                                          | Adjust response level of current output.                                                     |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

\* The above parameters allow its setting to be changed during operation in any operation mode even if "0" (initial value) is set in Pr. 77 Parameter write selection.

#### (1) Output signal list (Pr.54, Pr.158)

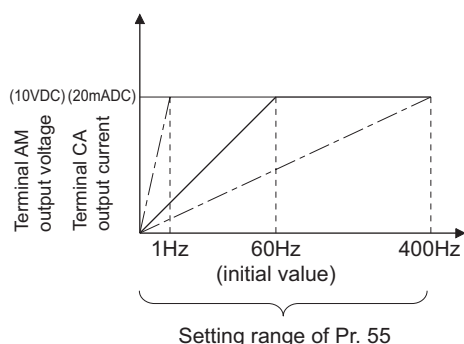
- In Pr. 54, set the monitor to be output to the terminal CA (Analog output (0 to 20 mADC current output)).
- In Pr. 158, set the monitor to be output to the terminal AM (analog output (0 to 10VDC voltage output)).
- Refer to the following table and set the monitor to be output.

| Types of Monitor                              | Increments         | Pr.54 (CA)<br>Pr.158 (AM)<br>Setting | Full Scale Value                                           | Description                                                                                                    |
|-----------------------------------------------|--------------------|--------------------------------------|------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------|
| Output frequency                              | 0.01Hz             | 1                                    | Pr. 55                                                     | Displays the inverter output frequency.                                                                        |
| Output current                                | 0.01A/0.1A *       | 2                                    | Pr. 56                                                     | Displays the inverter output current effective value.                                                          |
| Output voltage                                | 0.1V               | 3                                    | 200V class:400V<br>400V class:800V                         | Displays the inverter output voltage.                                                                          |
| Frequency setting                             | 0.01Hz             | 5                                    | Pr. 55                                                     | Displays the set frequency.                                                                                    |
| Running speed                                 | 1(r/min)           | 6                                    | Value of Pr. 55<br>represented in terms<br>of Pr. 37 value | Displays the motor speed.<br>(Depending on the Pr. 37 and Pr. 144 settings.<br>Refer to page 104 for details.) |
| Converter output voltage                      | 0.1V               | 8                                    | 200V class:400V<br>400V class:800V                         | Displays the DC bus voltage value.                                                                             |
| Regenerative brake duty                       | 0.1%               | 9                                    | Pr. 70                                                     | Output the brake duty.<br>(Setting can be made only for the FR-F720-03160 (FR-F740-01800) or more)             |
| Electronic thermal relay function load factor | 0.1%               | 10                                   | Electronic thermal relay function operation level          | Displays the motor thermal cumulative value on the assumption that the thermal operation level is 100%.        |
| Output current peak value                     | 0.01A/0.1A *       | 11                                   | Pr. 56                                                     | Holds and displays the peak value of the output power monitor. (Cleared at every start)                        |
| Converter output voltage peak value           | 0.1V               | 12                                   | 200V class:400V<br>400V class:800V                         | Holds and displays the peak value of the DC bus voltage value. (Cleared at every start)                        |
| Input power                                   | 0.01kW/<br>0.1kW * | 13                                   | Rated inverter power<br>× 2                                | Displays the power on the inverter input side.                                                                 |
| Output power                                  | 0.01kW/<br>0.1kW * | 14                                   | Rated inverter power<br>× 2                                | Displays the power on the inverter output side.                                                                |
| Load meter                                    | 0.1%               | 17                                   | Pr. 56                                                     | Displays the torque current in % on the assumption that the Pr. 56 setting is 100%.                            |

| Types of Monitor         | Increments         | Pr.54 (CA)<br>Pr.158 (AM)<br>Setting | Full Scale Value  | Description                                                                                                                                                         |
|--------------------------|--------------------|--------------------------------------|-------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Reference voltage output | —                  | 21                                   | —                 | Terminal CA: Outputs 20mA.<br>Terminal AM: Outputs 10V.                                                                                                             |
| Motor load factor        | 0.1%               | 24                                   | 200%              | Load factor with respect to motor rated current<br>Monitor value = output power monitor value/rated inverter current × 100 [%]                                      |
| Power saving effect      | 0.01kW/<br>0.1kW * | 50                                   | Inverter capacity | Displays the energy-saving effect monitor.<br>Power saving and power saving average value are displayed according to parameters.<br>(Refer to page 125 for details) |
| PID set point            | 0.1%               | 52                                   | 100%              | Displays the set value and measured value for PID control. (Refer to page 189 for details)                                                                          |
| PID measurement value    | 0.1%               | 53                                   | 100%              |                                                                                                                                                                     |

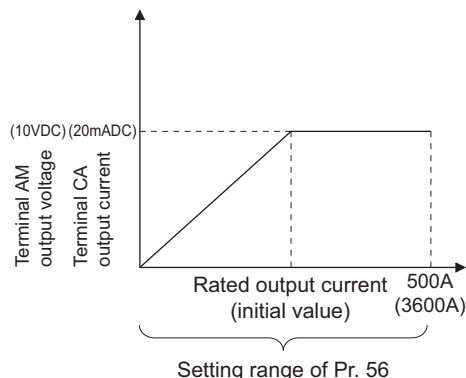
\* The setting depends on capacities. (FR-F720-02330 (FR-F740-01160) or less/FR-F720-03160 (FR-F740-01800) or more)

## (2) Frequency monitoring reference(Pr. 55)



- Set the frequency to be referenced when the frequency monitor (output frequency/set frequency) is selected for the terminal CA and terminal AM display.
- Set the frequency when the current output at terminal CA is 20mADC.  
The analog current output and inverter output frequency at terminal CA are proportional. (The maximum output current is 20mADC.)
- Set the frequency (output frequency/set frequency) when the voltage output at terminal AM is 10VDC.  
The analog voltage output and frequency at terminal AM are proportional. (The maximum output voltage is 10VDC.)

## (3) Current monitoring reference (Pr. 56)



- Set the current to be referenced when the current monitor (inverter output current, etc.) is selected for the terminal CA and terminal AM display.
- Set the current value when the current output at terminal CA is 20mADC.  
The analog current output and current value at terminal CA are proportional. (The maximum output current is 20mADC.)
- Set the current value when the voltage output at terminal AM is 10VDC.  
The analog voltage output and current value at terminal AM are proportional. (The maximum output voltage is 10VDC.)

## (4) Terminal AM response adjustment (Pr.867)

- Using Pr. 867, the output voltage response of the terminal AM can be adjusted within the range 0 to 5s.
- Increasing the setting stabilizes the terminal AM output more but reduces the response level. (Setting "0" sets the response level to 7ms)

## (5) Adjustment of response level of terminal CA (Pr.869)

- The response level of the output current of the terminal CA can be adjusted between 0 and 5s with Pr. 869.
- Increasing the setting stabilizes the terminal CA output more but reduces the response level. (Setting "0" sets the response level to about 7ms.)

### ◆ Parameters referred to ◆

Pr. 37 Speed display Refer to page 104

### 3.10.4 Terminal CA, AM calibration (Calibration parameter C0 (Pr. 900), C1 (Pr. 901), C8 (pr.930) to C11 (Pr. 931))

The operation panel and parameter unit can be used to calibrate the full scales of the terminals CA and AM.

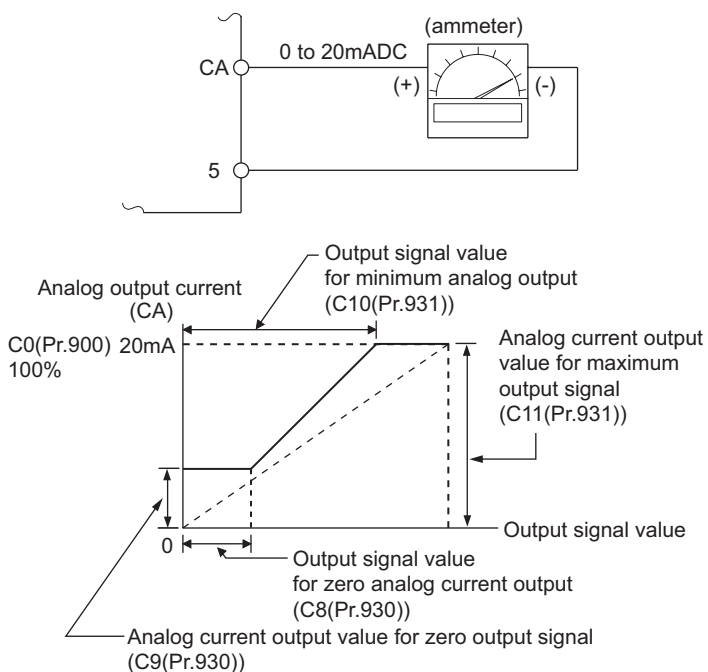
| Parameter Number | Name                        | Initial Value | Setting Range | Description                                                       |
|------------------|-----------------------------|---------------|---------------|-------------------------------------------------------------------|
| C0(900)          | CA terminal calibration     | —             | —             | Calibrate the scale of the meter connected to terminal CA.        |
| C1(901)          | AM terminal calibration     | —             | —             | Calibrate the scale of the analog meter connected to terminal AM. |
| C8(930)          | Current output bias signal  | 0%            | 0 to 100%     | Output signal value for minimum analog current output             |
| C9(930)          | Current output bias current | 0%            | 0 to 100%     | Output current value for minimum analog current output            |
| C10(931)         | Current output gain signal  | 100%          | 0 to 100%     | Output signal value for maximum analog current output             |
| C11(931)         | Current output gain current | 100%          | 0 to 100%     | Output current value for maximum analog current output            |

\*1 The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145.)

\*2 The parameter number in parentheses is the one for use with the parameter unit (FR-PU04).

\*3 The above parameters allow its setting to be changed during operation in any operation mode even if "0" (initial value) is set in Pr. 77 Parameter write selection.

#### (1) CA terminal calibration ( C0(Pr. 900), C8(Pr. 930) to C11(Pr. 931) )



- Terminal CA is factory-set to provide a 20mADC output in the full-scale status of the corresponding monitor item. Calibration parameter C0 (Pr. 900) allows the output current ratios (gains) to be adjusted according to the meter scale. Note that the maximum output current is 20mADC.
- Use calibration parameters C8(Pr. 930) and C9(Pr. 930) to set a value for zero analog current output (meter points zero). In addition, use calibration parameters C10(Pr. 931) and C11(Pr. 931) to set a value for maximum analog current output.
- Use calibration parameters C8(Pr. 930) and C10(Pr. 931) to set output signal values (monitor output set in Pr. 54) when the current output at terminal CA is zero or maximum. At this time, the full-scale of each monitor is 100%. (Refer to page 109)
- Use calibration parameters C9(Pr. 930) and C11(Pr. 931) to set the current output values at terminal CA when the output signal value (monitor output set in Pr. 54) is zero or maximum. At this time, the current output calibrated using calibration parameter C0(Pr.900) is 100%.

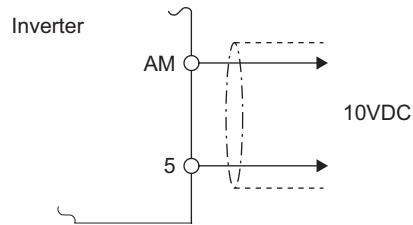
- Calibrate CA terminal in the following procedure.

- 1) Connect a 0-20mADC meter (DC ammeter) to across inverter terminals CA-5. (Note the polarity. Terminal CA is plus.)
- 2) Set calibration parameters C8(Pr. 930) to C11 (Pr. 931) to initial values. (When the meter needle does not point to 0, calibrate using C8(Pr. 930) and C9(Pr. 930))
- 3) Refer to the output signal list (page 109) to set Pr. 54.  
When running frequency, inverter output current or the like has been selected as the output signal, preset in Pr. 55 or Pr. 56 the running frequency or current value at which the output signal is 20mA.
- 4) Run the inverter. (The inverter may be run in either the PU or external operation mode.)
- 5) Use calibration parameter C0(Pr.900) to set the meter needle to point to full-scale.

#### Remarks

- When outputting the item that cannot achieve a 100% value easily by operation, e.g. output current, set "21" (reference voltage output) in Pr. 54 and perform calibration. (20mADC is output at terminal CA.)
- Even when calibration parameters are set as C8(Pr.930) ≥ C10(Pr.931) and C9(Pr.930) ≥ C11(Pr.931), current can be output at terminal CA.

## (2) AM terminal calibration (C1(Pr.901))



- Terminal AM is factory-set to provide a 10VDC output in the full-scale status of the corresponding monitor item. Calibration parameter C1 (Pr. 901) allows the output voltage ratios (gains) to be adjusted according to the meter scale. Note that the maximum output voltage is 10VDC.

- Calibrate the AM terminal in the following procedure.
  - 1) Connect a 0-10VDC meter (frequency meter) to across inverter terminals AM-5. (Note the polarity. The terminal AM is positive.)
  - 2) Refer to the output signal list (page 109) and set *Pr. 158*.  
When you selected the running frequency or inverter output current as the output signal, preset the running frequency or current value, at which the output signal will be 10V, to *Pr. 55* or *Pr. 56*.
  - 3) When outputting the item that cannot achieve a 100% value easily by operation, e.g. output current, set "21" (reference voltage output) in *Pr. 158* and perform the following operation. After that, set "2" (output current, for example) in *Pr. 158*.

### REMARKS

- When outputting such an item as the output current, which cannot reach a 100% value easily by operation, set *Pr. 54* to "21" (reference voltage output) and make calibration. 10VDC is output from the terminal AM.

### (3) How to calibrate the terminal CA when using the operation panel (FR-DU07)

| Operation                                                                                                                        | Display                                                                  |
|----------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------|
| 1. Confirmation of the RUN indication and operation mode indication                                                              | (When Pr. 54=1)<br>                                                      |
| 2. Press <b>(MODE)</b> to choose the parameter setting mode.                                                                     | (The parameter number read previously appears.)                          |
| 3. Turn <b>(C0)</b> until <b>C. . .</b> appears.                                                                                 | (C0 to C11 setting is enabled.)                                          |
| 4. Press <b>(SET)</b> to display <b>C. - - -</b> .                                                                               |                                                                          |
| 5. Turn <b>(C0)</b> until <b>C. 0</b> appears.<br>Set to C0 CA terminal calibration.                                             |                                                                          |
| 6. Press <b>(SET)</b> to enable setting.                                                                                         | (The monitor set to Pr. 54 CA terminal function selection is displayed.) |
| 7. If the inverter is at a stop, (press <b>(FWD)</b> or <b>(REV)</b> ) to start the inverter.<br>(Motor needs not be connected.) |                                                                          |
| 8. Turn <b>(C0)</b> to adjust the indicator needle to the desired position.                                                      | Analog indicator                                                         |
| 9. Press <b>(SET)</b> . Setting is complete.                                                                                     |                                                                          |

**Flicker...Parameter setting complete!!**

- By turning **(C0)**, you can read another parameter.
- Press **(SET)** to return to the **C. - - -** indication (step 4).
- Press **(SET)** twice to show the next parameter (**P. C. L.**).

#### REMARKS

- Calibration can also be made for external operation. Set the frequency in external operation mode, and make calibration in the above procedure.
- Calibration can be made even during operation.
- For the operation procedure using the parameter unit (FR-PU04), refer to the parameter unit instruction manual.

#### ◆ Parameters referred to ◆

Pr. 54 CA terminal function selection Refer to page 109  
 Pr. 55: Frequency monitoring reference Refer to page 109  
 Pr.56 Current monitoring reference Refer to page 109  
 Pr.158 AM terminal function selection Refer to page 109



### 3.11 Operation selection at power failure and instantaneous power failure

| Purpose                                                                                 | Parameter that must be set                                                   | Refer to Page                                        |
|-----------------------------------------------------------------------------------------|------------------------------------------------------------------------------|------------------------------------------------------|
| At instantaneous power failure occurrence, restart inverter without stopping motor      | Automatic restart operation after instantaneous power failure / flying start | Pr. 57, Pr. 58, Pr. 162 to Pr. 165, Pr. 299, Pr. 611 |
| When undervoltage or a power failure occurs, the inverter can be decelerated to a stop. | Power failure-time deceleration-to-stop function                             | Pr. 261 to Pr. 266                                   |

#### 3.11.1 Automatic restart after instantaneous power failure / flying start (Pr. 57, Pr. 58, Pr. 162 to Pr. 165, Pr. 299, Pr. 611)

You can restart the inverter without stopping the motor in the following cases.

- when commercial power supply operation is switched to inverter operation
- when power comes back on after an instantaneous power failure
- when motor is coasting at start

Pr. 56  
page 109

Pr. 59  
page 77

Pr. 161  
page 220

Pr. 268  
page 105

Pr. 331  
page 167

Pr. 166  
page 101

Pr. 557  
page 189

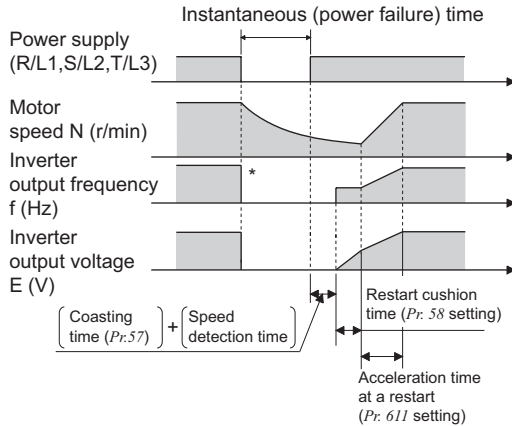
Pr. 867  
page 109

| Parameter Number | Name                                                          | Initial Value<br>200V class<br>(400V class) | Setting Range<br>200V class<br>(400V class) | Description<br>200V class (400V class)                                                                                                                                                    |
|------------------|---------------------------------------------------------------|---------------------------------------------|---------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 57               | Restart coasting time                                         | 9999                                        | 0                                           | 00077 (00038) or less.....0.5s,<br>00105 to 00340 (00052 to 00170) .1s,<br>00490 to 02330 (00250 to 01160) 3.0s,<br>03160 (01800) or more .....5.0s<br>The above times are coasting time. |
|                  |                                                               |                                             | 02330<br>(01160) or<br>less                 | 0.1 to<br>5s                                                                                                                                                                              |
|                  |                                                               |                                             | 03160<br>(01800) or<br>more                 | 0.1 to<br>30s                                                                                                                                                                             |
|                  |                                                               |                                             | 9999                                        | No restart                                                                                                                                                                                |
| 58               | Restart cushion time                                          | 1s                                          | 0 to 60s                                    | Set a voltage starting time at restart.                                                                                                                                                   |
| 162              | Automatic restart after instantaneous power failure selection | 0                                           | 0                                           | With frequency search                                                                                                                                                                     |
|                  |                                                               |                                             | 1                                           | Without frequency search (Reduced voltage system)                                                                                                                                         |
|                  |                                                               |                                             | 10                                          | Frequency search at every start                                                                                                                                                           |
|                  |                                                               |                                             | 11                                          | Reduced voltage system at every start                                                                                                                                                     |
| 163              | First cushion time for restart                                | 0s                                          | 0 to 20s                                    | Set a voltage starting time at restart.                                                                                                                                                   |
| 164              | First cushion voltage for restart                             | 0%                                          | 0 to 100%                                   | Consider using these parameters according to the load (moment of inertia, torque) magnitude.                                                                                              |
| 165              | Stall prevention operation level for restart                  | 110%*1                                      | 0 to 120%*1                                 | Consider the rated inverter current as 100% and set the stall prevention operation level during restart operation.                                                                        |
| 299              | Rotation direction detection selection at restarting          | 9999                                        | 0                                           | without rotation direction detection                                                                                                                                                      |
|                  |                                                               |                                             | 1                                           | with rotation direction detection                                                                                                                                                         |
|                  |                                                               |                                             | 9999                                        | When Pr. 78="0", the rotation direction is detected.<br>When Pr. 78="1","2", the rotation direction is not detected.                                                                      |
| 611              | Acceleration time at a restart                                | 02330<br>(01160) or<br>less                 | 5s                                          | Set the acceleration time to reach the set frequency at a restart.<br>Acceleration time for restart is the normal acceleration time (e.g. Pr. 7) when "9999" is set.                      |
|                  |                                                               | 03160<br>(01800) or<br>more                 | 15s                                         |                                                                                                                                                                                           |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

\*1 When Pr. 570 Multiple rating setting = "1", performing parameter clear changes the initial value and setting range. (Refer to page 66.)

**When Pr. 162 = 0, 10 (with frequency search)**



\* The output shut off timing differs according to the load condition.

**(1) Automatic restart operation selection (Pr.162, Pr. 299)**

**With frequency search**

- When "0" (initial value), "10" is set in Pr. 162, the inverter smoothly starts after detecting the motor speed upon power restoration.
- During reverse rotation, the inverter can be restarted smoothly as the direction of rotation is detected.
- You can select whether to make rotation direction detection or not with Pr. 299 "Rotation direction detection selection at restarting". When capacities of the motor and inverter differ, set "0" (without rotation direction detection) in Pr. 299.

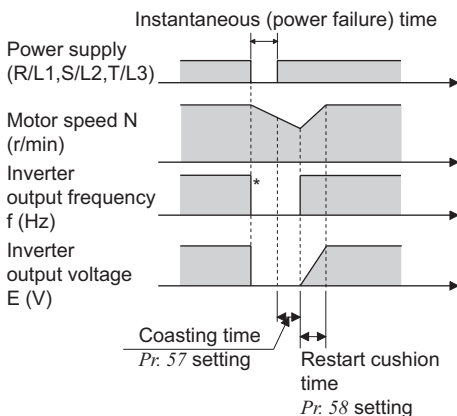
| Pr.299 setting       | Pr.78 setting |   |   |
|----------------------|---------------|---|---|
|                      | 0             | 1 | 2 |
| 9999 (initial value) | ○             | × | × |
| 0                    | ×             | × | × |
| 1                    | ○             | ○ | ○ |

○:with rotation direction detection  
×:with rotation direction detection

**REMARKS**

- When the inverter capacity is two rank or more larger than the motor capacity, the inverter may not start due to overcurrent (OCT) alarm.
- If two or more motors are connected to one inverter, the inverter functions abnormally. (The inverter does not start smoothly.)
- Since the DC injection brake is operated instantaneously when the speed is detected at a restart, the speed may reduce if the inertia moment (J) of the load is small.
- When reverse rotation is detected when Pr. 78="1" (reverse rotation disabled), the rotation direction is changed to forward rotation after decelerates in reverse rotation when the start command is forward rotation. The inverter will not start when the start command is reverse rotation.

**When Pr. 162 = 1, 11 (without frequency search)**



\* The output shut off timing differs according to the load condition.

**Without frequency search**

- When Pr. 162 = "1" or "11", automatic restart operation is performed in a reduced voltage system, where the voltage is gradually risen with the output frequency unchanged from prior to an instantaneous power failure independently of the coasting speed of the motor.

**REMARKS**

- This system stores the output frequency prior to an instantaneous power failure and increases the voltage. Therefore, if the instantaneous power failure time exceeds 0.2s, the inverter starts at Pr. 13 Starting frequency (initial value = 0.5Hz) since the stored output frequency cannot be retained.

**Restart operation at every start**

- When Pr. 162 = "10" or "11", automatic restart operation is also performed every start, in addition to the automatic restart after instantaneous power failure. When Pr. 162 = "0" or "1", automatic restart operation is performed at the first start after power supply-on, but the inverter starts at the starting frequency at the second time or later.

**(2) Restart coasting time (Pr. 57)**

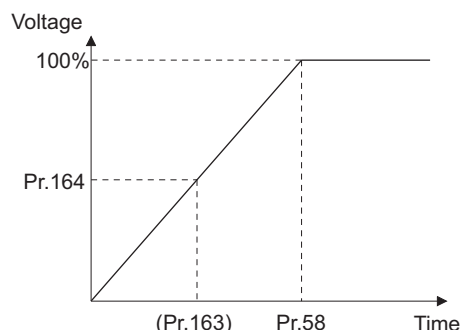
- Coasting time is the time from when the motor speed is detected until automatic restart control is started. Set Pr. 57 to "0" to perform automatic restart operation. The coasting time is automatically set to the value below. Generally this setting will pose no problems.

|               |               |                |                |               |
|---------------|---------------|----------------|----------------|---------------|
| 200V class    | 00077 or less | 00105 to 00340 | 00490 to 02330 | 03160 or more |
| 400V class    | 00038 or less | 00052 to 00170 | 00250 to 01160 | 01800 or more |
| Coasting time | 0.5s          | 1s             | 3s             | 5s            |

- Operation may not be performed well depending on the load inertia moment (J) magnitude or operation frequency. Adjust the coasting time between 0.1s and 5s according to the load specifications.

### (3) Restart cushion time (Pr. 58)

- Cushion time is the length of time taken to raise the voltage appropriate to the detected motor speed (output frequency prior to instantaneous power failure when Pr. 162 = "1" or "11").
- Normally the initial value need not be changed for operation, but adjust it according to the load inertia moment (J) or torque magnitude.



### (4) Automatic restart operation adjustment (Pr. 163 to Pr. 165, Pr. 611)

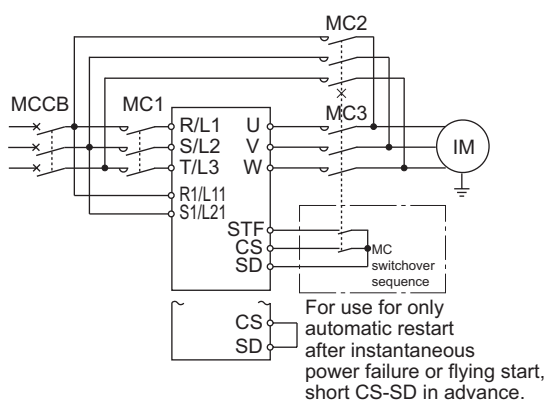
- Using Pr. 163 and Pr. 164, you can adjust the voltage rise time at a restart as shown on the left.
- Using Pr. 165, you can set the stall prevention operation level at a restart.
- Using Pr. 611, you can set the acceleration time until the set frequency is reached after automatic restart operation is performed besides the normal acceleration time.

#### REMARKS

- If the setting of Pr. 21 Acceleration/deceleration time increments is changed, the setting increments of Pr. 611 does not change.

### (5) Connection (CS signal)

- When the automatic restart after instantaneous power failure selection signal (CS) is turned on, automatic restart operation is enabled.
- When Pr. 57 is set to other than "9999" (automatic restart operation enabled), the inverter will not operate if used with the CS signal remained off.



#### CAUTION

- The CS signal can be assigned to the input terminal using any of Pr. 178 to Pr. 189 (input terminal function selection). When terminal assignment is changed, the other functions may be affected. Please make setting after confirming the function of each terminal.
- When automatic restart operation is selected, undervoltage protection (E.UVT) and instantaneous power failure protection (E.IPF) among the alarm outut signals will not be provided at occurrence of an instantaneous power failure.
- The SU and FU signals are not output during a restart. They are output after the restart cushion time has elapsed.
- Automatic restart operation will also be performed after a reset made by an inverter reset is canceled or when a retry is made by the retry function.

## CAUTION

- ⚠ Provide mechanical interlocks for MC1 and MC2. The inverter will be damaged if the power supply is input to the inverter output section.
- ⚠ When automatic restart after instantaneous power failure has been selected, the motor and machine will start suddenly (after the reset time has elapsed) after occurrence of an instantaneous power failure. Stay away from the motor and machine. When you have selected automatic restart after instantaneous power failure function, apply in easily visible places the CAUTION stickers supplied to the instruction manual (basic).

#### ◆ Parameters referred to ◆

- Pr. 13 Starting frequency Refer to page 81
- Pr. 65, Pr. 67 to Pr. 69 Retry function Refer to page 119
- Pr. 78 Reverse rotation prevention selection Refer to page 145
- Pr. 178 to Pr. 189 (input terminal function selection) Refer to page 90

### 3.11.2 Power failure-time deceleration-to-stop function (Pr. 261 to Pr. 266)

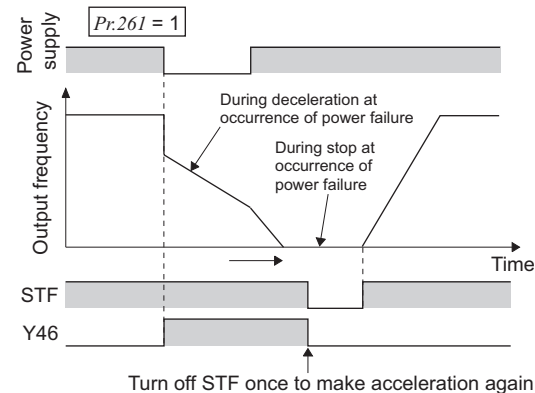
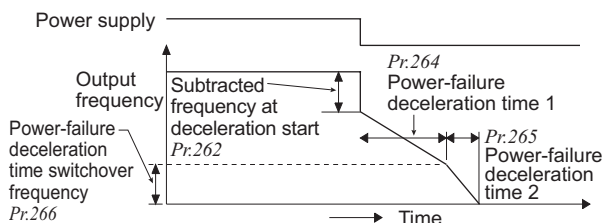
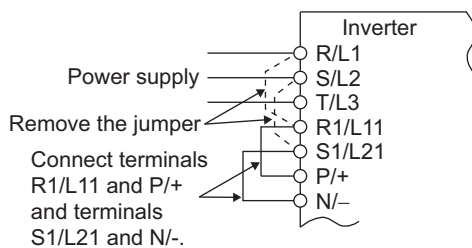
When a power failure or undervoltage occurs, the inverter can be decelerated to a stop or can be decelerated and re-accelerated to the set frequency.

Pr. 260  
page 129  
Pr. 267  
page 130

| Parameter Number | Name                                                 | Initial Value | Setting Range     | Description                                                                                                                                                                              |
|------------------|------------------------------------------------------|---------------|-------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 261              | Power failure stop selection                         | 0             | 0                 | Coasting to stop<br>When undervoltage or power failure occurs, the inverter output is shut off.                                                                                          |
|                  |                                                      |               | 1                 | When undervoltage or a power failure occurs, the inverter can be decelerated to a stop.                                                                                                  |
|                  |                                                      |               | 2                 | When undervoltage or a power failure occurs, the inverter can be decelerated to a stop.<br>If power is restored during a power failure, the inverter accelerates again.                  |
| 262              | Subtracted frequency at deceleration start           | 3Hz           | 0 to 20Hz         | Normally operation can be performed with the initial value unchanged. But adjust the frequency according to the magnitude of the load specifications (moment of inertia, torque).        |
| 263              | Subtraction starting frequency                       | 60Hz          | 0 to 120Hz        | When output frequency $\geq$ Pr. 263<br>Decelerate from the speed obtained from output frequency minus Pr. 262.<br>When output frequency $<$ Pr. 263<br>Decelerate from output frequency |
|                  |                                                      |               | 9999              | Decelerate from the speed obtained from output frequency minus Pr. 262.                                                                                                                  |
| 264              | Power-failure deceleration time 1                    | 5s            | 0 to 3600/ 360s * | Set a deceleration slope down to the frequency set in Pr. 266.                                                                                                                           |
| 265              | Power-failure deceleration time 2                    | 9999          | 0 to 3600/ 360s * | Set a deceleration slope below the frequency set in Pr. 266.                                                                                                                             |
|                  |                                                      |               | 9999              | Same slope as in Pr. 264                                                                                                                                                                 |
| 266              | Power failure deceleration time switchover frequency | 60Hz          | 0 to 400Hz        | Set the frequency at which the deceleration slope is switched from the Pr. 264 setting to the Pr. 265 setting.                                                                           |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

\* When the setting of Pr. 21 Acceleration/deceleration time increments is "0" (initial value), the setting range is "0 to 3600s" and the setting increments are "0.1s", and when the setting is "1", the setting range is "0 to 360s" and the setting increments are "0.01s"



#### (1) Connection and parameter setting

- Remove the jumpers across terminals R/L1-R1/L11 and across terminals S/L2-S1/L21, and connect terminals R1/L11 and P/+ and terminals S1/L21 and N/-.
- When Pr. 261 is set to "1" or "2", the inverter decelerates to a stop if an undervoltage or power failure occurs.

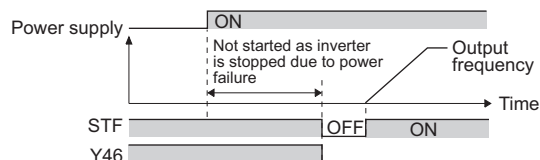
#### (2) Operation outline of deceleration to stop at power failure

- If an undervoltage or power failure occurs, the output frequency is dropped by the frequency set in Pr. 262.
- Deceleration is made in the deceleration time set in Pr. 264. (The deceleration time setting is the time required from Pr. 20 Acceleration/deceleration reference frequency to a stop.)
- When the frequency is low and enough regeneration energy is not provided, for example, the deceleration time (slope) from Pr. 265 to a stop can be changed.

#### (3) Power failure stop mode (Pr. 261 = "1")

- If power is restored during power failure deceleration, deceleration to a stop is continued and the inverter remains stopped. To restart, turn off the start signal once, then turn it on again.

#### REMARKS

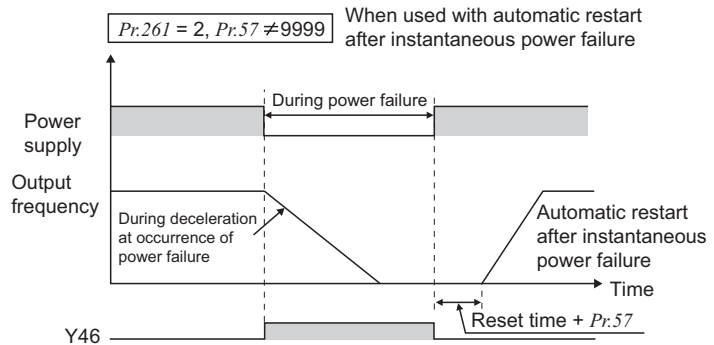
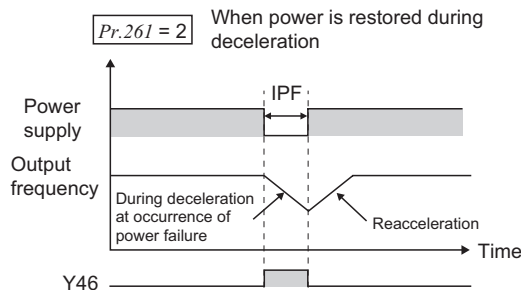


- When automatic restart after instantaneous power failure is selected (Pr. 57  $\neq$  "9999"), deceleration to stop function is invalid and the restart after instantaneous power failure operation is performed.
- After a power failure stop, the inverter will not start if the power supply is switched on with the start signal (STF/STR) input. After switching on the power supply, turn off the start signal once and then on again to make a start.



#### (4) Original operation continuation at instantaneous power failure function (*Pr. 261* = "2")

- When power is restored during deceleration after an instantaneous power failure, acceleration is made again up to the set frequency.
- When this function is used in combination with the automatic restart after instantaneous power failure operation, deceleration can be made at a power failure and acceleration can be made again after power restoration. When power is restored after a stop by deceleration at an instantaneous power failure, automatic restart operation is performed if automatic restart after instantaneous power failure has been selected (*Pr. 57* ≠ "9999")



#### (5) Power failure deceleration signal (Y46 signal)

- The Y46 signal is on during deceleration at an instantaneous power failure or during a stop after deceleration at an instantaneous power failure.
- For the Y46 signal, set "46 (forward action)" or "146 (reverse action)" in any of *Pr. 190* to *Pr. 196* (output terminal function selection) to assign the function.

#### REMARKS

When *Pr. 872* = "1" (input phase failure protection provided) and *Pr. 261* ≠ "0" (power failure stop function valid), input phase failure protection (E.I.LF) is not provided but power-failure deceleration is made.

#### CAUTION

- When *Pr. 30 Regenerative function selection* = "2" (FR-HC, MT-HC, FR-CV is used), the power failure deceleration function is invalid.
- When the (output frequency - *Pr. 262*) at undervoltage or power failure occurrence is negative, the calculation result is regarded as 0Hz. (DC injection brake operation is performed without deceleration).
- During a stop or error, the power failure stop selection is not performed.
- Changing the terminal assignment using *Pr. 190* to *Pr. 196* (output terminal function selection) may affect the other functions. Please make setting after confirming the function of each terminal.

## ⚠ CAUTION

- ⚠ If power-failure deceleration operation is set, some loads may cause the inverter to trip and the motor to coast. The motor will coast if enough regenerative energy is given from the motor.

#### ◆ Parameters referred to ◆

*Pr. 12* DC injection brake operation voltage Refer to page 86

*Pr. 20* Acceleration/deceleration reference frequency, *Pr. 21* Acceleration/deceleration time increments Refer to page 79

*Pr. 30* Regenerative function selection Refer to page 88

*Pr. 57* Restart coasting time Refer to page 114

*Pr. 190* to *Pr. 196* (output terminal function selection) Refer to page 96

## 3.12 Operation setting at alarm occurrence

| Purpose                                        | Parameter that must be set                      |                       | Refer to Page |
|------------------------------------------------|-------------------------------------------------|-----------------------|---------------|
| Recover by retry operation at alarm occurrence | Retry operation                                 | Pr.65, Pr.67 to Pr.69 | 119           |
| Output alarm code from terminal                | Alarm code output function                      | Pr.76                 | 121           |
| Do not input/output phase failure alarm        | Input/output phase failure protection selection | Pr.251, Pr.872        | 122           |

### 3.12.1 Retry function (Pr. 65, Pr. 67 to Pr.69)

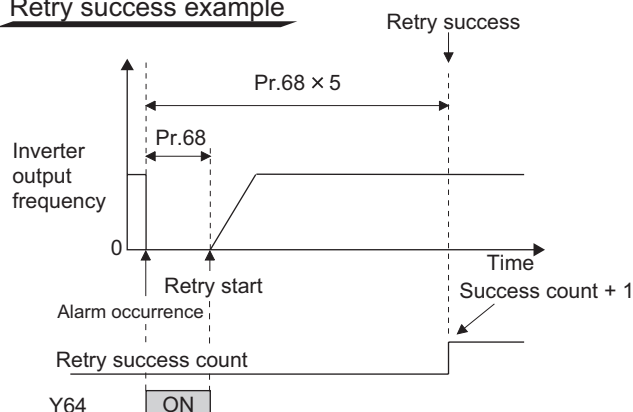
If an alarm occurs, the inverter resets itself automatically to restart. You can also select the alarm description for a retry.

When automatic restart after instantaneous power failure is selected (Pr. 57 Restart coasting time ≠ "9999"), restart operation is performed at retry operation as at an instantaneous power failure. (Refer to page 114 for the restart function.)

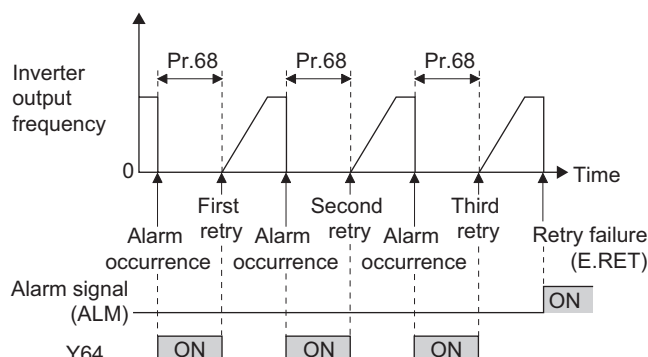
| Parameter Number | Name                                  | Initial Value | Setting Range | Description                                                                                                                                                   |
|------------------|---------------------------------------|---------------|---------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 65               | Retry selection                       | 0             | 0 to 5        | An alarm for retry can be selected. (Refer to the next page)                                                                                                  |
| 67               | Number of retries at alarm occurrence | 0             | 0             | No retry function                                                                                                                                             |
|                  |                                       |               | 1 to 10       | Set the number of retries at alarm occurrence. An alarm output is not provided during retry operation.                                                        |
|                  |                                       |               | 101 to 110    | Set the number of retries at alarm occurrence. (The setting value of minus 100 is the number of retries.) An alarm output is provided during retry operation. |
| 68               | Retry waiting time                    | 1s            | 0 to 10s      | Set the waiting time from when an inverter alarm occurs until a retry is made.                                                                                |
| 69               | Retry count display erase             | 0             | 0             | Clear the number of restarts succeeded by retry.                                                                                                              |

The above parameters can be set when Pr. 160 User group read selection= "0". (Refer to page 145)

#### Retry success example



#### Retry failure example



- Retry operation automatically resets an alarm and restarts the inverter at the starting frequency when the time set in Pr. 68 elapses after the inverter stopped due to the alarm.
- Retry operation is performed by setting Pr. 67 to any value other than "0". Set the number of retries at alarm occurrence in Pr. 67.
- When retries fail consecutively more than the number of times set in Pr. 67, a retry count excess alarm (E.RET) occurs, stopping the inverter output. (Refer to retry failure example)
- Use Pr. 68 to set the waiting time from when an inverter alarm occurs until a retry is made in the range 0 to 10s.
- Reading the Pr. 69 value provides the cumulative number of successful restart times made by retry. The cumulative count in Pr. 69 is increased by 1 when a retry is regarded as successful after normal operation continues without alarms occurring for more than four times longer than the time set in Pr. 68 after a retry start.
- Writing "0" in Pr. 69 clears the cumulative count.
- During a retry, the Y64 signal is on. For the Y64 signal, assign the function by setting "64 (positive operation)" or "164 (negative operation)" in any of Pr. 190 to Pr. 196 (output terminal function selection).

#### CAUTION

When terminal assignment is changed using Pr. 190 to Pr. 196, the other functions may be affected. Please make setting after confirming the function of each terminal.

Pr.60  
page 123

Pr.66  
page 61

Pr. 71  
page 85

- Using *Pr. 65* you can select the alarm that will cause a retry to be executed. No retry will be made for the alarm not indicated. (Refer to *page 231* for the alarm description.)
- indicates the errors selected for retry.

| Alarm Display for Retry | Pr. 65 Setting |   |   |   |   |   |
|-------------------------|----------------|---|---|---|---|---|
|                         | 0              | 1 | 2 | 3 | 4 | 5 |
| E.OC1                   | ●              | ● |   | ● | ● | ● |
| E.OC2                   | ●              | ● |   | ● | ● |   |
| E.OC3                   | ●              | ● |   | ● | ● | ● |
| E.OV1                   | ●              |   | ● | ● | ● |   |
| E.OV2                   | ●              |   | ● | ● | ● |   |
| E.OV3                   | ●              |   | ● | ● | ● |   |
| E.THM                   | ●              |   |   |   |   |   |
| E.THT                   | ●              |   |   |   |   |   |
| E.IPF                   | ●              |   |   |   | ● |   |
| E.UVT                   | ●              |   |   |   | ● |   |
| E.BE                    | ●              |   |   |   | ● |   |

| Alarm Display for Retry | Pr. 65 Setting |   |   |   |   |   |
|-------------------------|----------------|---|---|---|---|---|
|                         | 0              | 1 | 2 | 3 | 4 | 5 |
| E. GF                   | ●              |   |   |   | ● |   |
| E.OHT                   | ●              |   |   |   |   |   |
| E.OLT                   | ●              |   |   |   | ● |   |
| E.OPT                   | ●              |   |   |   | ● |   |
| E.OP1                   | ●              |   |   |   | ● |   |
| E. PE                   | ●              |   |   |   | ● |   |
| E.PTC                   | ●              |   |   |   |   |   |
| E.CDO                   | ●              |   |   |   | ● |   |
| E.SER                   | ●              |   |   |   | ● |   |
| E.ILF                   | ●              |   |   |   | ● |   |

### CAUTION

- For a retry error, only the description of the first alarm is stored.
- When an inverter alarm is reset by the retry function at the retry time, the accumulated data of the electronic thermal relay function, regeneration converter duty etc. are not cleared. (Different from the power-on reset.)

## CAUTION

-  When you have selected the retry function, stay away from the motor and machine unless required. They will start suddenly (after the reset time has elapsed) after occurrence of an alarm.
- When you have selected the retry function, apply in easily visible places the CAUTION stickers supplied.

### ◆ Parameters referred to ◆

*Pr. 57 Restart coasting time*  Refer to *page 114*

### 3.12.2 Alarm code output selection (Pr.76)

At alarm occurrence, its description can be output as a 4-bit digital signal from the open collector output terminals.

The alarm code can be read by a programmable controller, etc., and its corrective action can be shown on a display, etc.

**Pr. 75**  
page 141  
**Pr. 77**  
page 144

| Parameter Number | Name                        | Initial Value | Setting Range | Description                                                               |
|------------------|-----------------------------|---------------|---------------|---------------------------------------------------------------------------|
| 76               | Alarm code output selection | 0             | 0             | Without alarm code output                                                 |
|                  |                             |               | 1             | With alarm code output<br>(Refer to the following table)                  |
|                  |                             |               | 2             | Alarm code output at alarm occurrence only (Refer to the following table) |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

#### (1) Alarm code output function

- By setting Pr. 76 to "1" or "2", the alarm code can be output to the output terminals.
- When the setting is "2", an alarm code is output at only alarm occurrence, and during normal operation, the terminals output the signals assigned to Pr. 190 to Pr. 196 (output terminal function selection).
- The following table indicates alarm codes to be output. (0: output transistor off, 1: output transistor on)

| Operation Panel Indication (FR-DU07) | Output of Output Terminals |     |    |    | Alarm Code |
|--------------------------------------|----------------------------|-----|----|----|------------|
|                                      | SU                         | IPF | OL | FU |            |
| Normal *                             | 0                          | 0   | 0  | 0  | 0          |
| E.OC1                                | 0                          | 0   | 0  | 1  | 1          |
| E.OC2                                | 0                          | 0   | 1  | 0  | 2          |
| E.OC3                                | 0                          | 0   | 1  | 1  | 3          |
| E.OV1 to E.OV3                       | 0                          | 1   | 0  | 0  | 4          |
| E.THM                                | 0                          | 1   | 0  | 1  | 5          |
| E.THT                                | 0                          | 1   | 1  | 0  | 6          |
| E.IPF                                | 0                          | 1   | 1  | 1  | 7          |
| E.UVT                                | 1                          | 0   | 0  | 0  | 8          |
| E.FIN                                | 1                          | 0   | 0  | 1  | 9          |
| E. BE                                | 1                          | 0   | 1  | 0  | A          |
| E. GF                                | 1                          | 0   | 1  | 1  | B          |
| E.OHT                                | 1                          | 1   | 0  | 0  | C          |
| E.OLT                                | 1                          | 1   | 0  | 1  | D          |
| E.OPT                                | 1                          | 1   | 1  | 0  | E          |
| E.OP1                                | 1                          | 1   | 1  | 0  | E          |
| Other than the above                 | 1                          | 1   | 1  | 1  | F          |

\* When Pr. 76 = "2", the output terminals output the signals assigned to Pr. 190 to Pr. 196 .

#### CAUTION

- Refer to page 188 for details of alarm code.
- When "1 or 2" is set in Pr. 76.

When an alarm occurs, the output terminals SU, IPF, OL, FU output the signal in the above table, independently of the Pr. 190 to Pr. 196 (output terminal function selection) settings. Please be careful when inverter control setting has been made with the outut signals of Pr. 190 to Pr. 196.

#### ◆ Parameters referred to ◆

Pr. 190 to Pr. 196 (output terminal function selection) Refer to page 96

### 3.12.3 Input/output phase failure protection selection (Pr.251, Pr.872)

Pr. 250  
page 89

Pr. 252  
page 132

Pr. 867  
page 109

Pr. 882  
page 211

You can disable the output phase failure function that stops the inverter output if one of the inverter output side (load side) three phases (U, V, W) opens.

The input phase failure protection selection of the inverter input side (R/L1, S/L2, T/L3) can be made valid.

| Parameter Number | Name                                      | Initial Value | Setting Range | Description                             |
|------------------|-------------------------------------------|---------------|---------------|-----------------------------------------|
| 251              | Output phase failure protection selection | 1             | 0             | Without output phase failure protection |
|                  |                                           |               | 1             | With output phase failure protection    |
| 872              | Input phase failure protection selection  | 0             | 0             | Without input phase failure protection  |
|                  |                                           |               | 1             | With input phase failure protection     |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

#### (1) Output phase failure protection selection (Pr.251)

- When Pr. 251 is set to "0", output phase failure protection (E.LF) becomes invalid.

#### (2) Input phase failure protection selection (Pr.872)

- When Pr. 872 is set to "1", input phase failure protection (E.ILF) is provided if a phase failure of one phase among the three phases is detected for 1s continuously.

#### REMARKS

If an input phase failure has occurred when Pr. 872 = "1" (input phase failure protected) and a value other than "0" (power failure stop function valid) is set in Pr. 261, input phase failure protection (E.ILF) is not provided but power-failure deceleration is made.

#### CAUTION

- When an input phase failure occurs in the R/L1 and S/L2 phases, input phase failure protection is not provided but the inverter output is shut off.
- If an input phase failure continues for a long time, the converter section and capacitor lives of the inverter will be shorter.

### 3.13 Energy saving operation and energy saving monitor

| Purpose                      | Parameter that must be set                             |                                        | Refer to Page |
|------------------------------|--------------------------------------------------------|----------------------------------------|---------------|
| Energy saving operation      | Energy saving operation and optimum excitation control | Pr.60                                  | 123           |
| How much energy can be saved | Energy saving monitor                                  | Pr.52, Pr.54, Pr.158, Pr.891 to Pr.899 | 124           |

#### 3.13.1 Energy saving control and optimum excitation control (Pr.60)

Without a fine parameter setting, the inverter automatically performs energy saving control.  
This inverter is optimum for fan and pump applications.

Pr. 59  
page 77

Pr. 65  
page 119

| Parameter Number | Name                            | Initial Value | Setting Range | Description                     |
|------------------|---------------------------------|---------------|---------------|---------------------------------|
| 60               | Energy saving control selection | 0             | 0             | Normal operation mode           |
|                  |                                 |               | 4             | Energy saving operation mode    |
|                  |                                 |               | 9             | Optimum excitation control mode |

#### (1) Energy saving operation mode (Setting "4")

- When "4" is set in *Pr. 60*, the inverter operates in the energy saving operation mode.
- In the energy saving operation mode, the inverter automatically controls the output voltage to minimize the inverter output voltage during a constant operation.

##### REMARKS

- When the energy saving mode is selected, the *Pr. 0 Torque boost* and *Pr. 14 Load pattern selection* settings are made invalid to automatically control the output voltage.
- For applications a large load torque is applied to or machines repeat frequent acceleration/deceleration, an energy saving effect is not expected.

#### (2) Optimum excitation control mode (Setting "9")

- When "9" is set in *Pr. 60*, the inverter operates in the optimum excitation control mode.
- The optimum excitation control mode is a control system which controls excitation current to improve the motor efficiency to maximum and determines output voltage as an energy saving method.

##### REMARKS

- When the motor capacity is too small as compared to the inverter capacity or two or more motors are connected to the inverter, the energy saving effect is not expected.

#### CAUTION

- When the energy saving mode and optimum excitation control mode are selected, deceleration time may be longer than the setting value. Since overvoltage alarm tends to occur as compared to the constant torque load characteristics, set a longer deceleration time.
- The energy saving operation mode and optimum excitation control function only under V/F control. When a value other than "9999" is set in *Pr. 80 Motor capacity (simple magnetic flux vector control)*, the energy saving mode and optimum excitation control are invalid.

#### ◆ Parameters referred to

*Pr.0 Torque boost* Refer to page 58

*Pr.14 Load pattern selection* Refer to page 65

*Pr.80 Motor capacity (simple magnetic flux vector control)* Refer to page 59

### 3.13.2 Energy saving monitor (Pr. 891 to Pr. 899)

From the power consumption estimated value during commercial power supply operation, the energy saving effect by use of the inverter can be monitored/output.

Pr.51  
page 83

Pr.55  
page 109

Pr.157  
page 61

Pr.159  
page 197

Pr.889  
page 219

Pr.990  
page 222

| Parameter Number | Name                                                       | Initial Value                          | Setting Range<br>200V class (400V class)          |             | Description                                                                                                                                              |
|------------------|------------------------------------------------------------|----------------------------------------|---------------------------------------------------|-------------|----------------------------------------------------------------------------------------------------------------------------------------------------------|
| 52               | DU/PU main display data selection                          | 0<br>(output frequency)                | 0, 5, 6, 8 to 14, 17, 20, 23 to 25, 50 to 57, 100 |             | 50:Power saving monitor<br>51:Cumulative saving power monitor                                                                                            |
| 54               | CA terminal function selection                             | 1<br>(output frequency)                | 1 to 3, 5, 6, 8 to 14, 17, 21, 24, 50, 52, 53     |             | 50:Power saving monitor                                                                                                                                  |
| 158              | AM terminal function selection                             |                                        |                                                   |             |                                                                                                                                                          |
| 891              | Cumulative power monitor digit shifted times               | 9999                                   | 0 to 4                                            |             | Set the number of times to shift the cumulative power monitor digit<br>Clamp the monitoring value at maximum.                                            |
|                  |                                                            |                                        | 9999                                              |             | No shift<br>Clear the monitor value when it exceeds the maximum value.                                                                                   |
| 892              | Load factor                                                | 100%                                   | 30 to 150%                                        |             | Set the load factor for commercial power-supply operation. Multiplied by the power consumption rate (page 127) during commercial power supply operation. |
| 893              | Energy saving monitor reference (motor capacity)           | SLD/LD value of Applied moter Capacity | 02330<br>(01160) or less                          | 0.1 to 55kW | Set the motor capacity (pump capacity). Set when calculating power saving rate, average power saving rate value, commercial operation power.             |
|                  |                                                            |                                        | 03160<br>(01800) or more                          | 0 to 3600kW |                                                                                                                                                          |
| 894              | Control selection during commercial power-supply operation | 0                                      | 0                                                 |             | Discharge damper control (fan)                                                                                                                           |
|                  |                                                            |                                        | 1                                                 |             | Inlet damper control (fan)                                                                                                                               |
|                  |                                                            |                                        | 2                                                 |             | Valve control (pump)                                                                                                                                     |
|                  |                                                            |                                        | 3                                                 |             | Commercial power-supply drive (fixed value)                                                                                                              |
| 895              | Power saving rate reference value                          | 9999                                   | 0                                                 |             | Consider the value during commercial power-supply operation as 100%                                                                                      |
|                  |                                                            |                                        | 1                                                 |             | Consider the Pr. 893 setting as 100%.                                                                                                                    |
|                  |                                                            |                                        | 9999                                              |             | No function                                                                                                                                              |
| 896              | Power unit cost                                            | 9999                                   | 0 to 500                                          |             | Set the power unit cost. Display the power saving amount charge on the energy saving monitor.                                                            |
|                  |                                                            |                                        | 9999                                              |             | No function                                                                                                                                              |
| 897              | Power saving monitor average time                          | 9999                                   | 0                                                 |             | Average for 30 minutes                                                                                                                                   |
|                  |                                                            |                                        | 1 to 1000h                                        |             | Average for the set time                                                                                                                                 |
|                  |                                                            |                                        | 9999                                              |             | No function                                                                                                                                              |
| 898              | Power saving cumulative monitor clear                      | 9999                                   | 0                                                 |             | Cumulative monitor value clear                                                                                                                           |
|                  |                                                            |                                        | 1                                                 |             | Cumulative monitor value hold                                                                                                                            |
|                  |                                                            |                                        | 10                                                |             | Totalization continued (communication data upper limit 9999)                                                                                             |
|                  |                                                            |                                        | 9999                                              |             | Totalization continued (communication data upper limit 65535)                                                                                            |
| 899              | Operation time rate (estimated value)                      | 9999                                   | 0 to 100%                                         |             | Use for calculation of annual power saving amount. Set the annual operation ratio (consider 365 days × 24hr as 100%).                                    |
|                  |                                                            |                                        | 9999                                              |             | No function                                                                                                                                              |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

The above parameters allow its setting to be changed during operation in any operation mode even if "0" (initial value) is set in Pr. 77 Parameter write selection.

## (1) Energy saving monitor list

- The following provides the items that can be monitored by the power saving monitor (*Pr. 52, Pr. 54, Pr. 158* = "50").  
(Only 1) Power saving and 3) Power saving average value can be output to *Pr. 54* (terminal CA) and *Pr. 158* (terminal AM))

|    | Energy Saving Monitor Item        | Description and Formula                                                                                                                                                                                                       | Unit                  | Parameter Setting |               |               |               |
|----|-----------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------|-------------------|---------------|---------------|---------------|
|    |                                   |                                                                                                                                                                                                                               |                       | <i>Pr.895</i>     | <i>Pr.896</i> | <i>Pr.897</i> | <i>Pr.899</i> |
| 1) | Power saving                      | Difference between the estimated value of power necessary for commercial power supply operation and the input power calculated by the inverter<br><b>Power during commercial power supply operation – input power monitor</b> | 0.01kW/<br>0.1kW *3   | 9999              | —             | 9999          |               |
| 2) | Power saving rate                 | Ratio of power saving on the assumption that power during commercial power supply operation is 100%<br>$\frac{\text{1) Power saving}}{\text{Power during commercial power supply operation}} \times 100$                      | 0.1%                  | 0                 |               |               |               |
|    |                                   | Ratio of power saving on the assumption that <i>Pr. 893</i> is 100%<br>$\frac{\text{1) Power saving}}{\text{Pr.893}} \times 100$                                                                                              |                       | 1                 |               |               |               |
| 3) | Power saving average value        | Average value of power saving amount per hour during predetermined time ( <i>Pr. 897</i> )<br>$\frac{\sum (\text{1) Power saving} \times \Delta t)}{\text{Pr.897}}$                                                           | 0.01kWh<br>/0.1kWh *3 | 9999              | 9999          | 0 to 1000h    | —             |
| 4) | Power saving rate average value   | Ratio of power saving average value on the assumption that the value during commercial power supply operation is 100%<br>$\frac{\sum (\text{2) Power saving rate} \times \Delta t)}{\text{Pr.897}} \times 100$                | 0.1%                  | 0                 |               |               |               |
|    |                                   | Ratio of power saving average value on the assumption that <i>Pr. 893</i> is 100%<br>$\frac{\text{3) Power saving average value}}{\text{Pr.893}} \times 100$                                                                  |                       | 1                 |               |               |               |
| 5) | Power saving amount average value | Power saving average value represented in terms of charge<br><b>3) Power saving average value</b> × <i>Pr. 896</i>                                                                                                            | 0.01/0.1<br>*3        | —                 | 0 to 500      |               |               |

- The following shows the items which can be monitored by the cumulative saving power monitor (*Pr. 52* = "51").  
(The monitor value of the cumulative monitor can be shifted to the right with *Pr. 891* Cumulative power monitor digit shifted times.)

|    | Energy Saving Monitor Item        | Description and Formula                                                                                                                                                                                         | Unit                      | Parameter Setting |               |               |               |
|----|-----------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------|-------------------|---------------|---------------|---------------|
|    |                                   |                                                                                                                                                                                                                 |                           | <i>Pr.895</i>     | <i>Pr.896</i> | <i>Pr.897</i> | <i>Pr.899</i> |
| 6) | Power saving amount               | Power saving is added up per hour.<br>$\sum (\text{1) Power saving} \times \Delta t)$                                                                                                                           | 0.01kWh<br>/0.1kWh *1*2*3 | —                 | 9999          | —             | 9999          |
| 7) | Power saving amount charge        | Power saving amount represented in terms of charge<br><b>6) Power saving amount</b> × <i>Pr. 896</i>                                                                                                            | 0.01/0.1<br>*1*3          | —                 | 0 to 500      |               | 0 to 100%     |
| 8) | Annual power saving amount        | Estimated value of annual power saving amount<br>$\frac{\text{6) Power saving amount}}{\text{Operation time during accumulation of power saving amount}} \times 24 \times 365 \times \frac{\text{Pr.899}}{100}$ | 0.01kWh<br>/0.1kWh *1*2*3 | —                 | 9999          |               |               |
| 9) | Annual power saving amount charge | Annual power saving amount represented in terms of charge<br><b>8) Annual power saving amount</b> × <i>Pr. 896</i>                                                                                              | 0.01/0.1<br>*1*3          | —                 | 0 to 500      |               |               |

\*1 For communication (RS-485 communication, communication option), the display increments are 1. For example, the communication data is "10" for "10.00kWh".

\*2 When using the parameter unit (FR-PU04), "kW" is displayed.

\*3 The setting depends on capacities. (FR-F720-02330 (FR-F740-01160) or less/FR-F720-03160 (FR-F740-01800) or more)

### REMARKS

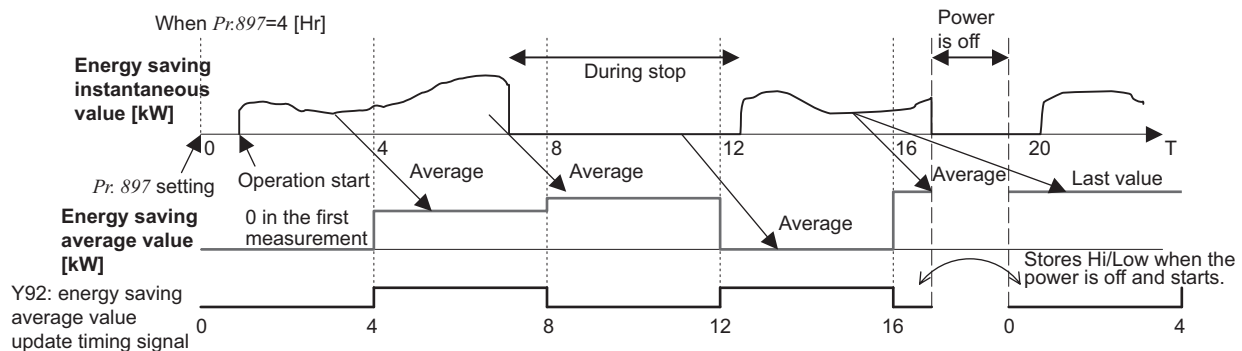
- As the operation panel (FR-DU07) is 4-digit display, it displays in 0.1 increments since a carry occurs, e.g. "100.0", when a monitor value in 0.01 increments exceeds "99.99". The maximum display is "9999".
- As the operation panel (FR-PU04) is 5-digit display, it displays in 0.1 increments since a carry occurs, e.g. "1000.0", when a monitor value in 0.01 increments exceeds "999.99". The maximum display is "99999".
- The upper limit of communication (RS-485 communication, communication option) is "65535" when *Pr. 898* Power saving cumulative monitor clear = "9999". The upper limit of 0.01 increments monitor is "655.35" and that of 0.1 increments monitor is "6553.5".

## (2) Power saving instantaneous monitor ( 1) Power savings, 2) Power saving rate )

- On the power saving monitor ( 1)), an energy saving effect as compared to the power consumption during commercial power supply operation (estimated value) is calculated and displays on the main monitor.
- In the following case, the power saving monitor ( 1)) is "0".
  - (a) Calculated values of the power saving monitor are negative values.
  - (b) During the DC injection brake operation
  - (c) Motor is not connected (output current monitor is 0A)
- On the power saving rate monitor ( 2)), setting "0" in *Pr. 895 Power saving rate reference value* displays the power saving rate on the assumption that power (estimated value) during commercial power supply operation is 100%. When *Pr. 895*="1", the power saving rate on the assumption that the *Pr. 893 Energy saving monitor reference (motor capacity)* value is 100% is displayed.

## (3) Power saving average value monitor ( 3) power saving average value, 4) average power saving rate value, 5) power saving amount average value)

- Power saving average value monitor can be displayed when a value other than "9999" is set in *Pr. 897 Power saving monitor average time*.
- The power saving average value monitor ( 3)) displays the average value per unit time of the power saving amount at averaging.
- The average value is updated every time an average time has elapsed after the *Pr. 897* setting is changed, power is turned on or the inverter is reset, assuming as a starting point. The power savings average value update timing signal (Y92) is inverted every time the average value is updated.



- The power saving average value monitor ( 4)) displays the average value per unit time of power saving rate ( 2)) at every average time by setting "0" or "1" in *Pr. 895 Power saving rate reference value*.
- By setting the charge (power unit) per 1kWh of power amount in *Pr. 896 Power unit cost*, the power saving amount average value monitor ( 5)) displays the charge relative to the power saving average value (power saving average value ( 3))  $\times$  *Pr. 896*).

## (4) Cumulative saving power monitor ( 6) power saving amount, 7) power saving amount charge, 8) annual power saving amount, 9) annual power saving amount charge)

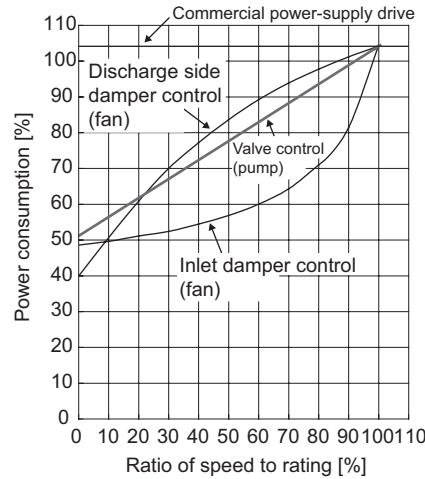
- On the cumulative saving power monitor, the monitor data digit can be shifted to the right by the number set in *Pr. 891 Cumulative power monitor digit shifted times*. For example, if the cumulative power value is 1278.56kWh when *Pr. 891* = "2", the PU/DU display is 12.78 (display in 100kWh increments) and the communication data is 12. If the maximum value is exceeded at *Pr. 891* = "0 to 4", the power is clamped at the maximum value, indicating that a digit shift is necessary. If the maximum value is exceeded at *Pr. 891* = "9999", the power returns to 0 and is recounted. The other monitors are clamped at the display maximum value.
- The cumulative saving power monitor ( 6)) can measure the power amount during a predetermined period. Measure according to the following steps
  - Write "9999" or "10" in *Pr. 898 Power saving cumulative monitor clear*.
  - Write "0" in *Pr. 898* at measurement start timing to clear the cumulative saving power monitor value and start totalization of power saving.
  - Write "1" in *Pr. 898* at measurement end timing to hold the cumulative saving power monitor value.

### REMARKS

- The cumulative saving power monitor value is stored every hour. Hence, when the power supply is switched on again within one hour after it was switched off, the previously stored monitor value is displayed and totalization starts. (The cumulative monitor value may decrease)

**(5) Power estimated value of commercial power supply operation (Pr.892, Pr.893, Pr.894)**

- Select the commercial power supply operation pattern from among the four patterns of discharge damper control (fan), inlet damper control (fan), valve control (pump) and commercial power supply drive, and set it to *Pr. 894 Control selection during commercial power-supply operation*.
- Set the motor capacity (pump capacity) in *Pr. 893 Energy saving monitor reference (motor capacity)*.
- The power consumption rate (%) during commercial power supply operation is estimated from the operation pattern and the ratio of speed to rating (current output frequency/*Pr. 3 Base frequency*) in the following chart.



- From the motor capacity set in *Pr. 893* and *Pr. 892 Load factor*, the power estimated value (kW) during commercial power supply operation is found by the following formula.

**Power estimated value (kW) during commercial power supply operation**

$$= \text{Pr. 893 (kW)} \times \frac{\text{Power consumption (\%)}}{100} \times \frac{\text{Pr.892 (\%)}}{100}$$

**REMARKS**

- Since the speed does not increase above the power supply frequency in commercial power supply operation, it becomes constant when the output frequency rises to or above *Pr. 3 Base frequency*.

## (6) Annual power saving amount, power charge (Pr.899)

- By setting the operation time rate [%] (ratio of time when the motor is actually driven by the inverter during a year) in Pr. 899, the annual energy saving effect can be predicted.
- When the operation pattern is predetermined to some degree, the estimated value of the annual power saving amount can be found by measurement of the power saving amount during a given measurement period.
- Refer to the following and set the operation time rate.
  - Predict the average time [h/day] of operation in a day.
  - Find the annual operation days [days/year]. (Monthly average operation days × 12 months)
  - Calculate the annual operation time [h/year] from 1) and 2).

$$\text{Annual operation time (h/year)} = \text{Average time (h/day)} \times \text{Operation days (days/year)}$$

- Calculate the operation time rate and set it to Pr. 899.

$$\text{Operation time rate (\%)} = \frac{\text{Annual operation time (h/year)}}{24 \text{ (h/day)} \times 365 \text{ (days/year)}} \times 100(\%)$$

### REMARKS

- Operation time rate setting example: When operation is performed for about 21 hours per day and the monthly average operation days are 16 days  
 Annual operation time =  $21 \text{ (h/day)} \times 16 \text{ (days/month)} \times 12 \text{ months} = 4032 \text{ (h/year)}$   

$$\text{Operation time rate (\%)} = \frac{4032 \text{ (h/year)}}{24 \text{ (h/day)} \times 365 \text{ (days/year)}} \times 100(\%) = 46.03\%$$
  
 Set 46.03% to Pr. 899.
- Calculate the annual power saving amount from Pr. 899 Operation time rate (estimated value) and power saving average value monitor

$$\text{Annual power saving amount (kWh/year)} = \frac{\text{Power saving average value (kW) during totalization when Pr. 898 = 10 or 9999}}{\text{Pr. 899}} \times 24\text{h} \times 365 \text{ days} \times \frac{100}{100}$$

- The annual power saving amount charge can be monitored by setting the power charge per hour in Pr. 896 Power unit cost.  
 Calculate the annual power saving amount charge in the following method.

$$\text{Annual power saving amount charge} = \text{Annual power saving amount (kWh/year)} \times \text{Pr. 896}$$

### REMARKS

In the regeneration mode, make calculation on the assumption that "power saving = power during commercial power supply operation (input power = 0)".

#### ◆ Parameters referred to ◆

Pr.3 Base frequency  Refer to page 69

Pr.52 DU/PU main display data selection  Refer to page 105

Pr. 54 CA terminal function selection  Refer to page 109

Pr. 158 AM terminal function selection  Refer to page 109



## 3.14 Motor noise, noise reduction

### 3.14.1 PWM carrier frequency and Soft-PWM control (Pr.72, Pr.240, Pr.260)

You can change the motor sound.

| Parameter Number | Name                               | Initial Value | Setting Range<br>200V class (400V class) |            | Description                                                                                                                                                                                                |
|------------------|------------------------------------|---------------|------------------------------------------|------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 72 *             | PWM frequency selection            | 2             | 02330<br>(01160) or less                 | 0 to 15    | PWM carrier frequency can be changed. The setting displayed is in [kHz]. Note that 0 indicates 0.7kHz, 15 indicates 14.5kHz and 25 indicates 2.5kHz.                                                       |
|                  |                                    |               | 03160<br>(01800) or more                 | 0 to 6, 25 |                                                                                                                                                                                                            |
| 240 *            | Soft-PWM operation selection       | 1             | 0                                        |            | Soft-PWM is invalid                                                                                                                                                                                        |
|                  |                                    |               | 1                                        |            | When Pr. 72 = "0 to 5" ("0 to 4" for FR-F720-03160 (FR-F740-01800) or more), soft-PWM is valid.                                                                                                            |
| 260              | PWM frequency automatic switchover | 1             | 0                                        |            | PWM carrier frequency is constant independently of load.<br>When the carrier frequency is set to 3kHz or more (Pr. 72 ≥ "3"), perform continuous operation at less than 85% of the rated inverter current. |
|                  |                                    |               | 1                                        |            | Decreases PWM carrier frequency automatically when load increases.                                                                                                                                         |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145.)

\* The above parameters allow its setting to be changed during operation in any operation mode even if "0" (initial value) is set in Pr. 77 Parameter write selection.

#### (1) PWM carrier frequency changing (Pr. 72)

- You can change the PWM carrier frequency of the inverter.
- Changing the PWM carrier frequency produces an effect on avoiding the resonance frequency of a mechanical system or motor or on reducing noise or leakage current generated from the inverter.
- When using an option sine wave filter (MT-BSL/BSC) for the FR-F720-03160 (FR-F740-01800) or more, set "25" in Pr.72 (2.5kHz).

#### (2) Soft-PWM control (Pr.240)

- Soft-PWM control is a control system that changes the motor noise from a metallic tone into an unoffending complex tone.

#### (3) PWM carrier frequency automatic reduction function (Pr.260)

- When continuous operation is performed at 85% or more of the inverter rated current (the parenthesized value of the rated output current on page 250 or more) with the carrier frequency of the inverter set to 3kHz or more (Pr. 72 ≥ "3"), the carrier frequency is automatically reduced to 2kHz to protect the output transistor of the inverter. (Motor noise increases, but it is not a failure)
- When Pr. 260 is set to "0", the carrier frequency becomes constant (Pr. 72 setting) independently of the load, making the motor sound uniform.

Note that continuous operation should be performed at less than 85% of the inverter rating.

#### CAUTION

- Decreasing the PWM carrier frequency reduces inverter-generated noise and leakage current, but increases motor noise.
- When Pr. 570 = "0" (initial value), functions of Pr. 260 become invalid. PWM carrier frequency automatically decreases when load increases. (Refer to page 66.)

|        |          |
|--------|----------|
| Pr.71  | page 85  |
| Pr.73  | page 132 |
| Pr.239 | page 72  |
| Pr.241 | page 134 |
| Pr.259 | page 214 |
| Pr.261 | page 117 |

### 3.15 Frequency setting by analog input (terminal 1, 2, 4)

| Purpose                                                                                                 | Parameter that must be set                                                         |                                                     | Refer to page |
|---------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------|-----------------------------------------------------|---------------|
| Selection of voltage/current input (terminal 1, 2, 4) Perform forward/reverse rotation by analog input. | Analog input selection                                                             | Pr.73, Pr.267                                       | 130           |
| Adjust the main speed by analog auxiliary input.                                                        | Analog auxiliary input and compensation (added compensation and override function) | Pr.73, Pr.242, Pr.243, Pr.252, Pr.253               | 132           |
| Noise elimination at the analog input                                                                   | Input filter                                                                       | Pr.74                                               | 133           |
| Adjustment (calibration) of analog input frequency and voltage (current)                                | Bias and gain of frequency setting voltage (current)                               | Pr.125, Pr.126, Pr.241, C2 to C7 (Pr.902 to Pr.905) | 134           |

#### 3.15.1 Analog input selection (Pr.73, Pr.267)

You can select the function that switches between forward rotation and reverse rotation according to the analog input selection specifications, the override function and the input signal polarity.

Pr.72  
page 129

Pr.74  
page 133

Pr.266  
page 117

Pr.268  
page 105

| Parameter Number | Name                       | Initial Value | Setting Range    | Description                                            |
|------------------|----------------------------|---------------|------------------|--------------------------------------------------------|
| 73               | Analog input selection     | 1             | 0 to 7, 10 to 17 | Select the input specifications of the terminals 1, 2. |
| 267              | Terminal 4 input selection | 0             | 0                | Terminal 4 input 4 to 20mA                             |
|                  |                            |               | 1                | Terminal 4 input 0 to 5V                               |
|                  |                            |               | 2                | Terminal 4 input 0 to 10V                              |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

#### (1) Selection of analog input selection

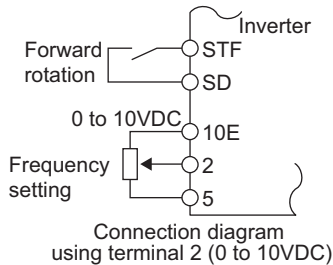
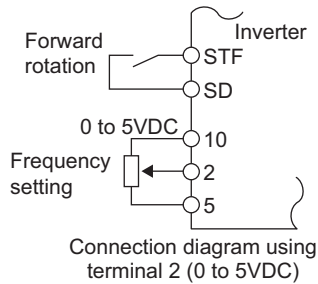
- For the terminals 1, 2, 4 used for analog input, voltage input (0 to 5V, 0 to 10V) or current input (4 to 20mA) can be selected.
- Refer to the following table and set Pr. 73 and Pr. 267. ( ☐ indicates the main speed setting)

| Pr. 73 Setting    | AU Signal        | Terminal 2 Input | Terminal 1 Input | Terminal 4 Input                                                                                                      | Pr. 73 Setting         | Compensation Input Terminal and Compensation Method | Polarity Reversible              |
|-------------------|------------------|------------------|------------------|-----------------------------------------------------------------------------------------------------------------------|------------------------|-----------------------------------------------------|----------------------------------|
| 0                 | OFF<br>(absence) | 0 to 10V         | 0 to ±10V        | When the AU signal is off<br>×                                                                                        | 0                      | Terminal 1<br>Added compensation                    | No                               |
| 1 (initial value) |                  | 0 to 5V          | 0 to ±10V        |                                                                                                                       | 1 (initial value)      |                                                     |                                  |
| 2                 |                  | 0 to 10V         | 0 to ±5V         |                                                                                                                       | 2                      |                                                     |                                  |
| 3                 |                  | 0 to 5V          | 0 to ±5V         |                                                                                                                       | 3                      |                                                     |                                  |
| 4                 |                  | 0 to 10V         | 0 to ±10V        |                                                                                                                       | 4                      |                                                     |                                  |
| 5                 |                  | 0 to 5V          | 0 to ±5V         |                                                                                                                       | 5                      | Terminal 2<br>Override                              |                                  |
| 6                 |                  | 4 to 20mA        | 0 to ±10V        |                                                                                                                       | 6                      |                                                     |                                  |
| 7                 |                  | 4 to 20mA        | 0 to ±5V         |                                                                                                                       | 7                      |                                                     |                                  |
| 10                |                  | 0 to 10V         | 0 to ±10V        |                                                                                                                       | 10                     |                                                     | Terminal 1<br>Added compensation |
| 11                |                  | 0 to 5V          | 0 to ±10V        |                                                                                                                       | 11                     |                                                     |                                  |
| 12                |                  | 0 to 10V         | 0 to ±5V         |                                                                                                                       | 12                     |                                                     |                                  |
| 13                |                  | 0 to 5V          | 0 to ±5V         |                                                                                                                       | 13                     |                                                     |                                  |
| 14                |                  | 0 to 10V         | 0 to ±10V        |                                                                                                                       | 14                     |                                                     |                                  |
| 15                |                  | 0 to 5V          | 0 to ±5V         |                                                                                                                       | 15                     | Terminal 2<br>Override                              |                                  |
| 16                |                  | 4 to 20mA        | 0 to ±10V        |                                                                                                                       | 16                     |                                                     |                                  |
| 17                |                  | 4 to 20mA        | 0 to ±5V         |                                                                                                                       | 17                     |                                                     |                                  |
| 17                |                  |                  |                  |                                                                                                                       |                        | 17                                                  | Added compensation               |
| 0                 | ON<br>(presence) | ×                | 0 to ±10V        | When the AU signal is on<br>According to Pr. 267 setting<br>0: 4 to 20mA (initial value)<br>1: 0 to 5V<br>2: 0 to 10V | 0                      | Terminal 1<br>Added compensation                    | No*                              |
| 1                 |                  |                  | 0 to ±10V        |                                                                                                                       | 1                      |                                                     |                                  |
| 2                 |                  |                  | 0 to ±5V         |                                                                                                                       | 2                      |                                                     |                                  |
| 3                 |                  |                  | 0 to ±5V         |                                                                                                                       | 3                      |                                                     |                                  |
| 4                 |                  | 0 to 10V         | ×                |                                                                                                                       | 4                      |                                                     |                                  |
| 5                 |                  | 0 to 5V          |                  |                                                                                                                       | 5                      |                                                     |                                  |
| 6                 |                  | ×                | 0 to ±10V        |                                                                                                                       | 6                      | Terminal 1<br>Added compensation                    |                                  |
| 7                 |                  | ×                | 0 to ±5V         |                                                                                                                       | 7                      |                                                     |                                  |
| 10                |                  |                  | 0 to ±10V        |                                                                                                                       | 10                     |                                                     |                                  |
| 11                |                  |                  | 0 to ±10V        |                                                                                                                       | 11                     |                                                     |                                  |
| 12                |                  |                  | 0 to ±5V         |                                                                                                                       | 12                     |                                                     |                                  |
| 13                |                  | 0 to ±5V         | 13               |                                                                                                                       | Terminal 2<br>Override |                                                     |                                  |
| 14                |                  | 0 to 10V         | ×                |                                                                                                                       |                        | 14                                                  |                                  |
| 15                |                  | 0 to 5V          |                  |                                                                                                                       |                        | 15                                                  |                                  |
| 16                |                  | ×                | 0 to ±10V        |                                                                                                                       |                        | 16                                                  | Terminal 1<br>Added compensation |
| 17                |                  |                  | 0 to ±5V         |                                                                                                                       |                        | 17                                                  |                                  |

\* Indicates that a frequency command signal of negative polarity is not accepted.

## CAUTION

- The terminal 1 (frequency setting auxiliary input) signal is added to the main speed setting signal of the terminal 2 or 4.
- When an override is selected, the terminal 1 or 4 is used for the main speed setting and the terminal 2 for the override signal (50% to 150% at 0 to 5V or 0 to 10V). (When the main speed of the terminal 1 or terminal 4 is not input, compensation by the terminal 2 is made invalid.)
- Use *Pr. 125 (Pr. 126) (frequency setting gain)* to change the maximum output frequency at input of the maximum output frequency command voltage (current). At this time, the command voltage (current) need not be input. Also, the acceleration/deceleration time, which is a slope up/down to the acceleration/deceleration reference frequency, is not affected by the change in *Pr. 73* setting.
- When *Pr. 22 Stall prevention operation level* = "9999", the value of the terminal 1 is as set to the stall prevention operation level.



## (2) Perform operation by analog input voltage

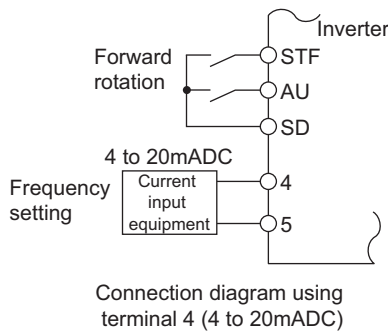
- The frequency setting signal inputs 0 to 5VDC (or 0 to 10VDC) to across the terminals 2-5. The 5V (10V) input is the maximum output frequency. The maximum output frequency is reached when 5V (10V) is input.
- The power supply 5V (10V) can be input by either using the internal power supply or preparing an external power supply. The internal power supply outputs 5VDC across terminals 10-5, or 10V across terminals 10E-5.

| Terminal | Inverter Built-in Power Supply Voltage | Frequency Setting Resolution | <i>Pr. 73</i> (terminal 2 input voltage) |
|----------|----------------------------------------|------------------------------|------------------------------------------|
| 10       | 5VDC                                   | 0.030Hz/60Hz                 | 0 to 5VDC input                          |
| 10E      | 10VDC                                  | 0.015Hz/60Hz                 | 0 to 10VDC input                         |

- When inputting 10VDC to the terminal 2, set any of "0, 2, 4, 10, 12, 14" in *Pr. 73*. (The initial value is 0 to 5V)
- Setting "1 (0 to 5VDC)" or "2 (0 to 10VDC)" in *Pr. 267* changes the terminal 4 to the voltage input specification. When the AU signal turns on, the terminal 4 input becomes valid.

## REMARKS

The wiring length of the terminal 10, 2, 5 should be 30m maximum.

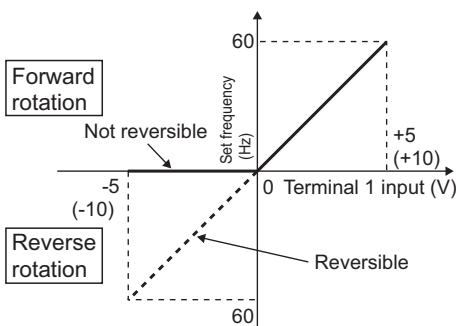


## (3) Perform operation by analog input current

- When the pressure or temperature is controlled constant by a fan, pump, etc., automatic operation can be performed by inputting the output signal 4 to 20mADC of the adjuster to across the terminals 4-5.
- The AU signal must be turned on to use the terminal 4.
- Setting any of "6, 7, 16, 17" in *Pr. 73* changes the terminal 2 to the current input specification. At this time, the AU signal need not be turned on.

## (4) Perform forward/reverse rotation by analog input (polarity reversible operation)

- Setting any of "10 to 17" in *Pr. 73* enables polarity reversible operation.
- Providing  $\pm$  input (0 to  $\pm 5$ V or 0 to  $\pm 10$ V) to the terminal 1 enables forward/reverse rotation operation according to the polarity.



## Parameters referred to

*Pr. 22 Stall prevention operation level* Refer to page 61

*Pr. 125 Terminal 2 frequency setting gain frequency, Pr. 126 Terminal 4 frequency setting gain frequency* Refer to page 134

*Pr. 252, Pr. 253 Override bias/gain* Refer to page 132

## 3.15.2 Analog input compensation (Pr.73, Pr.242, Pr.243, Pr.252, Pr.253)

A fixed ratio of analog compensation (override) can be made by the added compensation or terminal 2 as an auxiliary input for multi-speed operation or the speed setting signal (main speed) of the terminal 2 or terminal 4.

Pr. 72  
page 129

Pr.74  
page 133

Pr.241  
page 134

Pr. 244  
page 213

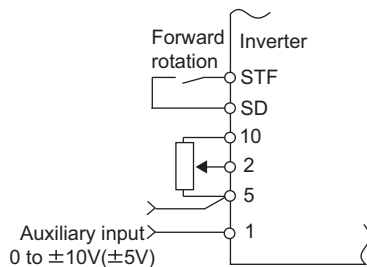
Pr. 251  
page 122

Pr.255  
page 214

| Parameter Number | Name                                              | Initial Value | Setting Range                  | Description                                                                   |
|------------------|---------------------------------------------------|---------------|--------------------------------|-------------------------------------------------------------------------------|
| 73               | Analog input selection                            | 1             | 0 to 3, 6, 7, 10 to 13, 16, 17 | Added compensation                                                            |
|                  |                                                   |               | 4, 5, 14, 15                   | Override compensation                                                         |
| 242              | Terminal 1 added compensation amount (terminal 2) | 100%          | 0 to 100%                      | Set the ratio of added compensation amount when terminal 2 is the main speed. |
| 243              | Terminal 1 added compensation amount (terminal 4) | 75%           | 0 to 100%                      | Set the ratio of added compensation amount when terminal 4 is the main speed. |
| 252              | Override bias                                     | 50%           | 0 to 200%                      | Set the bias side compensation value of override function.                    |
| 253              | Override gain                                     | 150%          | 0 to 200%                      | Set the gain side compensation value of override function.                    |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

## (1) Added compensation (Pr.242, Pr.243)



Added compensation connection example

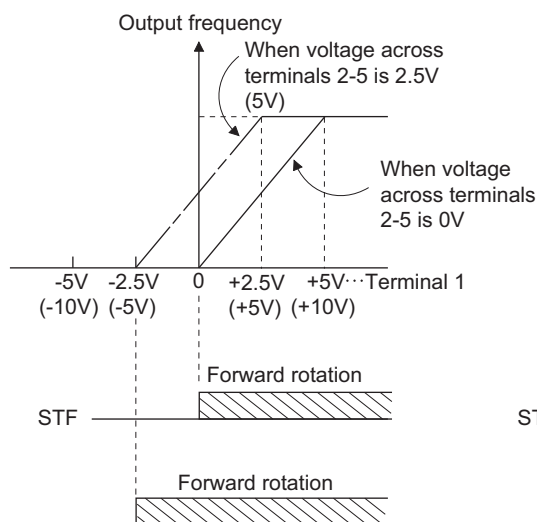
- The compensation signal can be input for the main speed setting for synchronous/continuous speed control operation, etc.
- Setting any of "0 to 3, 6, 7, 10 to 13, 16, 17" in Pr. 73 adds the voltage across terminals 1-5 to the voltage signal across terminals 2-5.
- If the result of addition is negative, it is regarded as 0 at the Pr. 73 setting of any of "0 to 3, 6, 7", or reverse rotation operation (polarity reversible operation) is performed when the STF signal turns on at the Pr. 73 setting of any of "10 to 13, 16, 17".
- The compensation input of the terminal 1 can also be added to the multi-speed setting or terminal 4 (initial value 4 to 20mA).
- The added compensation for terminal 2 can be adjusted by Pr. 242, and the compensation for terminal 4 by Pr. 243.

Analog command value using terminal 2

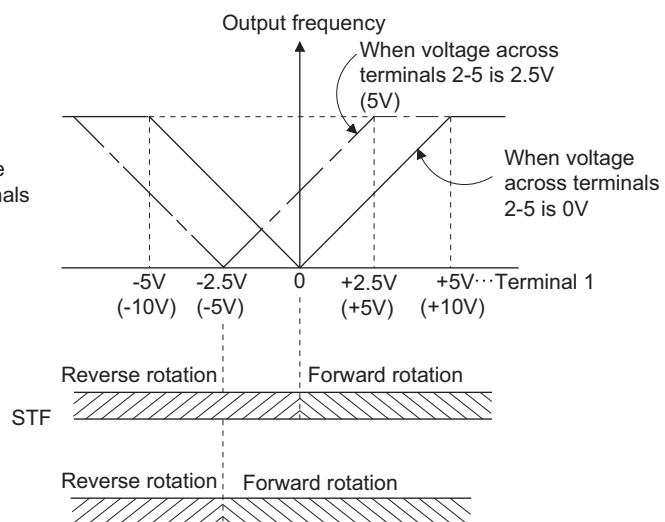
$$= \text{Terminal 2 input} + \text{Terminal 1 input} \times \frac{\text{Pr.242}}{100(\%)}$$

Analog command value using terminal 4

$$= \text{Terminal 4 input} + \text{Terminal 1 input} \times \frac{\text{Pr.243}}{100(\%)}$$



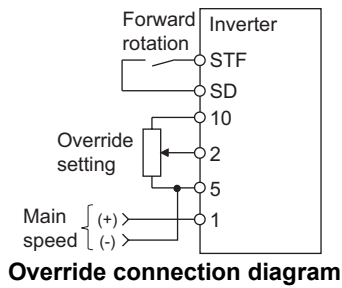
(a) When Pr. 73 setting is 0 to 5



(b) When Pr. 73 setting is 10 to 15

Auxiliary input characteristics

## (2) Override function (Pr.252, Pr.253)

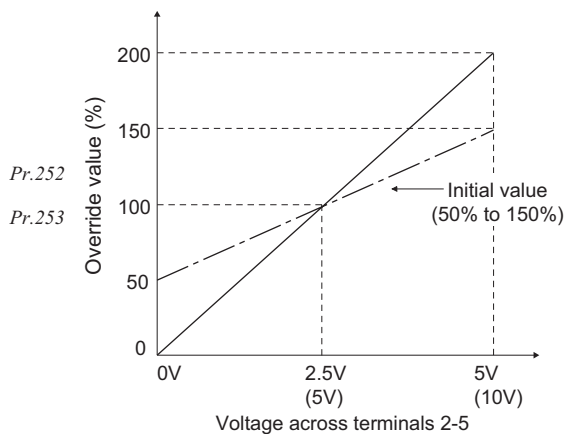


- Use the override function to change the main speed at a fixed ratio.
- Set any of "4, 5, 14, 15" in Pr. 73 to select an override.
- When an override is selected, the terminal 1 or terminal 4 is used for the main speed setting and the terminal 2 for the override signal. (When the main speed of the terminal 1 or terminal 4 is not input, compensation made by the terminal 2 becomes invalid.)
- Using Pr. 252 and Pr. 253, set the override range.
- How to find the set frequency for override

$$\text{Set frequency (Hz)} = \text{Main speed set frequency (Hz)} \times \frac{\text{Compensation amount (\%)}}{100(\%)}$$

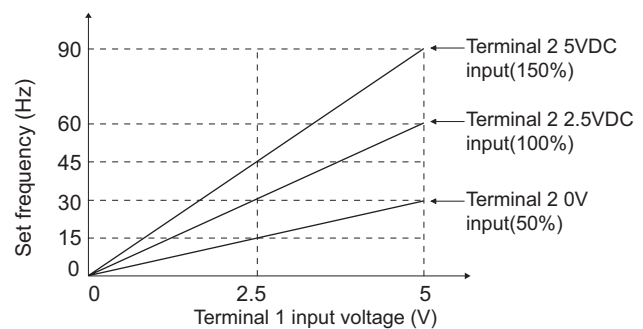
Main speed set frequency (Hz): Terminal 1, 4 input, multi-speed setting

Compensation amount (%): Terminal 2 input



Example) When Pr. 73 = "5"

The set frequency changes as shown below according to the terminal 1 (main speed) and terminal 2 (auxiliary) inputs.



### REMARKS

- The AU signal must be turned on to use the terminal 4.
- When inputting compensation to multi-speed operation or remote setting, set "1" (compensation made) to Pr. 28 Multi-speed input compensation selection. (Initial value is "0")

### ◆ Parameters referred to ◆

Pr.28 Multi-speed input compensation selection Refer to page 76

Pr.73 Analog input selection Refer to page 130

## 3.15.3 Input filter time constant (Pr.74)

The time constant of the primary delay filter can be set for the external frequency command (analog input (terminal 1, 2, 4) signal).

**Pr. 73**  
 page 132

**Pr. 75**  
 page 141

| Parameter Number | Name                              | Initial Value | Setting Range | Description                                                                                                   |
|------------------|-----------------------------------|---------------|---------------|---------------------------------------------------------------------------------------------------------------|
| <b>74</b>        | <b>Input filter time constant</b> | 1             | 0 to 8        | Set the primary delay filter time constant for the analog input. A larger setting results in a larger filter. |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

- Effective for eliminating noise in the frequency setting circuit.
- Increase the filter time constant if steady operation cannot be performed due to noise. A larger setting results in slower response. (The time constant can be set between approximately 10ms to 1s with the setting of 0 to 8.)

### 3.15.4 Bias and gain of frequency setting voltage (current) (Pr. 125, Pr. 126, Pr. 241, C2(Pr. 902) to C7(Pr. 905))

You can set the magnitude (slope) of the output frequency as desired in relation to the frequency setting signal (0 to 5V, 0 to 10V or 4 to 20mADC).

Set Pr. 73 and Pr. 267 to switch between 0 to 5VDC, 0 to 10VDC and 4 to 20mADC. (Refer to page 130)

Pr. 124  
page 166

Pr. 127  
page 189

Pr. 240  
page 129

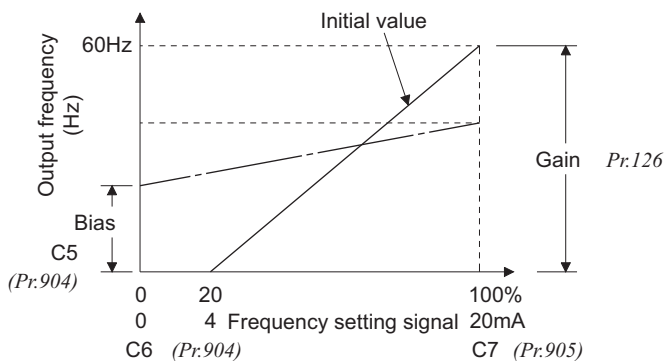
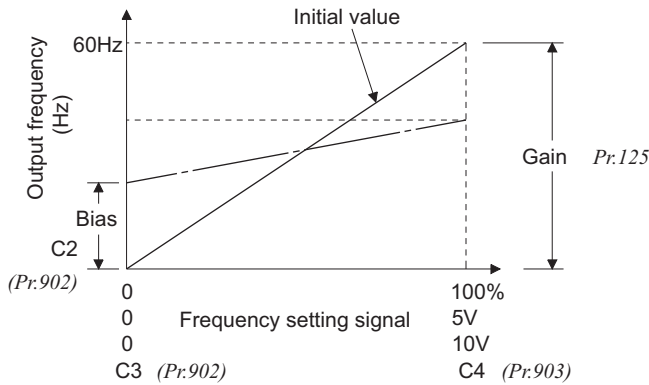
Pr. 242  
page 132

| Parameter Number | Name                                        | Initial Value | Setting Range | Description                                                                 |                                          |
|------------------|---------------------------------------------|---------------|---------------|-----------------------------------------------------------------------------|------------------------------------------|
| 125              | Terminal 2 frequency setting gain frequency | 60Hz          | 0 to 400Hz    | Set the frequency of terminal 2 input gain (maximum).                       |                                          |
| 126              | Terminal 4 frequency setting gain frequency | 60Hz          | 0 to 400Hz    | Set the frequency of terminal 4 input gain (maximum).                       |                                          |
| 241 *1, 3        | Analog input display unit switchover        | 0             | 0             | Displayed in %                                                              | Select the unit of analog input display. |
|                  |                                             |               | 1             | Displayed in V/mA                                                           |                                          |
| C2(902) *1, 2    | Terminal 2 frequency setting bias frequency | 0Hz           | 0 to 400Hz    | Set the frequency on the bias side of terminal 2 input.                     |                                          |
| C3(902) *1, 2    | Terminal 2 frequency setting bias           | 0%            | 0 to 300%     | Set the converted % of the bias side voltage (current) of terminal 2 input. |                                          |
| C4(903) *1, 2    | Terminal 2 frequency setting gain           | 100%          | 0 to 300%     | Set the converted % of the gain side voltage (current) of terminal 2 input. |                                          |
| C5(904) *1, 2    | Terminal 4 frequency setting bias frequency | 0Hz           | 0 to 400Hz    | Set the frequency on the bias side of terminal 4 input.                     |                                          |
| C6(904) *1, 2    | Terminal 4 frequency setting bias           | 20%           | 0 to 300%     | Set the converted % of the bias side current (voltage) of terminal 4 input. |                                          |
| C7(905) *1, 2    | Terminal 4 frequency setting gain           | 100%          | 0 to 300%     | Set the converted % of the gain side current (voltage) of terminal 4 input. |                                          |

\*1 The parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145.)

\*2 The parameter number in parentheses is the one for use with the parameter unit (FR-PU04).

\*3 The above parameters allow its setting to be changed during operation in any operation mode even if "0" (initial value) is set in Pr. 77 Parameter write selection.



### (1) Change the frequency at maximum analog input. (Pr. 125, Pr. 126)

- Set a value in Pr. 125 (Pr. 126) when changing only the frequency setting (gain) of the maximum analog input power (current). (C2 (Pr. 902) to C7 (Pr. 905) setting need not be changed)

### (2) Analog input bias/gain calibration (C2(Pr. 902) to C7(Pr. 905))

- The "bias" and "gain" functions are used to adjust the relationship between the input signal entered from outside the inverter to set the output frequency, e.g. 0 to 5V, 0 to 10V or 0 to 20mADC, and the output frequency.
- Set the bias frequency of the terminal 2 input using C2 (Pr. 902). (Factory-set to the frequency at 0V)
- Using Pr. 125, set the output frequency relative to the frequency command voltage (current) set in Pr. 73 Analog input selection.
- Set the bias frequency of the terminal 4 input using C5 (Pr. 904). (Factory-set to the frequency at 4mA)
- Using Pr. 126, set the output frequency relative to 20mA of the frequency command current (0 to 20mA).
- There are three methods to adjust the frequency setting voltage (current) bias/gain.
  - Method to adjust any point by application of voltage (current) to across the terminals 2-5 (4-5). [page 136](#)
  - Method to adjust any point without application of a voltage (current) to across terminals 2-5 (4-5). [page 137](#)
  - Adjusting only the frequency without adjusting the bias voltage (current). [page 138](#)

### CAUTION

- When the terminal 2 is calibrated to change the inclination of the set frequency, the setting of the terminal 1 is also changed.
- When a voltage is input to the terminal 1 to make calibration, (terminal 2 (4) analog value + terminal 1 analog value) is the analog calibration value.
- When the voltage/current input specifications were changed using Pr. 73 and Pr. 267, be sure to make calibration.

### (3) Analog input display unit changing (Pr. 241)

- You can change the analog input display unit (%/V/mA) for analog input bias/gain calibration.
- Depending on the terminal input specification set to Pr. 73 and Pr. 267, the display units of C3 (Pr. 902), C4 (Pr. 903), C6 (Pr. 904) C7 (Pr. 905) change as shown below.

| Analog Command<br>(terminal 2, 4)<br>(according to Pr. 73, Pr. 267) | Pr. 241 = 0 (initial value)               | Pr. 241 = 1                                 |
|---------------------------------------------------------------------|-------------------------------------------|---------------------------------------------|
| 0 to 5V input                                                       | 0 to 5V → 0 to 100%(0.1%) is displayed.   | 0 to 100% → 0 to 5V(0.01V) is displayed.    |
| 0 to 10V input                                                      | 0 to 10V → 0 to 100%(0.1%) is displayed.  | 0 to 100% → 0 to 10V(0.01V) is displayed.   |
| 4 to 20mA input                                                     | 0 to 20mA → 0 to 100%(0.1%) is displayed. | 0 to 100% → 0 to 20mA(0.01mA) is displayed. |

#### (4) Frequency setting signal (current) bias/gain adjustment method

(a) Method to adjust any point by application of voltage (current) to across the terminals 2-5 (4-5).

### Operation

- Confirmation of the RUN indication and operation mode indication
  - The inverter must be at a stop.
  - The inverter must be in the PU operation mode. (Using )
- Press  to choose the parameter setting mode.
- Turn  until  $\text{C} \dots$  appears.
- Press  to display  $\text{C} \dots$ .
- Turn  until  $\text{C} \dots 4$  ( $\text{C} \dots 7$ ) appears. Set to C4 Terminal 2 frequency setting gain.
- Press  to display the analog voltage (current) value (%).
- Apply a 5V (20mA) voltage (current). (Turn the external potentiometer connected across terminals 2-5 (across terminals 4-5) to maximum (any position).)

**CAUTION**  
After performing the operation in step 6, do not touch  until completion of calibration.

- Press  to set.

### Display



1. Confirmation of the RUN indication and operation mode indication

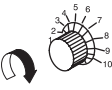
2. Press  to choose the parameter setting mode.  (The parameter number read previously appears.)

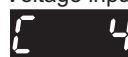
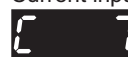
3. Turn  until  $\text{C} \dots$  appears. 

4. Press  to display  $\text{C} \dots$ . (C0 to C7 setting is enabled.) 

5. Turn  until  $\text{C} \dots 4$  ( $\text{C} \dots 7$ ) appears. Set to C4 Terminal 2 frequency setting gain.  Voltage input  Current input

6. Press  to display the analog voltage (current) value (%).  Analog voltage (current) value (%) across terminals 2-5 (across terminals 4-5)

7. Apply a 5V (20mA) voltage (current). (Turn the external potentiometer connected across terminals 2-5 (across terminals 4-5) to maximum (any position).)   \*  
\*The value is nearly 100 (%) in the maximum position of the potentiometer.

8. Press  to set.  \* Voltage input  Current input 

**Flicker...Parameter setting complete!!**  
(Adjustment completed)  
\*The value is nearly 100 (%) in the maximum position of the potentiometer.

- By turning , you can read another parameter.
- Press  to return to the  $\text{C} \dots$  indication (step 4).
- Press  twice to show the next parameter ( $P_r \text{C} \dots$ ).

#### REMARKS

If the gain and bias frequency settings are too close, an error ( $\text{E} \dots 3$ ) may be displayed at the time of write.

- (b) Method to adjust any point without application of a voltage (current) to across terminals 2-5(4-5).  
(To change from 4V (80%) to 5V (100%))

| Operation                                                                                                                                                                                                                                              | Display                                                                                                                                                                                                                                                                                           |
|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1. Confirmation of the RUN indication and operation mode indication<br>● The inverter must be at a stop.<br>● The inverter must be in the PU operation mode.(Using  ) |                                                                                                                                                                                                                 |
| 2. Press  to choose the parameter setting mode.                                                                                                                       |  →  (The parameter number read previously appears.)                                                                             |
| 3. Turn  until  appears.                                                                                                                                              |  →  →  (C0 to C7 setting is enabled.)                                                                                                                                                                            |
| 4. Press  to display .                                                                                                                                                |  →  (C0 to C7 setting is enabled.)                                                                                                                                                                               |
| 5. Turn  until  appears. Set to C4 Terminal 2 frequency setting gain.                                                                                                 |  →  Voltage input  Current input             |
| 6. Press  to display the analog voltage (current) value (%).                                                                                                          |  →  Analog voltage (current) value (%) across terminals 2-5 (across terminals 4-5)                                             |
| 7. Turn  to set the gain voltage (%).<br>"0V (0mA) equals to 0%, 5V (10V, 20mA) to 100%"                                                                              |  →  The gain frequency is reached when the analog voltage (current) value across terminals 2-5 (across terminals 4-5) is 100%. |
| <b>Remarks</b><br>The current setting at the instant of turning  is displayed.                                                                                      |                                                                                                                                                                                                               |
| 8. Press  to set.                                                                                                                                                   |  →  Voltage input  Current input      |
|                                                                                                                                                                                                                                                        | Flicker...Parameter setting complete!!<br>(Adjustment completed)                                                                                                                                                                                                                                  |

- By turning , you can read another parameter.
- Press  to return to the indication (step 4).
- Press  twice to show the next parameter (.

## REMARKS

By pressing  after step 6, you can confirm the current frequency setting bias/gain setting.  
It cannot be confirmed after execution of step 7.

- (c) Method to adjust only the frequency without adjustment of a gain voltage (current).  
(When changing the gain frequency from 60Hz to 50Hz)

| Operation                                                                                                                                                          | Display                                                                                                                                                                                        |
|--------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1. Turn  until <b>P. 125</b> (Pr. 125) or <b>P. 126</b> (Pr. 126) appears.        |  → <b>P. 125</b> Voltage input or <b>P. 126</b> Current input                                                 |
| 2. Press  to show the currently set value.<br>(60.00Hz)                           |  → <b>60.00</b> Hz                                                                                            |
| 3. Turn  to change the set value to<br>"50.00". (50.00Hz)                         |  → <b>50.00</b> Hz                                                                                            |
| 4. Press  to set.                                                                 |  → <b>50.00</b> <b>P. 125</b> <b>P. 126</b><br>Voltage input Current input                                    |
| 5. Mode/monitor check<br>Press  twice to choose the<br>monitor/frequency monitor. | <b>Flicker...Parameter setting complete!!</b><br> → <b>0.00</b> Hz <b>MON</b> <b>PU</b> <b>EXT</b> <b>NET</b> |
| 6. Apply a voltage across the inverter<br>terminals 2-5 (across 4-5) and turn on the<br>start command (STF, STR).<br>Operation starts at 50Hz.                     |                                                                                                                                                                                                |

## REMARKS

- Changing **C4** (Pr. 903) or **C5** (Pr. 905) (gain adjustment) value will not change the **Pr. 20** value. The input of terminal 1 (frequency setting auxiliary input) is added to the speed setting signal.
- For the operation procedure using the parameter unit (FR-PU04), refer to the FR-PU04 instruction manual.
- When setting the value to 120Hz or more, it is necessary to set **Pr. 18 High speed maximum frequency** to 120Hz or more. (Refer to page 67)
- Make the bias frequency setting using *calibration parameter C2* (Pr. 902) or **C5** (Pr. 904). (Refer to page 135)

## ⚠ CAUTION

- ⚠ Take care when setting any value other than "0" as the bias speed at 0V (0mA). Even if a frequency command is not given, merely turning on the start signal will start the motor at the preset frequency.

### ◆ Parameters referred to ◆

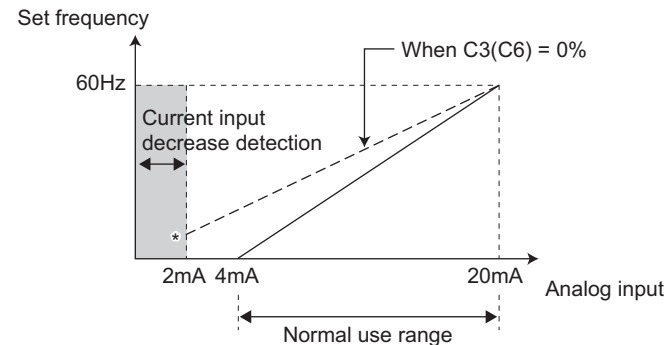
**Pr. 20** Acceleration/deceleration reference frequency  Refer to page 79  
**Pr. 73** Analog input selection, **Pr. 267** Terminal 4 input selection  Refer to page 130  
**Pr. 79** Operation mode selection  Refer to page 147

### 3.15.5 4mA input check of current input (Pr. 573)

When inputting 4 to 20mA current to terminal 2 or terminal 4, decrease in analog current input is detected to enable continuous operation even if input has decreased.

| Parameter Number | Name                      | Initial Value | Setting Range | Description                                                                                                                                                              |
|------------------|---------------------------|---------------|---------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 573              | 4mA input check selection | 9999          | 1             | When the current input drops to or below 2mA, the LF signal is output and inverter continues operation at the frequency (average value) just before current reaches 2mA. |
|                  |                           |               | 9999          | 4mA input is not checked.                                                                                                                                                |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145.)

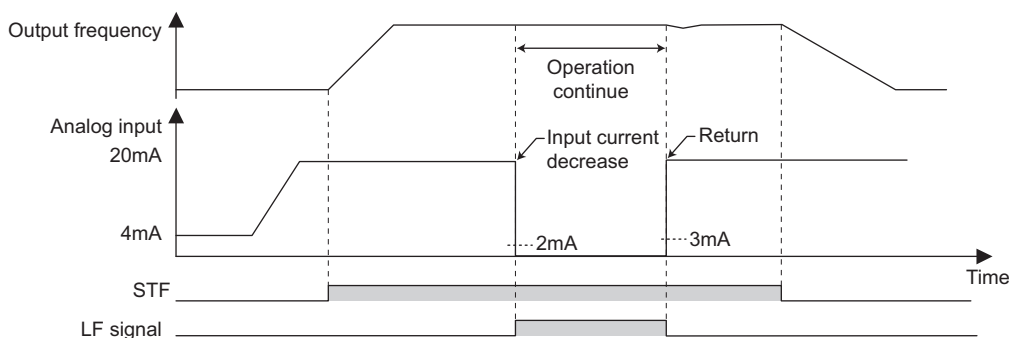


\* When Pr.573 = "1", input decrease is detected (LF signal output) even if the analog input value to bias frequency of terminal 2 or terminal 4 is set to 2mA or less using C2 (Pr. 902) or C5 (Pr. 904) and the value is not as bias frequency settings.

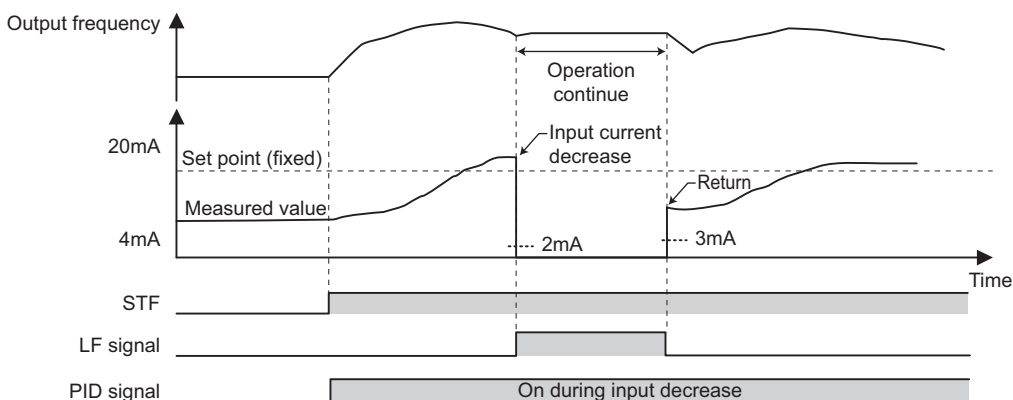
#### (1) Operation at a current input decrease continues (Pr. 573 = "1")

- When the input current of terminal 4 (terminal 2) falls 2mA or below, output minor fault signal (LF) is output.
- When the current falls below 2mA, the output frequency (average value) before detection is retained and operation at the retained frequency continues.
- When the current input increases above 3mA, the LF signal output is turned off and the inverter operates according to the current input.
- For the LF signal, set "98 (positive logic) or 198 (negative logic)" in Pr. 190 to Pr. 196 (output terminal function selection) and assign functions to the output terminal.
- Since turning off the start command clears the retained frequency, the inverter does not operate at the retained frequency even if restarted.

#### During external operation (Pr. 573=1)



#### During PID control (reverse action) (Pr. 573=1)



#### CAUTION

- When terminal assignment is changed using Pr. 190 to Pr. 196 (output terminal function selection), the other functions may be affected. Please make setting after confirming the function of each terminal.

## (2) Function related to 4mA input check

| Function                                     | Operation (Pr. 573 = 1)                                                                                                                                                                                                                                                                                                                                         | Refer to page |
|----------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------|
| <b>Minimum frequency</b>                     | Even if the input current decreases, minimum frequency setting clamp is valid.                                                                                                                                                                                                                                                                                  | 67            |
| <b>Multi-speed operation</b>                 | Operation by multiple speed signal has precedence even if input current decreases. (Frequency is not retained when the input current decreases.)<br>Operation stops when a multi-speed signal turns off.                                                                                                                                                        | 72            |
| <b>Jog operation</b>                         | The Jog signal has precedence even during decrease in input current. (Frequency is not retained when the input current decreases.)<br>Operation stops when the jog signal is turned off during decrease in input current.<br>PU/jog operation is enabled during PID control.<br>At this time, PU/jog operation has precedence during decrease in input current. | 74            |
| <b>MRS</b>                                   | Output is shut off by the MRS signal even if input current decreases. (The inverter stops when the MRS signal is turned off.)                                                                                                                                                                                                                                   | 92            |
| <b>Remote setting</b>                        | The retained frequency will not change even if remote acceleration/deceleration and clear are performed during decrease in input current. Reflected at restoration.                                                                                                                                                                                             | 77            |
| <b>Retry</b>                                 | When retry was successful at error occurrence during decrease in input current, retained frequency was not cleared and operation continues.                                                                                                                                                                                                                     | 119           |
| <b>Added compensation, override function</b> | Operation of added compensation (terminal 1) and override compensation (terminal 2) are invalid during decrease in input current.                                                                                                                                                                                                                               | 132           |
| <b>Input filter time constant</b>            | The value before filtering is detected.<br>When input current decreases, frequency after filtering (average value) is retained.                                                                                                                                                                                                                                 | 133           |
| <b>Forward/reverse rotation prevention</b>   | Motor rotation direction can be restricted independently of 4mA input check setting.                                                                                                                                                                                                                                                                            | 145           |
| <b>PID control</b>                           | Although PID operation is stopped when input current decreases, the X14 signal remains on. (PID operation is valid.)                                                                                                                                                                                                                                            | 189           |
| <b>Power failure stop</b>                    | Even if input current decreases when undervoltage or power failure occurs, the motor stops according to the setting of power-failure deceleration stop function                                                                                                                                                                                                 | 117           |
| <b>Pump function</b>                         | If auxiliary motor switchover conditions of pump function is satisfied even when input current decreases, motor connection/release operation is performed.                                                                                                                                                                                                      | 202           |
| <b>Switch-over</b>                           | When the switchover function is operated, frequency is the same as that of the retained frequency.<br>Note that if 4mA input is made invalid once in switchover mode, the frequency is not retained next time.                                                                                                                                                  | 147           |

### ◆ Parameters referred to ◆

Pr. 73 Analog input selection  Refer to page 132

Pr. 267 Terminal 4 input selection  Refer to page 130

## 3.16 Misoperation prevention and parameter setting restriction

| Purpose                                                                         | Parameter that must be set                                          |                          | Refer to page |
|---------------------------------------------------------------------------------|---------------------------------------------------------------------|--------------------------|---------------|
| Limit reset function<br>Make alarm stop when PU is disconnected<br>Stop from PU | Reset selection/<br>disconnected PU detection/<br>PU stop selection | Pr. 75                   | 141           |
| Prevention of parameter rewrite                                                 | Parameter write disable<br>selection                                | Pr. 77                   | 144           |
| Prevention of reverse rotation of the<br>motor                                  | Reverse rotation prevention<br>selection                            | Pr. 78                   | 145           |
| Display necessary parameters                                                    | Display of applied<br>parameters and user group<br>function         | Pr.160, Pr.172 to Pr.174 | 145           |
| Control of parameter write by<br>communication                                  | EEPROM write selection                                              | Pr.342                   | 167           |

### 3.16.1 Reset selection/disconnected PU detection/PU stop selection (Pr.75)

You can select the reset input acceptance, disconnected PU (FR-DU07/FR-PU04) connector detection function and PU stop function.

| Parameter Number | Name                                                           | Initial Value | Setting Range<br>200V class (400V class)        | Description                                                                                                                 |
|------------------|----------------------------------------------------------------|---------------|-------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------|
| 75               | Reset selection/disconnected<br>PU detection/PU stop selection | 14            | 02330<br>(01160)<br>or less                     | For the initial value, reset always<br>enabled, without disconnected PU<br>detection, and with PU stop function<br>are set. |
|                  |                                                                |               | 0 to 3, 14 to 17<br>03160<br>(01800)<br>or more |                                                                                                                             |

·The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

·The Pr. 75 value can be set any time. Also, if parameter (all) clear is executed, this setting will not return to the initial value.

| Pr.75<br>Setting         | Reset Selection                                           | Disconnected PU<br>Detection                                        | PU Stop Selection                                                                                                                                                                                          | Reset Limit<br>(FR-F720-03160<br>(FR-F740-01800)<br>or more) |
|--------------------------|-----------------------------------------------------------|---------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------|
| 0                        | Reset input always enabled                                | If the PU is disconnected,<br>operation will be continued.          | Pressing <br>decelerates the motor to a<br>stop only in the PU<br>operation mode.                                     | Not function                                                 |
| 1                        | Enabled only when the protective<br>function is activated |                                                                     |                                                                                                                                                                                                            |                                                              |
| 2                        | Reset input always enabled                                | When the PU is<br>disconnected, the inverter<br>output is shut off. |                                                                                                                                                                                                            |                                                              |
| 3                        | Enabled only when the protective<br>function is activated |                                                                     |                                                                                                                                                                                                            |                                                              |
| 14<br>(initial<br>value) | Reset input always enabled                                | If the PU is disconnected,<br>operation will be continued.          | Pressing <br>decelerates the<br>motor to a stop in any of<br>the PU, external and<br>communication operation<br>modes. |                                                              |
| 15                       | Enabled only when the protective<br>function is activated |                                                                     |                                                                                                                                                                                                            |                                                              |
| 16                       | Reset input always enabled                                | When the PU is<br>disconnected, the inverter<br>output is shut off. |                                                                                                                                                                                                            |                                                              |
| 17                       | Enabled only when the protective<br>function is activated |                                                                     |                                                                                                                                                                                                            |                                                              |
| 100                      | Reset input always enabled                                | If the PU is disconnected,<br>operation will be continued.          | Pressing <br>decelerates the motor to a<br>stop only in the PU<br>operation mode.                                     | Function                                                     |
| 101                      | Enabled only when the protective<br>function is activated |                                                                     |                                                                                                                                                                                                            |                                                              |
| 102                      | Reset input always enabled                                | When the PU is<br>disconnected, the inverter<br>output is shut off. |                                                                                                                                                                                                            |                                                              |
| 103                      | Enabled only when the protective<br>function is activated |                                                                     |                                                                                                                                                                                                            |                                                              |
| 114                      | Reset input always enabled                                | If the PU is disconnected,<br>operation will be continued.          | Pressing <br>decelerates the<br>motor to a stop in any of<br>the PU, external and<br>communication operation<br>modes. |                                                              |
| 115                      | Enabled only when the protective<br>function is activated |                                                                     |                                                                                                                                                                                                            |                                                              |
| 116                      | Reset input always enabled                                | When the PU is<br>disconnected, the inverter<br>output is shut off. |                                                                                                                                                                                                            |                                                              |
| 117                      | Enabled only when the protective<br>function is activated |                                                                     |                                                                                                                                                                                                            |                                                              |

Pr.74  
page 133

Pr.76  
page 121



### (1) Reset selection

- You can select the operation timing of reset function (RES signal, reset command through communication) input.
- When *Pr. 75* is set to any of "1, 3, 15, 17, 101, 103, 115, 117", a reset can be input only when the protective function is activated.

---

#### CAUTION

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- When the reset signal (RES) is input during operation, the motor coasts since the inverter being reset shuts off the output. Also, the cumulative value of the electronic thermal relay function is cleared.
  - The reset key of the PU is valid only when the protective function is activated, independently of the *Pr. 75* setting.
- 

### (2) Disconnected PU detection

- This function detects that the PU (FR-DU07/FR-PU04) has been disconnected from the inverter for longer than 1s and causes the inverter to provide an alarm output (E.PUE) and come to an alarm stop.
- When *Pr. 75* is set to any of "0, 1, 14, 15, 100, 101, 114, 115", operation is continued if the PU is disconnected.

---

#### CAUTION

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- When the PU has been disconnected since before power-on, it is not judged as an alarm.
  - To make a restart, confirm that the PU is connected and then reset the inverter.
  - The motor decelerates to a stop when the PU is disconnected during PU jog operation with *Pr. 75* set to any of "0, 1, 14, 15" (operation is continued if the PU is disconnected).
  - When RS-485 communication operation is performed through the PU connector, the reset selection/PU stop selection function is valid but the disconnected PU detection function is invalid.
- 

### (3) PU stop selection

- In any of the PU operation, external operation and network operation modes, the motor can be stopped by pressing  of the PU.
- When the inverter is stopped by the PU stop function, "PS" is displayed but an alarm is not output. An alarm output is not provided.
- When *Pr. 75* is set to any of "0 to 3, 100 to 103", deceleration to a stop by  is valid only in the PU operation mode.

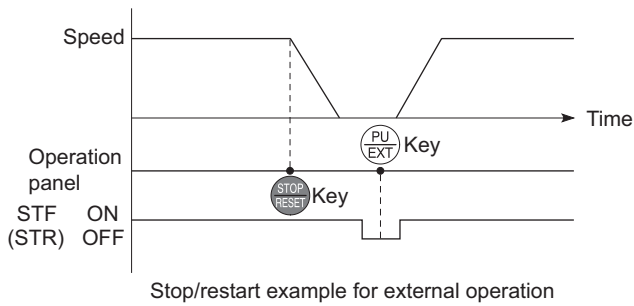
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#### REMARKS

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The motor will also decelerate to a stop (PU stop) when  is input during operation in the PU mode through RS-485 communication with *Pr. 551 PU mode operation command source selection* set to "1" (PU mode RS-485 terminals).

**(4) Restarting method when stop was made by pressing  from the PU during external operation**



**(a) When operation panel (FR- DU07) is used**

- 1) After the motor has decelerated to a stop, turn off the STF or STR signal.
- 2) Press  to display . .... ( *PS* canceled)
- 3) Press  to return to .
- 4) Turn on the STF or STR signal.

**(b) Connection of the parameter unit (FR-PU04)**

- 1) After the motor has decelerated to a stop, turn off the STF or STR signal.
- 2) Press . .... ( *PS* canceled)
- 3) Turn on the STF or STR signal.

- The motor can be restarted by making a reset using a power supply reset or RES signal.

**CAUTION**

- If *Pr. 250 Stop selection* is set to other than "9999" to select coasting to a stop, the motor will not be coasted to a stop but decelerated to a stop by the PU stop function during external operation.

 **CAUTION**

-  Do not reset the inverter with the start signal on. Doing so will cause the inverter to start immediately after a reset, leading to hazardous conditions.

**(5) Reset limit**

- Setting can be made for the FR-F720-03160 (FR-F740-01800) or more.
- You can set *Pr. 75* to disable reset operation until the thermal cumulative amount reaches 0 when a thermal trip (THM, THT) or an overcurrent trip (OC1 to OC3) occurs consecutively twice.
- When *Pr. 75* = "100 to 103, 114 to 117", reset limit is made valid.

**REMARKS**

When the power-on reset (no control power is supplied) is made, the thermal cumulative amount is cleared.

◆ **Parameters referred to** ◆

*Pr.250 Stop selection*  Refer to page 89



### 3.16.2 Parameter write disable selection (Pr.77)

You can select whether write to various parameters can be performed or not. Use this function to prevent parameter values from being rewritten by misoperation.

Pr.76

page 121

Pr.78

page 145

| Parameter Number | Name                      | Initial Value | Setting Range | Description                                                                      |
|------------------|---------------------------|---------------|---------------|----------------------------------------------------------------------------------|
| 77               | Parameter write selection | 0             | 0             | Write is enabled only during a stop.                                             |
|                  |                           |               | 1             | Parameter write is not enabled.                                                  |
|                  |                           |               | 2             | Parameter write is enabled in any operation mode regardless of operation status. |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145.)

Pr. 77 can be always set independently of the operation mode and operation status.

#### (1) Write parameters only at a stop (setting "0", initial vale)

- Parameters can be written only during a stop in the PU operation mode.
- The parameters marked in the parameter list (page 44)  can always be written, regardless of the operation mode and operation status. However, Pr. 72 PWM frequency selection and Pr. 240 Soft-PWM operation selection can be written during operation in the PU operation mode, but cannot be written in external operation mode.

#### (2) Disable parameter write (Setting "1")

- Parameter write is not enabled. (Reading is enabled.)
- Parameter clear and all parameter clear cannot be performed, either.
- The parameters given on the right can be written if Pr. 77 = "1".

| Parameter Number | Name                                                        |
|------------------|-------------------------------------------------------------|
| 22               | Stall prevention operation level                            |
| 75               | Reset selection/disconnected PU detection/PU stop selection |
| 77               | Parameter write selection                                   |
| 79               | Operation mode selection                                    |

#### (3) Write parameters during operation (Setting "2")

- Parameters can always be written.
- The following parameters cannot be written during operation if Pr. 77 = "2". Stop operation when changing their parameter settings.

| Parameter Number | Name                                                                                  |
|------------------|---------------------------------------------------------------------------------------|
| 19               | Base frequency voltage                                                                |
| 23               | Stall prevention operation level compensation factor at double speed                  |
| 48               | Second stall prevention operation current                                             |
| 49               | Second stall prevention operation frequency                                           |
| 60               | Energy saving control selection                                                       |
| 66               | Stall prevention operation reduction starting frequency                               |
| 71               | Applied motor                                                                         |
| 79               | Operation mode selection                                                              |
| 80               | Motor capacity (simple magnetic flux vector control)                                  |
| 90               | Motor constant (R1)                                                                   |
| 100 to 109       | (Adjustable 5 points V/F parameter)                                                   |
| 135              | Commercial power-supply switchover sequence output terminal selection                 |
| 136              | MC switchover interlock time                                                          |
| 137              | Waiting time at a start                                                               |
| 138              | Commercial power-supply operation switchover selection at an alarm                    |
| 139              | Automatic switchover frequency between inverter and commercial power-supply operation |
| 178 to 196       | (I/O terminal function selection)                                                     |
| 255              | Life alarm status display                                                             |
| 256              | Inrush current limit circuit life display                                             |
| 257              | Control circuit capacitor life display                                                |
| 258              | Main circuit capacitor life display                                                   |
| 329              | Digital input unit selection (Parameter for the plug-in option FR-A7AX)               |
| 343              | Communication error count                                                             |
| 563              | Energization time carrying-over times                                                 |
| 564              | Operating time carrying-over times                                                    |
| 570              | Multiple rating setting                                                               |

#### ◆ Parameters referred to ◆

Pr. 79 Operation mode selection  Refer to page 147

### 3.16.3 Reverse rotation prevention selection (Pr.78)

This function can prevent reverse rotation fault resulting from the incorrect input of the start signal.

Pr. 77  
page 144  
Pr. 79  
page 147

| Parameter Number | Name                                  | Initial Value | Setting Range | Description                                |
|------------------|---------------------------------------|---------------|---------------|--------------------------------------------|
| 78               | Reverse rotation prevention selection | 0             | 0             | Both forward and reverse rotations allowed |
|                  |                                       |               | 1             | Reverse rotation disabled                  |
|                  |                                       |               | 2             | Forward rotation disallowed                |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145.)

- Set this parameter when you want to limit the motor rotation to only one direction.
- This parameter is valid for all of the reverse rotation and forward rotation keys of the operation panel (FR-DU07), parameter unit (FR-PU04), signals (STF, STR signals) via external terminals, and the forward and reverse rotation commands through communication.

#### ◆ Parameters referred to ◆

Pr. 79 Operation mode selection  Refer to page 147

### 3.16.4 Display of applied parameters and user group function (Pr.160, Pr.172 to Pr.174)

Parameter which can be read from the operation panel and parameter unit can be restricted.  
In the initial setting, only the simple mode parameters are displayed.

Pr.159  
page 197  
Pr.161  
page 220  
Pr.171  
page 105  
Pr.178  
page 90

| Parameter Number | Name                                          | Initial Value | Setting Range  | Description                                                         |
|------------------|-----------------------------------------------|---------------|----------------|---------------------------------------------------------------------|
| 160              | User group read selection                     | 0             | 9999           | Only the simple mode parameters can be displayed.                   |
|                  |                                               |               | 0              | The simple mode and extended parameters can be displayed            |
|                  |                                               |               | 1              | Only parameters registered in the user group can be displayed.      |
| 172 *1           | User group registered display/<br>batch clear | 0             | (0 to 16)      | Displays the number of cases registered as a user group (Read only) |
|                  |                                               |               | 9999           | Batch clear the user group registration                             |
| 173 *1, 2        | User group registration                       | 9999          | 0 to 999, 9999 | Set the parameter numbers to be registered to the user group.       |
| 174 *1, 2        | User group clear                              | 9999          | 0 to 999, 9999 | Set the parameter numbers to be cleared from the user group.        |

\*1 They can be set when Pr. 160 User group read selection = "0".

\*2 The values read from Pr. 173 and Pr. 174 are always "9999".

#### (1) Display of simple mode parameters and extended parameters (Pr.160)

- When Pr. 160 = "9999" (initial value), only the simple mode parameters can be displayed on the operation panel (FR-DU07) and parameter unit (FR-PU04). (Refer to the parameter list, pages 44 to 55, for the simple mode parameters.)
- Setting "0" to Pr. 160 enables the display of the simple mode parameters and extended parameters.

#### REMARKS

- When a plug-in option is fitted to the inverter, the option parameters can also be read.
- When reading the parameters using the communication option, all parameters (simple mode, extended mode, parameters for options) can be read regardless of the Pr. 160 setting.
- When reading the parameters using the RS-485 terminals, all parameters can be read regardless of the Pr. 160 setting by setting Pr.550 NET mode operation command source selection and Pr. 551 PU mode operation command source selection.

| Pr.551                    | Pr.550                                | Pr.160 Valid/Invalid                  |
|---------------------------|---------------------------------------|---------------------------------------|
| 1 (RS-485)                | —                                     | Valid                                 |
| 2 (PU)<br>(initial value) | 0(OP)                                 | Valid                                 |
|                           | 1(RS-485)                             | Invalid (all readable)                |
|                           | 9999 (auto-detect)<br>(initial value) | With OP: valid                        |
|                           |                                       | Without OP: invalid<br>(all readable) |

\* OP indicates a communication option

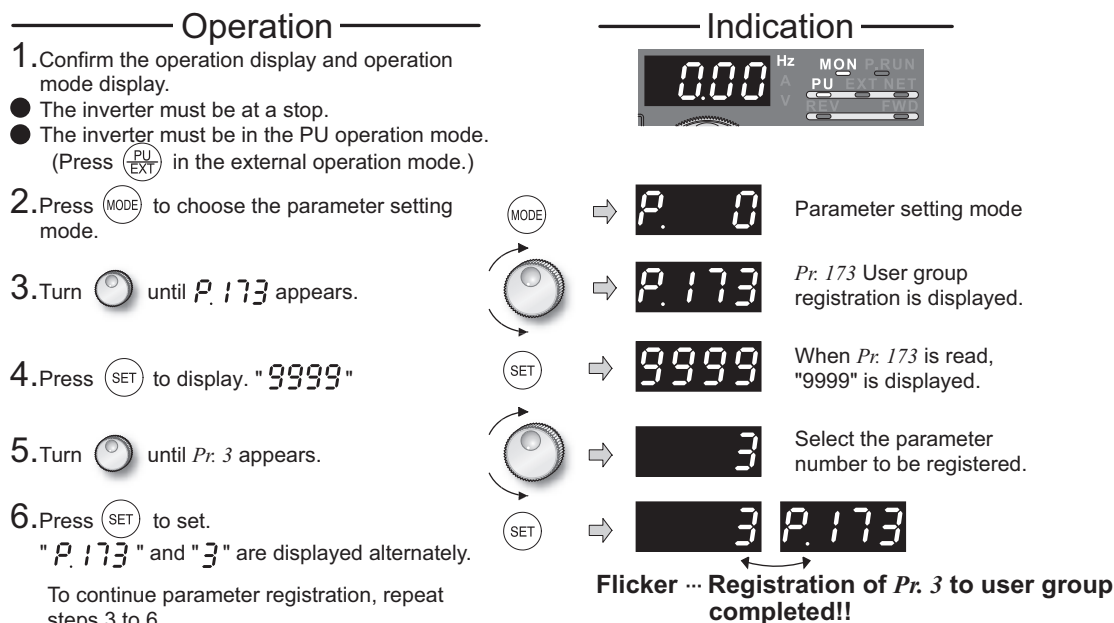
- Pr. 15 Jog frequency, Pr. 16 Jog acceleration/deceleration time, Pr. 145 PU display language selection, Pr. 991 PU contrast adjustment are displayed as simple mode parameters when the parameter unit (FR-PU04) is mounted.

## (2) User group function (Pr. 160, Pr. 172 to Pr. 174)

- The user group function is designed to display only the parameters necessary for setting.
- From among all parameters, a maximum of 16 parameters can be registered to a user group. When Pr. 160 is set to "1", only the parameters registered to the user group can be accessed. (Reading of parameters other than the user group registration is disabled.)
- To register a parameter to the user group, set its parameter number to Pr. 173.
- To delete a parameter from the user group, set its parameter number to Pr. 174. To batch-delete the registered parameters, set Pr. 172 to "9999".

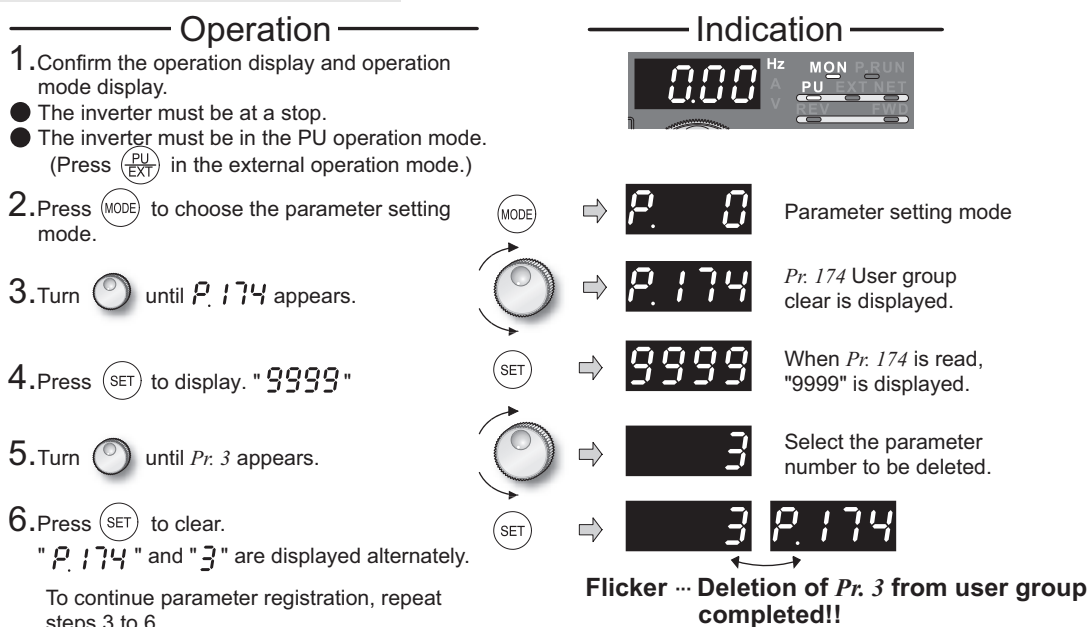
## (3) Registration of parameter to user group (Pr.173)

When registering Pr. 3 to user group



## (4) Deletion of parameter from user group (Pr.174)

When deleting Pr. 3 from user group



### REMARKS

- Pr. 77, Pr. 160 and Pr. 991 can always be read, independently of the user group setting.
- Pr. 77, Pr. 160 and Pr. 172 to Pr. 174 cannot be registered to the user group.
- When Pr. 174 or Pr. 175 is read, "9999" is always displayed. Although "9999" can be written, no function is available.
- When any value other than "9999" is set to Pr. 172, no function is available.

### ◆ Parameters referred to ◆

Pr.550 NET mode operation command source selection Refer to page 156  
Pr.551 PU mode operation command source selection Refer to page 156

### 3.17 Selection of operation mode and operation location

| Purpose                           | Parameter that must be set                                                                            |                                    | Refer to page |
|-----------------------------------|-------------------------------------------------------------------------------------------------------|------------------------------------|---------------|
| Operation mode selection          | Operation mode selection                                                                              | Pr. 79                             | 147           |
| Started in network operation mode | Operation mode at power on                                                                            | Pr. 79, Pr. 340                    | 155           |
| Selection of control location     | Selection of control source, speed command source and control location during communication operation | Pr. 338, Pr. 339, Pr. 550, Pr. 551 | 156           |

#### 3.17.1 Operation mode selection (Pr. 79)

Used to select the operation mode of the inverter.

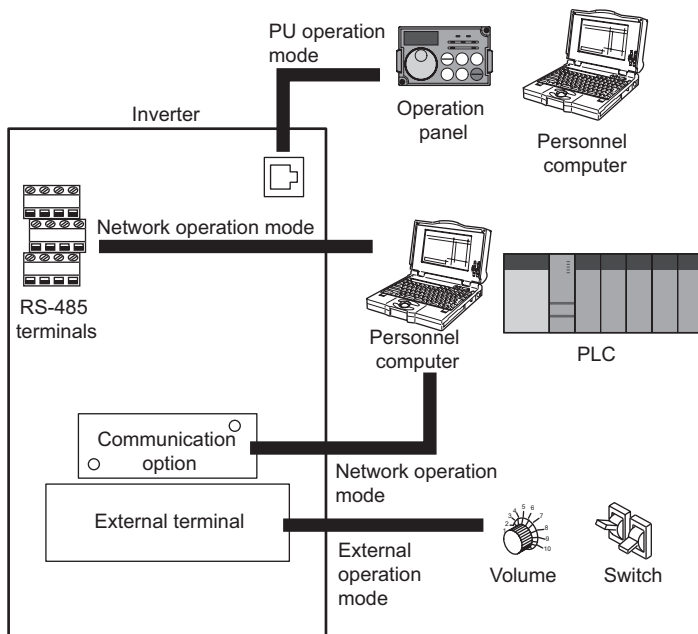
You can freely change between operation by external signal (external operation), operation by PU (FR-DU07/FR-PU04) (PU operation), operation by combination of PU operation and external operation (external/PU combined operation) and network operation (when the RS-485 terminals or communication option is used).

Pr. 78  
page 145

Pr. 80  
page 59

| Parameter Number | Name                     | Initial Value | Setting Range | Description                                                                                                                                                                                                                                                  | LED Indication<br>: Off<br>: On                                                                                                                                                                                                                                                                                                               |
|------------------|--------------------------|---------------|---------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 79               | Operation mode selection | 0             | 0             | Use external/PU switchover mode (press  to switch between the PU and external operation mode. At power on, the inverter is in the external operation mode.                | External operation mode<br><br>PU operation mode<br>                                                                                                                    |
|                  |                          |               | 1             | Fixed to PU operation mode                                                                                                                                                                                                                                   |                                                                                                                                                                                                                                                           |
|                  |                          |               | 2             | Fixed to external operation mode<br>Operation can be performed by switching between the external and Net operation mode.                                                                                                                                     | External operation mode<br><br>NET operation mode<br>                                                                                                               |
|                  |                          |               | 3             | External/PU combined operation mode 1                                                                                                                                                                                                                        |                                                                                                                                                                                                                                                          |
|                  |                          |               |               | <b>Running frequency</b> <b>Start signal</b>                                                                                                                                                                                                                 |                                                                                                                                                                                                                                                                                                                                               |
|                  |                          |               |               | PU (FR-DU07/FR-PU04) setting or external signal input (multi-speed setting, across terminals 4-5 (valid when AU signal turns on)).                                                                                                                           |                                                                                                                                                                                                                                                                                                                                               |
|                  |                          |               |               | External signal input (terminal STF, STR)                                                                                                                                                                                                                    |                                                                                                                                                                                                                                                                                                                                               |
|                  |                          |               | 4             | External/PU combined operation mode 2                                                                                                                                                                                                                        |                                                                                                                                                                                                                                                          |
|                  |                          |               |               | <b>Running frequency</b> <b>Start signal</b>                                                                                                                                                                                                                 |                                                                                                                                                                                                                                                                                                                                               |
|                  |                          |               |               | External signal input (Terminal 2, 4, 1, JOG, multi-speed selection, etc.)                                                                                                                                                                                   |                                                                                                                                                                                                                                                                                                                                               |
|                  |                          |               |               | Input from the PU (FR-DU07/FR-PU04)<br>(  ,  )                                      |                                                                                                                                                                                                                                                                                                                                               |
|                  |                          |               | 6             | Switch-over mode<br>Switch among PU operation, external operation, and NET operation while keeping the same operation status.                                                                                                                                | PU operation mode<br><br>External operation mode<br><br>NET operation mode<br> |
|                  |                          |               | 7             | External operation mode (PU operation interlock)<br>X12 signal ON*<br>Operation mode can be switched to the PU operation mode.<br>(output stop during external operation)<br>X12 signal OFF*<br>Operation mode can not be switched to the PU operation mode. | PU operation mode<br><br>External operation mode<br>                                                                                                                |

## (1) Operation mode basics



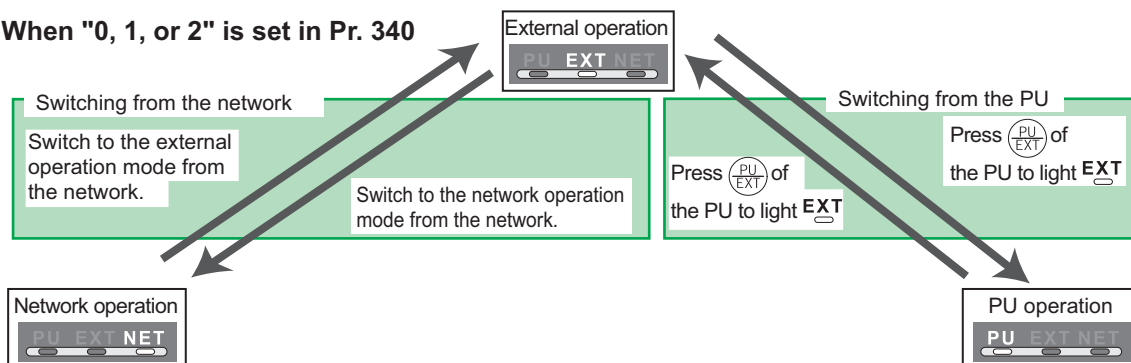
- The operation mode is to specify the source of inputting the start command and set frequency of the inverter.
- Select the "external operation mode" when performing operation by basically using the control circuit terminals and providing potentiometers, switches, etc. externally, select the "PU operation mode" when inputting the start command and frequency setting through communication from the operation panel (FR-DU07), parameter unit (FR-PU04), PU connector, or select the "network operation mode (NET operation mode)" when using the RS-485 terminals or communication option.
- The operation mode can be selected from the operation panel or with the communication instruction code.

### REMARKS

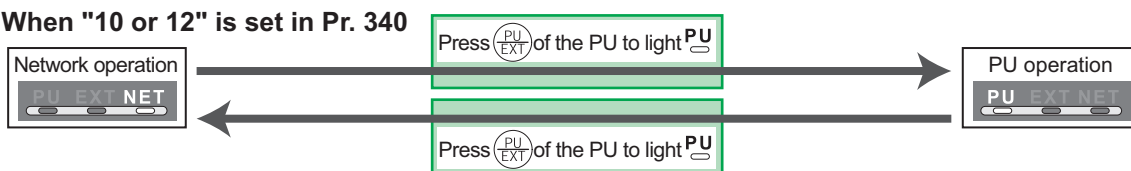
- Either "3" or "4" may be set to select the PU/external combined operation, and these settings differ in starting method.
- In the initial setting, the stop function by  of the PU (FR-DU07) (PU stop selection) is valid also in other than the PU operation mode. (Pr. 75 Reset selection/disconnected PU detection/PU stop selection. Refer to page 141.)

## (2) Operation mode switching method

When "0, 1, or 2" is set in Pr. 340



When "10 or 12" is set in Pr. 340

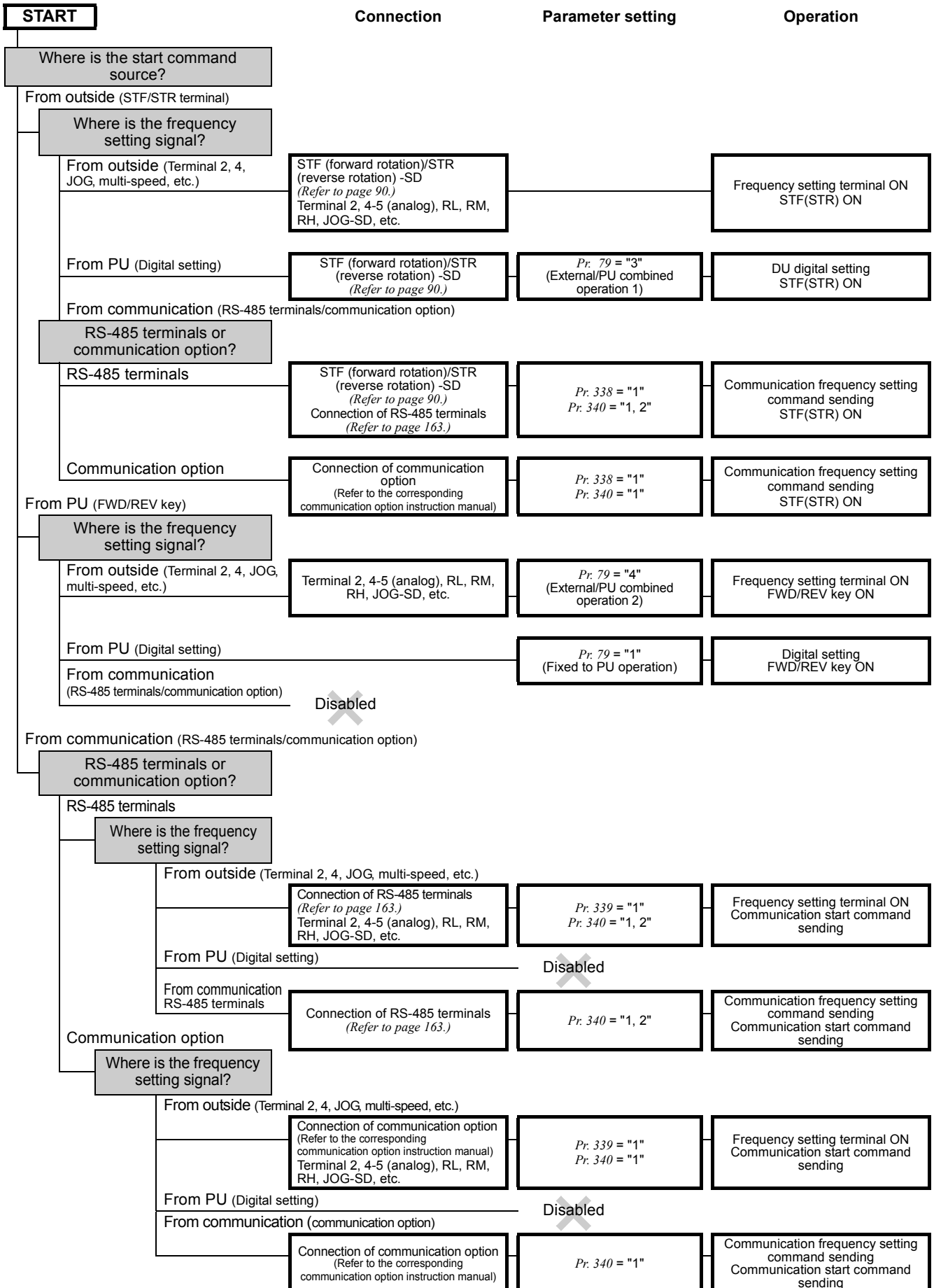


### REMARKS

- For switching of operation by external terminals, refer to the following:
  - PU operation external interlock signal (X12 signal)  page 152
  - PU-external operation switch-over signal (X16)  page 153
  - PU-NET operation switchover signal (X65), External-NET operation switchover signal (X66)  page 154
  - Pr. 340 Communication startup mode selection  page 155

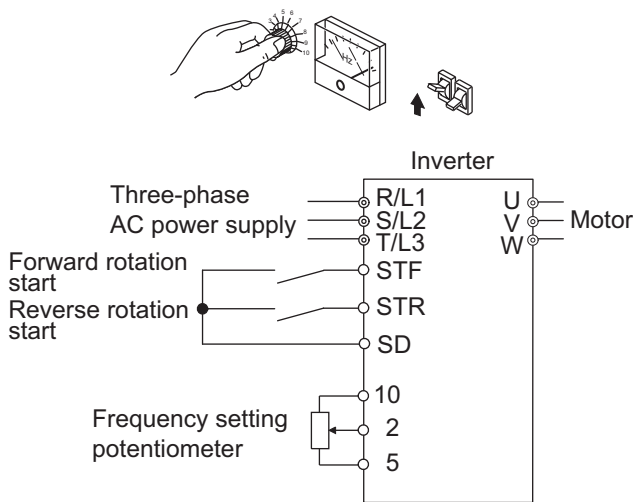
**(3) Operation mode selection flow**

In the following flowchart, select the basic parameter setting and terminal connection related to the operation mode.



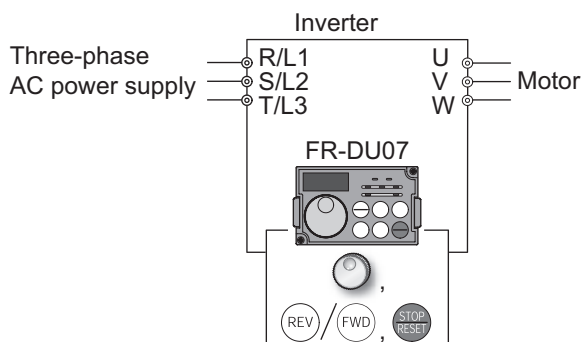
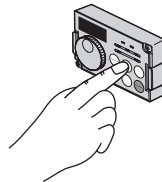


#### (4) External operation mode (setting "0" (initial value), "2")



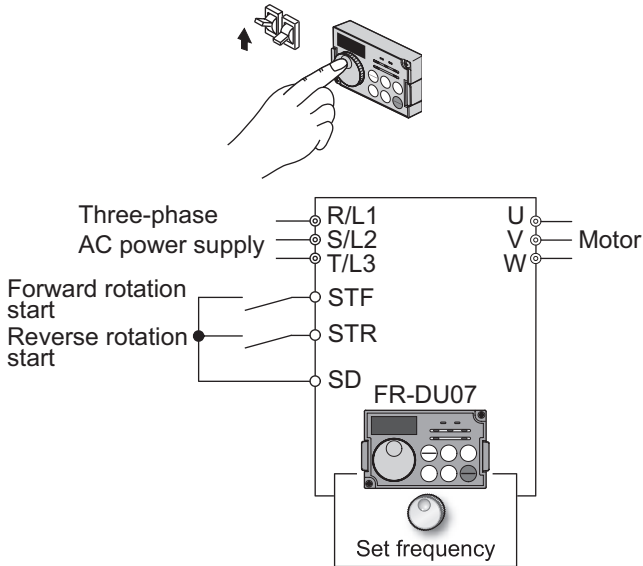
- Select the external operation mode when performing operation by providing a frequency setting potentiometer, start switch, etc. externally and connecting them to the control circuit terminals of the inverter.
- Basically, parameter changing is disabled in external operation mode. (Some parameters can be changed. Refer to *page 44* for the parameter list.)
- When "0" or "2" is selected for *Pr. 79*, the inverter enters the external operation mode at power on. (When using the network operation mode, refer to *page 155*.)
- When parameter changing is seldom necessary, setting "2" fixes the operation mode to external operation mode. When frequent parameter changing is necessary, setting "0" (initial value) allows the operation mode to be changed easily to PU operation mode by pressing  of the operation panel. When you switched to PU operation mode, always return to external operation mode.
- The STF and STR signal are used as a start command, and the terminal 2, 4, multi-speed setting, JOG signal, etc. are used as frequency setting.

#### (5) PU operation mode (setting "1")



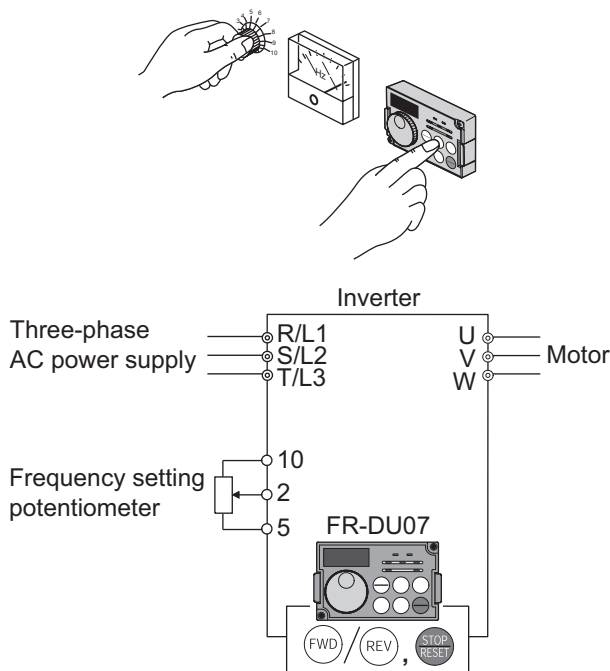
- Select the PU operation mode when performing operation by only the key operation of the operation panel (FR-DU07) or parameter unit (FR-PU04). Also select the PU operation mode when making communication using the PU connector.
- When "1" is selected for *Pr. 79*, the inverter enters the PU operation mode at power on. You cannot change to the other operation mode.
- The setting dial of the operation panel can be used for setting like a volume. (*Pr. 161 Frequency setting/key lock operation selection, refer to page 220.*)

## (6) PU/external combined operation mode 1 (setting "3")



- Select the PU/external combined operation mode 1 when making frequency setting from the operation panel (FR-DU07) or parameter unit (FR-PU04) and inputting the start command with the external start switch.
- Select "3" for *Pr.* 79. You cannot change to the other operation mode.
- When a frequency is input from the external signal by multi-speed setting, it has a higher priority than the frequency setting of the PU. When AU is on, the terminal 4 is used.

## (7) PU/external combined operation mode 2 (setting "4")



- Select the PU/external combined operation mode 2 when making frequency setting from the external potentiometer, multi-speed or JOG signal and inputting the start command by key operation of the operation panel (FR-DU07) or parameter unit (FR-PU04).
- Select "4" for *Pr.* 79. You cannot change to the other operation mode.



## (8) Switch-over mode (Setting "6")

- While continuing operation, you can switch between the PU operation, external operation and network operation (when RS-485 terminals or communication option is used).

| Operation Mode Switching           | Switching Operation/Operating Status                                                                                                                                                                                                                                                                                                                                                                  |
|------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| External operation → PU operation  | Select the PU operation mode with the operation panel or parameter unit. <ul style="list-style-type: none"> <li>Rotation direction is the same as that of external operation.</li> <li>The frequency set with the volume (frequency setting potentiometer) or like is used unchanged. (Note that the setting will disappear when power is switched off or the inverter is reset.)</li> </ul>          |
| External operation → NET operation | Send the mode change command to network operation mode through communication. <ul style="list-style-type: none"> <li>Rotation direction is the same as that of external operation.</li> <li>The value set with the setting volume (frequency setting potentiometer) or like is used unchanged. (Note that the setting will disappear when power is switched off or the inverter is reset.)</li> </ul> |
| PU operation → external operation  | Press the external operation key of the operation panel, parameter unit. <ul style="list-style-type: none"> <li>The rotation direction is determined by the input signal of the external operation.</li> <li>The set frequency is determined by the external frequency setting signal.</li> </ul>                                                                                                     |
| PU operation → NET operation       | Send the mode change command to network operation mode through communication. <ul style="list-style-type: none"> <li>Rotation direction and set frequency are the same as those of PU operation.</li> </ul>                                                                                                                                                                                           |
| NET operation → external operation | Command to change to external mode is transmitted by communication. <ul style="list-style-type: none"> <li>Rotation direction is determined by the external operation input signal.</li> <li>The set frequency is determined by the external frequency setting signal.</li> </ul>                                                                                                                     |
| NET operation → PU operation       | Select the PU operation mode with the operation panel or parameter unit. <ul style="list-style-type: none"> <li>The rotation direction and set frequency signal in network operation mode are used unchanged.</li> </ul>                                                                                                                                                                              |

## (9) PU operation interlock (Setting "7")

- The PU operation interlock function is designed to forcibly change the operation mode to external operation mode when the PU operation interlock signal (X12) input turns off. This function prevents the inverter from being inoperative by the external command if the mode is accidentally left unswitched from the PU operation mode.
- Set "7" (PU operation interlock) in *Pr. 79*.
- For the terminal used for X12 signal (PU operation interlock signal) input, set "12" in any of *Pr. 178 to Pr. 189* (input terminal function selection) to assign the function. (Refer to *page 90* for *Pr. 178 to Pr. 189*.)
- When the X 12 signal has not been assigned, the function of the MRS signal switches from MRS (output stop) to the PU operation interlock signal.

| X12 (MRS) signal | Function/Operation                                                                                                            |                                                                                                                                                                                |
|------------------|-------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
|                  | Operation Mode                                                                                                                | Parameter Write                                                                                                                                                                |
| ON               | Operation mode (external, PU, NET) switching enabled<br>Output stop during external operation                                 | Parameter write enabled ( <i>Pr. 77 Parameter write selection</i> , depending on the corresponding parameter write condition (Refer to <i>page 44</i> for the parameter list)) |
| OFF              | Forcibly switched to external operation mode<br>External operation allowed.<br>Switching to PU or NET operation mode disabled | Parameter write disabled with exception of <i>Pr. 79</i>                                                                                                                       |

### <Function/operation changed by switching on-off the X12 (MRS) signal>

| Operating Condition |             | X12 (MRS) Signal | Operation Mode | Operating Status                                                                                             | Switching to PU, NET Operation Mode |
|---------------------|-------------|------------------|----------------|--------------------------------------------------------------------------------------------------------------|-------------------------------------|
| Operation mode      | Status      |                  |                |                                                                                                              |                                     |
| PU/NET              | During stop | ON→OFF *1        | External *2    | If external operation frequency setting and start signal are entered, operation is performed in that status. | Disallowed                          |
|                     | Running     | ON→OFF *1        |                |                                                                                                              | Disallowed                          |
| External            | During stop | OFF→ON           | External *2    | During stop                                                                                                  | Enable                              |
|                     |             | ON→OFF           |                |                                                                                                              | Disallowed                          |
|                     | Running     | OFF→ON           |                | During operation → output stop                                                                               | Disallowed                          |
|                     |             | ON→OFF           |                | Output stop → operation                                                                                      | Disallowed                          |

\*1 The operation mode switches to external operation mode independently of whether the start signal (STF, STR) is on or off. Therefore, the motor is run in external operation mode when the X12 (MRS) signal is turned off with either of STF and STR on.

\*2 At alarm occurrence, pressing  of the operation panel resets the inverter.

### CAUTION

- If the X12 (MRS) signal is on, the operation mode cannot be switched to PU operation mode when the start signal (STF, STR) is on.
- When the MRS signal is used as the PU interlock signal, the MRS signal serves as the normal MRS function (output stop) by turning on the MRS signal and then changing the *Pr. 79* value to other than "7" in the PU operation mode. Also as soon as "7" is set in *Pr. 79*, the signal acts as the PU interlock signal.
- When the MRS signal is used as the PU operation interlock signal, the logic of the signal is as set in *Pr. 17*. When *Pr. 17* = "2", read ON as OFF and OFF as ON in the above explanation.
- Changing the terminal assignment using *Pr. 178 to Pr. 189* (input terminal function selection) may affect the other functions. Please make setting after confirming the function of each terminal.

**(10) Switching of operation mode by external terminal (X16 signal)**

- When external operation and operation from the operation panel are used together, use of the PU-external operation switching signal (X16) allows switching between the PU operation mode and external operation mode during a stop (during a motor stop, start command off).
- When *Pr. 79* = any of "0, 6, 7", the operation mode can be switched between the PU operation mode and external operation mode. (*Pr. 79* = "6" switch-over mode can be changed during operation)
- For the terminal used for X16 signal input, set "16" in any of *Pr. 178 to Pr. 189* (*input terminal function selection*) to assign the function.

| <i>Pr. 79</i><br>Setting |              | X16 Signal State Operation Mode     |                   | Remarks                                                                                        |
|--------------------------|--------------|-------------------------------------|-------------------|------------------------------------------------------------------------------------------------|
|                          |              | ON (external)                       | OFF (PU)          |                                                                                                |
| 0 (initial value)        |              | External operation mode             | PU operation mode | Can be switched to external, PU or NET operation mode                                          |
| 1                        |              | PU operation mode                   |                   | Fixed to PU operation mode                                                                     |
| 2                        |              | External operation mode             |                   | Fixed to external operation mode (Can be switched to NET operation mode)                       |
| 3, 4                     |              | External/PU combined operation mode |                   | External/PU combined mode fixed                                                                |
| 6                        |              | External operation mode             | PU operation mode | Can be switched to external, PU or NET operation mode with operation continued                 |
| 7                        | X12(MRS) ON  | External operation mode             | PU operation mode | Can be switched to external, PU or NET operation mode (Output stop in external operation mode) |
|                          | X12(MRS) OFF | External operation mode             |                   | Fixed to external operation mode (Forcibly switched to external operation mode.)               |

**REMARKS**

- The operation mode status changes depending on the setting of *Pr. 340 Communication startup mode selection* and the ON/OFF states of the X65 and X66 signals. (For details, refer to *page 154*.)
- The priorities of *Pr. 79*, *Pr. 340* and signals are *Pr. 79* > X12 > X66 > X65 > X16 > *Pr. 340*.

**CAUTION**

- Changing the terminal assignment using *Pr. 178 to Pr. 189* (*input terminal function selection*) may affect the other functions. Please make setting after confirming the function of each terminal.



### (11) Switching of operation mode by external terminal (X65, X66 signal)

- When *Pr. 79* = any of "0, 2, 6, 7", the operation mode switching signals (X65, X66) can be used to change the PU or external operation mode to network operation mode during a stop (during a motor stop or start command off). (*Pr. 79* = "6" switch-over mode can be changed during operation)
- When switching between the network operation mode and PU operation mode
  - 1) Set *Pr. 79* to "0" (initial value), "6" or "7". (At the *Pr. 79* setting of "7", the operation mode can be switched when the X12 (MRS) signal turns on.)
  - 2) Set "10 or 12" in *Pr. 340 Communication startup mode selection*.
  - 3) Set "65" in any of *Pr. 178 to Pr. 189* to assign the PU-NET operation switchover signal (X65) to the external terminal.
  - 4) The operation mode changes to PU operation mode when the X65 signal turns on, or to network operation mode when the X65 signal turns off.

| Pr. 340<br>Setting | Pr. 79<br>Setting | X65 Signal State                    |                         | Remarks                                                                                                  |                                              |
|--------------------|-------------------|-------------------------------------|-------------------------|----------------------------------------------------------------------------------------------------------|----------------------------------------------|
|                    |                   | ON (PU)                             | OFF (NET)               |                                                                                                          |                                              |
| 10, 12             | 0 (initial value) | PU operation mode *1                | NET operation mode *2   | Cannot be switched to external operation mode                                                            |                                              |
|                    | 1                 | PU operation mode                   |                         | Fixed to PU operation mode                                                                               |                                              |
|                    | 2                 | NET operation mode                  |                         | Fixed to NET operation mode                                                                              |                                              |
|                    | 3, 4              | External/PU combined operation mode |                         | External/PU combined mode fixed                                                                          |                                              |
|                    | 6                 | PU operation mode *1                | NET operation mode *2   | Operation mode can be switched with operation continued<br>Cannot be switched to external operation mode |                                              |
|                    | 7                 | X12(MRS)<br>ON                      | PU operation mode *1    | NET operation mode *2, 3                                                                                 | Output stop in external operation mode       |
|                    |                   | X12(MRS)<br>OFF                     | External operation mode |                                                                                                          | Forcibly switched to external operation mode |

\*1 NET operation mode when the X66 signal is on.

\*2 PU operation mode when the X16 signal is off. PU operation mode also when *Pr. 550 NET mode operation command source selection* = "1" (communication option control source) and the communication option is not fitted.

\*3 External operation mode when the X16 signal is on.

- When switching between the network operation mode and external operation mode
  - 1) Set *Pr. 79* to "0" (initial value), "2", "6" or "7". (At the *Pr. 79* setting of "7", the operation mode can be switched when the X12 (MRS) signal turns on.)
  - 2) Set "0 (initial value), 1 or 2" in *Pr. 340 Communication startup mode selection*.
  - 3) Set "66" in any of *Pr. 178 to Pr. 189* to assign the external-NET operation switchover signal (X66) to the external terminal.
  - 4) The operation mode changes to network operation mode when the X66 signal turns on, or to external operation mode when the X66 signal turns off.

| Pr. 340<br>Setting            | Pr. 79<br>Setting | X66 signal state                    |                            | Remarks                                                 |                                              |
|-------------------------------|-------------------|-------------------------------------|----------------------------|---------------------------------------------------------|----------------------------------------------|
|                               |                   | ON (NET)                            | OFF(external)              |                                                         |                                              |
| 0<br>(initial value),<br>1, 2 | 0 (initial value) | NET operation mode *1               | External operation mode *2 |                                                         |                                              |
|                               | 1                 | PU operation mode                   |                            | Fixed to PU operation mode                              |                                              |
|                               | 2                 | NET operation mode *1               | External operation mode    | Cannot be switched to PU operation mode                 |                                              |
|                               | 3, 4              | External/PU combined operation mode |                            | External/PU combined mode fixed                         |                                              |
|                               | 6                 | NET operation mode *1               | External operation mode *2 | Operation mode can be switched with operation continued |                                              |
|                               | 7                 | X12(MRS)<br>ON                      | NET operation mode *1      | External operation mode *2                              | Output stop in external operation mode       |
|                               |                   | X12(MRS)<br>OFF                     | External operation mode    |                                                         | Forcibly switched to external operation mode |

\*1 PU operation mode also when *Pr. 550 NET mode operation command source selection* = "1" (communication option control source) and the communication option is not fitted.

\*2 PU operation mode when the X16 signal is off. When the X65 signal has been assigned, the operation mode changes with the ON/OFF state of the X65 signal.

#### REMARKS

- The priorities of *Pr. 79*, *Pr. 340* and signals are *Pr. 79* > X12 > X66 > X65 > X16 > *Pr. 340*.

#### CAUTION

- Changing the terminal assignment using *Pr. 178 to Pr. 189 (input terminal function selection)* may affect the other functions. Please make setting after confirming the function of each terminal.

#### ◆ Parameters referred to ◆

*Pr. 15 Jog frequency* Refer to page 74.  
*Pr. 4 to 6, Pr. 24 to 27, Pr. 232 to Pr. 239 Multi-speed operation* Refer to page 72.  
*Pr. 75 Reset selection/disconnected PU detection/PU stop selection* Refer to page 141.  
*Pr. 161 Frequency setting/key lock operation selection* Refer to page 220.  
*Pr. 178 to Pr. 189 (Input terminal function selection)* Refer to page 90.  
*Pr. 340 Communication startup mode selection* Refer to page 155.  
*Pr. 550 NET mode operation command source selection* Refer to page 156.

### 3.17.2 Operation mode at power on (Pr. 79, Pr. 340)

When power is switched on or when power comes back on after instantaneous power failure, the inverter can be started up in network operation mode.

After the inverter has started up in the network operation mode, parameter write and operation can be performed from a program.

Set this mode for communication operation using the RS-485 terminals or communication option.

|         |          |
|---------|----------|
| Pr. 78  | page 145 |
| Pr. 80  | page 59  |
| Pr. 339 | page 156 |
| Pr. 341 | page 166 |

| Parameter Number | Name                                 | Initial Value | Setting Range | Description                                                                                                                                                                                                                                                                                  |
|------------------|--------------------------------------|---------------|---------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 79               | Operation mode selection             | 0             | 0 to 4, 6, 7  | Select the operation mode. (Refer to page 149.)                                                                                                                                                                                                                                              |
| 340 *            | Communication startup mode selection | 0             | 0             | As set in Pr. 79.                                                                                                                                                                                                                                                                            |
|                  |                                      |               | 1, 2          | Started in network operation mode. When the setting is "2", it will resume the pre-instantaneous power failure operation mode after an instantaneous power failure occurs.                                                                                                                   |
|                  |                                      |               | 10, 12        | Started in network operation mode. Operation mode can be changed between the PU operation mode and network operation mode from the operation panel. When the setting is "12", it will resume the pre-instantaneous power failure operation mode after an instantaneous power failure occurs. |

\* The parameters can be set when Pr. 160 User group read selection = "0". However, the parameters can be set whenever the communication option is connected. (Refer to page 145.). It can also be changed independently of the operation mode.

#### (1) Specify operation mode at power on (Pr. 340)

Depending on the Pr. 79 and Pr. 340 settings, the operation mode at power on (reset) changes as described below.

| Pr. 340 Setting      | Pr. 79 Setting       | Operation Mode at Power on, Power Restoration, Reset                                                | Operation Mode Switching                                                                                                                     |
|----------------------|----------------------|-----------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------|
| 0<br>(initial value) | 0<br>(initial value) | External operation mode                                                                             | Can be switched to external, PU or NET operation mode *2                                                                                     |
|                      | 1                    | PU operation mode                                                                                   | Fixed to PU operation mode                                                                                                                   |
|                      | 2                    | External operation mode                                                                             | Can be switched to external or NET operation mode<br>Switching to PU operation mode disabled                                                 |
|                      | 3, 4                 | External/PU combined operation mode                                                                 | Operation mode switching disabled                                                                                                            |
|                      | 6                    | External operation mode                                                                             | Can be switched to external, PU or NET operation mode<br>with operation continued                                                            |
|                      | 7                    | X12 (MRS) signal ON .... External operation mode<br>X12 (MRS) signal OFF .. External operation mode | Can be switched to external, PU or NET operation mode *2<br>Fixed to external operation mode (Forcibly switched to external operation mode.) |
| 1, 2 *1              | 0                    | NET operation mode                                                                                  | Same as when Pr. 340 = "0"                                                                                                                   |
|                      | 1                    | PU operation mode                                                                                   |                                                                                                                                              |
|                      | 2                    | NET operation mode                                                                                  |                                                                                                                                              |
|                      | 3, 4                 | External/PU combined operation mode                                                                 |                                                                                                                                              |
|                      | 6                    | NET operation mode                                                                                  |                                                                                                                                              |
|                      | 7                    | X12 (MRS) signal ON .... NET operation mode<br>X12 (MRS) signal OFF .. External operation mode      |                                                                                                                                              |
| 10, 12<br>*1         | 0                    | NET operation mode                                                                                  | Can be switched to PU or NET operation mode *3                                                                                               |
|                      | 1                    | PU operation mode                                                                                   | Same as when Pr. 340 = "0"                                                                                                                   |
|                      | 2                    | NET operation mode                                                                                  | Fixed to NET operation mode                                                                                                                  |
|                      | 3, 4                 | External/PU combined operation mode                                                                 | Same as when Pr. 340 = "0"                                                                                                                   |
|                      | 6                    | NET operation mode                                                                                  | Can be switched to PU or NET operation mode with<br>operation continued *3                                                                   |
|                      | 7                    | External operation mode                                                                             | Same as when Pr. 340 = "0"                                                                                                                   |

\*1 The Pr. 340 setting "2" or "12" is mainly used for communication operation using the inverter RS-485 terminals. When a value other than "9999" (selection of automatic restart after instantaneous power failure) is set in Pr. 57 Restart coasting time, the inverter will resume the same operation state which was in before after power has been restored from an instantaneous power failure.

\*2 The operation mode cannot be switched directly between the PU operation mode and network operation mode.

\*3 Operation mode can be changed between the PU operation mode and network operation mode with  key of the operation panel (FR-DU07) and X65 signal.

#### ◆ Parameters referred to ◆

Pr. 57 Restart coasting time  Refer to page 114.

Pr. 79 Operation mode selection  Refer to page 147.



### 3.17.3 Operation command source and speed command source during communication operation (Pr. 338, Pr. 339, Pr. 550, Pr. 551)

When the RS-485 terminals or communication option is used, the external operation command and speed command can be made valid. Also, the control command source in the PU operation mode can be selected.

| Parameter Number | Name                                        | Initial Value | Setting Range | Description                                                                                                                                                                |
|------------------|---------------------------------------------|---------------|---------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 338              | Communication operation command source      | 0             | 0             | Operation command source communication                                                                                                                                     |
|                  |                                             |               | 1             | Operation command source external                                                                                                                                          |
| 339              | Communication speed command source          | 0             | 0             | Speed command source communication                                                                                                                                         |
|                  |                                             |               | 1             | Speed command source external (Frequency setting from communication is invalid, terminal 2 and 1 setting from external is valid)                                           |
|                  |                                             |               | 2             | Speed command source external (Frequency setting from communication is valid, terminal 2 and 1 setting from external is invalid)                                           |
| 550 *            | NET mode operation command source selection | 9999          | 0             | Communication option valid                                                                                                                                                 |
|                  |                                             |               | 1             | RS-485 terminals valid                                                                                                                                                     |
|                  |                                             |               | 9999          | Automatic recognition of the communication option<br>Normally, the RS-485 terminals are valid. When the communication option is fitted, the communication option is valid. |
| 551 *            | PU mode operation command source selection  | 2             | 1             | Select the RS-485 terminals as the PU operation mode control source.                                                                                                       |
|                  |                                             |               | 2             | Select the PU connector as the PU operation mode control source.                                                                                                           |

The above parameters can be set when Pr. 160 User group read selection = "0". However, the parameters can be set whenever the communication option is connected. (Refer to page 145.)

\* Pr. 550 and Pr. 551 are always write-enabled.

#### (1) Select the control source of the network operation mode (Pr. 550)

- Either the RS-485 terminals or communication option can be specified as the source of control in network operation mode.
- For example, set Pr. 550 to "1" when executing parameter write, start command or frequency setting from the inverter RS-485 terminals in the network operation mode independently of whether the communication option is connected or not.

#### CAUTION

- Since Pr. 550 = "9999" (Automatic recognition of the communication option) in the initial setting, parameter write, start command and frequency setting cannot be executed by communication using the inverter RS-485 terminals when the communication option is fitted. (Monitor and parameter read can be performed.)

#### (2) Select the control source of the PU operation mode (Pr. 551)

- Either the PU connector or RS-485 terminals can be specified as the source of control in the PU operation mode.
- In the PU operation mode, set Pr. 551 to "1" when executing parameter write, start command or frequency setting through communication from the RS-485 terminals.

#### CAUTION

- The PU operation mode has a higher priority when Pr. 550 = "1" (NET mode RS-485 terminals) and Pr. 551 = "1" (PU mode RS-485 terminals). When the communication option is not fitted, therefore, the operation mode cannot be switched to network operation mode.

| Pr. 550 Setting         | Pr. 551 Setting   | Operation Mode of Control Source |                      |                       | Remarks                                  |
|-------------------------|-------------------|----------------------------------|----------------------|-----------------------|------------------------------------------|
|                         |                   | PU connector                     | RS-485 terminals     | Communication option  |                                          |
| 0                       | 1                 | ×                                | PU operation mode *1 | NET operation mode *2 |                                          |
|                         | 2 (initial value) | PU operation mode                | ×                    | NET operation mode *2 |                                          |
| 1                       | 1                 | ×                                | PU operation mode *1 | ×                     | Switching to NET operation mode disabled |
|                         | 2 (initial value) | PU operation mode                | NET operation mode   | ×                     |                                          |
| 9999<br>(initial value) | 1                 | ×                                | PU operation mode *1 | NET operation mode *2 |                                          |
|                         | 2 (initial value) | PU operation mode                | ×                    | NET operation mode    | Communication option fitted              |
|                         |                   |                                  | NET operation mode   | ×                     | Communication option not fitted          |

\*1 The Modbus-RTU protocol cannot be used in the PU operation mode. When using the Modbus-RTU protocol, set Pr. 551 to "2".

\*2 When the communication option is not fitted, the operation mode cannot be switched to network operation mode.

## (3) Controllability through communication

| Operation Location                                 | Condition (Pr. 551 setting) | Operation Mode<br>Item    | PU Operation            | External Operation      | External/PU Combined Operation Mode 1 (Pr. 79 =3) | External/PU Combined Operation Mode 2 (Pr. 79 =4) | NET Operation (when RS-485 terminals are used) *6 | NET Operation (when communication option is used) *7 |
|----------------------------------------------------|-----------------------------|---------------------------|-------------------------|-------------------------|---------------------------------------------------|---------------------------------------------------|---------------------------------------------------|------------------------------------------------------|
| Control by RS-485 communication from PU connector  | 2 (PU connector)            | Run command (start, stop) | ○                       | ×<br>PU stop enabled *3 | ×<br>PU stop enabled *3                           | ○                                                 | ×<br>PU stop enabled *3                           |                                                      |
|                                                    |                             | Running frequency setting | ○                       | ×                       | ○                                                 | ×                                                 | ×                                                 |                                                      |
|                                                    |                             | Monitor                   | ○                       | ○                       | ○                                                 | ○                                                 | ○                                                 |                                                      |
|                                                    |                             | Parameter write           | ○ *4                    | ×                       | ○ *4                                              | ○ *4                                              | ×                                                 |                                                      |
|                                                    |                             | Parameter read            | ○                       | ○                       | ○                                                 | ○                                                 | ○                                                 |                                                      |
|                                                    |                             | Inverter reset            | ○                       | ○                       | ○                                                 | ○                                                 | ○                                                 |                                                      |
|                                                    | 1 (RS-485 terminals)        | Run command (start, stop) | ×<br>PU stop enabled *3 | ×<br>PU stop enabled *3 | ×<br>PU stop enabled *3                           | ×<br>PU stop enabled *3                           | ×<br>PU stop enabled *3                           |                                                      |
|                                                    |                             | Running frequency setting | ×                       | ×                       | ×                                                 | ×                                                 | ×                                                 |                                                      |
|                                                    |                             | Monitor                   | ○                       | ○                       | ○                                                 | ○                                                 | ○                                                 |                                                      |
|                                                    |                             | Parameter write           | ×                       | ×                       | ×                                                 | ×                                                 | ×                                                 |                                                      |
|                                                    |                             | Parameter read            | ○                       | ○                       | ○                                                 | ○                                                 | ○                                                 |                                                      |
|                                                    |                             | Inverter reset            | ○                       | ○                       | ○                                                 | ○                                                 | ○                                                 |                                                      |
| Control by communication from RS-485 terminals     | 1 (RS-485 terminals)        | Run command (start, stop) | ○                       | ×                       | ×                                                 | ○                                                 | ×                                                 |                                                      |
|                                                    |                             | Running frequency setting | ○                       | ×                       | ○                                                 | ×                                                 | ×                                                 |                                                      |
|                                                    |                             | Monitor                   | ○                       | ○                       | ○                                                 | ○                                                 | ○                                                 |                                                      |
|                                                    |                             | Parameter write           | ○ *4                    | ×                       | ○ *4                                              | ○ *4                                              | ×                                                 |                                                      |
|                                                    |                             | Parameter read            | ○                       | ○                       | ○                                                 | ○                                                 | ○                                                 |                                                      |
|                                                    |                             | Inverter reset            | ○                       | ○                       | ○                                                 | ○                                                 | ○                                                 |                                                      |
|                                                    | 2 (PU connector)            | Run command (start, stop) | ×                       | ×                       | ×                                                 | ×                                                 | ○ *1                                              | ×                                                    |
|                                                    |                             | Running frequency setting | ×                       | ×                       | ×                                                 | ×                                                 | ○ *1                                              | ×                                                    |
|                                                    |                             | Monitor                   | ○                       | ○                       | ○                                                 | ○                                                 | ○                                                 | ○                                                    |
|                                                    |                             | Parameter write           | ×                       | ×                       | ×                                                 | ×                                                 | ○ *4                                              | ×                                                    |
|                                                    |                             | Parameter read            | ○                       | ○                       | ○                                                 | ○                                                 | ○                                                 | ○                                                    |
|                                                    |                             | Inverter reset            | ×                       | ×                       | ×                                                 | ×                                                 | ○ *2                                              | ×                                                    |
| Control by communication from communication option | —                           | Run command (start, stop) | ×                       | ×                       | ×                                                 | ×                                                 | ×                                                 | ○ *1                                                 |
|                                                    |                             | Running frequency setting | ×                       | ×                       | ×                                                 | ×                                                 | ×                                                 | ○ *1                                                 |
|                                                    |                             | Monitor                   | ○                       | ○                       | ○                                                 | ○                                                 | ○                                                 | ○                                                    |
|                                                    |                             | Parameter write           | ×                       | ×                       | ×                                                 | ×                                                 | ×                                                 | ○ *4                                                 |
|                                                    |                             | Parameter read            | ○                       | ○                       | ○                                                 | ○                                                 | ○                                                 | ○                                                    |
|                                                    |                             | Inverter reset            | ×                       | ×                       | ×                                                 | ×                                                 | ×                                                 | ○ *2                                                 |
| Control circuit external terminals                 | —                           | Inverter reset            | ○                       | ○                       | ○                                                 | ○                                                 | ○                                                 |                                                      |
|                                                    |                             | Run command (start, stop) | ×                       | ○                       | ○                                                 | ×                                                 | ×                                                 |                                                      |
|                                                    |                             | Frequency setting         | ×                       | ○                       | ×                                                 | ○                                                 | ×                                                 |                                                      |

○: Enabled, ×: Disabled

\*1 As set in Pr. 338 Communication operation command source and Pr. 339 Communication speed command source. (Refer to page 156)

\*2 At occurrence of RS-485 communication error, the inverter cannot be reset from the computer.

\*3 At a PU stop, PS is displayed on the operation panel. As set in Pr. 75 Reset selection/disconnected PU detection/PU stop selection. (Refer to page 141)

\*4 Some parameters may be write-disabled according to the Pr. 77 Parameter write selection setting and operating status. (Refer to page 144)

\*5 Some parameters are write-enabled independently of the operation mode and command source presence/absence. When Pr. 77 = 2, write is enabled. (Refer to page 44 for the parameter list)Parameter clear is disabled.

\*6 When Pr. 550 NET mode operation command source selection = 1 (RS-485 terminals valid) or Pr. 550 NET mode operation command source selection = 9999 and the communication option is not fitted.

\*7 When Pr. 550 NET mode operation command source selection = 0 (communication option valid) or Pr. 550 NET mode operation command source selection = 9999 and the communication option is fitted.



#### (4) Operation at alarm occurrence

| Alarm Definition                            | Operation Mode<br>Condition<br>(Pr. 551 setting) | PU Operation         | External Operation | External/PU Combined Operation Mode 1<br>(Pr. 79 =3) | External/PU Combined Operation Mode 2<br>(Pr. 79 =4) | NET Operation (when RS-485 terminals are used) *5 | NET Operation (when communication option is used) *6 |
|---------------------------------------------|--------------------------------------------------|----------------------|--------------------|------------------------------------------------------|------------------------------------------------------|---------------------------------------------------|------------------------------------------------------|
| Inverter fault                              | —                                                | Stop                 |                    |                                                      |                                                      |                                                   |                                                      |
| PU disconnection of the PU connector        | 2 (PU connector)                                 | Stop/continued *1, 4 |                    |                                                      |                                                      |                                                   |                                                      |
|                                             | 1 (RS-485 terminals)                             | Stop/continued *1    |                    |                                                      |                                                      |                                                   |                                                      |
| Communication alarm of PU connector         | 2 (PU connector)                                 | Stop/continued *2    | Continued          | Stop/continued *2                                    | Continued                                            |                                                   |                                                      |
|                                             | 1 (RS-485 terminals)                             | Continued            |                    |                                                      |                                                      |                                                   |                                                      |
| Communication alarm of RS-485 terminals     | 1 (RS-485 terminals)                             | Stop/continued *2    | Continued          | Stop/continued *2                                    | Continued                                            |                                                   |                                                      |
|                                             | 2 (PU connector)                                 | Continued            |                    |                                                      |                                                      | Stop/continued *2                                 | Continued                                            |
| Communication alarm of communication option | —                                                | Continued            |                    |                                                      |                                                      | Stop/continued *3                                 | Continued                                            |

\*1 Can be selected using Pr. 75 Reset selection/disconnected PU detection/PU stop selection

\*2 Can be selected using Pr. 122 PU communication check time interval or Pr. 336 RS-485 communication check time interval

\*3 As controlled by the communication option.

\*4 In the PU jog operation mode, operation is always stopped when the PU is disconnected. Whether error (E.PEU) occurrence is allowed or not is as set in Pr. 75 Reset selection/disconnected PU detection/PU stop selection.

\*5 When Pr. 550 NET mode operation command source selection = 1 (RS-485 terminals valid) or Pr. 550 NET mode operation command source selection = 9999 and the communication option is not fitted

\*6 When Pr. 550 NET mode operation command source selection = 0 (communication option valid) or Pr. 550 NET mode operation command source selection = 9999 and the communication option is fitted

**(5) Selection of control source in network operation mode (Pr. 338, Pr. 339)**

- As control sources, there are the operation command sources that control the signals related to the inverter start command and function selection and the speed command source that controls the signals related to frequency setting.
- In network operation mode, the commands from the external terminals and communication (RS-485 terminals or communication option) are as listed below.

| Operation Location Selection                     |    |      |                                                                  | Pr. 338 Communication operation command source | 0: NET       |             |             | 1: External |             |                                                          | Remarks                                         |
|--------------------------------------------------|----|------|------------------------------------------------------------------|------------------------------------------------|--------------|-------------|-------------|-------------|-------------|----------------------------------------------------------|-------------------------------------------------|
|                                                  |    |      |                                                                  | Pr. 339 Communication speed command source     | 0: NET       | 1: External | 2: External | 0: NET      | 1: External | 2: External                                              |                                                 |
| Fixed function (Terminal-equivalent function)    |    |      |                                                                  | Running frequency from communication           | NET          | —           | NET         | NET         | —           | NET                                                      |                                                 |
|                                                  |    |      |                                                                  | Terminal 2                                     | —            | External    | —           | —           | External    | —                                                        |                                                 |
|                                                  |    |      |                                                                  | Terminal 4                                     | —            | External    |             | —           | External    |                                                          |                                                 |
|                                                  |    |      |                                                                  | Terminal 1                                     | Compensation |             |             |             |             |                                                          |                                                 |
| Selective function<br>Pr. 178 to Pr. 189 setting | 0  | RL   | Low speed operation command/remote setting clear                 | NET                                            | External     |             | NET         | External    |             | Pr. 59 = "0" (multi-speeds)<br>Pr. 59 = "1 , 2" (remote) |                                                 |
|                                                  | 1  | RM   | Middle-speed operation command/remote setting deceleration       | NET                                            | External     |             | NET         | External    |             |                                                          |                                                 |
|                                                  | 2  | RH   | High speed operation command/remote setting acceleration         | NET                                            | External     |             | NET         | External    |             |                                                          |                                                 |
|                                                  | 3  | RT   | Second function selection                                        | NET                                            |              |             | External    |             |             |                                                          |                                                 |
|                                                  | 4  | AU   | Terminal 4 input selection                                       | —                                              | Combined     |             | —           | Combined    |             |                                                          |                                                 |
|                                                  | 5  | JOG  | Jog operation selection                                          | —                                              |              |             | External    |             |             |                                                          |                                                 |
|                                                  | 6  | CS   | Selection of automatic restart after instantaneous power failure | External                                       |              |             |             |             |             |                                                          |                                                 |
|                                                  | 7  | OH   | External thermal relay input                                     | External                                       |              |             |             |             |             |                                                          |                                                 |
|                                                  | 8  | REX  | Fifteen speed selection                                          | NET                                            | External     |             | NET         | External    |             | Pr. 59 = "0" (multi-speeds)                              |                                                 |
|                                                  | 10 | X10  | Inverter operation enable signal                                 | External                                       |              |             |             |             |             |                                                          |                                                 |
|                                                  | 11 | X11  | FR-HC or MT-HC connection, instantaneous power failure detection | External                                       |              |             |             |             |             |                                                          |                                                 |
|                                                  | 12 | X12  | PU operation external interlock                                  | External                                       |              |             |             |             |             |                                                          |                                                 |
|                                                  | 13 | X13  | External DC injection brake operation is started                 | NET                                            |              |             | External    |             |             |                                                          |                                                 |
|                                                  | 14 | X14  | PID control valid terminal                                       | NET                                            | External     |             | NET         | External    |             |                                                          |                                                 |
|                                                  | 16 | X16  | PU-external operation switchover                                 | External                                       |              |             |             |             |             |                                                          |                                                 |
|                                                  | 24 | MRS  | Output stop                                                      | Combined                                       |              |             | External    |             |             | Pr. 79 ≠ "7"                                             |                                                 |
|                                                  |    |      | PU operation interlock                                           | External                                       |              |             |             |             |             |                                                          | Pr. 79 = "7"<br>When X12 signal is not assigned |
|                                                  | 25 | STOP | Start self-holding selection                                     | —                                              |              |             | External    |             |             |                                                          |                                                 |
|                                                  | 60 | STF  | Forward rotation command                                         | NET                                            |              |             | External    |             |             |                                                          |                                                 |
|                                                  | 61 | STR  | Reverse rotation command                                         | NET                                            |              |             | External    |             |             |                                                          |                                                 |
|                                                  | 62 | RES  | Reset                                                            | External                                       |              |             |             |             |             |                                                          |                                                 |
|                                                  | 63 | PTC  | PID forward action switchover                                    | External                                       |              |             |             |             |             |                                                          |                                                 |
|                                                  | 64 | X64  | PID forward action switchover                                    | NET                                            | External     |             | NET         | External    |             |                                                          |                                                 |
|                                                  | 65 | X65  | PU-NET operation switchover                                      | External                                       |              |             |             |             |             |                                                          |                                                 |
|                                                  | 66 | X66  | External-NET operation switchover                                | External                                       |              |             |             |             |             |                                                          |                                                 |
|                                                  | 67 | X67  | Command source switchover                                        | External                                       |              |             |             |             |             |                                                          |                                                 |

**[Explanation of table]**

External : Operation is valid only from external terminal signal.

NET : Control only from communication is valid

Combined : Operation is valid from either of external terminal and communication.

— : Operation is invalid from either of external terminal and communication.

Compensation : Control only from external terminal signals is valid when Pr. 28 Multi-speed input compensation selection = "1"

**REMARKS**

- The control source of communication is as set in Pr. 550 and Pr. 551.



## (6) Switching of command source by external terminal (X67)

- In network operation mode, the command source switching signal (X67) can be used to switch the operation command source and speed command source. This signal can be utilized to control the signal input from both the external terminal and communication.
- Set "67" to any of *Pr. 178* to *Pr. 186* to assign the X67 signal to the external terminal.
- When the X67 signal is off, the operation command source and speed command source are external.

| X67 Signal State     | Operation Command Source                               | Speed Command Source        |
|----------------------|--------------------------------------------------------|-----------------------------|
| No signal assignment | According to <i>Pr. 338</i>                            | According to <i>Pr. 339</i> |
| ON                   |                                                        |                             |
| OFF                  | Operation is valid only from external terminal signal. |                             |

### REMARKS

- The ON/OFF state of the X67 signal is reflected only during a stop. It is reflected after a stop when the terminal is switched during operation.
- When the X67 signal is off, a reset via communication is disabled.

### ◆ Parameters referred to ◆

*Pr. 28 Multi-speed input compensation selection*  Refer to page 76.  
*Pr. 59 Remote function selection*  Refer to page 77.  
*Pr. 79 Operation mode selection*  Refer to page 147.

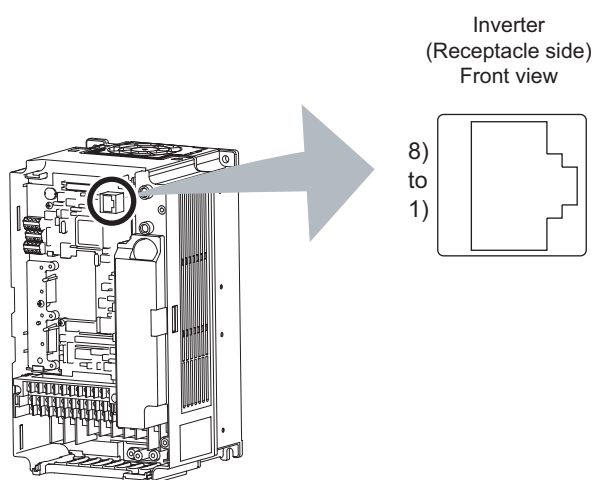
## 3.18 Communication operation and setting

| Purpose                                               | Parameter that must be set                                        |                                             | Refer to Page |
|-------------------------------------------------------|-------------------------------------------------------------------|---------------------------------------------|---------------|
| Communication operation from PU connector             | Initial setting of computer link communication (PU connector)     | Pr. 117 to Pr. 124                          | 166           |
| Communication operation from RS-485 terminals         | Initial setting of computer link communication (RS-485 terminals) | Pr. 331 to Pr. 337, Pr. 341                 |               |
|                                                       | Modbus-RTU communication specifications                           | Pr. 331, Pr. 332, Pr. 334, Pr. 343, Pr. 549 | 178           |
| Restrictions on parameter write through communication | Communication EEPROM write selection                              | Pr. 342                                     | 167           |

### 3.18.1 Wiring and configuration of PU connector

Using the PU connector, you can perform communication operation from a personal computer etc. When the PU connector is connected with a personal, FA or other computer by a communication cable, a user program can run and monitor the inverter or read and write to parameters.

#### (1) PU connector pin-outs



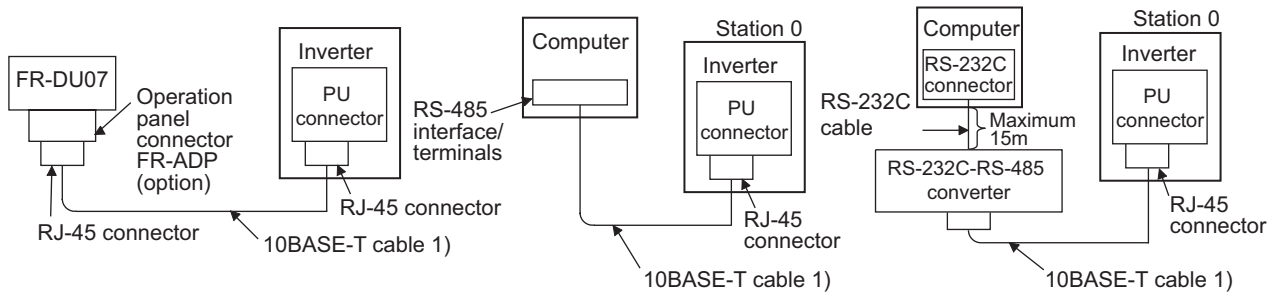
| Pin Number | Name | Description                                 |
|------------|------|---------------------------------------------|
| 1)         | SG   | Earth (Ground)<br>(connected to terminal 5) |
| 2)         | —    | Operation panel power supply                |
| 3)         | RDA  | Inverter receive+                           |
| 4)         | SDB  | Inverter send-                              |
| 5)         | SDA  | Inverter send+                              |
| 6)         | RDB  | Inverter receive-                           |
| 7)         | SG   | Earth (Ground)<br>(connected to terminal 5) |
| 8)         | —    | Operation panel power supply                |

#### CAUTION

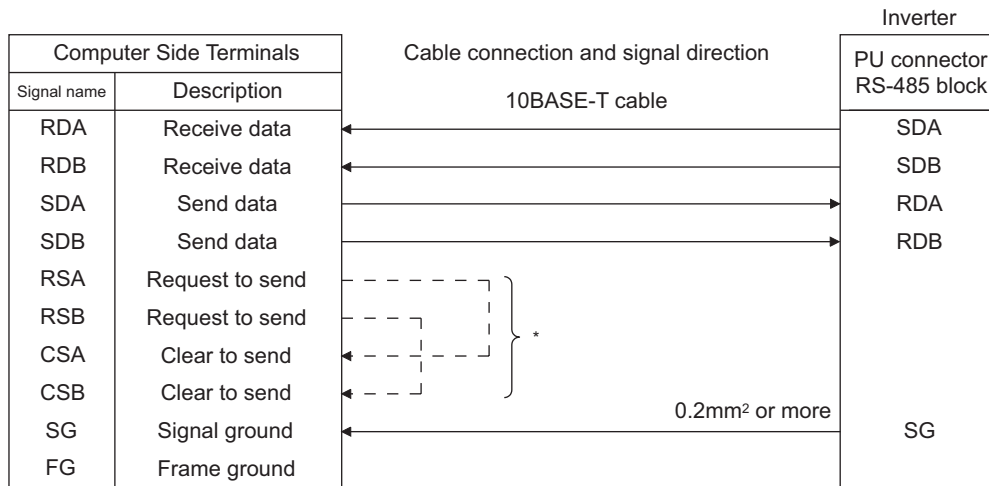
- Pins No. 2 and 8 provide power to the operation panel or parameter unit. Do not use these pins for RS-485 communication.
- Do not connect the PU connector to the computer's LAN board, FAX modem socket or telephone modular connector. The product could be damaged due to differences in electrical specifications.

## (2) PU connector communication system configuration and wiring

### ● System configuration



### ● Connection with RS-485 computer



\* Make connections in accordance with the manual of the computer used. Fully check the terminal numbers of the computer since they change with the model.

### REMARKS

· Computer-inverter connection cable  
Refer to the following for the cable (RS-232C ⇔ RS-485 converter) for connection of the computer having the RS-232C interface with the inverter. Commercially available product examples (as of April, 2004)

| Type         | Maker                                     |
|--------------|-------------------------------------------|
| FA-T-RS40□ * | Mitsubishi Electric Engineering Co., Ltd. |

\* The converter cable cannot connect two or more inverters (the computer and inverter are connected on a 1:1 basis). Since the product is packed with the RS-232C cable and RS-485 cable (10BASE-T + RJ-45 connector), the cable and connector need not be prepared separately. Contact a maker for details of the product.

· Refer to the following when fabricating the cable on the user side.  
Commercially available product examples (as of April, 2004)

|    | Product        | Type                  | Maker                             |
|----|----------------|-----------------------|-----------------------------------|
| 1) | 10BASE-T cable | SGLPEV-T 0.5mm × 4P * | Mitsubishi Cable Industries, Ltd. |

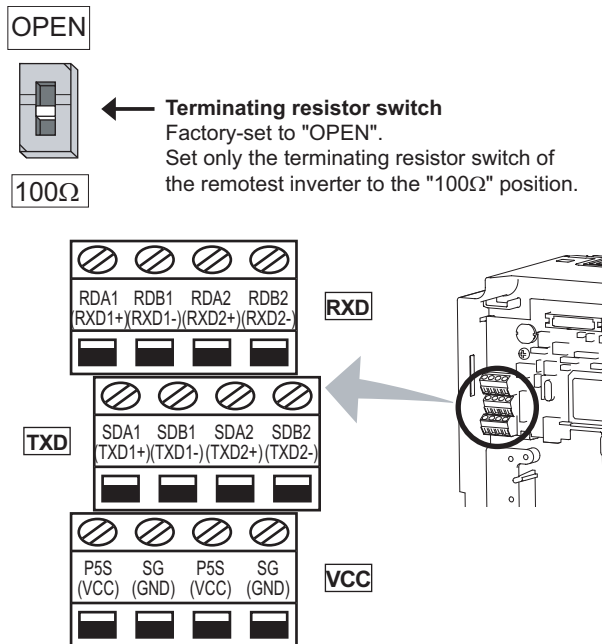
\* Do not use pins No. 2, 8 of the 10- BASE-T cable.

### CAUTION

When performing RS-485 communication with multiple inverters, use the RS-485 terminals. (Refer to page 164)

### 3.18.2 Wiring and arrangement of RS-485 terminals

#### (1) RS-485 terminal layout



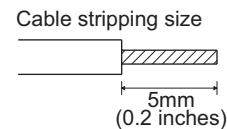
| Name            | Description                                  |
|-----------------|----------------------------------------------|
| RDA1<br>(RXD1+) | Inverter receive+                            |
| RDB1<br>(RXD1-) | Inverter receive-                            |
| RDA2<br>(RXD2+) | Inverter receive+<br>(for branch)            |
| RDB2<br>(RXD2-) | Inverter receive-<br>(for branch)            |
| SDA1<br>(TXD1+) | Inverter send+                               |
| SDB1<br>(TXD1-) | Inverter send-                               |
| SDA2<br>(TXD2+) | Inverter send+<br>(for branch)               |
| SDB2<br>(TXD2-) | Inverter send-<br>(for branch)               |
| P5S<br>(VCC)    | 5V<br>Permissible load current 100mA         |
| SG<br>(GND)     | Earth (Ground)<br>(connected to terminal SD) |

#### (2) Connection of RS-485 terminals and wires

Loosen the terminal screw and insert the cable into the terminal.

|                          |                                                                            |
|--------------------------|----------------------------------------------------------------------------|
| <b>Screw Size</b>        | M2                                                                         |
| <b>Tightening Torque</b> | 0.22N·m to 0.25N·m                                                         |
| <b>Cable Size</b>        | 0.3mm <sup>2</sup> to 0.75mm <sup>2</sup>                                  |
| <b>Screwdriver</b>       | Small ⊖ flat-blade screwdriver<br>(Tip thickness: 0.4mm /tip width: 2.5mm) |

Wire the stripped cable after twisting it to prevent it from becoming loose. In addition, do not solder it.



Use a bar terminal as necessary.

#### CAUTION

Undertightening can cause cable disconnection or malfunction. Overtightening can cause a short circuit or malfunction due to damage to the screw or unit.

#### REMARKS

##### Information on bar terminals

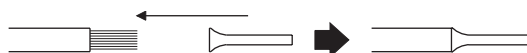
Introduced products (as of October, 2003): Phoenix Contact Co.,Ltd.

| Terminal Screw Size | Bar Terminal Model (with insulation sleeve) | Bar Terminal Model (without insulation sleeve) | Wire Size (mm <sup>2</sup> ) |
|---------------------|---------------------------------------------|------------------------------------------------|------------------------------|
| M2                  | AI 0.5-6WH                                  | A 0.5-6                                        | 0.3 to 0.5                   |

☞ Bar terminal crimping tool: CRIMPFOX ZA3 (Phoenix Contact Co., (Ltd.))

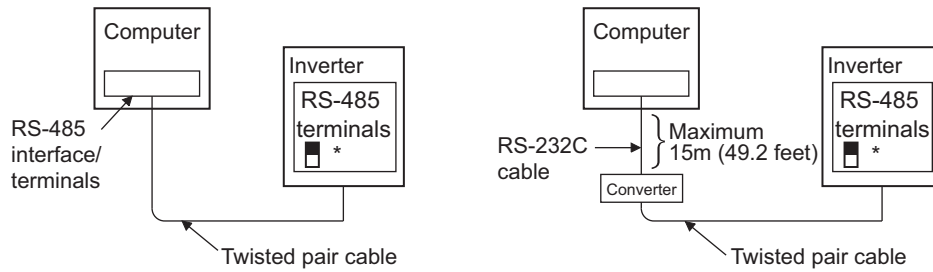
Use shielded or twisted cables for connection to the control circuit terminals and run them away from the main and power circuits (including the 200V relay sequence circuit).

When using the bar terminal (without insulation sleeve), use care so that the twisted wires do not come out.



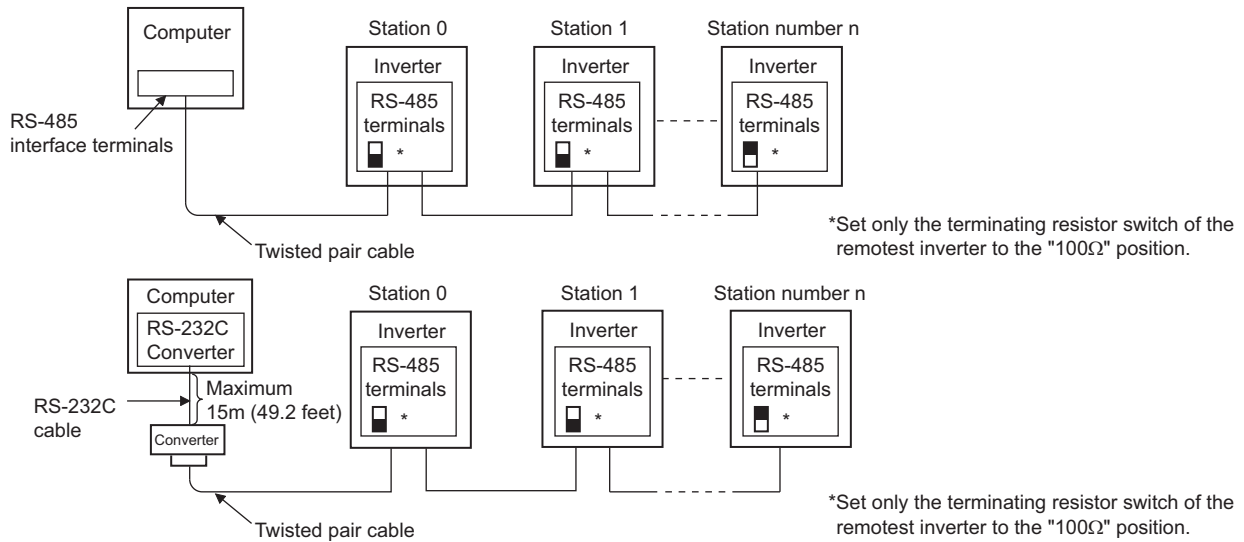
### (3) RS-485 terminal system configuration

#### ● Connection of a computer to the inverter (1:1 connection)



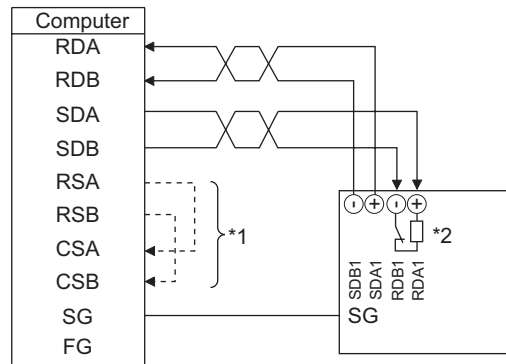
\*Set the terminating resistor switch to the "100Ω" position.

#### ● Combination of computer and multiple inverters (1:n connection)

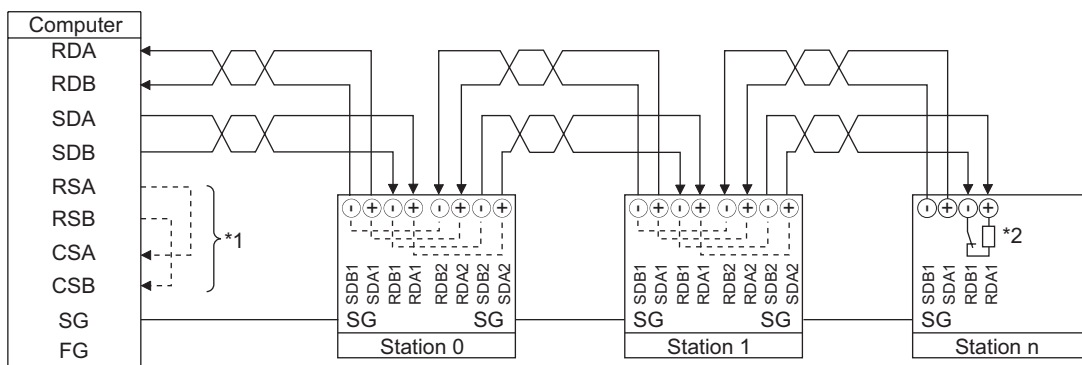


#### (4) RS-485 terminal wiring method

##### ● Wiring of one RS-485 computer and one inverter



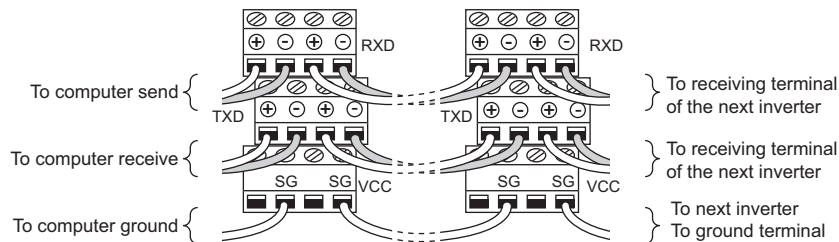
##### ● Wiring of one RS-485 computer and "n" inverters (several inverters)



- \*1 Make connections in accordance with the manual of the computer used.  
Fully check the terminal numbers of the computer since they change with the model.
- \*2 For the inverter farthest from the computer, set the terminating resistor switch to ON (100Ω side).

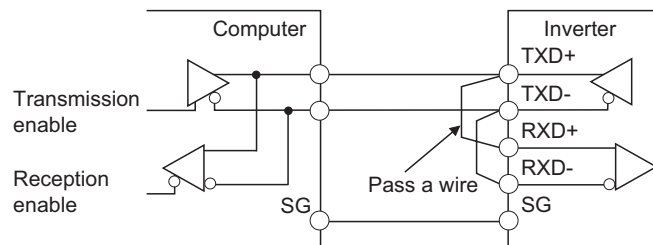
#### REMARKS

For branching, connect the wires as shown below.



#### (5) 2-wire type connection

If the computer is 2-wire type, pass wires across receiving terminals and transmission terminals of the RS-485 terminals to enable 2-wire type connection with the inverter.



#### REMARKS

Create a program so that transmission is disabled (receiving state) when the computer is not sending and reception is disabled (sending state) during sending to prevent the computer from receiving its own data.

### 3.18.3 Initial settings and specifications of RS-485 communication (Pr. 117 to Pr. 124, Pr. 331 to Pr. 337, Pr. 341)

Used to perform required settings for communication between the inverter and personal computer.

- There are two different communications: communication using the PU connector of the inverter and communication using the RS-485 terminals.
- You can perform parameter setting, monitor, etc. from the PU connector or RS-485 terminals of the inverter using the Mitsubishi inverter protocol (computer link communication).
- To make communication between the personal computer and inverter, initialization of the communication specifications must be made to the inverter.  
Data communication cannot be made if the initial settings are not made or there is any setting error.

#### [PU connector communication related parameter]

| Parameter Number | Name                                              | Initial Value | Setting Range    | Description                                                                                                                                                                              |
|------------------|---------------------------------------------------|---------------|------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 117              | PU communication station                          | 0             | 0 to 31          | Specify the inverter station number.<br>Set the inverter station numbers when two or more inverters are connected to one personal computer.                                              |
| 118              | PU communication speed                            | 192           | 48, 96, 192, 384 | Set the communication speed.<br>The setting value $\times 100$ equals the communication speed.<br>For example, the communication speed is 19200bps when the setting value is "192".      |
| 119              | PU communication stop bit length.                 | 1             | 0                | Stop bit length<br>1bit                                                                                                                                                                  |
|                  |                                                   |               | 1                | 2bit                                                                                                                                                                                     |
|                  |                                                   |               | 10               | 1bit                                                                                                                                                                                     |
|                  |                                                   |               | 11               | 2bit                                                                                                                                                                                     |
| 120              | PU communication parity check                     | 2             | 0                | Without parity check                                                                                                                                                                     |
|                  |                                                   |               | 1                | With odd parity check                                                                                                                                                                    |
|                  |                                                   |               | 2                | With even parity check                                                                                                                                                                   |
| 121              | Number of PU communication retries                | 1             | 0 to 10          | Set the permissible number of retries at occurrence of a data receive error. If the number of consecutive errors exceeds the permissible value, the inverter will come to an alarm stop. |
|                  |                                                   |               | 9999             | If a communication error occurs, the inverter will not come to an alarm stop.                                                                                                            |
| 122              | PU communication check time interval              | 9999          | 0                | No PU connector communication                                                                                                                                                            |
|                  |                                                   |               | 0.1 to 999.8s    | Set the interval of communication check time.<br>If a no-communication state persists for longer than the permissible time, the inverter will come to an alarm stop.                     |
|                  |                                                   |               | 9999             | No communication check                                                                                                                                                                   |
| 123              | PU communication waiting time setting             | 9999          | 0 to 150ms       | Set the waiting time between data transmission to the inverter and response.                                                                                                             |
|                  |                                                   |               | 9999             | Set with communication data.                                                                                                                                                             |
| 124              | PU communication CR/LF presence/absence selection | 1             | 0                | Without CR/LF                                                                                                                                                                            |
|                  |                                                   |               | 1                | With CR                                                                                                                                                                                  |
|                  |                                                   |               | 2                | With CR/LF                                                                                                                                                                               |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

**[RS-485 terminal communication related parameter]**

| Parameter Number | Name                                        | Initial Value | Setting Range                  | Description                                                                                                           |
|------------------|---------------------------------------------|---------------|--------------------------------|-----------------------------------------------------------------------------------------------------------------------|
| 331              | RS-485 communication station                | 0             | 0 to 31 (0 to 247)<br>*1       | Set the inverter station number. (same specifications as <i>Pr. 117</i> )                                             |
| 332              | RS-485 communication speed                  | 96            | 3, 6, 12, 24, 48, 96, 192, 384 | Used to select the communication speed. (same specifications as <i>Pr. 118</i> )                                      |
| 333 *2           | RS-485 communication stop bit length        | 1             | 0, 1, 10, 11                   | Select stop bit length and data length. (same specifications as <i>Pr. 119</i> )                                      |
| 334              | RS-485 communication parity check selection | 2             | 0, 1, 2                        | Select the parity check specifications. (same specifications as <i>Pr. 120</i> )                                      |
| 335 *3           | RS-485 communication number of retries      | 1             | 0 to 10, 9999                  | Set the permissible number of retries at occurrence of a data receive error. (same specifications as <i>Pr. 121</i> ) |
| 336 *3           | RS-485 communication check time interval    | 0s            | 0                              | RS-485 communication can be made, but the inverter will come to an alarm stop in the NET operation mode.              |
|                  |                                             |               | 0.1 to 999.8s                  | Set the interval of communication check time. (same specifications as <i>Pr. 122</i> )                                |
|                  |                                             |               | 9999                           | No communication check                                                                                                |
| 337 *3           | RS-485 communication waiting time setting   | 9999          | 0 to 150ms, 9999               | Set the waiting time between data transmission to the inverter and response. (same specifications as <i>Pr. 123</i> ) |
| 341 *3           | RS-485 communication CR/LF selection        | 1             | 0, 1, 2                        | Select presence/absence of CR/LF. (same specifications as <i>Pr. 124</i> )                                            |
| 549              | Protocol selection                          | 1             | 0                              | Mitsubishi inverter (computer link) protocol                                                                          |
|                  |                                             |               | 1                              | Modbus-RTU protocol *4                                                                                                |

\*1 When "1" (Modbus-RTU protocol) is set in *Pr. 549*, the setting range within parenthesis is applied.

\*2 For the Modbus-RTU protocol, the data length is fixed to 8 bits and the stop bit depends on the *Pr. 334* setting. (Refer to page 178)

\*3 The Modbus-RTU protocol becomes invalid.

\*4 The Modbus-RTU protocol is valid for only communication from the RS-485 terminals.

\*5 The above parameters can be set when *Pr. 160 User group read selection* = "0". (Refer to page 145)

**CAUTION**

- If communication is made without *Pr. 336 RS-485 communication check time interval* being changed from "0" (initial value), monitor, parameter read, etc. can be performed, but the inverter results in an alarm as soon as it is switched to the NET operation mode. If the operation mode at power on is the network operation mode, a communication alarm (E.SER) occurs after first communication.

When performing operation or parameter write through communication, set "9999" or more to *Pr. 336*. (The setting depends on the computer side program.) (Refer to page 172)

- Always reset the inverter after making the initial settings of the parameters. After you have changed the communication-related parameters, communication cannot be made until the inverter is reset.

**3.18.4 Communication EEPROM write selection (Pr. 342)**

Parameters written via the inverter's PU connector or RS-485 terminals or from the communication option can be written to the RAM. Set this parameter when frequent parameter changes are required.

**Pr.343**  
page 178

| Parameter Number | Name                                 | Initial Value | Setting Range | Description                                                                  |
|------------------|--------------------------------------|---------------|---------------|------------------------------------------------------------------------------|
| 342              | Communication EEPROM write selection | 0             | 0             | Parameter values written by communication are written to the EEPROM and RAM. |
|                  |                                      |               | 1             | Parameter values written by communication are written to the RAM.            |

The above parameters can be set when *Pr. 160 User group read selection* = "0". However, it can be set any time when the communication option is connected. (Refer to page 145)

- When changing the parameter values frequently, set "1" in *Pr. 342* to write them to the RAM. The life of the EEPROM will be shorter if parameter write is performed frequently with the setting unchanged from "0" (initial value) (EEPROM write).

**REMARKS**

- When *Pr. 342* is set to "1" (only RAM write), the new values of the parameters will be cleared at power supply-off of the inverter. Therefore, the parameter values available when power is switched on again are the values stored in EEPROM previously.

### 3.18.5 Mitsubishi inverter protocol (computer link communication)

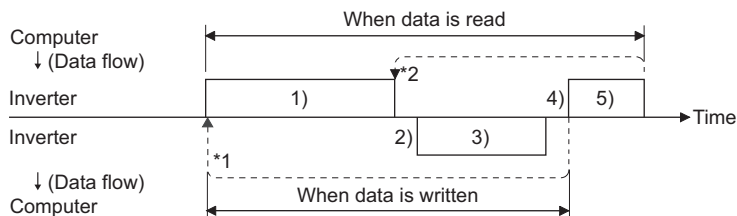
You can perform parameter setting, monitor, etc. from the PU connector or RS-485 terminals of the inverter using the Mitsubishi inverter protocol (computer link communication).

#### (1) Communication specifications

- The communication specifications are given below.

| Item                          |                  | Description                                                               | Related Parameters |
|-------------------------------|------------------|---------------------------------------------------------------------------|--------------------|
| Communication protocol        |                  | Mitsubishi protocol (computer link)                                       | Pr. 551            |
| Conforming standard           |                  | EIA-485 (RS-485)                                                          | —                  |
| Number of inverters connected |                  | 1:N (maximum 32 units), setting is 0 to 31 stations                       | Pr. 117<br>Pr. 331 |
| Communication speed           | PU connector     | Selected from among 4800/9600/19200 and 38400bps                          | Pr. 118            |
|                               | RS-485 terminal  | Can be selected from 300, 600, 1200, 2400, 4800, 9600, 19200 and 38400bps | Pr. 332            |
| Control protocol              |                  | Asynchronous system                                                       | —                  |
| Communication method          |                  | Half-duplex system                                                        | —                  |
| Communication specifications  | Character system | ASCII (7 bits or 8 bits can be selected)                                  | Pr. 119<br>Pr. 333 |
|                               | Start bit        | 1bit                                                                      | —                  |
|                               | Stop bit length  | 1 bit or 2 bits can be selected                                           | Pr. 119<br>Pr. 333 |
|                               | Parity check     | Check (even, odd) or no check can be selected                             | Pr. 120<br>Pr. 334 |
|                               | Error check      | Sum code check                                                            | —                  |
|                               | Terminator       | CR/LF (presence or absence can be selected)                               | Pr. 124<br>Pr. 341 |
| Waiting time setting          |                  | Selectable between presence and absence                                   | Pr. 123<br>Pr. 337 |

#### (2) Communication procedure



- Data communication between the computer and inverter is made in the following procedure.

- 1) Request data is sent from the computer to the inverter. (The inverter will not send data unless requested.)
- 2) After waiting for the waiting time
- 3) The inverter sends return data to the computer in response to the computer request.
- 4) After having waited for the time taken for inverter processing
- 5) Answer from computer in response to reply data 3) is sent. (Even if 5) is not sent, subsequent communication is made properly.)

\*1 If a data error is detected and a retry must be made, execute retry operation with the user program. The inverter comes to an alarm stop if the number of consecutive retries exceeds the parameter setting.

\*2 On receipt of a data error occurrence, the inverter returns "reply data 3)" to the computer again. The inverter comes to an alarm stop if the number of consecutive data errors reaches or exceeds the parameter setting.

### (3) Communication operation presence/absence and data format types

- Data communication between the computer and inverter is made in ASCII code (hexadecimal code).
- Communication operation presence/absence and data format types are as follows:

| Symbol | Operation                                                                                          | Run Command                             | Running Frequency | Parameter Write | Inverter Reset | Monitor         | Parameter Read |
|--------|----------------------------------------------------------------------------------------------------|-----------------------------------------|-------------------|-----------------|----------------|-----------------|----------------|
| 1)     | Communication request is sent to the inverter in accordance with the user program in the computer. | A<br>A'                                 | A                 | A               | A              | B               | B              |
| 2)     | Inverter data processing time                                                                      | Present                                 | Present           | Present         | Absent         | Present         | Present        |
| 3)     | Reply data from the inverter (Data 1) is checked for error)                                        | No error *1<br>(Request accepted)       | C                 | C               | C              | C *2<br>E<br>E' | E              |
|        |                                                                                                    | With error.<br>(Request rejected)       | D                 | D               | D              | D *2<br>D       | D              |
| 4)     | Computer processing delay time                                                                     | Absent                                  | Absent            | Absent          | Absent         | Absent          | Absent         |
| 5)     | Answer from computer in response to reply data 3)<br>(Data 3) is checked for error)                | No error *1<br>(No inverter processing) | Absent            | Absent          | Absent         | Absent<br>(C)   | Absent<br>(C)  |
|        |                                                                                                    | With error<br>(Inverter re-outputs 3))  | Absent            | Absent          | Absent         | F               | F              |

\*1 In the communication request data from the computer to the inverter, 10ms or more is also required after "no data error (ACK)". (Refer to page 171)

\*2 The inverter response to the inverter reset request can be selected. (Refer to page 174)

#### 1) Communication request data from the computer to the inverter

| Format             | Number of Characters |                               |   |                     |   |                    |           |   |           |    |           |    |    |
|--------------------|----------------------|-------------------------------|---|---------------------|---|--------------------|-----------|---|-----------|----|-----------|----|----|
|                    | 1                    | 2                             | 3 | 4                   | 5 | 6                  | 7         | 8 | 9         | 10 | 11        | 12 | 13 |
| A<br>(Data write)  | ENQ<br>*1            | Inverter station<br>number *2 |   | Instruction<br>code |   | Waiting<br>time *3 | Data      |   |           |    | Sum check |    | *4 |
| A'<br>(Data write) | ENQ<br>*1            | Inverter station<br>number *2 |   | Instruction<br>code |   | Waiting<br>time *3 | Data      |   | Sum check |    | *4        |    |    |
| B<br>(Data read)   | ENQ<br>*1            | Inverter station<br>number *2 |   | Instruction<br>code |   | Waiting<br>time *3 | Sum check |   | *4        |    |           |    |    |

#### 3) Reply data from the inverter to the computer

- When data is written

| Format                               | Number of Characters |                           |            |    |   |
|--------------------------------------|----------------------|---------------------------|------------|----|---|
|                                      | 1                    | 2                         | 3          | 4  | 5 |
| <b>C</b><br>(No data error detected) | ACK<br>*1            | Inverter station number 2 | *4         |    |   |
| <b>D</b><br>(Data error detected)    | NAK<br>*1            | Inverter station number 2 | Error Code | *4 |   |

- When data is read

| Format                                | Number of Characters |                               |               |    |   |           |           |           |           |    |    |
|---------------------------------------|----------------------|-------------------------------|---------------|----|---|-----------|-----------|-----------|-----------|----|----|
|                                       | 1                    | 2                             | 3             | 4  | 5 | 6         | 7         | 8         | 9         | 10 | 11 |
| <b>E</b><br>(No data error detected)  | STX<br>*1            | Inverter station<br>number *2 | Read data     |    |   |           |           | ETX<br>*1 | Sum check |    | *4 |
| <b>E'</b><br>(No data error detected) | STX<br>*1            | Inverter station<br>number *2 | Read data     |    |   | ETX<br>*1 | Sum check |           | *4        |    |    |
| <b>D</b><br>(Data error detected)     | NAK<br>*1            | Inverter station<br>number *2 | Error<br>Code | *4 |   |           |           |           |           |    |    |

#### 5) Send data from the computer to the inverter during data read

| Format                               | Number of Characters |                            |    |   |
|--------------------------------------|----------------------|----------------------------|----|---|
|                                      | 1                    | 2                          | 3  | 4 |
| <b>C</b><br>(No data error detected) | ACK<br>*1            | Inverter station number *2 | *4 |   |
| <b>F</b><br>(Data error detected)    | NAK<br>*1            | Inverter station number *2 | *4 |   |

\*1 Indicate a control code

\*2 Specify the inverter station numbers between H00 and H1F (stations 0 to 31) in hexadecimal.

\*3 When Pr. 123, Pr. 337 (waiting time setting) ≠ "9999", create the communication request data without "waiting time" in the data format. (The number of characters decreases by 1.)

\*4 CR, LF code

When data is transmitted from the computer to the inverter, CR (carriage return) and LF (line feed) codes are automatically set at the end of a data group on some computers. In this case, setting must also be made on the inverter according to the computer. Whether the CR and LF codes will be present or absent can be selected using Pr. 124 or Pr. 341 (CR, LF presence/absence selection).

#### (4) Data definitions

##### 1) Control codes

| Signal Name | ASCII Code | Description                                |
|-------------|------------|--------------------------------------------|
| STX         | H02        | Start Of Text (start of data)              |
| ETX         | H03        | End Of Text (end of data)                  |
| ENQ         | H05        | Enquiry (communication request)            |
| ACK         | H06        | Acknowledge (no data error detected)       |
| LF          | H0A        | Line Feed                                  |
| CR          | H0D        | Carriage Return                            |
| NAK         | H15        | Negative Acknowledge (data error detected) |

##### 2) Inverter station number

Specify the station number of the inverter which communicates with the computer.

##### 3) Instruction code

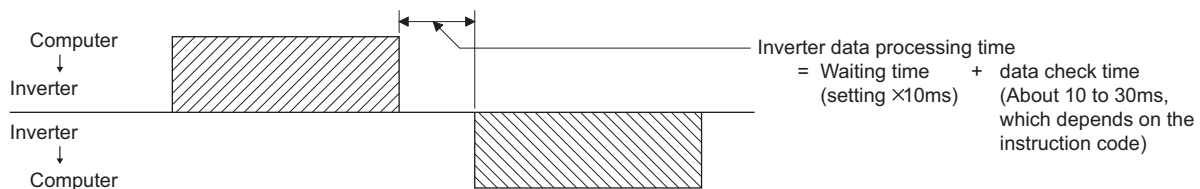
Specify the processing request, e.g. operation or monitoring, given by the computer to the inverter. Hence, the inverter can be run and monitored in various ways by specifying the instruction code as appropriate. (Refer to page 44)

##### 4) Data

Indicates the data such as frequency and parameters transferred to and from the inverter. The definitions and ranges of set data are determined in accordance with the instruction codes. (Refer to page 44)

##### 5) Waiting time

Specify the waiting time between the receipt of data at the inverter from the computer and the transmission of reply data. Set the waiting time in accordance with the response time of the computer between 0 and 150ms in 10ms increments (e.g. 1 = 10ms, 2 = 20ms).

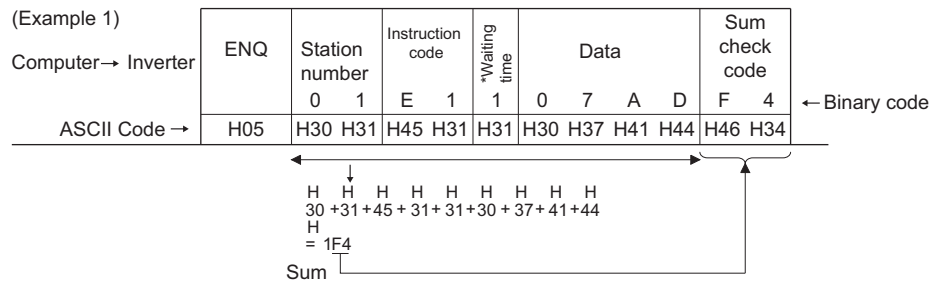


#### REMARKS

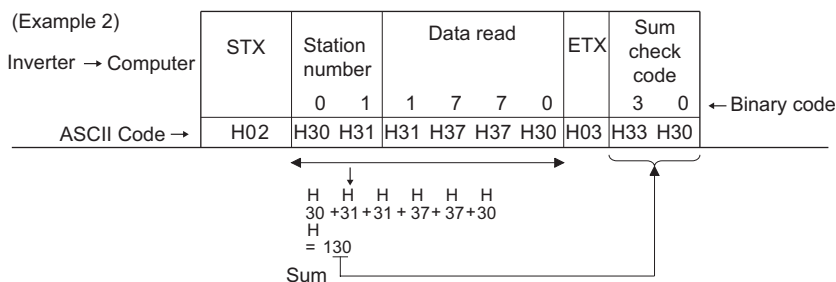
- When Pr. 123, Pr. 337 (waiting time setting) ≠ "9999", create the communication request data without "waiting time" in the data format. (The number of characters decreases by 1.)
- The data check time changes depending on the instruction code. (Refer to page 172)

## 6) Sum check code

The sum check code is 2-digit ASCII (hexadecimal) representing the lower 1 byte (8 bits) of the sum (binary) derived from the checked ASCII data



\* When the Pr. 123 "waiting time setting" ≠ "9999", create the communication request data without "waiting time" in the data format. (The number of characters decreases by 1.)

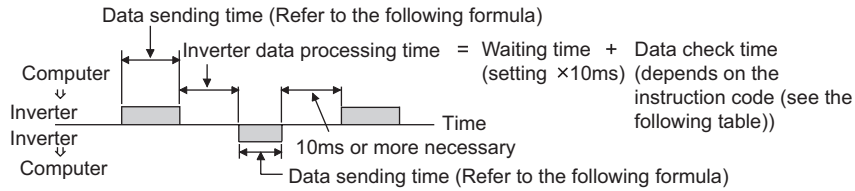


## 7) Error Code

If any error is found in the data received by the inverter, its definition is sent back to the computer together with the NAK code.

| Error Code | Error Item             | Error Definition                                                                                                                                                                  | Inverter Operation                                                                                             |
|------------|------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------|
| H0         | Computer NAK error     | The number of errors consecutively detected in communication request data from the computer is greater than allowed number of retries.                                            | Brought to an alarm stop if error occurs continuously more than the allowable number of retries. (E.PUE/E.SER) |
| H1         | Parity error           | The parity check result does not match the specified parity.                                                                                                                      |                                                                                                                |
| H2         | Sum check error        | The sum check code in the computer does not match that of the data received by the inverter.                                                                                      |                                                                                                                |
| H3         | Protocol error         | The data received by the inverter has a grammatical mistake. Alternatively, data receive is not completed within the predetermined time. CR or LF is not as set in the parameter. |                                                                                                                |
| H4         | Framing error          | The stop bit length differs from the initial setting.                                                                                                                             |                                                                                                                |
| H5         | Overrun error          | New data has been sent by the computer before the inverter completes receiving the preceding data.                                                                                |                                                                                                                |
| H6         | —                      | —                                                                                                                                                                                 | —                                                                                                              |
| H7         | Character error        | The character received is invalid (other than 0 to 9, A to F, control code).                                                                                                      | Does not accept received data but is not brought to alarm stop.                                                |
| H8         | —                      | —                                                                                                                                                                                 |                                                                                                                |
| H9         | —                      | —                                                                                                                                                                                 |                                                                                                                |
| HA         | Mode error             | Parameter write was attempted in other than the computer link operation mode, when operation command source is not selected or during inverter operation.                         | Does not accept received data but is not brought to alarm stop.                                                |
| HB         | Instruction code error | The specified command does not exist.                                                                                                                                             |                                                                                                                |
| HC         | Data range error       | Invalid data has been specified for parameter write, frequency setting, etc.                                                                                                      |                                                                                                                |
| HD         | —                      | —                                                                                                                                                                                 |                                                                                                                |
| HE         | —                      | —                                                                                                                                                                                 | —                                                                                                              |
| HF         | —                      | —                                                                                                                                                                                 | —                                                                                                              |

## (5) Response time



[Formula for data sending time]

$$\frac{1}{\text{Communication speed (bps)}} \times \text{Number of data characters} \times \text{Communication specifications (total number of bits)} = \text{Data send time (s)}$$

(Refer to page 169) (See below.)

### ●Communication specifications

| Name            | Number of Bits    |
|-----------------|-------------------|
| Stop bit length | 1 bit<br>2 bits   |
| Data length     | 7 bits<br>8 bits  |
| Parity check    | Yes 1 bit<br>No 0 |

In addition to the above, 1 start bit is necessary.

Minimum number of total bits..... 9 bits

Maximum number of total bits..... 12 bits

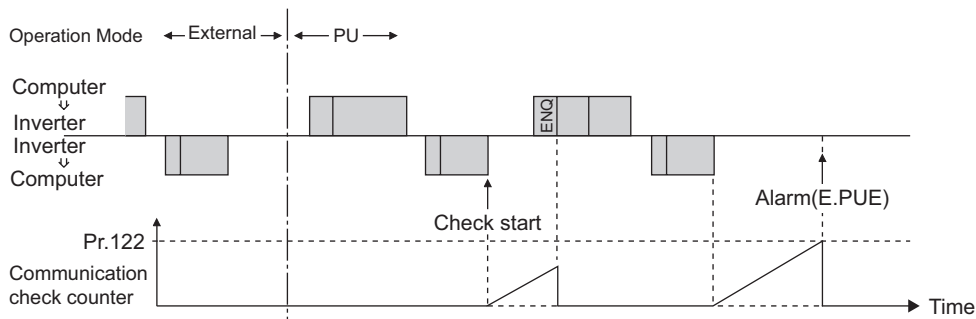
### ●Data check time

| Item                                                   | Check Time |
|--------------------------------------------------------|------------|
| Various monitors, run command, frequency setting (RAM) | <12ms      |
| Parameter read/write, frequency setting (EEPROM)       | <30ms      |
| Parameter clear/all clear                              | <5ms       |
| Reset command                                          | No answer  |

## (6) Open cable detection (Pr. 122, Pr. 336 RS-485 communication check time interval)

- If disconnection (communication stop) is detected between the inverter and computer as a result of disconnection check, a communication error (PU connector communication: E.PUE, RS-485 terminal communication: E.SER) occurs and the inverter output is shut off.
- Disconnection check is made when the setting is any of "0.1s" to "999.8s". To make disconnection check, it is necessary to send data (control code *refer to page 170*) from the computer within the communication check time interval. (The send data has nothing to do with the station number)
- Communication check is started at the first communication in the operation mode having the operation source (PU operation mode for PU connector communication in the default setting or network operation mode for RS-485 terminal communication).
- When the setting is "9999", communication check (disconnection detection) is not made.
- When the setting is "0", communication from the PU connector cannot be performed. For communication via the RS-485 terminals, monitor, parameter read, etc. can be performed, but a communication error (E.SER) occurs as soon as the inverter is switched to network operation mode.

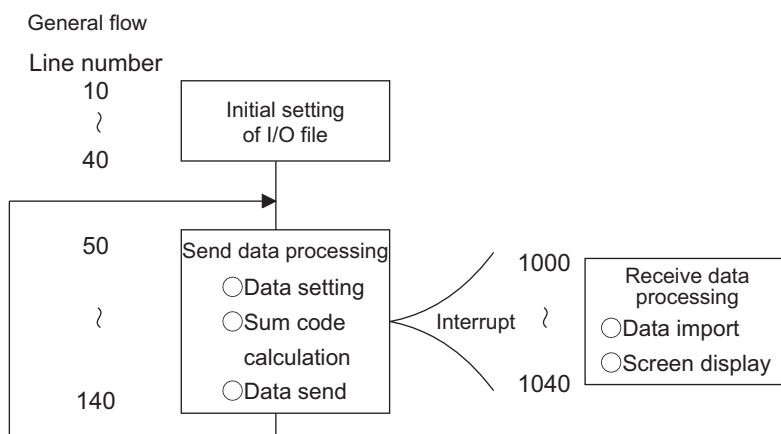
Example: PU connector communication, Pr. 122 = "0.1 to 999.8s"



## (7) Instructions for the program

- 1) When data from the computer has any error, the inverter does not accept that error. Hence, in the user program, always insert a retry program for data error.
- 2) All data communication, e.g. run command or monitoring, are started when the computer gives a communication request. The inverter does not return any data without the computer's request. Hence, design the program so that the computer gives a data read request for monitoring, etc. as required.
- 3) Program example  
To change the operation mode to computer link operation

|                                            |                                                  |
|--------------------------------------------|--------------------------------------------------|
| 10 OPEN"COM1:9600,E,8,2,HD"AS #1           | : Communication file open                        |
| 20 COMST1,1,1:COMST1,2,1                   | : Circuit control signal (RS, ER) ON/OFF setting |
| 30 ON COM(1)GOSUB*REC                      | : Interrupt definition at data receive           |
| 40 COM(1)ON                                | : Interrupt enable                               |
| 50 D\$="01FB10002"                         |                                                  |
| 60 S=0                                     |                                                  |
| 70 FOR I=1 TO LEN(D\$)                     |                                                  |
| 80 A\$=MID\$(D\$,I,1)                      |                                                  |
| 90 A=ASC(A\$)                              |                                                  |
| 100 S=S+A                                  |                                                  |
| 110 NEXTI                                  |                                                  |
| 120 D\$=CHR\$(&H5)+D\$+RIGHT\$(HEX\$(S),2) | : Addition of control code and sum code          |
| 130 PRINT#1,D\$                            |                                                  |
| 140 GOTO 50                                |                                                  |
| 1000 *REC                                  |                                                  |
| 1010 IF LOC(1)=0 THEN RETURN               |                                                  |
| 1020 PRINT"RECEIVE DATA"                   |                                                  |
| 1030 PRINT INPUT\$(LOC(1),#1)              |                                                  |
| 1040 RETURN                                |                                                  |



## **CAUTION**

- ⚠ Always set the communication check time interval before starting operation to prevent hazardous conditions.
- ⚠ Data communication is not started automatically but is made only once when the computer provides a communication request. If communication is disabled during operation due to signal cable breakage etc., the inverter cannot be stopped. When the communication check time interval has elapsed, the inverter will come to an alarm stop (E.PUE, E.SER). The inverter can be coasted to a stop by switching on its RES signal or by switching power off.
- ⚠ If communication is broken due to signal cable breakage, computer fault etc., the inverter does not detect such a fault. This should be fully noted.

## (8) Setting items and set data

After completion of parameter setting, set the instruction codes and data then start communication from the computer to allow various types of operation control and monitoring.

| No. | Item                               |                               | Read /write | Instruction Code                                                                                                                                                                                                                                                                                                                                                          | Data Description                                                                                                                                                                                                                                                                                                                                                                                                                                                    | Number of Data Digits (format) |
|-----|------------------------------------|-------------------------------|-------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------|
| 1   | Operation Mode                     |                               | Read        | H7B                                                                                                                                                                                                                                                                                                                                                                       | H0000: Network operation<br>H0001: External operation<br>H0002: PU operation<br>(RS-485 communication operation via PU connector)                                                                                                                                                                                                                                                                                                                                   | 4 digits (B.E/D)               |
|     |                                    |                               | Write       | HFB                                                                                                                                                                                                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                     | 4 digits (A,C/D)               |
| 2   | Monitor                            | Output frequency/speed        | Read        | H6F                                                                                                                                                                                                                                                                                                                                                                       | H0000 to HFFFF: Output frequency in 0.01Hz increments<br>Speed in 1r/min increments (when <i>Pr</i> : 37 = 1 to 9998 or <i>Pr</i> : 144 = 2 to 10, 102 to 110)                                                                                                                                                                                                                                                                                                      | 4 digits (B.E/D)               |
|     |                                    | Output current                | Read        | H70                                                                                                                                                                                                                                                                                                                                                                       | H0000 to HFFFF: Output current (hexadecimal) in 0.01A increments (FR-F720-02330(FR-F740-01160) or less) / 0.1A increments (FR-F720-03160(FR-F740-01800) or more)                                                                                                                                                                                                                                                                                                    | 4 digits (B.E/D)               |
|     |                                    | Output voltage                | Read        | H71                                                                                                                                                                                                                                                                                                                                                                       | H0000 to HFFFF: Output voltage (hexadecimal) in 0.1V increments                                                                                                                                                                                                                                                                                                                                                                                                     | 4 digits (B.E/D)               |
|     |                                    | Special monitor               | Read        | H72                                                                                                                                                                                                                                                                                                                                                                       | H0000 to HFFFF: Monitor data selected in instruction code HF3                                                                                                                                                                                                                                                                                                                                                                                                       | 4 digits (B.E/D)               |
|     |                                    | Special monitor selection No. | Read        | H73                                                                                                                                                                                                                                                                                                                                                                       | H01 to H36: Monitor selection data<br>Refer to the special monitor No. table (page 176)                                                                                                                                                                                                                                                                                                                                                                             | 2digits (B.E/D)                |
|     |                                    |                               | Write       | HF3                                                                                                                                                                                                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                     | 2digits (A',C/D)               |
|     |                                    | Alarm definition              | Read        | H74 to H77                                                                                                                                                                                                                                                                                                                                                                | H0000 to HFFFF: Two most recent alarm definitions<br><div><div><div><div>b15b8b7b0</div><div>H74<div>Second alarm in past</div><div>Latest alarm</div></div><div>H75<div>Fourth alarm in past</div><div>Third alarm in past</div></div><div>H76<div>Sixth alarm in past</div><div>Fifth alarm in past</div></div><div>H77<div>Eighth alarm in past</div><div>Seventh alarm in past</div></div></div></div><div>Refer to the alarm data table (page 176)</div></div> | 4 digits (B.E/D)               |
| 3   | Run command (extended)             | Write                         | HF9         | You can set the control input commands such as the forward rotation signal (STF) and reverse rotation signal (STR). (Refer to page 177 for details)                                                                                                                                                                                                                       | 4 digits (A,C/D)                                                                                                                                                                                                                                                                                                                                                                                                                                                    |                                |
|     | Run command                        | Write                         | HFA         |                                                                                                                                                                                                                                                                                                                                                                           | 2digits (A',C/D)                                                                                                                                                                                                                                                                                                                                                                                                                                                    |                                |
| 4   | Inverter status monitor (extended) | Read                          | H79         | You can monitor the states of the output signals such as forward rotation, reverse rotation and inverter running (RUN). (Refer to page 177 for details)                                                                                                                                                                                                                   | 4 digits (B.E/D)                                                                                                                                                                                                                                                                                                                                                                                                                                                    |                                |
|     | Inverter status monitor            | Read                          | H7A         |                                                                                                                                                                                                                                                                                                                                                                           | 2digits (B.E/D)                                                                                                                                                                                                                                                                                                                                                                                                                                                     |                                |
| 5   | Set frequency (RAM)                | Read                          | H6D         | Read the set frequency/speed from the RAM or EEPROM.<br>H0000 to HFFFF: Set frequency in 0.01Hz increments<br>Speed in 1r/min increments (When <i>Pr</i> : 37 = 1 to 9998 or <i>Pr</i> : 144 = 2 to 10, 102 to 110)                                                                                                                                                       | 4 digits (B.E/D)                                                                                                                                                                                                                                                                                                                                                                                                                                                    |                                |
|     | Set frequency (EEPROM)             |                               | H6E         |                                                                                                                                                                                                                                                                                                                                                                           |                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |                                |
|     | Set frequency (RAM)                | Write                         | HED         | Write the set frequency/speed into the RAM or EEPROM.<br>H0000 to H9C40 (0 to 400.00Hz) : frequency in 0.01Hz increments<br>H0000 to H270E (0 to 9998) : speed in r/min increments (when <i>Pr</i> : 37 = 1 to 9998 or <i>Pr</i> : 144 = 2 to 10, 102 to 110)<br>· To change the running frequency consecutively, write data to the inverter RAM. (Instruction code: HED) | 4 digits (A,C/D)                                                                                                                                                                                                                                                                                                                                                                                                                                                    |                                |
|     | Set frequency (RAM, EEPROM)        |                               | HEE         |                                                                                                                                                                                                                                                                                                                                                                           |                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |                                |
| 6   | Inverter reset                     | Write                         | HFD         | H9696: Resets the inverter.<br>· As the inverter is reset at start of communication by the computer, the inverter cannot send reply data back to the computer.                                                                                                                                                                                                            | 4 digits (A,C/D)                                                                                                                                                                                                                                                                                                                                                                                                                                                    |                                |
|     |                                    |                               |             | H9666: Resets the inverter.<br>· When data is sent normally, ACK is returned to the computer and then the inverter is reset.                                                                                                                                                                                                                                              | 4 digits (A,D)                                                                                                                                                                                                                                                                                                                                                                                                                                                      |                                |

Refer to page 169 for data formats (A, A', B, B', C, D)

| No.         | Item                                               | Read /write           | Instruction Code | Data Description                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               | Number of Data Digits (format) |                              |                       |                 |                   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |                  |
|-------------|----------------------------------------------------|-----------------------|------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------|------------------------------|-----------------------|-----------------|-------------------|-------|---|---|---|---|-------|---|---|---|---|-------|---|---|---|---|-------|---|---|---|---|------------------|
| 7           | Alarm definition all clear                         | Write                 | HF4              | H9696: Alarm history batch clear                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               | 4 digits (A,C/D)               |                              |                       |                 |                   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |                  |
| 8           | All parameter clear                                | Write                 | HFC              | <div>All parameters return to the initial values.<br/>Any of four different all clear operations are performed according to the data.</div> <table><tr><th>Pr.<br/>Data</th><th>Communi-<br/>cation Pr.<br/>*1</th><th>Calibration<br/>Pr. *2</th><th>Other Pr.<br/>*3</th><th>HEC<br/>HF3<br/>HFF</th></tr><tr><td>H9696</td><td>○</td><td>×</td><td>○</td><td>○</td></tr><tr><td>H9966</td><td>○</td><td>○</td><td>○</td><td>○</td></tr><tr><td>H5A5A</td><td>×</td><td>×</td><td>○</td><td>○</td></tr><tr><td>H55AA</td><td>×</td><td>○</td><td>○</td><td>○</td></tr></table> <div>When all parameter clear is executed for H9696 or H9966, communication-related parameter settings also return to the initial values. When resuming operation, set the parameters again.<br/>*1 Refer to <i>page 166, 167</i>.<br/>*2 Refer to <i>page 134</i>.<br/>*3 <i>Pr. 75</i> is not cleared</div> | Pr.<br>Data                    | Communi-<br>cation Pr.<br>*1 | Calibration<br>Pr. *2 | Other Pr.<br>*3 | HEC<br>HF3<br>HFF | H9696 | ○ | × | ○ | ○ | H9966 | ○ | ○ | ○ | ○ | H5A5A | × | × | ○ | ○ | H55AA | × | ○ | ○ | ○ | 4 digits (A,C/D) |
| Pr.<br>Data | Communi-<br>cation Pr.<br>*1                       | Calibration<br>Pr. *2 | Other Pr.<br>*3  | HEC<br>HF3<br>HFF                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |                                |                              |                       |                 |                   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |                  |
| H9696       | ○                                                  | ×                     | ○                | ○                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |                                |                              |                       |                 |                   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |                  |
| H9966       | ○                                                  | ○                     | ○                | ○                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |                                |                              |                       |                 |                   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |                  |
| H5A5A       | ×                                                  | ×                     | ○                | ○                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |                                |                              |                       |                 |                   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |                  |
| H55AA       | ×                                                  | ○                     | ○                | ○                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |                                |                              |                       |                 |                   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |                  |
| 9           | Parameters                                         | Read                  | H00 to H63       | Refer to the instruction code of the parameter list ( <i>page44</i> ) and write and/or read the values as required.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | 4 digits (B,E/D)               |                              |                       |                 |                   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |                  |
| 10          |                                                    | Write                 | H80 to HE3       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                | 4 digits (A,C/D)               |                              |                       |                 |                   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |                  |
| 11          | Link parameter extended setting                    | Read                  | H7F              | Parameter description is changed according to the H00 to H09 setting.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          | 2digits (B,E/D)                |                              |                       |                 |                   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |                  |
|             |                                                    | Write                 | HFF              | For details of the setting, refer to the instruction code of the parameter list ( <i>page 44</i> ).                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | 2digits (A',C/D)               |                              |                       |                 |                   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |                  |
| 12          | Second parameter changing (instruction code HFF=1) | Read                  | H6C              | When setting the bias/gain (instruction codes H5E to H61, HDE to HE1) parameters<br>H00:Frequency *1<br>H01: Parameter-set analog value<br>H02: Analog value input from terminal                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               | 2digits (B,E/D)                |                              |                       |                 |                   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |                  |
|             |                                                    | Write                 | HEC              | *1 The gain frequency can also be written using <i>Pr. 125</i> (instruction code H99) or <i>Pr. 126</i> (instruction code H9A).                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                | 2digits (A',C/D)               |                              |                       |                 |                   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |       |   |   |   |   |                  |

Refer to page 169 for data formats (A, A', B, B', C, D)

#### REMARKS

- Set 65520 (HFFF0) as a parameter value "8888" and 65535 (HFFFF) as "9999".
- For the instruction codes HFF, HEC and HF3, their values are held once written but cleared to zero when an inverter reset or all clear is performed.

Example) When reading the C3 (Pr. 902) and C6 (Pr. 904) settings from the inverter of station No. 0

|    | Computer Send Data | Inverter Send Data | Description                               |
|----|--------------------|--------------------|-------------------------------------------|
| 1) | ENQ 00 FF 0 01 82  | ACK 00             | Set "H01" in the extended link parameter. |
| 2) | ENQ 00 EC 0 01 7E  | ACK 00             | Set "H01" in second parameter changing.   |
| 3) | ENQ 00 5E 0 0F     | STX 00 0000 ETX 25 | C3 (Pr. 902) is read. 0% is read.         |
| 4) | ENQ 00 60 0 FB     | STX 00 0000 ETX 25 | C6 (Pr. 904) is read. 0% is read.         |

To read/write C3 (Pr. 902) and C6 (Pr. 904) after inverter reset or parameter clear, execute from 1) again.

### [Special monitor selection No.]

Refer to *page 105* for details of the monitor description.

| Data | Description                                   | Unit                |
|------|-----------------------------------------------|---------------------|
| H01  | Output frequency                              | 0.01Hz              |
| H02  | Output current                                | 0.01A/0.1A *3       |
| H03  | Output voltage                                | 0.1V                |
| H05  | Frequency setting                             | 0.01Hz              |
| H06  | Running speed                                 | 1r/min              |
| H08  | Converter output voltage                      | 0.1V                |
| H09  | Regenerative brake duty                       | 0.1%                |
| H0A  | Electronic thermal relay function load factor | 0.1%                |
| H0B  | Output current peak value                     | 0.01A/0.1A *3       |
| H0C  | Converter output voltage peak value           | 0.1V                |
| H0D  | Input power                                   | 0.01kW/<br>0.1kW *3 |

| Data | Description                  | Unit                |
|------|------------------------------|---------------------|
| H0E  | Output power                 | 0.01kW/<br>0.1kW *3 |
| H0F  | Input terminal status *1     | —                   |
| H10  | Output terminal status *2    | —                   |
| H11  | Load meter                   | 0.1%                |
| H14  | Cumulative energization time | 1h                  |
| H17  | Actual operation time        | 1h                  |
| H18  | Motor load factor            | 0.1%                |
| H19  | Cumulative power             | 1kWh                |
| H32  | Power saving effect          | Variable            |
| H33  | Cumulative saving power      | Variable            |
| H34  | PID set point                | 0.1%                |
| H35  | PID measurement value        | 0.1%                |
| H36  | PID deviation value          | 0.1%                |

\*1 Input terminal monitor details

b15

|   |   |   |   |    |     |      |     |     |    |    |    |    |    |     |     |
|---|---|---|---|----|-----|------|-----|-----|----|----|----|----|----|-----|-----|
| — | — | — | — | CS | RES | STOP | MRS | JOG | RH | RM | RL | RT | AU | STR | STF |
|---|---|---|---|----|-----|------|-----|-----|----|----|----|----|----|-----|-----|

b0

\*2 Output terminal monitor details

b15

|   |   |   |   |   |   |   |   |   |   |      |      |    |    |     |    |     |
|---|---|---|---|---|---|---|---|---|---|------|------|----|----|-----|----|-----|
| — | — | — | — | — | — | — | — | — | — | ABC2 | ABC1 | FU | OL | IPF | SU | RUN |
|---|---|---|---|---|---|---|---|---|---|------|------|----|----|-----|----|-----|

b0

\*3 The setting depends on capacities. (FR-F720-02330 (FR-F740-01160) or less/FR-F720-03160 (FR-F740-01800) or more)

### [Alarm data]

Refer to *page 230* for details of alarm description.

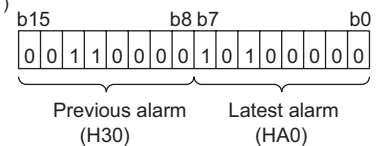
| Data | Description | Data | Description | Data | Description |
|------|-------------|------|-------------|------|-------------|
| H00  | No alarm    | H60  | OLT         | HC1  | CTE         |
| H10  | OC1         | H70  | BE          | HC2  | P24         |
| H11  | OC2         | H80  | GF          | HC4  | CDO         |
| H12  | OC3         | H81  | LF          | HC5  | IOH         |
| H20  | OV1         | H90  | OHT         | HC6  | SER         |
| H21  | OV2         | H91  | PTC         | HC7  | AIE         |
| H22  | OV3         | HA0  | OPT         | HF1  | E.1         |
| H30  | THT         | HA1  | OP1         | HF6  | E.6         |
| H31  | THM         | HB0  | PE          | HF7  | E.7         |
| H40  | FIN         | HB1  | PUE         | HFD  | E.13        |
| H50  | IPF         | HB2  | RET         |      |             |
| H51  | UVT         | HB3  | PE2         |      |             |
| H52  | ILF         | HC0  | CPU         |      |             |

#### Alarm description display example (instruction code H74)

For read data H30A0

(Previous alarm ..... THT)

(Latest alarm ..... OPT)



**[Run command]**

| Item                   | Instruction Code | Bit Length | Description                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       | Example                                                                                                                                                                                                                                   |
|------------------------|------------------|------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Run command            | HFA              | 8bit       | b0: AU (current input selection) *1<br>b1: Forward rotation command<br>b2: Reverse rotation command<br>b3: RL (low speed operation command) *1<br>b4: RM (middle speed operation command) *1<br>b5: RH (high speed operation command) *1<br>b6: RT (second function selection) *1<br>b7: MRS (output stop) *1                                                                                                                                                                                                     | [Example 1] H02 Forward rotation<br>b7 b0<br>0 0 0 0 0 0 1 0<br><br>[Example 2] H00 Stop<br>b7 b0<br>0 0 0 0 0 0 0 0                                                                                                                      |
| Run command (extended) | HF9              | 16bit      | b0:AU (current input selection) *1<br>b1:Forward rotation command<br>b2:Reverse rotation command<br>b3:RL (low speed operation command) *1<br>b4:RM (middle speed operation command) *1<br>b5: RH (high speed operation command) *1<br>b6:RT (second function selection) *1<br>b7:MRS (output stop) *1<br>b8:JOG (Jog operation) *2<br>b9:CS (selection of automatic restart after instantaneous power failure) *2<br>b10: STOP (start self-holding) *2<br>b11:RES (reset) *2<br>b12:—<br>b13:—<br>b14:—<br>b15:— | [Example 1] H0002 Forward rotation<br>b15 b0<br>0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 0<br><br>[Example 2] H0800 low speed operation<br>(When Pr. 189 RES terminal function selection is set to "0")<br>b15 b0<br>0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 |

\*1 The signal within parentheses is the initial setting. The description changes depending on the setting of Pr. 180 to Pr. 189 (input terminal function selection) (page 90).

\*2 The signal within parentheses is the initial setting. Since jog operation/selection of automatic restart after instantaneous power failure/start self-holding/reset cannot be controlled by the network, bit 8 to bit 11 are invalid in the initial status. When using bit 8 to bit 11, change the signals with Pr. 185, Pr. 186, Pr. 188, Pr. 189 (input terminal function selection) (page 96). (Reset can be executed with the instruction code HFD.)

**[Inverter status monitor]**

| Item                               | Instruction Code | Bit Length | Description                                                                                                                                                                                                                                                                                                                 | Example                                                                                                                                                                                       |
|------------------------------------|------------------|------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Inverter status monitor            | H7A              | 8bit       | b0:RUN (inverter running) *<br>b1:Forward rotation<br>b2:Reverse rotation<br>b3:SU (up to frequency) *<br>b4:OL (overload) *<br>b5:IPF (instantaneous power failure) *<br>b6:FU (frequency detection) *<br>b7:ABC1 (alarm) *                                                                                                | [Example 1] H02 ... During forward rotation<br>b7 b0<br>0 0 0 0 0 0 1 0<br><br>[Example 2] H80 ... Stop at alarm occurrence<br>b7 b0<br>0 0 0 0 0 0 1 0                                       |
| Inverter status monitor (extended) | H79              | 16bit      | b0:RUN (inverter running) *<br>b1:Forward rotation<br>b2:Reverse rotation<br>b3:SU (up to frequency) *<br>b4:OL (overload) *<br>b5:IPF (instantaneous power failure) *<br>b6:FU (frequency detection) *<br>b7:ABC1 (alarm) *<br>b8:ABC2 (—) *<br>b9:—<br>b10:—<br>b11:—<br>b12:—<br>b13:—<br>b14:—<br>b15: Alarm occurrence | [Example 1] H0002 ... During forward rotation<br>b15 b0<br>0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 0<br><br>[Example 2] H8080 ... Stop at alarm occurrence<br>b15 b0<br>1 0 0 0 0 0 0 0 1 0 0 0 0 0 0 0 |

\* The signal within parentheses is the initial setting. The description changes depending on the setting of Pr. 190 to Pr. 196 (output terminal function selection).

### 3.18.6 Modbus-RTU communication specifications (Pr. 331, Pr. 332, Pr. 334, Pr. 343, Pr. 549)

Using the Modbus-RTU communication protocol, communication operation or parameter setting can be performed from the RS-485 terminals of the inverter.

Pr.268  
page 105

Pr.333  
page 166

Pr.335  
page 166

Pr.342  
page 167

Pr.495  
page 103

Pr.504  
page 216

Pr.550  
page 156

| Parameter Number | Name                                        | Initial Value | Setting Range                  | Description                                                                                                                                                          |
|------------------|---------------------------------------------|---------------|--------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 331              | RS-485 communication station                | 0             | 0 to 247                       | Specify the inverter station number. Set the inverter station numbers when two or more inverters are connected to one personal computer.                             |
| 332              | RS-485 communication speed                  | 96            | 3, 6, 12, 24, 48, 96, 192, 384 | Set the communication speed. The setting value × 100 equals the communication speed. For example, the communication speed is 9600bps when the setting value is "96". |
| 334              | RS-485 communication parity check selection | 2             | 0                              | Without parity check<br>Stop bit length 2bits                                                                                                                        |
|                  |                                             |               | 1                              | With odd parity check<br>Stop bit length 1bit                                                                                                                        |
|                  |                                             |               | 2                              | With even parity check<br>Stop bit length 1bit                                                                                                                       |
| 343              | Communication error count                   | 0             | —                              | Display the number of communication errors during Modbus-RTU communication. Reading only                                                                             |
| 549              | Protocol selection                          | 1             | 0                              | Mitsubishi inverter (computer link) protocol                                                                                                                         |
|                  |                                             |               | 1                              | Modbus-RTU protocol                                                                                                                                                  |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

#### REMARKS

- When using the Modbus-RTU protocol, set Pr. 549 Protocol selection to "1".
- When the communication option is fitted with Pr. 550 NET mode operation command source selection set to "9999" (initial value), the command source (e.g. run command) from the RS-485 terminals is invalid. (Refer to page 156)

#### (1) Communication specifications

- The communication specifications are given below.

| Item                          | Description                                                               | Related Parameters                                                                                                                                          |
|-------------------------------|---------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Communication protocol        | Modbus-RTU protocol                                                       | Pr. 549                                                                                                                                                     |
| Conforming standard           | EIA-485 (RS-485)                                                          | —                                                                                                                                                           |
| Number of inverters connected | 1: N (maximum 32 units), setting is 0 to 247 stations                     | Pr. 331                                                                                                                                                     |
| Communication speed           | Can be selected from 300, 600, 1200, 2400, 4800, 9600, 19200 and 38400bps | Pr. 332                                                                                                                                                     |
| Control protocol              | Asynchronous system                                                       | —                                                                                                                                                           |
| Communication method          | Half-duplex system                                                        | —                                                                                                                                                           |
| Communication specifications  | Character system                                                          | Binary(fixed to 8 bits)                                                                                                                                     |
|                               | Start bit                                                                 | 1bit                                                                                                                                                        |
|                               | Stop bit length                                                           | Select from the following three types<br>· No parity, stop bit length 2 bits<br>· Odd parity, stop bit length 1 bit<br>· Even parity, stop bit length 1 bit |
|                               | Parity check                                                              | Pr. 334                                                                                                                                                     |
|                               | Error check                                                               | CRC code check                                                                                                                                              |
|                               | Terminator                                                                | Not used                                                                                                                                                    |
| Waiting time setting          | Not used                                                                  | —                                                                                                                                                           |

## (2) Outline

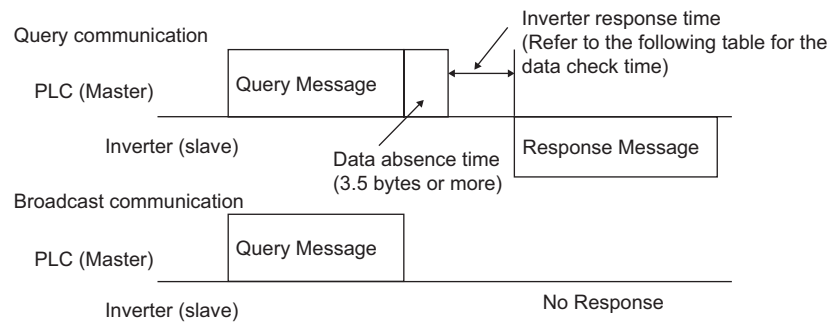
The Modbus protocol is the communication protocol developed by Modicon for PLC.

The Modbus protocol performs serial communication between the master and slave using the dedicated message frame. The dedicated message frame has the functions that can perform data read and write. Using the functions, you can read and write the parameter values from the inverter, write the input command of the inverter, and check the operating status. In this product, the inverter data are classified in the holding register area (register addresses 40001 to 49999). By accessing the assigned holding register address, the master can communicate with the inverter which is a slave.

### REMARKS

There are two different serial transmission modes: ASCII (American Standard Code for Information Interchange) mode and RTU (Remote Terminal Unit) mode. This product supports only the RTU mode in which 1-byte (8-bit) data is transmitted as-is. Only the communication protocol is defined by the Modbus protocol, and the physical layer is not stipulated.

## (3) Message format



### ●Data check time

| Item                                                         | Check Time |
|--------------------------------------------------------------|------------|
| Various monitors, operation command, frequency setting (RAM) | < 12ms     |
| Parameter read/write, frequency setting (EEPROM)             | < 30ms     |
| Parameter clear/all clear                                    | < 5ms      |
| Reset command                                                | No answer  |

#### 1)Query

The master sends a message to the slave (= inverter) at the specified address.

#### 2)Normal Response

After receiving the query from the master, the slave executes the requested function and returns the corresponding normal response to the master.

#### 3)Error Response

If an invalid function code, address or data is received, the slave returns it to the master.

When a response description is returned, the error code indicating that the request from the master cannot be executed is added.

No response is returned for the hardware-detected error, frame error and CRC check error.

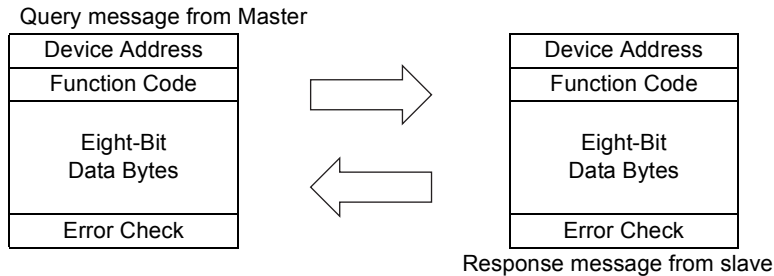
#### 4)Broadcast

By specifying address 0, the master can send a message to all slaves. All slaves that received the message from the master execute the requested function. In this communication, the slaves do not return a response to the master.

#### (4) Message frame (protocol)

- Communication method

Basically, the master sends a query message (question) and the slave returns a response message (response). When communication is normal, Device Address and Function Code are copied as they are, and when communication is abnormal (function code or data code is illegal), bit 7 (= 80h) of Function Code is turned on and the error code is set to Data Bytes.



The message frame consists of the four message fields as shown above.

By adding the no-data time (T1: Start, End) of 3.5 characters to the beginning and end of the message data, the slave recognizes it as one message.

- Protocol details

The four message fields will be explained below.

| Start | 1) ADDRESS | 2) FUNCTION | 3) DATA  | 4) CRC CHECK |           | End |
|-------|------------|-------------|----------|--------------|-----------|-----|
| T1    | 8bit       | 8bit        | n × 8bit | L<br>8bit    | H<br>8bit | T1  |

| Message Field               | Description                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |                                                                          |                                                        |                         |     |                       |                                  |            |     |                        |                                      |         |     |             |                                                        |            |     |                           |                                                        |         |     |                                  |                                                                          |            |
|-----------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------|--------------------------------------------------------|-------------------------|-----|-----------------------|----------------------------------|------------|-----|------------------------|--------------------------------------|---------|-----|-------------|--------------------------------------------------------|------------|-----|---------------------------|--------------------------------------------------------|---------|-----|----------------------------------|--------------------------------------------------------------------------|------------|
| 1) ADDRESS field            | Is 1 byte long (8 bits), and can be set to any of 0 to 247. Set 0 to send a broadcast message (all-address instruction) or any of 1 to 247 to send a message to each slave. When the slave responds, it returns the address set from the master. The value set to <i>Pr. 331 RS-485 communication station</i> is the slave address.                                                                                                                                                                                                                           |                                                                          |                                                        |                         |     |                       |                                  |            |     |                        |                                      |         |     |             |                                                        |            |     |                           |                                                        |         |     |                                  |                                                                          |            |
| 2) FUNCTION field           | The function code is 1 byte long (8 bits) and can be set to any of 1 to 255. The master sets the function that it wants to request from the slave, and the slave performs the requested operation. The following table gives the supported function codes. An error response is returned if the set function code is other than those in the following table. When the slave returns a normal response, it returns the function code set by the master. When the slave returns an error response, it returns H80 + function code.                             |                                                                          |                                                        |                         |     |                       |                                  |            |     |                        |                                      |         |     |             |                                                        |            |     |                           |                                                        |         |     |                                  |                                                                          |            |
|                             | Code                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          | Function Name                                                            | Outline                                                | Broadcast Communication | H03 | Read Holding Register | Reads the holding register data. | Disallowed | H06 | Preset Single Register | Writes data to the holding register. | Allowed | H08 | Diagnostics | Makes a function diagnosis. (communication check only) | Disallowed | H10 | Preset Multiple Registers | Writes data to multiple consecutive holding registers. | Allowed | H46 | Read Holding Register Access Log | Reads the number of registers that succeeded in communication last time. | Disallowed |
|                             | Code                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          | Function Name                                                            | Outline                                                | Broadcast Communication |     |                       |                                  |            |     |                        |                                      |         |     |             |                                                        |            |     |                           |                                                        |         |     |                                  |                                                                          |            |
|                             | H03                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           | Read Holding Register                                                    | Reads the holding register data.                       | Disallowed              |     |                       |                                  |            |     |                        |                                      |         |     |             |                                                        |            |     |                           |                                                        |         |     |                                  |                                                                          |            |
|                             | H06                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           | Preset Single Register                                                   | Writes data to the holding register.                   | Allowed                 |     |                       |                                  |            |     |                        |                                      |         |     |             |                                                        |            |     |                           |                                                        |         |     |                                  |                                                                          |            |
|                             | H08                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           | Diagnostics                                                              | Makes a function diagnosis. (communication check only) | Disallowed              |     |                       |                                  |            |     |                        |                                      |         |     |             |                                                        |            |     |                           |                                                        |         |     |                                  |                                                                          |            |
|                             | H10                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           | Preset Multiple Registers                                                | Writes data to multiple consecutive holding registers. | Allowed                 |     |                       |                                  |            |     |                        |                                      |         |     |             |                                                        |            |     |                           |                                                        |         |     |                                  |                                                                          |            |
| H46                         | Read Holding Register Access Log                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              | Reads the number of registers that succeeded in communication last time. | Disallowed                                             |                         |     |                       |                                  |            |     |                        |                                      |         |     |             |                                                        |            |     |                           |                                                        |         |     |                                  |                                                                          |            |
| Table 1: Function code list |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |                                                                          |                                                        |                         |     |                       |                                  |            |     |                        |                                      |         |     |             |                                                        |            |     |                           |                                                        |         |     |                                  |                                                                          |            |
| 3) DATA field               | The format changes depending on the function code ( <i>refer to page181</i> ). Data includes the byte count, number of bytes, description of access to the holding register, etc.                                                                                                                                                                                                                                                                                                                                                                             |                                                                          |                                                        |                         |     |                       |                                  |            |     |                        |                                      |         |     |             |                                                        |            |     |                           |                                                        |         |     |                                  |                                                                          |            |
| 4) CRC CHECK field          | The received message frame is checked for error. CRC check is performed, and 2 byte long data is added to the end of the message. When CRC is added to the message, the low-order byte is added first and is followed by the high-order byte. The CRC value is calculated by the sending side that adds CRC to the message. The receiving side recalculates CRC during message receiving, and compares the result of that calculation and the actual value received in the CRC CHECK field. If these two values do not match, the result is defined as error. |                                                                          |                                                        |                         |     |                       |                                  |            |     |                        |                                      |         |     |             |                                                        |            |     |                           |                                                        |         |     |                                  |                                                                          |            |

## (5) Message format types

The message formats corresponding to the function codes in Table 1 on page 180 will be explained.

### ● Read holding register data (H03 or 03)

Can read the description of 1) system environment variables, 2) real-time monitor, 3) alarm history, and 4) inverter parameters assigned to the holding register area (refer to the register list).

Query Message

| 1) Slave Address | 2) Function   | 3) Starting Address |             | 4) No. of Points |             | CRC Check   |             |
|------------------|---------------|---------------------|-------------|------------------|-------------|-------------|-------------|
| (8bit)           | H03<br>(8bit) | H<br>(8bit)         | L<br>(8bit) | H<br>(8bit)      | L<br>(8bit) | L<br>(8bit) | H<br>(8bit) |

Response message

| 1) Slave Address | 2) Function   | 5) Byte Count | 6) Data     |             |                    | CRC Check   |             |
|------------------|---------------|---------------|-------------|-------------|--------------------|-------------|-------------|
| (8bit)           | H03<br>(8bit) | (8bit)        | H<br>(8bit) | L<br>(8bit) | ...<br>(n × 16bit) | L<br>(8bit) | H<br>(8bit) |

#### · Query message setting

| message            | Setting description                                                                                                                                                                                                                    |
|--------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1)Slave Address    | Set the address to which the message will be sent. Broadcast communication cannot be made (0 is invalid)                                                                                                                               |
| 2) Function        | Set H03.                                                                                                                                                                                                                               |
| 3)Starting Address | Set the address at which holding register data read will be started. Starting address = starting register address (decimal) – 40001<br>For example, setting of the starting address 0001 reads the data of the holding register 40002. |
| 4)No. of Points    | Set the number of holding registers from which data will be read. The number of registers from which data can be read is a maximum of 125.                                                                                             |

#### · Description of normal response

| message      | Setting description                                                                                                                                                                            |
|--------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 5)Byte Count | The setting range is H02 to H14 (2 to 20).<br>Twice greater than the No. of Points specified at 4) is set.                                                                                     |
| 6)Data       | The number of data specified at 4) is set. Data are read in order of Hi byte and Lo byte, and set in order of starting address data, starting address + 1 data, starting address + 2 data, ... |

Example) To read the register values of 41004 (Pr. 4) to 41006 (Pr. 6) from the slave address 17 (H11)

Query message

| Slave Address | Function      | Starting Address |               | No. of Points |               | CRC Check     |               |
|---------------|---------------|------------------|---------------|---------------|---------------|---------------|---------------|
| H11<br>(8bit) | H03<br>(8bit) | H03<br>(8bit)    | HEB<br>(8bit) | H00<br>(8bit) | H03<br>(8bit) | H77<br>(8bit) | H2B<br>(8bit) |

Normal response (Response message)

| Slave Address | Function      | Byte Count    | Data          |               |               |               |               |               | CRC Check     |               |
|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|
| H11<br>(8bit) | H03<br>(8bit) | H06<br>(8bit) | H17<br>(8bit) | H70<br>(8bit) | H0B<br>(8bit) | HB8<br>(8bit) | H03<br>(8bit) | HE8<br>(8bit) | H2C<br>(8bit) | HE6<br>(8bit) |

Read value

Register 41004 (Pr. 4): H1770 (60.00Hz)

Register 41005 (Pr. 5): H0BB8 (30.00Hz)

Register 41006 (Pr. 6): H03E8 (10.00Hz)

● **Write multiple holding register data (H06 or 06)**

You can write the description of 1) system environment variables and 4) inverter parameters assigned to the holding register area (refer to the register list).

Query message

| 1) Slave Address | 2) Function   | 3) Register Address |          | 4) Preset Data |          | CRC Check |          |
|------------------|---------------|---------------------|----------|----------------|----------|-----------|----------|
| (8bit)           | H06<br>(8bit) | H (8bit)            | L (8bit) | H (8bit)       | L (8bit) | L (8bit)  | H (8bit) |

Normal response (Response message)

| 1) Slave Address | 2) Function   | 3) Register Address |          | 4) Preset Data |          | CRC Check |          |
|------------------|---------------|---------------------|----------|----------------|----------|-----------|----------|
| (8bit)           | H06<br>(8bit) | H (8bit)            | L (8bit) | H (8bit)       | L (8bit) | L (8bit)  | H (8bit) |

· **Query message setting**

| Message            | Setting Description                                                                                                                                                                                                                         |
|--------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1) Slave Address   | Set the address to which the message will be sent. Setting of address 0 enables broadcast communication                                                                                                                                     |
| 2) Function        | Set H06.                                                                                                                                                                                                                                    |
| 3) RegisterAddress | Set the address of the holding register to which data will be written.<br>Register address = holding register address (decimal) – 40001<br>For example, setting of register address 0001 writes data to the holding register address 40002. |
| 4) Prese Data      | Set the data that will be written to the holding register. The written data is fixed to 2 bytes.                                                                                                                                            |

· **Description of normal response**

1) to 4) (including CRC check) of the normal response are the same as those of the query message.  
No response is made for broadcast communication.

Example) To write 60Hz (H1770) to 40014 (running frequency RAM) at slave address 5 (H05).

Query message

| Slave Address | Function      | Register Address |               | Preset Data   |               | CRC Check     |               |
|---------------|---------------|------------------|---------------|---------------|---------------|---------------|---------------|
| H05<br>(8bit) | H06<br>(8bit) | H00<br>(8bit)    | H0D<br>(8bit) | H17<br>(8bit) | H70<br>(8bit) | H17<br>(8bit) | H99<br>(8bit) |

Normal Response (Response message)

Same data as the query message

**CAUTION**

For broadcast communication, no response is returned in reply to a query. Therefore, the next query must be made when the inverter processing time has elapsed after the previous query.

● **Function diagnosis (H08 or 08)**

A communication check can be made since the query message sent is returned unchanged as a response message (function of subfunction code H00). Subfunction code H00 (Return Query Data)

Query Message

| 1) Slave Address | 2) Function   | 3) Subfunction |               | 4) Date     |             | CRC Check   |             |
|------------------|---------------|----------------|---------------|-------------|-------------|-------------|-------------|
| (8bit)           | H08<br>(8bit) | H00<br>(8bit)  | H00<br>(8bit) | H<br>(8bit) | L<br>(8bit) | L<br>(8bit) | H<br>(8bit) |

Normal Response (Response message)

| 1) Slave Address | 2) Function   | 3) Subfunction |               | 4) Date     |             | CRC Check   |             |
|------------------|---------------|----------------|---------------|-------------|-------------|-------------|-------------|
| (8bit)           | H08<br>(8bit) | H00<br>(8bit)  | H00<br>(8bit) | H<br>(8bit) | L<br>(8bit) | L<br>(8bit) | H<br>(8bit) |

· **Query message setting**

| Message          | Setting Description                                                                                      |
|------------------|----------------------------------------------------------------------------------------------------------|
| 1) Slave Address | Set the address to which the message will be sent. Broadcast communication cannot be made (0 is invalid) |
| 2) Function      | Set H08.                                                                                                 |
| 3) Subfunction   | Set H0000.                                                                                               |
| 4) Data          | Any data can be set if it is 2 bytes long. The setting range is H0000 to HFFFF.                          |

· **Description of normal response**

1) to 4) (including CRC check) of the normal response are the same as those of the query message.

● **Write multiple holding register data (H10 or 16)**

You can write data to multiple holding registers.

Query message

| 1) Slave Address | 2) Function   | 3) Starting Address |             | 4) No. of Registers |             | 5) ByteCount | 6) Data     |             |                       | CRC Check   |             |
|------------------|---------------|---------------------|-------------|---------------------|-------------|--------------|-------------|-------------|-----------------------|-------------|-------------|
| (8bit)           | H10<br>(8bit) | H<br>(8bit)         | L<br>(8bit) | H<br>(8bit)         | L<br>(8bit) | (8bit)       | H<br>(8bit) | L<br>(8bit) | ...<br>(n × 2 × 8bit) | L<br>(8bit) | H<br>(8bit) |

Normal Response (Response message)

| 1) Slave Address | 2) Function   | 3) Starting Address |             | 4) No. of Registers |             | CRC Check   |             |
|------------------|---------------|---------------------|-------------|---------------------|-------------|-------------|-------------|
| (8bit)           | H10<br>(8bit) | H<br>(8bit)         | L<br>(8bit) | H<br>(8bit)         | L<br>(8bit) | L<br>(8bit) | H<br>(8bit) |

· **Query message setting**

| Message             | Setting Description                                                                                                                                                                                                                  |
|---------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1) Slave Address    | Set the address to which the message will be sent. Setting of address 0 enables broadcast communication                                                                                                                              |
| 2) Function         | Set H10.                                                                                                                                                                                                                             |
| 3) Starting Address | Set the address where holding register data write will be started. Starting address = starting register address (decimal) – 40001<br>For example, setting of the starting address 0001 reads the data of the holding register 40002. |
| 4) No. of Points    | Set the number of holding registers where data will be written. The number of registers where data can be written is a maximum of 125.                                                                                               |
| 5) Byte Count       | The setting range is H02 to HFA (0 to 250).<br>Set twice greater than the value specified at 4).                                                                                                                                     |
| 6) Data             | Set the data specified by the number specified at 4). The written data are set in order of Hi byte and Lo byte, and arranged in order of the starting address data, starting address + 1 data, starting address + 2 data ...         |

• **Description of normal response**

1) to 4) (including CRC check) of the normal response are the same as those of the query message.

Example) To write 0.5s (H05) to 41007 (Pr. 7) at the slave address 25 (H19) and 1s (H0A) to 41008 (Pr. 8).

Query Message

| Slave Address | Function      | Starting Address |               | No. of Points |               | Byte Count    | Data          |               |               |               | CRC Check     |               |
|---------------|---------------|------------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|
| H19<br>(8bit) | H10<br>(8bit) | H03<br>(8bit)    | HEE<br>(8bit) | H00<br>(8bit) | H02<br>(8bit) | H04<br>(8bit) | H00<br>(8bit) | H05<br>(8bit) | H00<br>(8bit) | H0A<br>(8bit) | H86<br>(8bit) | H3D<br>(8bit) |

Response message (Response message)

| Slave Address | Function      | Starting Address |               | No. of Points |               | CRC Check     |               |
|---------------|---------------|------------------|---------------|---------------|---------------|---------------|---------------|
| H19<br>(8bit) | H10<br>(8bit) | H03<br>(8bit)    | HEE<br>(8bit) | H00<br>(8bit) | H02<br>(8bit) | H22<br>(8bit) | H61<br>(8bit) |

● **Read holding register access log (H46 or 70)**

A response can be made to a query made by the function code H03, H06 or H0F.

The starting address of the holding registers that succeeded in access during previous communication and the number of successful registers are returned.

In response to the query for other than the above function code, 0 is returned for the address and number of registers.

Query Message

| 1) Slave Address | 2) Function   | CRC Check   |             |
|------------------|---------------|-------------|-------------|
| (8bit)           | H46<br>(8bit) | L<br>(8bit) | H<br>(8bit) |

Normal Response (Response message)

| 1) Slave Address | 2) Function   | 3) Starting Address |             | 4) No. of Points |             | CRC Check   |             |
|------------------|---------------|---------------------|-------------|------------------|-------------|-------------|-------------|
| (8bit)           | H46<br>(8bit) | H<br>(8bit)         | L<br>(8bit) | H<br>(8bit)      | L<br>(8bit) | L<br>(8bit) | H<br>(8bit) |

• **Query message setting**

| Message          | Setting Description                                                                                      |
|------------------|----------------------------------------------------------------------------------------------------------|
| 1) Slave Address | Set the address to which the message will be sent. Broadcast communication cannot be made (0 is invalid) |
| 2) Function      | Set H46.                                                                                                 |

• **Description of normal response**

| Message             | Setting Description                                                                                                                                                                                                                                                                      |
|---------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 3) Starting Address | The starting address of the holding registers that succeeded in access is returned.<br>Starting address = starting register address (decimal) – 40001<br>For example, when the starting address 0001 is returned, the address of the holding register that succeeded in access is 40002. |
| 4) No. of Points    | The number of holding registers that succeeded in access is returned.                                                                                                                                                                                                                    |

Example) To read the successful register starting address and successful count from the slave address 25 (H19).

Query Message

| Slave Address | Function      | CRC Check     |               |
|---------------|---------------|---------------|---------------|
| H19<br>(8bit) | H46<br>(8bit) | H8B<br>(8bit) | HD2<br>(8bit) |

Normal Response (Response message)

| Slave Address | Function      | Starting Address |               | No. of Points |               | CRC Check     |               |
|---------------|---------------|------------------|---------------|---------------|---------------|---------------|---------------|
| H19<br>(8bit) | H10<br>(8bit) | H03<br>(8bit)    | HEE<br>(8bit) | H00<br>(8bit) | H02<br>(8bit) | H22<br>(8bit) | H61<br>(8bit) |

Success of two registers at starting address 41007 (Pr. 7) is returned.

● **Error response**

An error response is returned if the query message received from the master has an illegal function, address or data. No response is returned for a parity, CRC, overrun, framing or busy error.

Error response (Response message)

| 1) Slave Address | 2) Function              | 3) Exception Code | CRC Check   |             |
|------------------|--------------------------|-------------------|-------------|-------------|
| (8bit)           | H80 + Function<br>(8bit) | (8bit)            | L<br>(8bit) | H<br>(8bit) |

| Message           | Setting Description                              |
|-------------------|--------------------------------------------------|
| 1) Slave address  | Set the address received from the master.        |
| 2) Function       | The master-requested function code + H80 is set. |
| 3) Exception code | The code in the following table is set.          |

**Error code list**

| Code | Error Item                                   | Error Definition                                                                                                                                                      |
|------|----------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 01   | ILLEGAL FUNCTION<br>(Function code illegal)  | The set function code in the query message from the master cannot be handled by the slave.                                                                            |
| 02   | ILLEGAL DATA ADDRESS *1<br>(Address illegal) | The set register address in the query message from the master cannot be handled by the inverter.<br>(No parameter, parameter read disabled, parameter write disabled) |
| 03   | ILLEGAL DATA VALUE<br>(Data illegal)         | The set data in the query message from the master cannot be handled by the inverter.<br>(Out of parameter write range, mode specified, other error)                   |

\*1 An error will not occur in the following cases.

1) Function code H03 (Read Holding Register Data )

When the No. of Points is 1 or more and there is one or more holding registers from which data can be read

2) Function code H10 (Write Multiple Holding Register Data)

When the No. of Points is 1 or more and there is 1 or more holding registers to which data can be written

Namely, when the function code H03 or H10 is used to access multiple holding registers, an error will not occur if a non-existing holding register or read disabled or write disabled holding register is accessed.

**REMARKS**

An error will occur if all accessed holding registers do not exist.

Data read from a non-existing holding register is 0, and data written there is invalid.

· **Message data mistake detection**

To detect the mistakes of message data from the master, they are checked for the following errors. If an error is detected, an alarm stop will not occur.

**Error check item**

| Error Item          | Error Definition                                                                                                     | Inverter Side Operation                                                                                |
|---------------------|----------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------|
| Parity error        | The data received by the inverter differs from the specified parity (Pr. 334 setting).                               | 1) Pr. 343 is increased by 1 at error occurrence.<br>2) The terminal LF is output at error occurrence. |
| Framing error       | The data received by the inverter differs from the specified stop bit length (Pr. 333).                              |                                                                                                        |
| Overrun error       | The following data was sent from the master before the inverter completes data receiving.                            |                                                                                                        |
| Message frame error | The message frame data length is checked, and the received data length of less than 4 bytes is regarded as an error. |                                                                                                        |
| CRC check error     | A mismatch found by CRC check between the message frame data and calculation result is regarded as an error.         |                                                                                                        |

## 1) Pr. 343 Communication error count

You can check the cumulative number of communication errors.

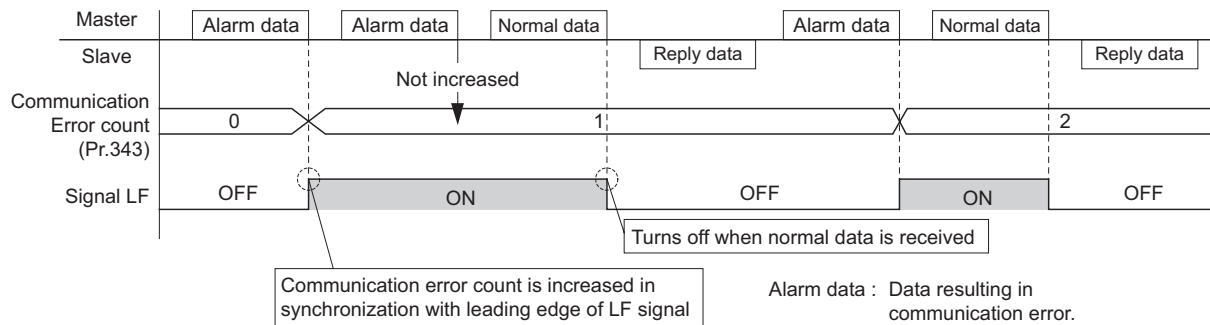
| Parameters | Setting Range | Minimum setting range | Initial Value |
|------------|---------------|-----------------------|---------------|
| 343        | (Read only)   | 1                     | 0             |

### CAUTION

The number of communication errors is temporarily stored into the RAM. As it is not stored into the EEPROM, performing a power supply reset or inverter reset clears the value to 0.

## 2) Output signal LF "minor failure output(communication error warnings)"

During a communication error, the minor failure output (LF signal) is output by open collector output. Assign the used terminal using any of Pr. 190 to Pr. 196 (output terminal function selection).



### CAUTION

The LF signal can be assigned to the output terminal using any of Pr. 190 to Pr. 196. When terminal assignment is changed, the other functions may be affected. Please make setting after confirming the function of each terminal.

## (6) Modbus registers

### ● System environment variable

| Register | Definition                                   | Read/write | Remarks                                                                                                    |
|----------|----------------------------------------------|------------|------------------------------------------------------------------------------------------------------------|
| 40002    | Inverter reset                               | Write      | Any value can be written                                                                                   |
| 40003    | Parameter clear                              | Write      | Set H965A as a written value.                                                                              |
| 40004    | All parameter clear                          | Write      | Set H99AA as a written value.                                                                              |
| 40006    | Parameter clear *1                           | Write      | Set H5A96 as a written value.                                                                              |
| 40007    | All parameter clear *1                       | Write      | Set HAA99 as a written value.                                                                              |
| 40009    | Inverter status/control input instruction *2 | Read/write | See below.                                                                                                 |
| 40010    | Operation mode/inverter setting *3           | Read/write | See below.                                                                                                 |
| 40014    | Running frequency (RAM value)                | Read/write | According to the Pr. 37 and Pr. 144 settings, the frequency and selectable speed are in 1r/min increments. |
| 40015    | Running frequency (EEPROM value)             | Write      |                                                                                                            |

\*1 The communication parameter values are not cleared.

\*2 For write, set the data as a control input instruction. For read, data is read as an inverter operating status.

\*3 For write, set data as the operation mode setting. For read, data is read as the operation mode status.

#### <Inverter status/control input instruction>

| Bit | Definition                                                                  |                                      |
|-----|-----------------------------------------------------------------------------|--------------------------------------|
|     | Control input instruction                                                   | Inverter status                      |
| 0   | Stop command                                                                | RUN (inverter running) *2            |
| 1   | Forward rotation command                                                    | Forward rotation                     |
| 2   | Reverse rotation command                                                    | Reverse rotation                     |
| 3   | RH (high speed operation command) *1                                        | SU (up to frequency) *2              |
| 4   | RM (middle speed operation command) *1                                      | OL (overload) *2                     |
| 5   | RL (low speed operation command) *1                                         | IPF (instantaneous power failure) *2 |
| 6   | JOG (Jog operation) *1                                                      | FU (frequency detection) *2          |
| 7   | RT (second function selection) *1                                           | ABC1 (alarm) *2                      |
| 8   | AU (current input selection) *1                                             | ABC2 (—) *2                          |
| 9   | CS<br>(selection of automatic restart after instantaneous power failure) *1 | 0                                    |
| 10  | MRS (output stop) *1                                                        | 0                                    |
| 11  | STOP (start self-holding) *1                                                | 0                                    |
| 12  | RES (reset) *1                                                              | 0                                    |
| 13  | 0                                                                           | 0                                    |
| 14  | 0                                                                           | 0                                    |
| 15  | 0                                                                           | Alarm occurrence                     |

#### <Operation mode/inverter setting>

| Mode    | Read value | Written value |
|---------|------------|---------------|
| EXT     | H0000      | H0010         |
| PU      | H0001      | —             |
| EXT JOG | H0002      | —             |
| NET     | H0004      | H0014         |
| PU+ EXT | H0005      | —             |

The restrictions depending on the operation mode changes according to the computer link specifications.

\*1 The signal within parentheses is the initial setting. The description changes depending on the setting of Pr. 180 to Pr. 189 (input terminal function selection) (page90).

Each assigned signal is valid or invalid depending on NET. (Refer to page 156)

\*2 The signal within parentheses is the initial setting. The description changes depending on the setting of Pr. 190 to Pr. 196 (output terminal function selection) (page96).

### ● Real-time monitor

Refer to page 105 for details of the monitor description.

| Register | Description                                   | Unit                |
|----------|-----------------------------------------------|---------------------|
| 40201    | Output frequency                              | 0.01Hz              |
| 40202    | Output current                                | 0.01A/0.1A*3        |
| 40203    | Output voltage                                | 0.1V                |
| 40205    | Frequency setting                             | 0.01Hz              |
| 40206    | Running speed                                 | 1r/min              |
| 40208    | Converter output voltage                      | 0.1V                |
| 40209    | Regenerative brake duty                       | 0.1%                |
| 40210    | Electronic thermal relay function load factor | 0.1%                |
| 40211    | Output current peak value                     | 0.01A/0.1A*3        |
| 40212    | Converter output voltage peak value           | 0.1V                |
| 40213    | Input power                                   | 0.01kW/<br>0.1kW *3 |

| Register | Description                  | Unit                |
|----------|------------------------------|---------------------|
| 40214    | Output power                 | 0.01kW/<br>0.1kW *3 |
| 40215    | Input terminal status *1     | —                   |
| 40216    | Output terminal status *2    | —                   |
| 40217    | Load meter                   | 0.1%                |
| 40220    | Cumulative energization time | 1h                  |
| 40223    | Actual operation time        | 1h                  |
| 40224    | Motor load factor            | 0.1%                |
| 40225    | Cumulative power             | 1kWh                |
| 40250    | Power saving effect          | Variable            |
| 40251    | Cumulative saving power      | Variable            |
| 40252    | PID set point                | 0.1%                |
| 40253    | PID measurement value        | 0.1%                |
| 40254    | PID deviation value          | 0.1%                |

\*1 Input terminal monitor details

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|   |   |   |   |    |     |      |     |     |    |    |    |    |    |     |     |
|---|---|---|---|----|-----|------|-----|-----|----|----|----|----|----|-----|-----|
| — | — | — | — | CS | RES | STOP | MRS | JOG | RH | RM | RL | RT | AU | STR | STF |
|---|---|---|---|----|-----|------|-----|-----|----|----|----|----|----|-----|-----|

b0

\*2 Output terminal monitor details

b15

|   |   |   |   |   |   |   |   |   |      |      |    |    |     |    |     |
|---|---|---|---|---|---|---|---|---|------|------|----|----|-----|----|-----|
| — | — | — | — | — | — | — | — | — | ABC2 | ABC1 | FU | OL | IPF | SU | RUN |
|---|---|---|---|---|---|---|---|---|------|------|----|----|-----|----|-----|

b0

\*3 The setting depends on capacities. (FR-F720-02330 (FR-F740-01160) or less/FR-F720-03160 (FR-F740-01800) or more)

● Parameter

| Parameters | Register       | Parameter Name                                                 | Read/write | Remarks                                                                          |
|------------|----------------|----------------------------------------------------------------|------------|----------------------------------------------------------------------------------|
| 0 to 999   | 41000 to 41999 | Refer to the parameter list (page 44) for the parameter names. | Read/write | The parameter number + 41000 is the register number.                             |
| C2(902)    | 41902          | Terminal 2 frequency setting bias (frequency)                  | Read/write |                                                                                  |
| C3(902)    | 42092          | Terminal 2 frequency setting bias (analog value)               | Read/write | The analog value (%) set to C3 (902) is read.                                    |
|            | 43902          | Terminal 2 frequency setting bias (terminal analog value)      | Read       | The analog value (%) of the voltage (current) applied to the terminal 2 is read. |
| 125(903)   | 41903          | Terminal 2 frequency setting gain (frequency)                  | Read/write |                                                                                  |
| C4(903)    | 42093          | Terminal 2 frequency setting gain (analog value)               | Read/write | The analog value (%) set to C4 (903) is read.                                    |
|            | 43903          | Terminal 2 frequency setting gain (terminal analog value)      | Read       | The analog value (%) of the voltage (current) applied to the terminal 2 is read. |
| C5(904)    | 41904          | Terminal 4 frequency setting bias (frequency)                  | Read/write |                                                                                  |
| C6(904)    | 42094          | Terminal 4 frequency setting bias (analog value)               | Read/write | The analog value (%) set to C6 (904) is read.                                    |
|            | 43904          | Terminal 4 frequency setting bias (terminal analog value)      | Read       | The analog value (%) of the current (voltage) applied to the terminal 4 is read. |
| 126(905)   | 41905          | Terminal 4 frequency setting gain (frequency)                  | Read/write |                                                                                  |
| C7(905)    | 42095          | Terminal 4 frequency setting gain (analog value)               | Read/write | The analog value (%) set to C7 (905) is read.                                    |
|            | 43905          | Terminal 4 frequency setting gain (terminal analog value)      | Read       | The analog value (%) of the current (voltage) applied to the terminal 4 is read. |
| C8(930)    | 41930          | Current output bias signal                                     | Read/write |                                                                                  |
| C9(930)    | 42120          | Current output bias current                                    | Read/write |                                                                                  |
| C10(931)   | 41931          | Current output gain signal                                     | Read/write |                                                                                  |
| C11(931)   | 42121          | Current output gain current                                    | Read/write |                                                                                  |

● Alarm history

| Register | Definition      | Read/write | Remarks                                                                                                                                                                                                             |
|----------|-----------------|------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 40501    | Alarm history 1 | Read/write | Being 2 bytes in length, the data is stored as "H0000". The error code can be referred to in the low-order 1 byte. Performing write using the register 40501 batch-clears the alarm history. Set any value as data. |
| 40502    | Alarm history 2 | Read       |                                                                                                                                                                                                                     |
| 40503    | Alarm history 3 | Read       |                                                                                                                                                                                                                     |
| 40504    | Alarm history 4 | Read       |                                                                                                                                                                                                                     |
| 40505    | Alarm history 5 | Read       |                                                                                                                                                                                                                     |
| 40506    | Alarm history 6 | Read       |                                                                                                                                                                                                                     |
| 40507    | Alarm history 7 | Read       |                                                                                                                                                                                                                     |
| 40508    | Alarm history 8 | Read       |                                                                                                                                                                                                                     |

Alarm code list

| Data | Description | Data | Description | Data | Description |
|------|-------------|------|-------------|------|-------------|
| H00  | No alarm    | H52  | ILF         | HB3  | PE2         |
| H10  | OC1         | H60  | OLT         | HC0  | CPU         |
| H11  | OC2         | H70  | BE          | HC1  | CTE         |
| H12  | OC3         | H80  | GF          | HC2  | P24         |
| H20  | OV1         | H81  | LF          | HC4  | CDO         |
| H21  | OV2         | H90  | OHT         | HC5  | IOH         |
| H22  | OV3         | H91  | PTC         | HC6  | SER         |
| H30  | THT         | HA0  | OPT         | HC7  | AIE         |
| H31  | THM         | HA1  | OP1         | HF1  | E.1         |
| H40  | FIN         | HB0  | PE          | HF6  | E.6         |
| H50  | IPF         | HB1  | PUE         | HF7  | E.7         |
| H51  | UVT         | HB2  | RET         | HFD  | E.13        |

## 3.19 Special operation and frequency control

| Purpose                                                                                 | Parameter that must be set                           |                                        | Refer to page |
|-----------------------------------------------------------------------------------------|------------------------------------------------------|----------------------------------------|---------------|
| Perform process control such as pump and air volume.                                    | PID control                                          | Pr. 127 to Pr. 134, Pr. 575 to Pr. 577 | 189           |
| Pump function by multiple motors                                                        | Advanced PID function                                | Pr. 575 to Pr. 591                     | 202           |
| Switch between the inverter operation and commercial power-supply operation to operate. | Commercial power supply-inverter switchover function | Pr. 135 to Pr. 139, Pr. 159            | 197           |
| Avoid overvoltage alarm due to regeneration by automatic adjustment of output frequency | Regeneration avoidance function                      | Pr. 882 to Pr. 886                     | 211           |

### 3.19.1 PID control (Pr. 127 to Pr. 134, Pr. 575 to Pr. 577)

The inverter can be used to exercise process control, e.g. flow rate, air volume or pressure.

The terminal 2 input signal or parameter setting is used as a set point and the terminal 4 input signal used as a feedback value to constitute a feedback system for PID control.

|        |          |
|--------|----------|
| Pr.126 | page 134 |
| Pr.135 | page 197 |
| Pr.571 | page 81  |
| Pr.611 | page 114 |

| Parameter Number | Name                                       | Initial Value | Setting Range  | Description                                                                                                                                                                                                                                                                                                                         |
|------------------|--------------------------------------------|---------------|----------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 127              | PID control automatic switchover frequency | 9999          | 0 to 400Hz     | Set the frequency at which the control is automatically changed to PID control.                                                                                                                                                                                                                                                     |
|                  |                                            |               | 9999           | Without PID automatic switchover function                                                                                                                                                                                                                                                                                           |
| 128              | PID action selection                       | 10            | 10             | PID reverse action                                                                                                                                                                                                                                                                                                                  |
|                  |                                            |               | 11             | PID forward action                                                                                                                                                                                                                                                                                                                  |
|                  |                                            |               | 20             | PID reverse action                                                                                                                                                                                                                                                                                                                  |
|                  |                                            |               | 21             | PID forward action                                                                                                                                                                                                                                                                                                                  |
|                  |                                            |               | 50             | PID reverse action                                                                                                                                                                                                                                                                                                                  |
|                  |                                            |               | 51             | PID forward action                                                                                                                                                                                                                                                                                                                  |
|                  |                                            |               | 60             | PID reverse action                                                                                                                                                                                                                                                                                                                  |
|                  |                                            |               | 61             | PID forward action                                                                                                                                                                                                                                                                                                                  |
| 129 *1           | PID proportional band                      | 100%          | 0.1 to 1000%   | If the proportional band is narrow (parameter setting is small), the manipulated variable varies greatly with a slight change of the measured value. Hence, as the proportional band narrows, the response sensitivity (gain) improves but the stability deteriorates, e.g. hunting occurs. Gain $K_p = 1/\text{proportional band}$ |
|                  |                                            |               | 9999           | No proportional control                                                                                                                                                                                                                                                                                                             |
| 130 *1           | PID integral time                          | 1s            | 0.1 to 3600s   | For deviation step input, time (Ti) required for only the integral (I) action to provide the same manipulated variable as that for the proportional (P) action. As the integral time decreases, the set point is reached earlier but hunting occurs more easily.                                                                    |
|                  |                                            |               | 9999           | No integral control.                                                                                                                                                                                                                                                                                                                |
| 131              | PID upper limit                            | 9999          | 0 to 100%      | Set the upper limit value. If the feedback value exceeds the setting, the FUP signal is output. The maximum input (20mA/5V/10V) of the measured value (terminal 4) is equivalent to 100%.                                                                                                                                           |
|                  |                                            |               | 9999           | No function                                                                                                                                                                                                                                                                                                                         |
| 132              | PID lower limit                            | 9999          | 0 to 100%      | Set the lower limit value. If the measured value falls below the setting range, the FDN signal is output. The maximum input (20mA/5V/10V) of the process value (terminal 4) is equivalent to 100%.                                                                                                                                  |
|                  |                                            |               | 9999           | No function                                                                                                                                                                                                                                                                                                                         |
| 133 *1           | PID action set point                       | 9999          | 0 to 100%      | Used to set the set point for PID control.                                                                                                                                                                                                                                                                                          |
|                  |                                            |               | 9999           | Terminal 2 input is the set point.                                                                                                                                                                                                                                                                                                  |
| 134 *1           | PID differential time                      | 9999          | 0.01 to 10.00s | For deviation lamp input, time (Td) required for providing only the manipulated variable for the proportional (P) action. As the differential time increases, greater response is made to a deviation change.                                                                                                                       |
|                  |                                            |               | 9999           | No differential control.                                                                                                                                                                                                                                                                                                            |

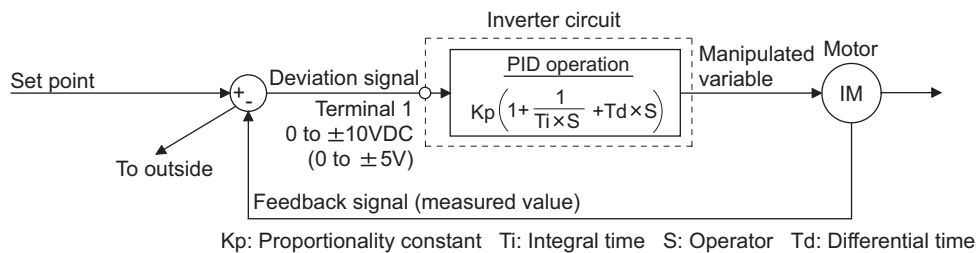
| Parameter Number | Name                                | Initial Value | Setting Range | Description                                                                                                                                                |
|------------------|-------------------------------------|---------------|---------------|------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 575              | Output interruption detection time  | 1s            | 0 to 3600s    | The inverter stops operation if the output frequency after PID operation remains at less than the Pr. 576 setting for longer than the time set in Pr. 575. |
|                  |                                     |               | 9999          | Without output interruption function                                                                                                                       |
| 576              | Output interruption detection level | 0Hz           | 0 to 400Hz    | Set the frequency at which the output interruption processing is performed.                                                                                |
| 577              | Output interruption release level   | 1000%         | 900 to 1100%  | Set the level (Pr. 577 minus 1000%) to release the PID output interruption function.                                                                       |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

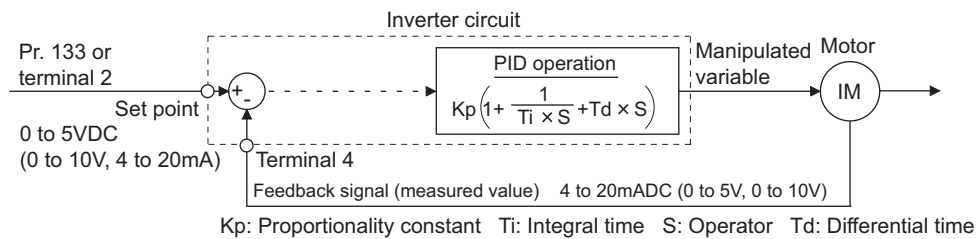
\*1 Pr. 129, Pr. 130, Pr. 133 and Pr. 134 can be set during operation. They can also be set independently of the operation mode.

## (1) PID control basic configuration

- Pr. 128 = "10, 11" (Deviation value signal input)



- Pr. 128 = "20, 21" (Measured value input)



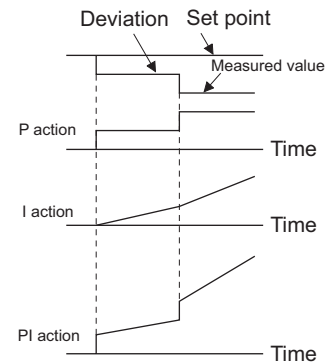
## (2) PID action overview

### 1) PI action

A combination of P action (P) and I action (I) for providing a manipulated variable in response to deviation and changes with time.

[Operation example for stepped changes of process value]

(Note) PI action is the sum of P and I actions.

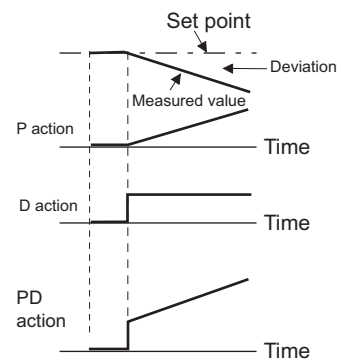


### 2) PD action

A combination of P action (P) and differential control action (D) for providing a manipulated variable in response to deviation speed to improve the transient characteristic.

[Operation example for proportional changes of process value]

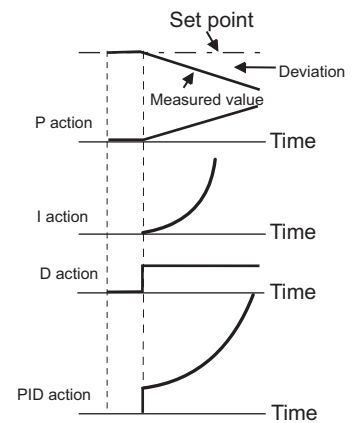
(Note) PD action is the sum of P and D actions.



### 3) PID action

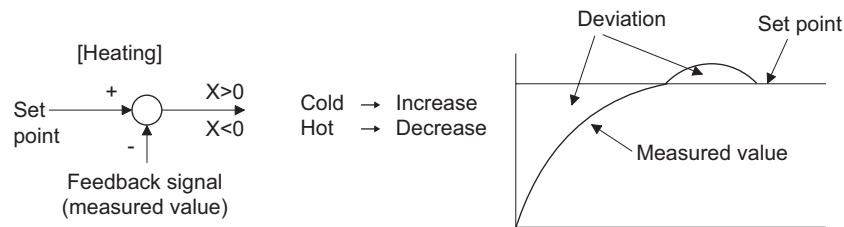
The PI action and PD action are combined to utilize the advantages of both actions for control.

(Note) PID action is the sum of P, I and D actions.



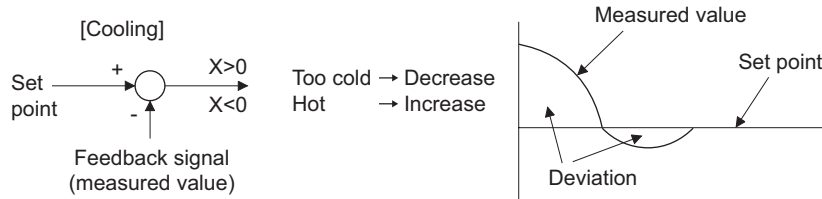
#### 4) Reverse action

Increases the manipulated variable (output frequency) if deviation  $X = (\text{set point} - \text{measured value})$  is positive, and decreases the manipulated variable if deviation is negative.



5) Forward action

Increases the manipulated variable (output frequency) if deviation  $X = (\text{set point} - \text{measured value})$  is negative, and decreases the manipulated variable if deviation is positive.

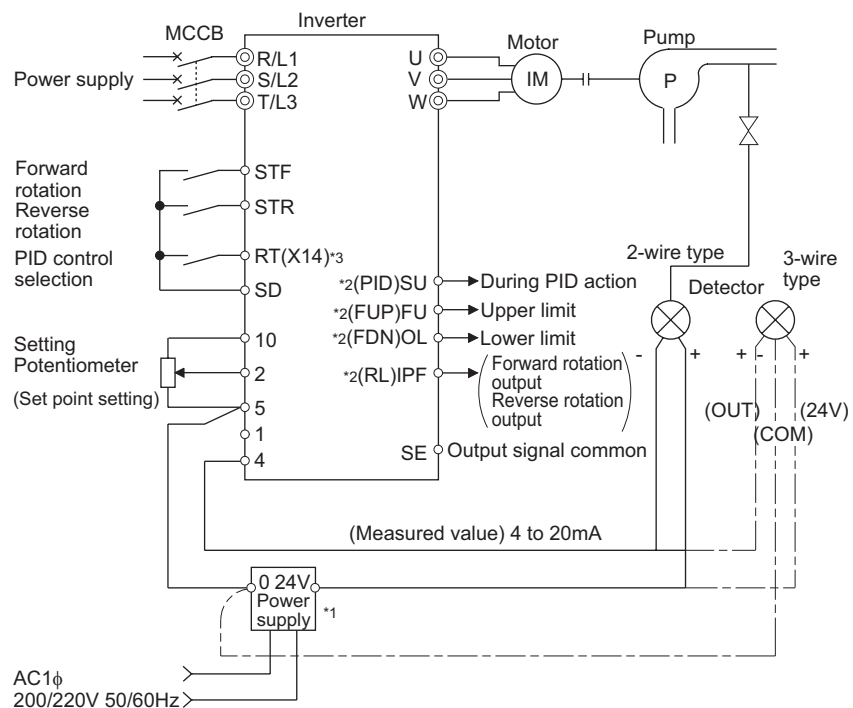


Relationships between deviation and manipulated variable (output frequency)

|                | Deviation |          |
|----------------|-----------|----------|
|                | Positive  | Negative |
| Reverse action | ↗         | ↘        |
| Forward action | ↘         | ↗        |

### (3) Connection diagram

- Sink logic
- $Pr. 128 = 20$
- $Pr. 183 = 14$
- $Pr. 191 = 47$
- $Pr. 192 = 16$
- $Pr. 193 = 14$
- $Pr. 194 = 15$



\*1 The power supply must be selected in accordance with the power specifications of the detector used.

\*2 The used output signal terminal changes depending on the *Pr. 190 to Pr. 196 (output terminal selection)* setting.

\*3 The used output signal terminal changes depending on the *Pr: 178 to Pr: 189 (input terminal selection)* setting.

#### (4) I/O signals and parameter setting

- Turn on the X14 signal to perform PID control. When this signal is off, PID action is not performed and normal inverter operation is performed. (Note that the X14 signal need not be turned on for PID control via LONWORKS communication.)
- Enter the set point across inverter terminals 2-5 or into *Pr. 133* and enter the measured value signal across inverter terminals 4-5. At this time, set "20" or "21" in *Pr. 128*.
- When entering the externally calculated deviation signal, enter it across terminals 1-5. At this time, set "10" or "11" in *Pr. 128*.

| Signal                      | Terminal Used                             | Function                                    | Description                                                                                                                                                                  | Parameter Setting                                                                                                                             |
|-----------------------------|-------------------------------------------|---------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------|
| X14                         | Depending on<br><i>Pr. 178 to Pr. 189</i> | PID control selection                       | Turn on X14 to perform PID control.                                                                                                                                          | Set 14 to any of <i>Pr. 178 to Pr. 189</i> .                                                                                                  |
| X64                         |                                           | PID forward/reverse action switchover       | By turning on X64, forward action can be selected for PID reverse action ( <i>Pr. 128 = 10, 20</i> ), and reverse action for forward action ( <i>Pr. 128 = 11, 21</i> ).     | Set 64 to any of <i>Pr. 178 to Pr. 189</i> .                                                                                                  |
| 2                           | 2                                         | Set point input                             | Enter the set point for PID control.<br>0 to 5V..... 0 to 100%<br>0 to 10V.... 0 to 100%<br>4 to 20mA. 0 to 100%                                                             | <i>Pr. 128 = 20, 21, Pr. 133 = 9999</i><br><i>Pr. 73 = 1, 3, 5, 11, 13, 15</i><br><i>Pr. 73 = 0, 2, 4, 10, 12, 14</i><br><i>Pr. 73 = 6, 7</i> |
| PU                          | —                                         | Set point input                             | Set the set value ( <i>Pr. 133</i> ) from the operation panel or parameter unit.                                                                                             | <i>Pr. 128 = 20, 21, Pr. 133 = 0 to 100%</i>                                                                                                  |
| 1                           | 1                                         | Deviation signal input                      | Input the deviation signal calculated externally.<br>-5V to +5V.....-100% to +100%<br>-10V to +10V.....-100% to +100%                                                        | <i>Pr. 128 = 10, 11</i><br><i>Pr. 73 = 2, 3, 5, 7, 12, 13, 15, 17</i><br><i>Pr. 73 = 0, 1, 4, 6, 10, 11, 14, 16</i>                           |
| 4                           | 4                                         | Measured value input                        | Input the signal from the detector (measured value signal).<br>4 to 20mA. 0 to 100%<br>0 to 5V..... 0 to 100%<br>0 to 10V.... 0 to 100%                                      | <i>Pr. 128 = 20, 21</i><br><i>Pr. 267 = 0, 1</i><br><i>Pr. 267 = 1</i><br><i>Pr. 267 = 2</i>                                                  |
| Communication <sup>*2</sup> | —                                         | Deviation value input                       | Input the deviation value from LONWORKS, CC-Link communication.                                                                                                              | <i>Pr. 128 = 50, 51</i>                                                                                                                       |
|                             |                                           | Set value, measured value input             | Input the set value and measured value from LONWORKS, CC-Link communication.                                                                                                 | <i>Pr. 128 = 60, 61</i>                                                                                                                       |
| FUP                         | Depending on<br><i>Pr. 190 to Pr. 196</i> | Upper limit output                          | Output to indicate that the measured value signal exceeded the upper limit value ( <i>Pr. 131</i> ).                                                                         | <i>Pr. 128 = 20, 21, 60, 61</i><br><i>Pr. 131 ≠ 9999</i><br>Set 15 or 115 to any of <i>Pr. 190 to Pr. 196</i> . <sup>*3</sup>                 |
| FDN                         |                                           | Lower limit output                          | Output when the measured value signal falls below the lower limit ( <i>Pr. 132</i> ).                                                                                        | <i>Pr. 128 = 20, 21, 60, 61</i><br><i>Pr. 132 ≠ 9999</i><br>Set 14 or 114 to any of <i>Pr. 190 to Pr. 196</i> . <sup>*3</sup>                 |
| RL                          |                                           | Forward (reverse) rotation direction output | "Hi" is output to indicate that the output indication of the parameter unit is forward rotation (FWD) or "Low" to indicate that it is reverse rotation (REV) or stop (STOP). | Set 16 or 116 to any of <i>Pr. 190 to Pr. 196</i> . <sup>*3</sup>                                                                             |
| PID                         |                                           | During PID control activated                | Turns on during PID control.                                                                                                                                                 | Set 47 or 147 to any of <i>Pr. 190 to Pr. 196</i> . <sup>*3</sup>                                                                             |
| SLEEP                       |                                           | PID output interruption                     | Turns on when the PID output interruption function is performed.                                                                                                             | <i>Pr. 575 ≠ 9999</i><br>Set 70 or 170 to any of <i>Pr. 190 to Pr. 196</i> . <sup>*3</sup>                                                    |
| SE                          | SE                                        | Output terminal common                      | Common terminal for terminals FUP, FDN, RL, PID and SLEEP                                                                                                                    |                                                                                                                                               |

\*1 The hatched area indicates the parameter initial value.

\*2 For the setting method via LONWORKS communication, refer to the LONWORKS communication option (FR-A7NL) instruction manual. For the setting method via CC-Link communication, refer to the CC-Link communication option (FR-A7NC) instruction manual.

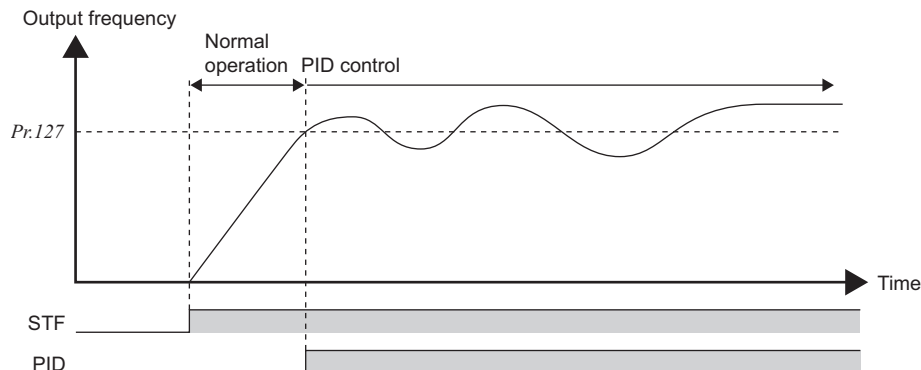
\*3 When 100 or larger value is set to any of *Pr. 190 to Pr. 196* (output terminal function selection), the terminal output has negative logic. (Refer to page 96 for details)

#### CAUTION

- Changing the terminal function using any of *Pr. 178 to Pr. 189, 190 to Pr. 196* may affect the other functions. Please make setting after confirming the function of each terminal.

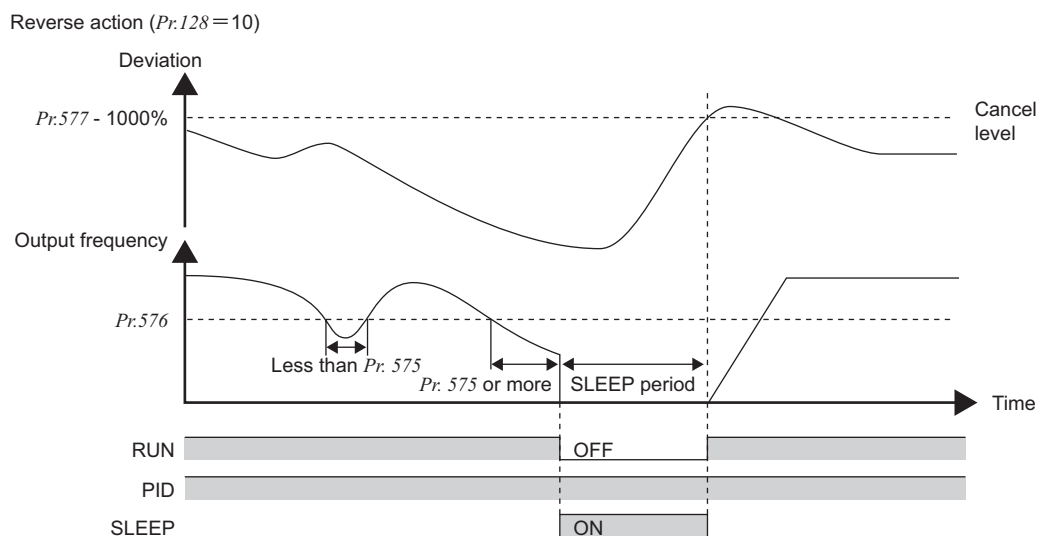
### (5) PID control automatic switchover control (Pr.127)

- For a fast system startup at an operation start, the system can be started up in normal operation mode only at a start.
- When the frequency is set to *Pr. 127 PID control automatic switchover frequency* within the range 0 to 400Hz, the system starts up in normal operation mode from a start until *Pr. 127* is reached, and then it shifts to PID control operation mode. Once the system has entered PID control operation, it continues PID control if the output frequency falls to or below *Pr. 127*.



### (6) PID output suspension function (SLEEP function) (SLEEP signal, Pr. 575 to Pr. 577)

- The inverter stops operation if the output frequency after PID operation remains at less than the *Pr. 576 Output interruption detection level* setting for longer than the time set in *Pr. 575 Output interruption detection time*. This function can reduce energy consumption in the low-efficiency, low-speed range.
- When the deviation (= set value - measured value) reaches the PID output shutoff cancel level (*Pr. 577* setting - 1000%) while the PID output interruption function is on, the PID output interruption function is canceled and PID control operation is resumed automatically.
- While the PID output interruption function is on, the PID output interruption signal (SLEEP) is output. At this time, the inverter running signal (RUN) is off and the PID control operating signal (PID) is on.

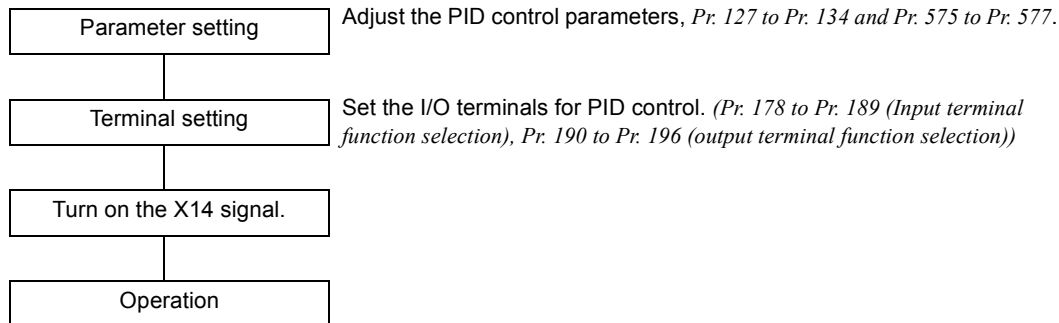


### (7) PID monitor function

- The PID control set value, process value and deviation value can be output to the operation panel monitor display and terminal CA, AM.
- The deviation monitor can display a negative value on the assumption that 1000 is 0%. (The deviation monitor cannot be output from the terminal CA, AM.)
- For the monitors, set the following values in *Pr. 52 DU/PU main display data selection*, *Pr. 54 CA terminal function selection*, and *Pr. 158 AM terminal function selection*.

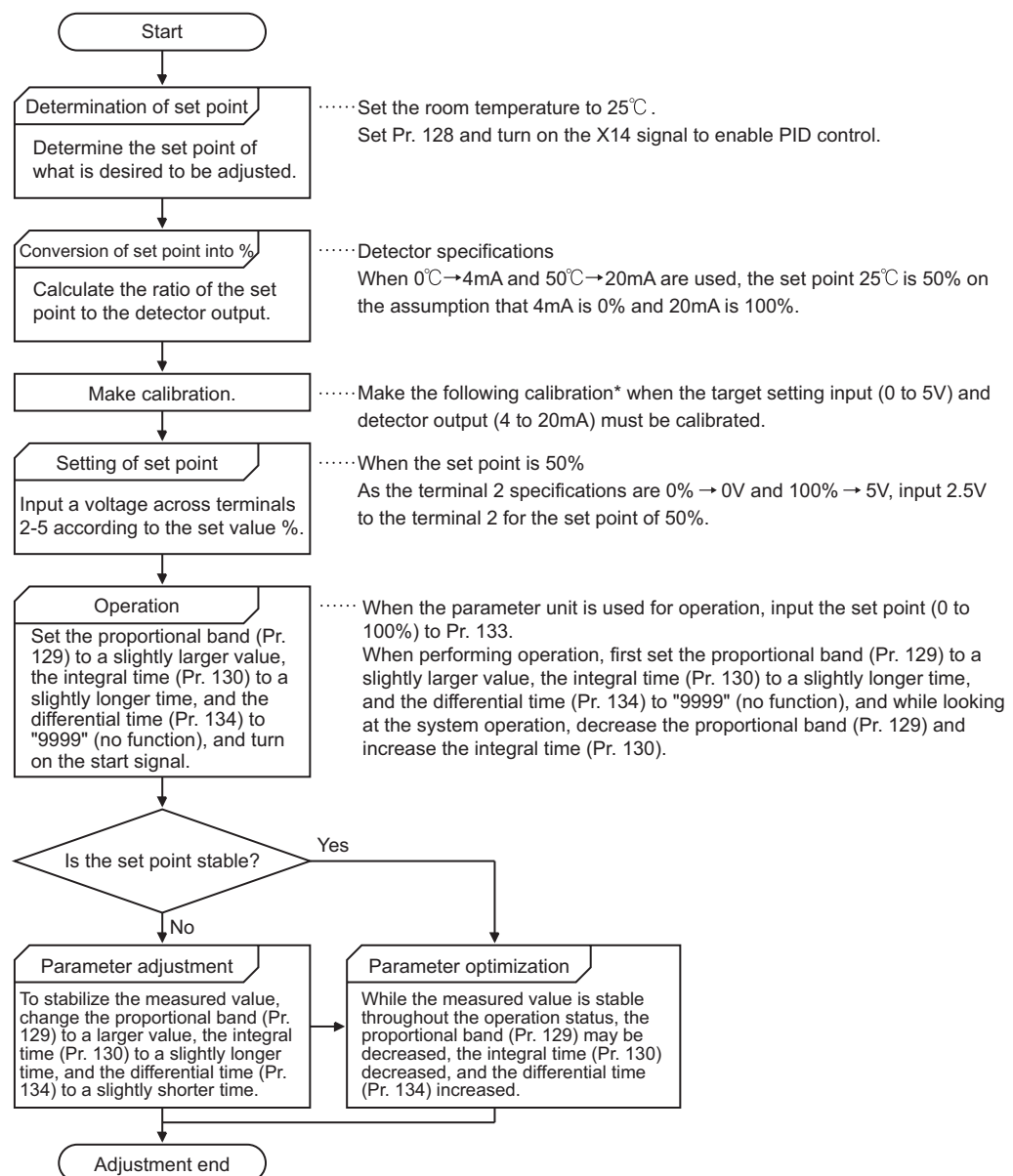
| Setting | Monitor Description   | Minimum Increments | Terminal CA, AM Full Scale | Remarks                                                                                          |
|---------|-----------------------|--------------------|----------------------------|--------------------------------------------------------------------------------------------------|
| 52      | PID set point         | 0.1%               | 100%                       | For deviation input (Pr. 128 = 10, 11), the monitor value is always displayed as 0.              |
| 53      | PID measurement value | 0.1%               | 100%                       |                                                                                                  |
| 54      | PID deviation value   | 0.1%               | —                          | Value cannot be set to Pr. 54 or Pr. 158.<br>The PID deviation value of 0% is displayed as 1000. |

## (8) Adjustment procedure



## (9) Calibration example

(A detector of 4mA at 0°C and 20mA at 50°C is used to adjust the room temperature to 25°C under PID control. The set point is given to across inverter terminals 2-5 (0 to 5V).)



\* When calibration → Using calibration Pr. 902 and Pr. 903 (terminal 2) or Pr. 904 and Pr. 905 (terminal 4), calibrate the detector output and target setting input. Make calibration in the PU mode during an inverter stop.

### <Set point input calibration>

1. Apply the input voltage of 0% set point setting (e.g. 0V) across terminals 2-5.
2. Enter in *C2* (Pr. 902) the frequency which should be output by the inverter at the deviation of 0% (e.g. 0Hz).
3. In *C3* (Pr. 902), set the voltage value at 0%.
4. Apply the voltage of 100% set point (e.g. 5V) to across terminals 2-5.
5. Enter in Pr. 125 the frequency which should be output by the inverter at the deviation of 100% (e.g. 60Hz).
6. In *C4* (Pr. 903), set the voltage value at 100%.

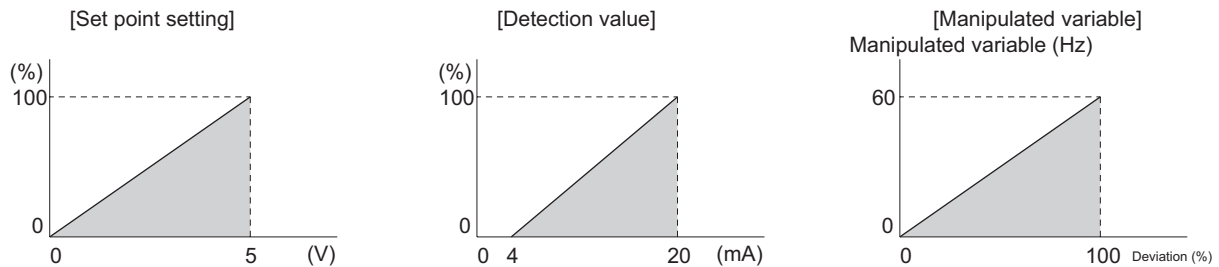
### <Detector output calibration>

1. Apply the output current of 0% detector setting (e.g. 4mA) across terminals 4-5.
2. Make calibration using *C6* (Pr. 904).
3. Apply the output current of 100% detector setting (e.g. 20mA) across terminals 4-5.
4. Make calibration using *C7* (Pr. 905).

#### REMARKS

- The frequency set in *C5* (Pr. 904) and Pr. 126 should be the same as set in *C2* (Pr. 902) and Pr. 125.

The results of the above calibration are as shown below:



#### CAUTION

- If the multi-speed (RH, RM, RL signal) or jog operation (jog signal) is entered with the X14 signal on, PID control is stopped and multi-speed or jog operation is started.
- If the setting is as follows, PID control becomes invalid.  
Pr. 22 = "9999" (analog variable)  
Pr. 79 = "6" (switchover mode)
- When the Pr. 128 setting is "20" or "21", note that the input across inverter terminals 1-5 is added to the set value across terminals 2-5.
- Changing the terminal function using any of Pr. 178 to Pr. 189, Pr. 190 to Pr. 196 may affect the other functions. Please make setting after confirming the function of each terminal.
- The remote operation function is invalid during PID operation.

#### ◆ Parameters referred to ◆

Pr.59 Remote function selection  Refer to page 77  
 Pr.73 iAnalog input selectioni  Refer to page 130  
 Pr.79 Operation mode selection  Refer to page 147  
 Pr. 178 to Pr.189 (Input terminal function selection)  Refer to page 90  
 Pr. 190 to Pr. 196 (output terminal function selection)  Refer to page 96  
 C2 (Pr. 902) to C7 (Pr. 905) Frequency setting voltage (current) bias/gain  Refer to page 134

### 3.19.2 Commercial power supply-inverter switchover function (Pr. 135 to Pr. 139, Pr. 159)

The complicated sequence circuit for commercial power supply-inverter switchover is built in the inverter. Hence, merely inputting the start, stop or automatic switchover selection signal facilitates the interlock operation of the switchover magnetic contactor.

|                |          |
|----------------|----------|
| <b>Pr. 134</b> | page 189 |
| <b>Pr. 140</b> | page 82  |
| <b>Pr. 158</b> | page 109 |
| <b>Pr. 160</b> | page 145 |

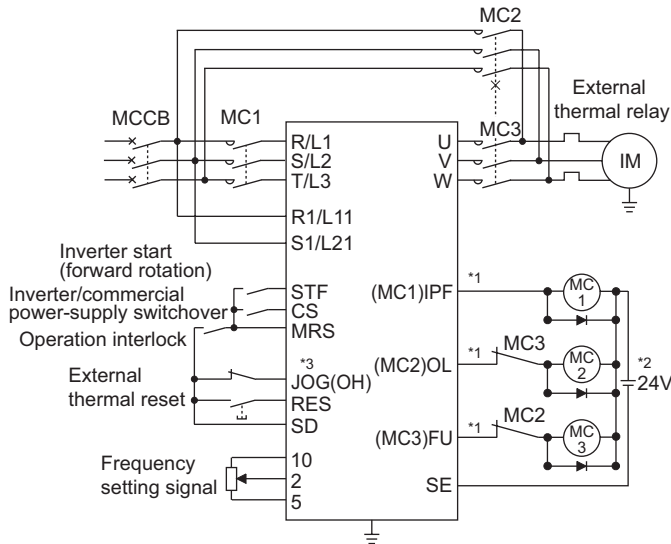
| Parameter Number | Name                                                                                  | Initial Value | Setting Range | Description                                                                                                                                                                                                                                                                                                                                                                                                                                                          |
|------------------|---------------------------------------------------------------------------------------|---------------|---------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 135              | Commercial power-supply switchover sequence output terminal selection                 | 0             | 0             | Without commercial power-supply switchover sequence                                                                                                                                                                                                                                                                                                                                                                                                                  |
|                  |                                                                                       |               | 1             | With commercial power-supply switchover sequence                                                                                                                                                                                                                                                                                                                                                                                                                     |
| 136              | MC switchover interlock time                                                          | 1s            | 0 to 100s     | Set the operation interlock time of MC2 and MC3.                                                                                                                                                                                                                                                                                                                                                                                                                     |
| 137              | Waiting time at a start                                                               | 0.5s          | 0 to 100s     | Set the time slightly longer (0.3 to 0.5s or so) than the time from when the ON signal enters MC3 until it actually turns on.                                                                                                                                                                                                                                                                                                                                        |
| 138              | Commercial power-supply operation switchover selection at an alarm                    | 0             | 0             | Inverter output is stopped (motor coast) at inverter fault.                                                                                                                                                                                                                                                                                                                                                                                                          |
|                  |                                                                                       |               | 1             | Operation is automatically switched to the commercial power-supply operation at inverter fault (Not switched when an external thermal error occurs)                                                                                                                                                                                                                                                                                                                  |
| 139              | Automatic switchover frequency between inverter and commercial power-supply operation | 9999          | 0 to 60Hz     | Set the frequency to switch the inverter operation to the commercial power-supply operation.<br>Inverter operation is performed from a start until Pr. 139 is reached, and when the output frequency is at or above Pr. 139, inverter operation is automatically switched to commercial power supply operation.                                                                                                                                                      |
|                  |                                                                                       |               | 9999          | Without automatic switchover                                                                                                                                                                                                                                                                                                                                                                                                                                         |
| 159              | Automatic switchover ON range between commercial power-supply and inverter operation  | 9999          | 0 to 10Hz     | Valid during automatic switchover operation (Pr. 139 ≠ 9999)<br>When the frequency command decreases below (Pr. 139 to Pr. 159) after operation is switched from inverter operation to commercial power-supply operation, the inverter automatically switches operation to the inverter operation and operates at the frequency of frequency command. When the inverter start command (STF/STR) is turned off, operation is switched to the inverter operation also. |
|                  |                                                                                       |               | 9999          | Valid during automatic switchover operation (Pr. 139 ≠ 9999)<br>When the inverter start command (STF/STR) is turned off after operation is switched from the inverter operation to commercial power-supply inverter operation, operation is switched to the inverter operation and the motor decelerates to stop.                                                                                                                                                    |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145.)

- When the motor is operated at 60Hz (or 50Hz), more efficient operation can be performed by the commercial power supply than by the inverter. When the motor cannot be stopped for a long time for the maintenance/inspection of the inverter, it is recommended to provide the commercial power supply circuit.
- To switch between inverter operation and commercial power supply operation, an interlock must be provided to stop the motor once and then start it by the inverter in order to prevent the inverter from resulting in an overcurrent alarm. Using the commercial power supply switchover sequence function that outputs the timing signal for operation of the magnetic contactor, a complicated commercial power supply switchover interlock can be provided by the inverter.

## (1) Connection diagram

- The following shows the connection diagram of a typical commercial power supply switchover sequence. Sink logic, Pr. 185 = "7", Pr. 192 = "17", Pr. 193 = "18", Pr. 194 = "19"



Commercial power supply switchover sequence connection diagram

\*1 Take caution for the capacity of the sequence output terminal.

The used terminal changes depending on the setting of Pr. 190 to Pr. 196 (output terminal function selection).

| Output Terminal Capacity                                                            | Output Terminal Permissible Load |
|-------------------------------------------------------------------------------------|----------------------------------|
| Inverter open collector output (RUN, SU, IPF, OL, FU)                               | 24VDC 0.1A                       |
| Inverter relay output (A1-C1, B1-C1, A2-B2, B2-C2)<br>Relay output option (FR-A7AR) | 230VAC 0.3A<br>30VDC 0.3A        |

\*2 When connecting a DC power supply, insert a protective diode. When connecting an AC power supply, connect a relay output option (FR-A7AR) and use a contact output.

\*3 The used terminal changes depending on the setting of Pr. 180 to Pr. 189 (input terminal function selection).

### CAUTION

- Use the commercial power supply switchover function in external operation mode. Be sure to connect the other power supply since the function is not performed normally unless the connection terminals R1/L11, S1/L21 are not connected to the other power supply (power supply that does not pass MC1).
- Be sure to provide mechanical interlocks for MC2 and MC3.

- Operations of magnetic contactors (MC1, MC2, MC3)

| Magnetic Contactor | Installation Place                      | Operation (O: Shorted, ×: Open)   |                           |                                                                                     |
|--------------------|-----------------------------------------|-----------------------------------|---------------------------|-------------------------------------------------------------------------------------|
|                    |                                         | Commercial Power Supply Operation | During Inverter Operation | At an Inverter Alarm Occurrence                                                     |
| MC1                | Between power supply and inverter input | O                                 | O                         | ×<br>(Shorted by reset)                                                             |
| MC2                | Between power supply and motor          | O                                 | ×                         | ×<br>(Can be selected using Pr. 138, always open when external thermal relay is on) |
| MC3                | Between inverter output and motor       | ×                                 | O                         | ×                                                                                   |

· The input signals are as indicated below.

| Signal    | Terminal Used                        | Function                                                         | Operation                                     | MC Operation *6 |     |           |
|-----------|--------------------------------------|------------------------------------------------------------------|-----------------------------------------------|-----------------|-----|-----------|
|           |                                      |                                                                  |                                               | MC1 *5          | MC2 | MC3       |
| MRS       | MRS                                  | Operation enable/disable selection *1                            | ON .....Commercial-inverter operation enabled | ○               | —   | —         |
|           |                                      |                                                                  | OFF ...Commercial-inverter operation disabled | ○               | ×   | No change |
| CS        | CS                                   | Inverter/commercial switchover *2                                | ON .....Inverter operation                    | ○               | ×   | ○         |
|           |                                      |                                                                  | OFF ...Commercial power supply operation      | ○               | ○   | ×         |
| STF (STR) | STF(STR)                             | Inverter operation command (Invalid for commercial operation) *3 | ON .....Forward rotation (reverse rotation)   | ○               | ×   | ○         |
|           |                                      |                                                                  | OFF ....Stop ... OFF                          | ○               | ×   | ○         |
| OH        | Set *7 to any of Pr. 180 to Pr. 189. | External thermal relay input                                     | ON .....Motor normal                          | ○               | —   | —         |
|           |                                      |                                                                  | OFF ....Motor abnormal                        | ×               | ×   | ×         |
| RES       | RES                                  | Operating status initialization *4                               | ON .....Initialization                        | No change       | ×   | No change |
|           |                                      |                                                                  | OFF ....Normal operation                      | ○               | —   | —         |

\*1 Unless the MRS signal is turned on, neither commercial power supply operation nor inverter operation can be performed.

\*2 The CS signal functions only when the MRS signal is on.

\*3 STF (STR) functions only when both the MRS signal and CS signal are on.

\*4 The RES signal enables reset input acceptance selection using Pr. 75 Reset selection/disconnected PU detection/PU stop selection.

\*5 MC1 turns off when an inverter alarm occurs.

\*6 MC operation

○ : MC-ON

×

— : Inverter operation.....MC2 is off and MC3 is on

Commercial power supply operation .....MC2 is on and MC3 is off

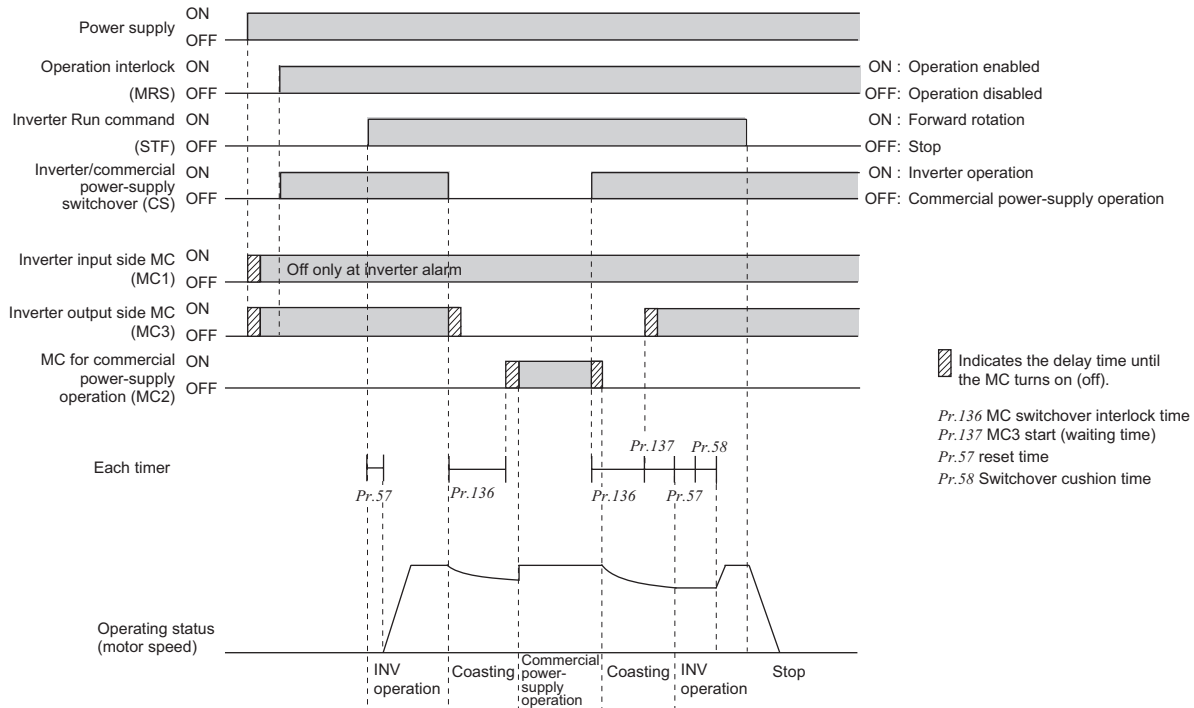
No change : The status before the signal turns on or off is held.

· The output signals are as indicated below.

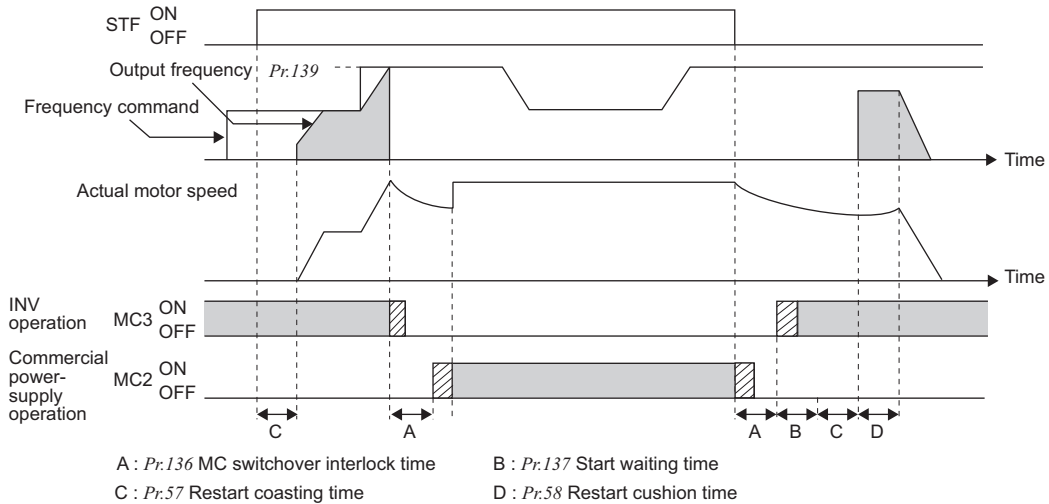
| Signal | Terminal Used<br>(Pr. 190 to Pr. 196 setting) | Description                                                                       |
|--------|-----------------------------------------------|-----------------------------------------------------------------------------------|
| MC1    | 17                                            | Control signal output of inverter input side magnetic contactor MC1               |
| MC2    | 18                                            | Control signal output of inverter output side magnetic contactor MC2              |
| MC3    | 19                                            | Control signal output of commercial power supply operation magnetic contactor MC3 |

## (2) Commercial power supply-inverter switchover operation sequence

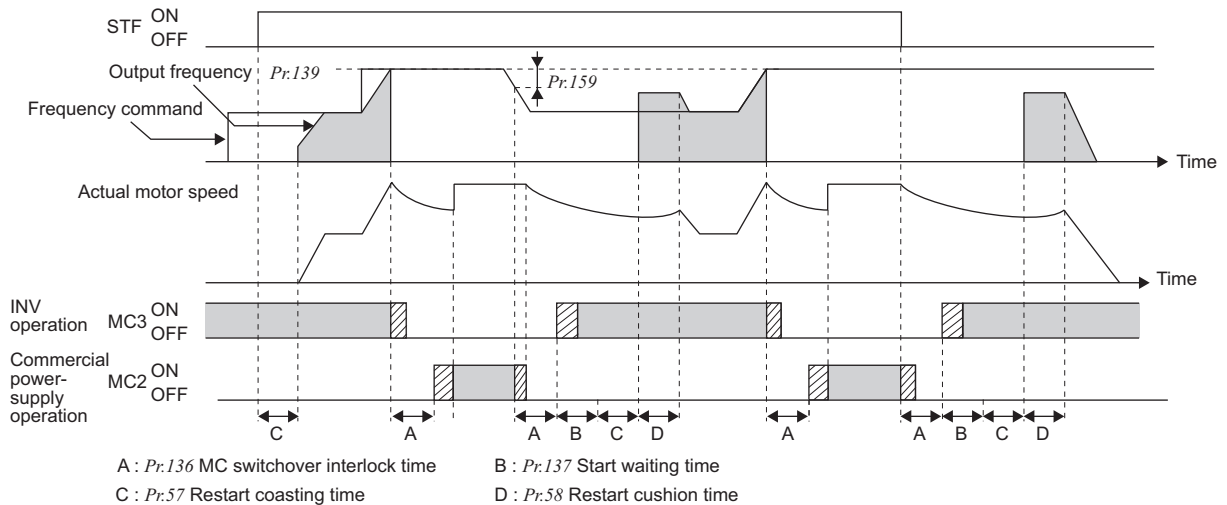
- Operation sequence example when there is no automatic switchover sequence (*Pr. 139* = "9999")



- Operation sequence example when there is automatic switchover sequence (*Pr. 139* ≠ "9999", *Pr. 159* = "9999")

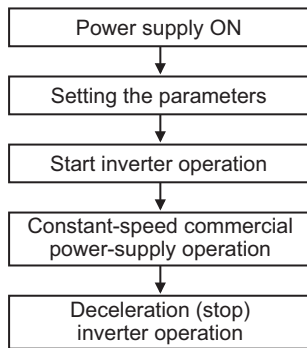


- Operation sequence example when there is automatic switchover sequence (*Pr. 139* ≠ "9999", *Pr. 159* ≠ "9999")



### (3) Operation procedure

- Procedure for operation
- Operation pattern



- Pr: 135 = "1" (open collector output terminal of inverter)
- Pr: 136 = "2.0s"
- Pr: 137 = "1.0s" (Set the time longer than the time from when MC3 actually turns on until the inverter and motor are connected. If the time is short, a restart may not function properly.)
- Pr: 57 = "0.5s"
- Pr: 58 = "0.5s" (Be sure to set this parameter when commercial power supply operation is switched to inverter operation.)

#### 2)Signal ON/OFF after parameter setting

|                                                  | MRS       | CS        | STF       | MC1                 | MC2       | MC3                 | Remarks                                                                               |
|--------------------------------------------------|-----------|-----------|-----------|---------------------|-----------|---------------------|---------------------------------------------------------------------------------------|
| Power supply ON                                  | OFF (OFF) | OFF (OFF) | OFF (OFF) | OFF → ON (OFF → ON) | OFF (OFF) | OFF → ON (OFF → ON) | External operation mode (PU operation mode)                                           |
| At start (inverter)                              | OFF → ON  | OFF → ON  | OFF → ON  | ON                  | OFF       | ON                  |                                                                                       |
| At constant speed (commercial power supply)      | ON        | ON → OFF  | ON        | ON                  | OFF → ON  | ON → OFF            | MC2 turns on after MC3 turns off (coasting status during this period) Waiting time 2s |
| Switched to inverter for deceleration (inverter) | ON        | OFF → ON  | ON        | ON                  | ON → OFF  | OFF → ON            | MC3 turns on after MC2 turns off (coasting status during this period) Waiting time 4s |
| Stop                                             | ON        | ON        | ON → OFF  | ON                  | OFF       | ON                  |                                                                                       |

#### CAUTION

- Connect the control power supply (R1/L11, S1/L21) in front of input side MC1. If the control power supply is connected behind input side MC1, the commercial power supply-inverter switchover sequence function is not executed.
- The commercial power supply-inverter switchover sequence function is valid only when Pr: 135 = "1" in the external operation or combined operation mode (PU speed command, external operation command Pr: 79 = "3"). When Pr: 135 = "1" in the operation mode other than the above, MC1 and MC3 turn on.
- When the MRS and CS signals are on and the STF (STR) signal is off, MC3 is on, but when the motor was coasted to a stop from commercial power supply operation last time, a start is made after the time set to Pr: 137 has elapsed.
- Inverter operation can be performed when the MRS, STF (STR) and CS signals turn on. In any other case (MRS signal - ON), commercial power supply operation is performed.
- When the CS signal is turned off, the motor switches to commercial power supply operation. However, when the STF (STR) signal is turned off, the motor is decelerated to a stop in the inverter operation mode.
- When both MC2 and MC3 are off and either MC2 or MC3 is then turned on, there is a waiting time set in Pr: 136.
- If commercial power supply-inverter switchover sequence is made valid (Pr: 135 = "1"), the Pr: 136 and Pr: 137 settings are ignored in the PU operation mode. The input terminals (STF, CS, MRS, OH) of the inverter return to their normal functions.
- When the commercial power supply-inverter switchover sequence function (Pr: 135 = "1") and PU operation interlock function (Pr: 79 = "7") are used simultaneously, the MRS signal is shared by the PU operation external interlock signal unless the X12 signal is assigned. (When the MRS and CS signals turn on, inverter operation is enabled)
- Changing the terminal function using any of Pr: 178 to Pr: 189, 190 to Pr: 196 may affect the other functions. Please make setting after confirming the function of each terminal.

#### ◆ Parameters referred to ◆

- Pr: 11 DC injection brake operation time Refer to page 86
- Pr: 57 Restart coasting time Refer to page 114
- Pr: 58 Restart cushion time Refer to page 114
- Pr: 79 Operation mode selection Refer to page 147
- Pr: 178 to Pr: 189 (Input terminal function selection) Refer to page 90
- Pr: 190 to Pr: 196 (Output terminal function selection) Refer to page 96

### 3.19.3 Advanced PID function (pump function) (Pr. 575 to Pr. 591)

Pr.573  
page 139

PID control function can adjust the volume of water, etc. by controlling a pump. Multiple motors (4 motors maximum) can be controlled by switching between the inverter-driven operation and commercial power-driven operation. Use *Pr. 579 Motor connection function selection* to select switchover operation of the motor. Up to three auxiliary motors can be connected.

Pr.611  
page 114

| Parameter Number | Name                                                 | Initial Value | Setting Range | Description                                                                                                                                                              |
|------------------|------------------------------------------------------|---------------|---------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 575              | Output interruption detection time                   | 1s            | 0 to 3600s    | If the output frequency after PID operation remains lower than the <i>Pr. 576</i> setting for longer than the time set in <i>Pr. 575</i> , the inverter stops operation. |
|                  |                                                      |               | 9999          | Without output interruption function                                                                                                                                     |
| 576              | Output interruption detection level                  | 0Hz           | 0 to 400Hz    | Set the frequency at which the output interruption processing is performed.                                                                                              |
| 577              | Output interruption release level                    | 1000%         | 900 to 1100%  | Level at PID output interruption function is canceled<br>Set ( <i>Pr. 577</i> – 1000%)                                                                                   |
| 578              | Auxiliary motor operation selection                  | 0             | 0             | No auxiliary motor operation                                                                                                                                             |
|                  |                                                      |               | 1 to 3        | Set the number of auxiliary motors to be run                                                                                                                             |
| 579              | Motor connection function selection                  | 0             | 0             | Basic system                                                                                                                                                             |
|                  |                                                      |               | 1             | Alternative system                                                                                                                                                       |
|                  |                                                      |               | 2             | Direct system                                                                                                                                                            |
|                  |                                                      |               | 3             | Alternative-direct system                                                                                                                                                |
| 580              | MC switching interlock time                          | 1s            | 0 to 100s     | You can set the time until MC switchover interlock time when <i>Pr. 579</i> = "2, 3" is set.                                                                             |
| 581              | Start waiting time                                   | 1s            | 0 to 100s     | You can set the time from when the MC is switched until it starts when <i>Pr. 579</i> = "2, 3". Set this time a little longer than the MC switching time.                |
| 582              | Auxiliary motor connection-time deceleration time    | 1s            | 0 to 3600s    | You can set the deceleration time for decreasing the output frequency of the inverter if a motor connection occurs under advanced PID control.                           |
|                  |                                                      |               | 9999          | The output frequency is not forcibly changed.                                                                                                                            |
| 583              | Auxiliary motor disconnection-time acceleration time | 1s            | 0 to 3600s    | You can set the acceleration time for increasing the output frequency of the inverter if a motor disconnection occurs under advanced PID control.                        |
|                  |                                                      |               | 9999          | The output frequency is not forcibly changed.                                                                                                                            |
| 584              | Auxiliary motor 1 starting frequency                 | 50Hz          | 0 to 400Hz    | Set the frequency to connect an auxiliary motor.                                                                                                                         |
| 585              | Auxiliary motor 2 starting frequency                 | 50Hz          | 0 to 400Hz    |                                                                                                                                                                          |
| 586              | Auxiliary motor 3 starting frequency                 | 50Hz          | 0 to 400Hz    |                                                                                                                                                                          |
| 587              | Auxiliary motor 1 stopping frequency                 | 0Hz           | 0 to 400Hz    | Set the frequency to open an auxiliary motor.                                                                                                                            |
| 588              | Auxiliary motor 2 stopping frequency                 | 0Hz           | 0 to 400Hz    |                                                                                                                                                                          |
| 589              | Auxiliary motor 3 stopping frequency                 | 0Hz           | 0 to 400Hz    |                                                                                                                                                                          |
| 590              | Auxiliary motor start detection time                 | 5s            | 0 to 3600s    | You can set the delay time until the auxiliary motor is started.                                                                                                         |
| 591              | Auxiliary motor stop detection time                  | 5s            | 0 to 3600s    | You can set the delay time until the auxiliary motor is stopped.                                                                                                         |

The above parameters can be set when *Pr. 160 User group read selection* = "0". (Refer to page 145)

· Set the number of commercial power supply operation motors in *Pr. 578 Auxiliary motor operation selection* and motor switching method in *Pr. 579 Motor connection function selection*.

Figure 10 illustrates the flow rate  $Q$  and the operation of four pumps (M1, M2, M3, M4) over time for different values of  $Pr. 579$  (0, 1, 2, 3). The top graph shows the flow rate  $Q$  (Y-axis, ranging from  $Q_1$  to  $Q_{max}$ ) versus Time (X-axis). The flow rate curve shows peaks and troughs, with vertical dashed lines indicating specific time points.

The bottom part of the figure shows four scenarios (1) to (4) for  $Pr. 579 = 0, 1, 2, 3$  respectively. Each scenario displays a table of motor operation (M1, M2, M3, M4) over time, with symbols indicating the drive type: filled circle for Inverter operation drive, open circle for Commercial power supply operation drive, and dash for Stop.

Legend:

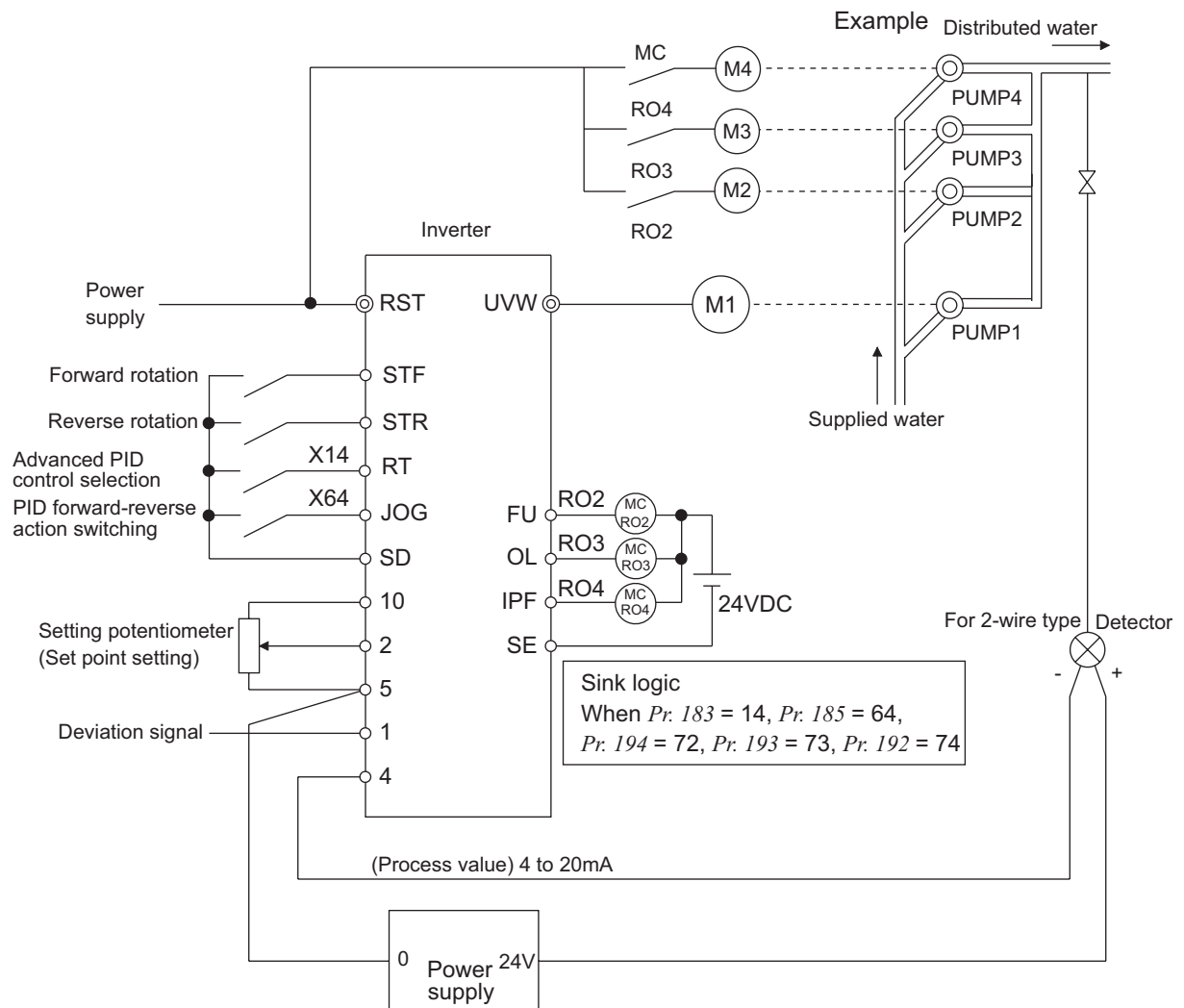
- Inverter operation drive
- Commercial power supply operation drive
- Stop

\*2 The motor starts in order from the longest time (has not inverter-driven for the longest time) after the last inverter driving completion. The motor 1 (M1) starts first when power is turned on for the first time or after reset. (Pr. 579 = "3")

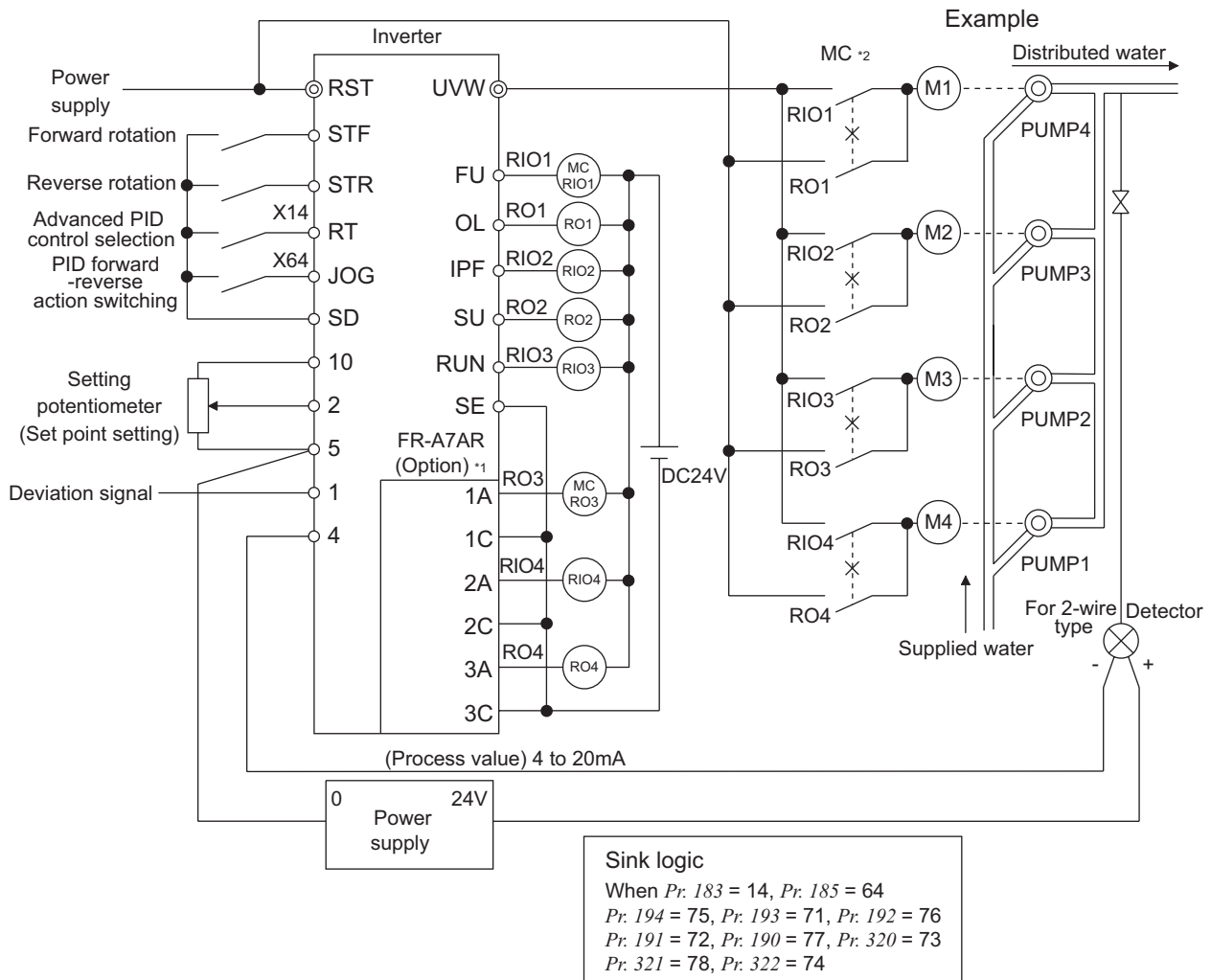
- The starting order of motors to be driven returns to the initial status at an inverter reset. (*Pr. 579* = "1, 2, 3")
- For *Pr. 578* and *Pr. 579*, parameter write is disabled during operation. In addition, when the *Pr. 578* or *Pr. 579* setting has been changed during stop, the starting order of motors also returns to the initial status.

## (2) System configuration

- Basic system (*Pr. 579* = "0")



- Alternative system (Pr. 579 = "1"), direct system (Pr. 579 = "2"), alternative-direct system (Pr. 579 = "3")



- \*1 When driving three or more motors, use the plug-in option (FR-A7AR).
- \*2 Always provide mechanical interlocks for the MC.

## (3) I/O signals

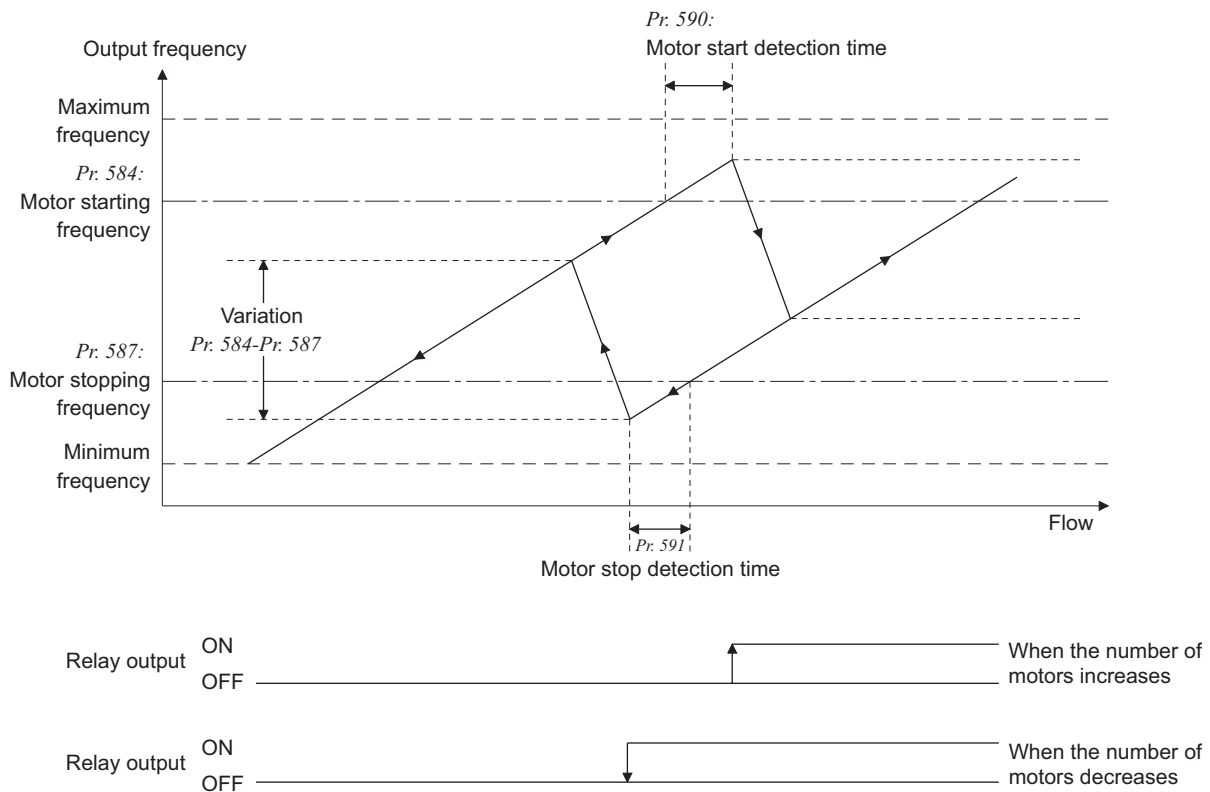
- Turn the X14 signal on when performing advanced PID control. Set "14" in Pr. 186 to Pr. 189 (input terminal function selection) to assign a function to the X14 signal.
- PID control depends on the Pr. 127 to Pr. 134 settings. (Refer to page 189)
- Use Pr.190 to Pr.196 (output terminal function selection) or relay output option (FR-A7AR) to assign functions of motor control signal to Pr.320 to Pr.322 (RA1, RA2, RA3 output selection). (Only positive logic is available for output terminals).

| Signal | Output Terminal Function Selection Setting |                | Function                                        |
|--------|--------------------------------------------|----------------|-------------------------------------------------|
|        | Positive logic                             | Negative logic |                                                 |
| SLEEP  | 70                                         | 170 *1         | During PID output interruption                  |
| RO1    | 71                                         | — *2           | Commercial-power supply side motor 1 connection |
| RO2    | 72                                         | — *2           | Commercial-power supply side motor 2 connection |
| RO3    | 73                                         | — *2           | Commercial-power supply side motor 3 connection |
| RO4    | 74                                         | — *2           | Commercial-power supply side motor 4 connection |
| RIO1   | 75                                         | — *2           | Inverter side motor 1 connection                |
| RIO2   | 76                                         | — *2           | Inverter side motor 2 connection                |
| RIO3   | 77                                         | — *2           | Inverter side motor 3 connection                |
| RIO4   | 78                                         | — *2           | Inverter side motor 4 connection                |
| SE     | —                                          | — *2           | Output terminal common                          |

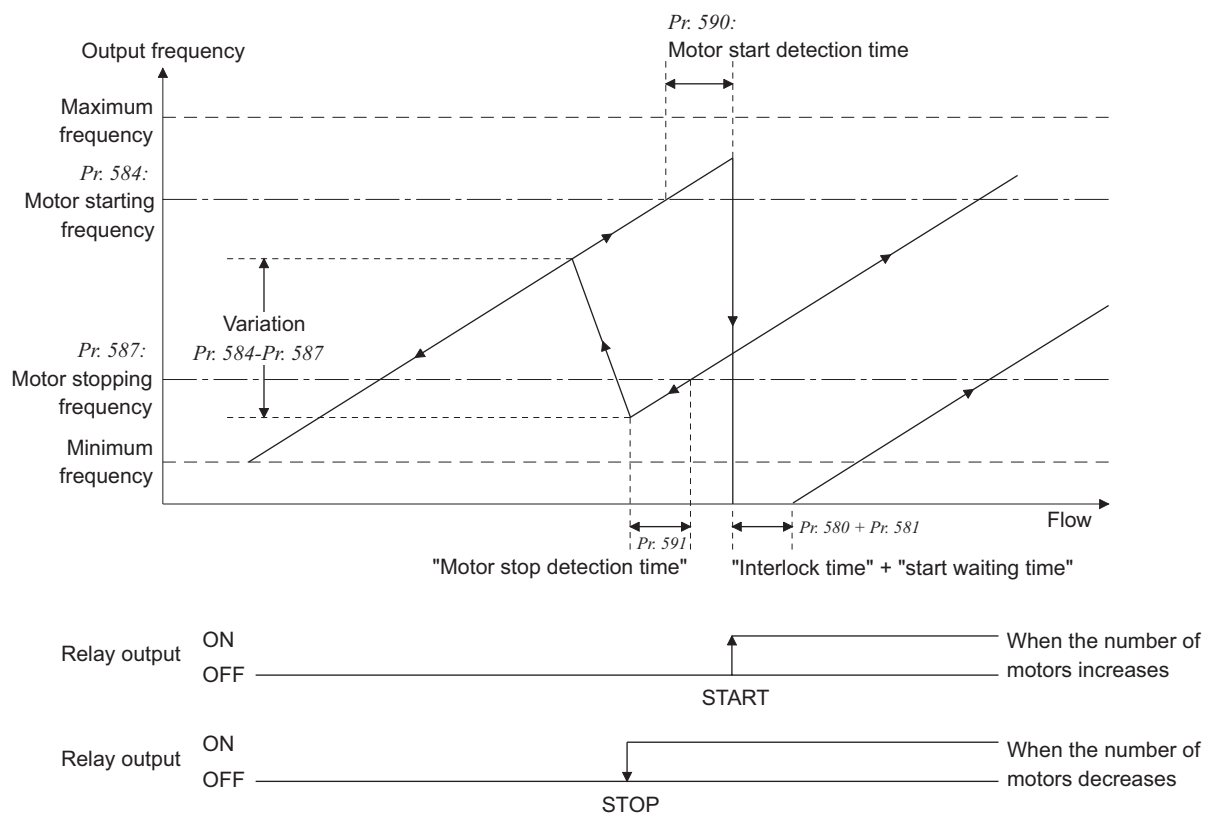
- \*1 This value can not be set in Pr. 320 to Pr. 322 (RA1, RA2, RA3 output selection), parameters for relay output option (FR-A7AR).
- \*2 Negative logic can not be set.

#### (4) Motor switchover timing

- Switchover timing at a start (stop) of an auxiliary motor 1 in the basic system ( $Pr. 579 = "0"$ ) and alternative system ( $Pr. 579 = "1"$ ).



- Switchover timing at a start (stop) of an auxiliary motor 1 in the direct system ( $Pr. 579 = "2"$ ) and alternative-direct system ( $Pr. 579 = "3"$ ).

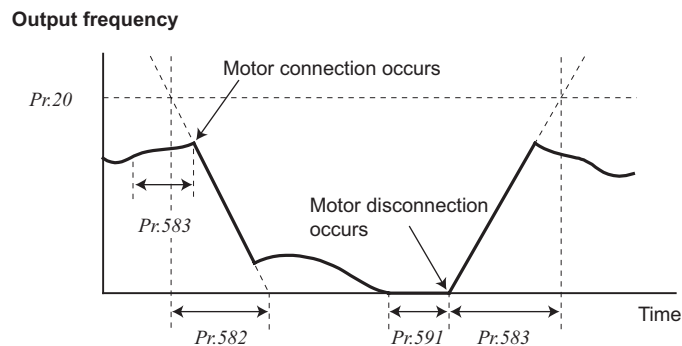


### (5) Waiting time setting at MC switchover (Pr. 580, Pr. 581)

- Set a switching time of MC (e.g. time until RIO1 turns on after RO1 turns off) in *Pr. 580 MC switching interlock time* in the direct system (*Pr. 579 = "2"*). You can set the time from MC switch-over to a start (time from when RIO1 turns off and RIO2 turns on until inverter output starts). Set this time a little longer than the MC switching time.
- You can set the time from MC switch-over to a start (time from when RIO1 turns off and RIO2 turns on until inverter output starts) in *Pr. 581 Start waiting time* in the direct system (*Pr. 579 = "2"*). Set this time a little longer than the MC switching time.

### (6) Acceleration/deceleration time when an auxiliary motor is connected and disconnected (Pr. 582, Pr.583)

- You can set the deceleration time in *Pr. 582 Auxiliary motor connection-time deceleration time* for decreasing the output frequency of the inverter if an auxiliary motor connection occurs. Set the deceleration time in *Pr. 582* from *Pr. 20 Acceleration/deceleration reference frequency* to stop. The output frequency is not forcibly changed when "9999" is set.
- You can set the acceleration time in *Pr. 583 Auxiliary motor disconnection-time acceleration time* for accelerating the output frequency of the inverter if an auxiliary motor disconnection occurs. Set the deceleration time in *Pr. 583* from *Pr. 20 Acceleration/deceleration reference frequency* to stop. The output frequency is not forcibly changed when "9999" is set.



#### REMARKS

*Pr. 582* and *Pr. 583* are not affected by the *Pr. 21 Acceleration/deceleration time increments* setting. (Setting range and setting increments do not change.)

### (7) Start of auxiliary motor (Pr. 584 to Pr. 586, Pr. 590)

- You can set the output frequency of the inverter-operated motor in *Pr. 584 to Pr. 586* at which the commercial-power supply operation motors start. When the output frequency equal to or higher than the setting continues for longer than the time set in *Pr. 590 Auxiliary motor start detection time*, the commercial-power supply motors start. In this case, the starting sequence depends on the pattern in *Pr. 579 Motor connection function selection*.
- *Pr. 584 Auxiliary motor 1 starting frequency* value means the frequency at which the first commercial-power supply motor starts when the number of commercial-power supply motors. When starting the second commercial-power supply motor when one commercial-power supply motor is running, set *Pr. 585 Auxiliary motor 2 starting frequency*.

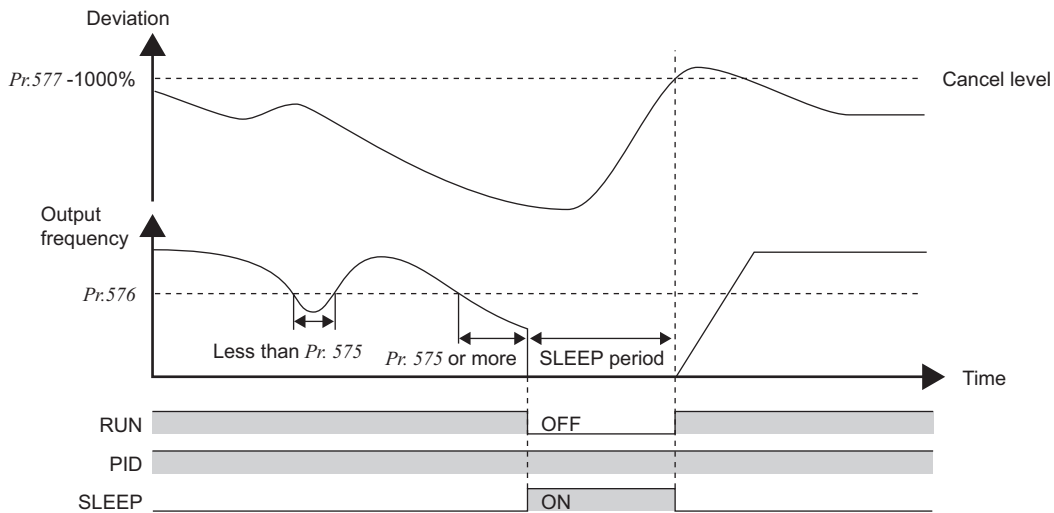
### (8) Stop of auxiliary motor (Pr. 587 to Pr. 589, Pr. 591)

- You can set the output frequency of the inverter-operated motor in *Pr. 587 to Pr. 589* at which the commercial-power supply operation motors stop. When the output frequency equal to or lower than the setting continues for longer than the time set in *Pr. 591 Auxiliary motor stop detection time*, the commercial-power supply motors stop. In this case, the stopping sequence depends on the pattern in *Pr. 579 Motor connection function selection*.
- Use *Pr. 587 Auxiliary motor 1 stopping frequency* to set the frequency at which one commercial-power supply motor running stops. When stopping one commercial-power supply motor when two commercial-power supply motors are running, set *Pr. 588 Auxiliary motor 2 stopping frequency*.

## (9) PID output interruption function (SLEEP function) (SLEEP signal, Pr. 575 to Pr. 577)

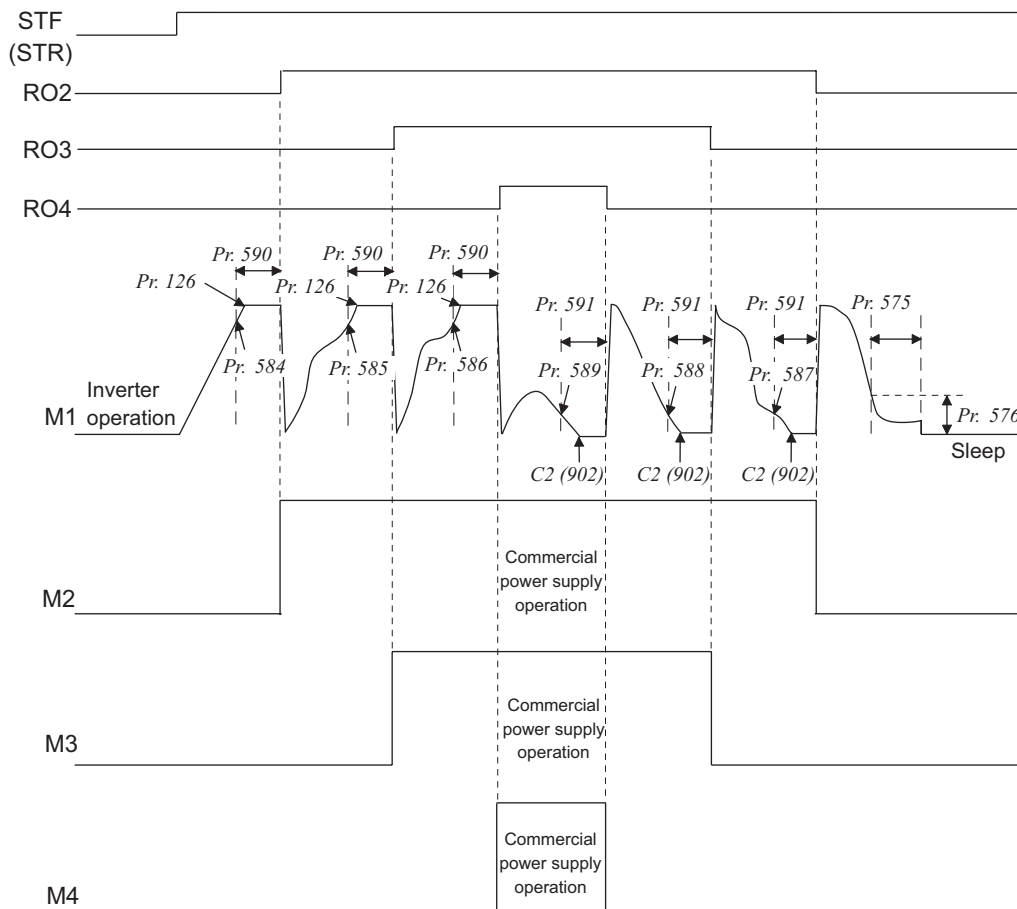
- If the output frequency after PID operation remains lower than the Pr. 576 Output interruption detection level for longer than the time set in Pr. 575 Output interruption detection time, the inverter stops operation. The energy consumption in the inefficient low speed region can be reduced.
- When the deviation (= set point – measured value) reaches PID output interruption release level (Pr. 577 setting – 1000%) when the PID output interruption function is activated, PID output interruption function is released and PID control operation is automatically resumed.
- PID output suspension signal (SLEEP) is output when the PID output interruption function is activated. At this time, the inverter running signal (RUN) turns off and the PID control activated signal (PID) turns on.

Reverse action (Pr. 128 = 10)

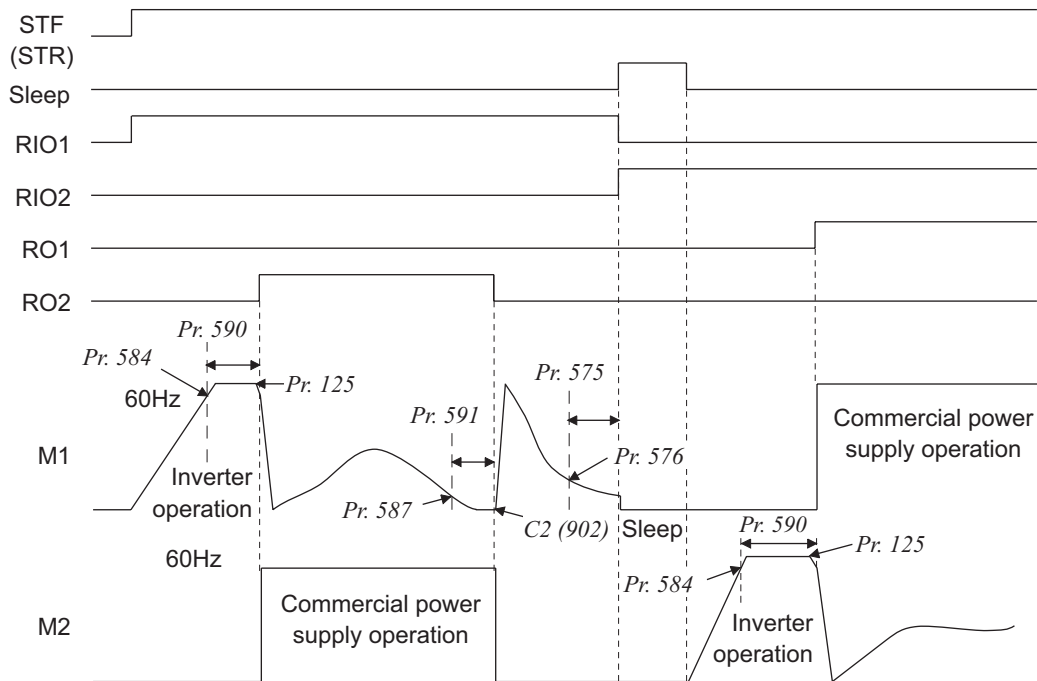


## (10) Timing diagram

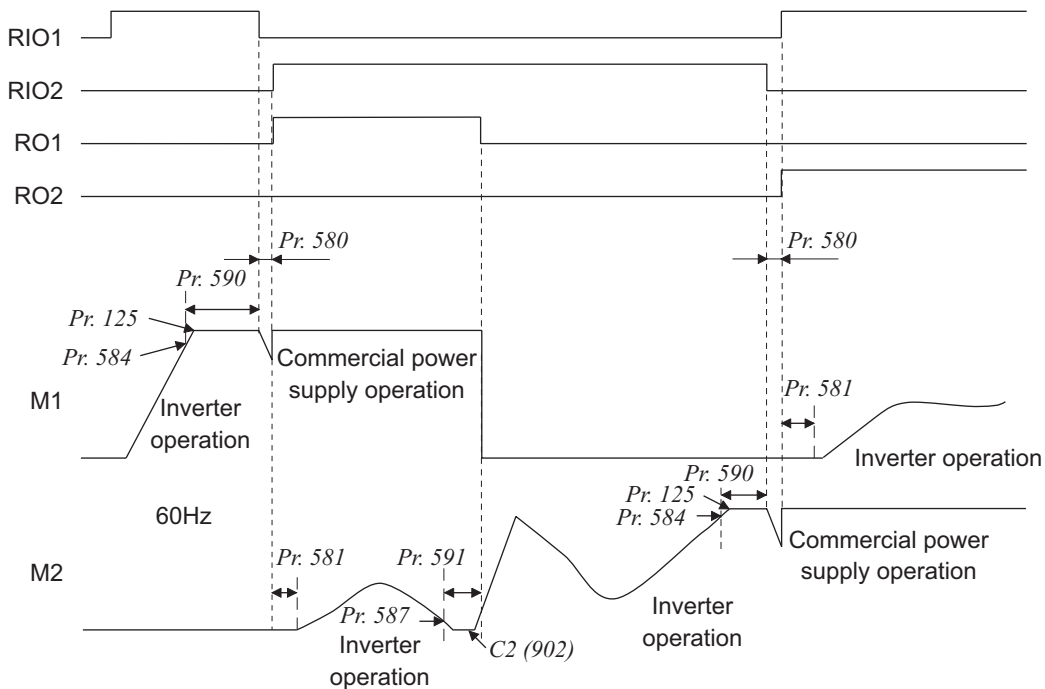
- When using four motors in the basic system (Pr. 579 = "0")



- When using two motors in the alternative system ( $Pr. 597 = "1"$ )



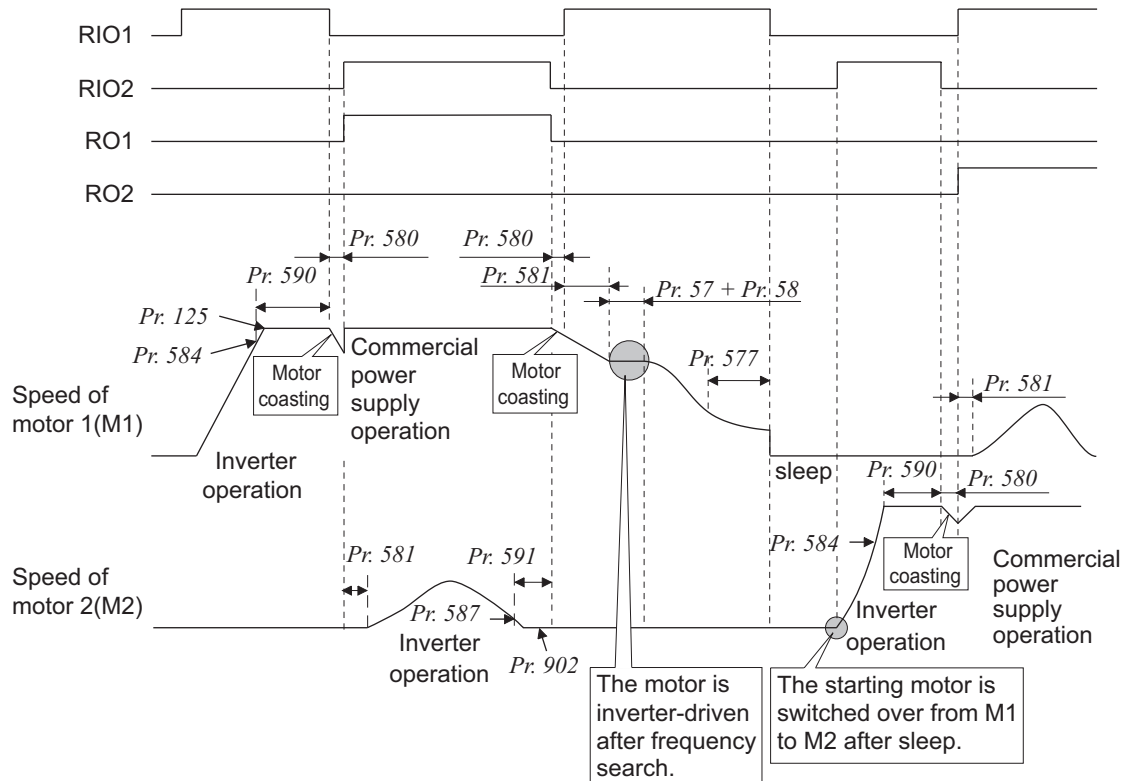
- When using two motors in the direct system ( $Pr. 597 = "2"$ )



## CAUTION

- When a start signal is turned off while running, MC (RO1 to RO4) turns off and the inverter decelerates.
- When an error occurs while running, MC (RO1 to RO4) turns off and the inverter output is shut off.

- When using two motors in the alternative-direct system ( $Pr. 579 = "3"$ )



### CAUTION

- If the start signal is turned off during operation, the inverter-driven motor is decelerated to stop, and the motors under commercial power supply operation are switched over to inverter-driven operation one at a time and decelerated to a stop after frequency search in order from the longest operation time.
- When an error occurs while running, MC (RO1 to RO4) turns off and the inverter output is shut off.
- If the MRS signal is turned on during operation, the motor driven by the inverter stops output. Although only the motor whose commercial power supply operation is the longest time is switched to the inverter operation after elapse of time set in  $Pr. 591$  Auxiliary motor stop detection time, the inverter remains in the output shut off status. Frequency search is made after the MRS signal turns off and inverter operation is started.
- If the starting signal is turned on during deceleration to a stop independently of the  $Pr. 579$  setting, operation by the advanced PID control is performed again at the point when the signal is turned on.

### ◆ Parameters referred to ◆

$Pr. 20$  Acceleration/deceleration reference frequency,  $Pr. 21$  Acceleration/deceleration time increments Refer to page 79  
 $Pr. 127$  to  $Pr. 134$  (PID control) Refer to page 189  
 $Pr. 178$  to  $Pr. 189$  (input terminal function selection) Refer to page 90  
 $Pr. 190$  to  $Pr. 196$  (output terminal function selection) Refer to page 96

### 3.19.4 Regeneration avoidance function (Pr.882 to Pr.886)

This function detects a regeneration status and increases the frequency to avoid the regeneration status.

- Possible to avoid regeneration by automatically increasing the frequency and continue operation if the fan happens to rotate faster than the set speed due to the effect of another fan in the same duct.

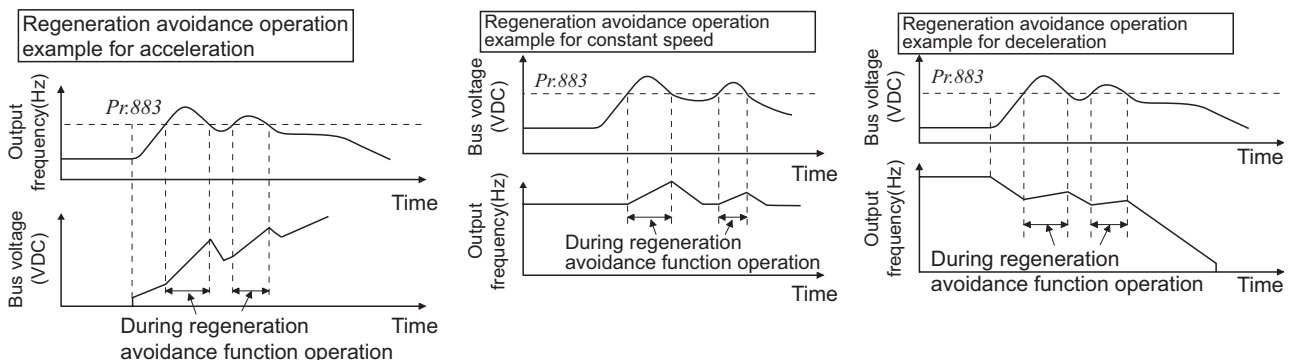
Pr.872  
page 122  
Pr.888  
page 219

| Parameter Number | Name                                                         | Initial Value     | Setting Range | Description                                                                                                                                                                                                                                                                                                                                                             |
|------------------|--------------------------------------------------------------|-------------------|---------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 882              | Regeneration avoidance operation selection                   | 0                 | 0             | Regeneration avoidance function invalid                                                                                                                                                                                                                                                                                                                                 |
|                  |                                                              |                   | 1             | Regeneration avoidance function valid                                                                                                                                                                                                                                                                                                                                   |
| 883              | Regeneration avoidance operation level                       | DC380V/<br>760V * | 300 to 800V   | Set the bus voltage level at which regeneration avoidance operates. When the bus voltage level is set to low, overvoltage error will be less apt to occur. However, the actual deceleration time increases. The set value must be higher than the power supply voltage $\times \sqrt{2}$ .<br>* The initial value differs according to the voltage level. (200V / 400V) |
| 884              | Regeneration avoidance at deceleration detection sensitivity | 0                 | 0             | Regeneration avoidance by bus voltage change ratio is invalid                                                                                                                                                                                                                                                                                                           |
|                  |                                                              |                   | 1 to 5        | Set sensitivity to detect the bus voltage change<br>Setting 1 $\rightarrow$ 5<br>Detection sensitivity low $\rightarrow$ high                                                                                                                                                                                                                                           |
| 885              | Regeneration avoidance compensation frequency limit value    | 6Hz               | 0 to 10Hz     | Set the limit value of frequency which rises at activation of regeneration avoidance function.                                                                                                                                                                                                                                                                          |
|                  |                                                              |                   | 9999          | Frequency limit invalid                                                                                                                                                                                                                                                                                                                                                 |
| 886              | Regeneration avoidance voltage gain                          | 100%              | 0 to 200%     | Adjust responsiveness at activation of regeneration avoidance. A larger setting will improve responsiveness to the bus voltage change. However, the output frequency could become unstable.                                                                                                                                                                             |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

#### (1) What is regeneration avoidance function? (Pr.882, Pr.883)

- When the regeneration status is serious, the DC bus voltage rises and an overvoltage alarm (E. OV□) may occur. When this bus voltage rise is detected and the bus voltage level reaches or exceeds Pr. 883, increasing the frequency avoids the regeneration status.
- The regeneration avoidance function is performed during any of acceleration, constant speed and deceleration.



- Setting Pr. 882 to "1" validates the regeneration avoidance function.

#### REMARKS

- The inclination of the frequency increased or decreased by the regeneration avoidance function changes depending on the regeneration status.
- The DC bus voltage of the inverter is normally about  $\sqrt{2}$  times greater than the input voltage.  
When the input voltage is 220VAC, the bus voltage is about 311VDC.  
When the input voltage is 440VAC, the bus voltage is about 622VDC.  
However, it varies with the input power supply waveform.
- The Pr. 883 setting should be kept higher than the DC bus voltage level. Otherwise, the regeneration avoidance function is always on.
- While overvoltage stall (OL) stops the output frequency during deceleration, the regeneration avoidance function is always on and increases the frequency according to the regeneration amount.

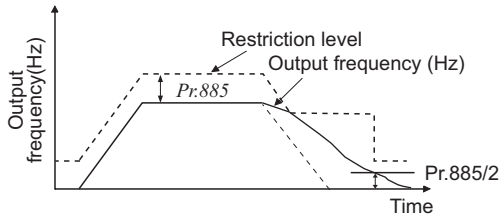
## (2) To detect the regeneration status during deceleration faster (Pr.884)

- As the regeneration avoidance function cannot respond to an abrupt voltage change by detection of the bus voltage level, the ratio of bus voltage change is detected to stop deceleration if the bus voltage is less than *Pr. 883 Regeneration avoidance operation level*.  
Set that detectable bus voltage change ratio to *Pr. 884* as detection sensitivity.  
Increasing the setting raises the detection sensitivity

### CAUTION

Too small setting (low detection sensitivity) will disable detection, and too large setting will turn on the regeneration avoidance function if the bus voltage is varied by an input power change, etc.

## (3) Limit the output frequency (Pr.885)



You can limit the output frequency compensated for (increased) by the regeneration avoidance function.

- The frequency is limited to the output frequency (frequency prior to regeneration avoidance operation) + *Pr. 885 Regeneration avoidance compensation frequency limit value* during acceleration or constant speed. If the regeneration avoidance frequency exceeds the limit value during deceleration, the limit value is held until the output frequency falls to 1/2 of *Pr. 885*.
- When the regeneration avoidance frequency has reached *Pr. 1 Maximum frequency*, it is limited to the maximum frequency.
- Pr. 885* is set to "9999", the frequency setting is invalid.

## (4) Regeneration avoidance function adjustment (Pr.886)

- If the frequency becomes unstable during regeneration avoidance operation, decrease the setting of *Pr. 886 Regeneration avoidance voltage gain*. Reversely, if sudden regeneration causes an overvoltage alarm, increase the setting.
- When the load inertia of the motor is large, decrease the *Pr. 886* setting.

### CAUTION

- When regeneration avoidance operation is performed,  $\overline{\text{OL}}$  (overvoltage stall) is displayed and the OL signal is output.
- When regeneration avoidance operation is performed, stall prevention is also activated at the same time.
- The regeneration avoidance function cannot shorten the actual deceleration time taken to stop the motor. The actual deceleration time depends on the regeneration capability. When shortening the deceleration time, consider using the regeneration unit (BU, FR-BU, MT-BU5, FR-CV, FR-HC, MT-HC).
- When using the regeneration unit (BU, FR-BU, MT-BU5, FR-CV, FR-HC, MT-HC), set *Pr. 882* to "0 (initial value)" (regeneration avoidance function invalid).
- When regeneration avoidance operation is performed, the OL signal output item of *Pr. 156* also becomes the target of  $\overline{\text{OL}}$  (overvoltage stall). *Pr. 157 OL signal output timer* also becomes the target of  $\overline{\text{OL}}$  (overvoltage stall).

### ◆ Parameters referred to ◆

- Pr.1 Maximum frequency* Refer to page 67  
*Pr. 8 Deceleration time* Refer to page 79  
*Pr.22 Stall prevention operation level* Refer to page 61

## 3.20 Useful functions

| Purpose                                     | Parameter that must be set           |                  | Refer to page |
|---------------------------------------------|--------------------------------------|------------------|---------------|
| Increase cooling fan life                   | Cooling fan operation selection      | Pr. 244          | 213           |
| To determine the maintenance time of parts. | Inverter part life display           | Pr.255 to Pr.259 | 214           |
|                                             | Maintenance output function          | Pr.503, Pr.504   | 216           |
|                                             | Current average value monitor signal | Pr.555 to Pr.557 | 217           |
| Freely available parameter                  | Free parameter                       | Pr.888, Pr.889   | 219           |

### 3.20.1 Cooling fan operation selection (Pr.244)

You can control the operation of the cooling fan (FR-F720-00105 or more, FR-F740-00083 or more) built in the inverter.

| Parameter Number | Name                            | Initial Value | Setting Range | Description                                                                                                                                                                                       |
|------------------|---------------------------------|---------------|---------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 244              | Cooling fan operation selection | 1             | 0             | Operates at power on<br>Cooling fan on/off control invalid (The cooling fan is always on at power on)                                                                                             |
|                  |                                 |               | 1             | Cooling fan on/off control valid<br>The fan is always on while the inverter is running. During a stop, the inverter status is monitored and the fan switches on-off according to the temperature. |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

- In either of the following cases, fan operation is regarded as faulty, [FN] is shown on the operation panel, and the fan fault (FAN) and minor fault (LF) signals are output.
  - Pr. 244 = "0"  
When the fan comes to a stop with power on.
  - Pr. 244 = "1"  
When the fan stops during the fan ON command while the inverter is running.
- For the terminal used for FAN signal output, set "25" (positive logic) or "125" (negative logic) to any of Pr. 190 to Pr. 196 (output terminal function selection), and for the LF signal, set "98" (positive logic) or "198" (negative logic).

#### CAUTION

- When terminal assignment is changed using Pr. 190 to Pr. 196 (Output terminal function selection), the other functions may be affected. Please make setting after confirming the function of each terminal.

#### ◆ Parameters referred to ◆

Pr. 190 to Pr. 196 (Output terminal function selection)  Refer to page 96

Pr.243  
page 132

Pr.245  
page 60



### 3.20.2 Display of the life of the inverter parts (Pr. 255 to Pr. 259)

Pr.253  
page 132

Pr.260  
page 129

Degrees of deterioration of main circuit capacitor, control circuit capacitor, cooling fan and inrush current limit circuit can be diagnosed by monitor.

When any part has approached the end of its life, an alarm can be output by self diagnosis to prevent a fault. (Use the life check of this function as a guideline since the life except the main circuit capacitor is calculated theoretically.)

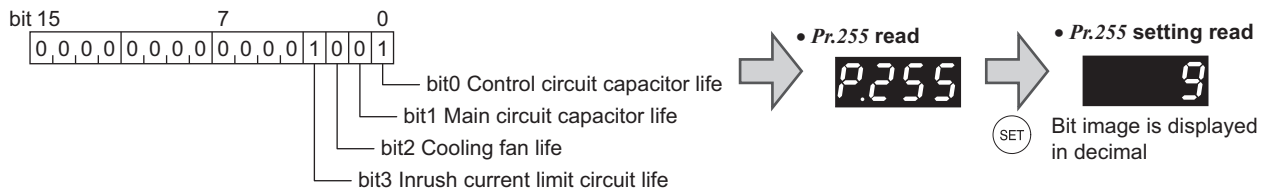
For the life check of the main circuit capacitor, the alarm signal (Y90) will not be output if a measuring method of (4) is not performed.

| Parameter Number | Name                                      | Initial Value | Setting Range        | Description                                                                                                                                                                                                                               |
|------------------|-------------------------------------------|---------------|----------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 255              | Life alarm status display                 | 0             | (0 to 15)            | Display whether the control circuit capacitor, main circuit capacitor, cooling fan, and each parts of the inrush current limit circuit has reached the life alarm output level or not. Reading only                                       |
| 256              | Inrush current limit circuit life display | 100%          | (0 to 100%)          | Display the deterioration degree of the inrush current limit circuit. Reading only                                                                                                                                                        |
| 257              | Control circuit capacitor life display    | 100%          | (0 to 100%)          | Display the deterioration degree of the control circuit capacitor. Reading only                                                                                                                                                           |
| 258              | Main circuit capacitor life display       | 100%          | (0 to 100%)          | Display the deterioration degree of the main circuit capacitor. Reading only<br>The value measured by Pr. 259 is displayed.                                                                                                               |
| 259              | Main circuit capacitor life measuring     | 0             | 0, 1<br>(2, 3, 8, 9) | Setting "1" and switching the power supply off starts the measurement of the main circuit capacitor life.<br>When the Pr. 259 value is "3" after powering on again, the measuring is completed. Read the deterioration degree in Pr. 258. |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145.)

#### (1) Life alarm display and signal output (Y90 signal, Pr. 255)

- Whether any of the control board capacitor, main circuit capacitor, cooling fan and inrush current limit circuit has reached the life alarm output level or not can be checked by Pr. 255 Life alarm status display and life alarm signal (Y90).



| Pr.255 (decimal) | Bit (binary) | Inrush Current Limit Circuit Life | Cooling Fan Life | Main Circuit Capacitor Life | Control Circuit Capacitor Life |
|------------------|--------------|-----------------------------------|------------------|-----------------------------|--------------------------------|
| 15               | 1111         | ○                                 | ○                | ○                           | ○                              |
| 14               | 1110         | ○                                 | ○                | ○                           | ×                              |
| 13               | 1101         | ○                                 | ○                | ×                           | ○                              |
| 12               | 1100         | ○                                 | ○                | ×                           | ×                              |
| 11               | 1011         | ○                                 | ×                | ○                           | ○                              |
| 10               | 1010         | ○                                 | ×                | ○                           | ×                              |
| 9                | 1001         | ○                                 | ×                | ×                           | ○                              |
| 8                | 1000         | ○                                 | ×                | ×                           | ×                              |
| 7                | 0111         | ×                                 | ○                | ○                           | ○                              |
| 6                | 0110         | ×                                 | ○                | ○                           | ×                              |
| 5                | 0101         | ×                                 | ○                | ×                           | ○                              |
| 4                | 0100         | ×                                 | ○                | ×                           | ×                              |
| 3                | 0011         | ×                                 | ×                | ○                           | ○                              |
| 2                | 0010         | ×                                 | ×                | ○                           | ×                              |
| 1                | 0001         | ×                                 | ×                | ×                           | ○                              |
| 0                | 0000         | ×                                 | ×                | ×                           | ×                              |

○: With warnings, ×: Without warnings

- The life alarm signal (Y90) turns on when any of the control board capacitor, main circuit capacitor, cooling fan and inrush current limit circuit reaches the life alarm output level.
- For the terminal used for the Y90 signal, set "90" (positive logic) or "190" (negative logic) to any of *Pr. 190 to Pr. 196 (output terminal function selection)*.

**REMARKS**

- The digital output option (FR-A7AY) allows the control circuit capacitor life signal (Y86), main circuit capacitor life signal (Y87), cooling fan life signal (Y88) and inrush current limit circuit life signal (Y89) to be output individually.

**CAUTION**

- When terminal assignment is changed using *Pr. 190 to Pr. 196 (output terminal function selection)*, the other functions may be affected. Please make setting after confirming the function of each terminal.

**(2) Life display of the inrush current limit circuit (Pr.256)**

- The life of the inrush current limit circuit (relay, contactor and inrush resistor) is displayed in *Pr. 259*.
- The number of contact (relay, contactor, thyristor) ON times is counted, and it is counted down from 100% (1 million times) every 1%/10,000 times. As soon as 10% (900,000 times) is reached, *Pr. 255 bit 3* is turned on and also an alarm is output to the Y90 signal.

**(3) Control circuit capacitor life display (Pr.257)**

- The deterioration degree of the control circuit capacitor is displayed in *Pr. 257* as a life.
- In the operating status, the control circuit capacitor life is calculated from the energization time and temperature, and is counted down from 100%. As soon as the control circuit capacitor life falls below 10%, *Pr. 255 bit 0* is turned on and also an alarm is output to the Y90 signal.

**(4) Main circuit capacitor life display (Pr.258, Pr.259)**

- The deterioration degree of the main circuit capacitor is displayed in *Pr. 258* as a life.
- On the assumption that the main circuit capacitor capacitance at factory shipment is 100%, the capacitor life is displayed in *Pr. 258* every time measurement is made. When the measured value falls to or below 85%, *Pr. 255 bit 1* is turned on and also an alarm is output to the Y90 signal.
- Measure the capacitor capacity according to the following procedure and check the deterioration level of the capacitor capacity.
  - 1) Check that the motor is connected and at a stop.
  - 2) Set "1" (measuring start) in *Pr. 259*
  - 3) Switch power off. The inverter applies DC voltage to the motor to measure the capacitor capacity while the inverter is off.
  - 4) After making sure that the power lamp is off, switch on the power supply again.
  - 5) Check that "3" (measuring completion) is set in *Pr. 259*, read *Pr. 255*, and check the deterioration degree of the main circuit capacitor.

| Pr.259 | Description                                   | Remarks                                                   |
|--------|-----------------------------------------------|-----------------------------------------------------------|
| 0      | No measurement                                | Initial value                                             |
| 1      | Measurement start                             | Measurement starts when the power supply is switched off. |
| 2      | During measurement                            | Only displayed and cannot be set                          |
| 3      | Measurement complete                          |                                                           |
| 8      | Forced end<br>See (c), (g), (h), (i) below.   |                                                           |
| 9      | Measurement error<br>See (d), (e), (f) below. |                                                           |

**REMARKS**

- The life of the main circuit capacitor can not be measured in the following conditions.
  - (a) The FR-HC, MT-HC, FR-CV, FR-BU, MT-BU5 or BU is connected
  - (b) Terminals R1/L11, S1/L21 or DC power supply is connected to the terminal P/+ and N/-.
  - (c) Switch power on during measuring.
  - (d) The motor is not connected to the inverter.
  - (e) The motor is running. (The motor is coasting.)
  - (f) The motor capacity is two rank smaller as compared to the inverter capacity.
  - (g) The inverter is at an alarm stop or an alarm occurred while power is off.
  - (h) The inverter output is shut off with the MRS signal.
  - (i) The start command is given while measuring.
- Operating environment: Ambient Temperature (annual average 40°C (104°F) (free from corrosive gas, flammable gas, oil mist, dust and dirt))  
Output current (80% of the rated current of Mitsubishi standard 4P motor)



### (5) Cooling fan life display

- The cooling fan speed of 50% or less is detected and "FN" is displayed on the operation panel (FR-DU07) and parameter unit (FR-PU04). As an alarm display, Pr. 255 bit 2 is turned on and also an alarm is output to the Y90 signal.

#### REMARKS

- When the inverter is mounted with two or more cooling fans, the life of even one cooling fan is diagnosed.

#### CAUTION

- For replacement of each part, contact the nearest Mitsubishi FA center.

### 3.20.3 Maintenance timer alarm (Pr.503, Pr.504)

When the cumulative energization time of the inverter reaches the parameter set time, the maintenance timer output signal (Y95) is output. **MT** (MT) is displayed on the operation panel (FR-DU07).

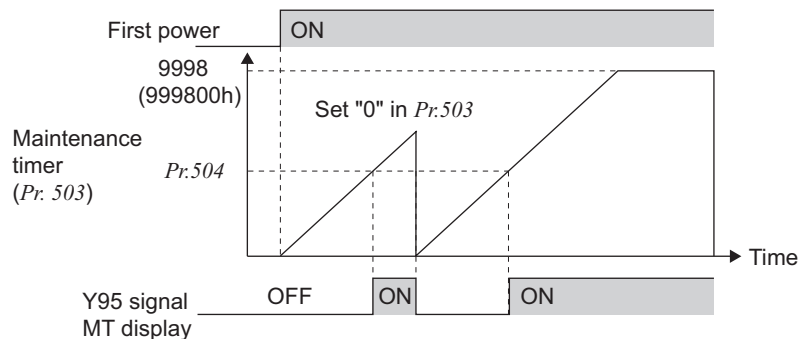
This can be used as a guideline for the maintenance time of peripheral devices.

Pr.497  
page 103

Pr.549  
page 178

| Parameter Number | Name                                    | Initial Value | Setting Range | Description                                                                                                                                                      |
|------------------|-----------------------------------------|---------------|---------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 503              | Maintenance timer                       | 0             | 0 (1 to 9998) | Display the cumulative energization time of the inverter in 100h increments. Reading only<br>Writing the setting of "0" clears the cumulative energization time. |
| 504              | Maintenance timer alarm output set time | 9999          | 0 to 9998     | Set the time taken until when the maintenance timer alarm output signal (Y95) is output.                                                                         |
|                  |                                         |               | 9999          | No function                                                                                                                                                      |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145.)



- The cumulative energization time of the inverter is stored into the EEPROM every hour and indicated in Pr. 503 Maintenance timer in 100h increments. Pr. 503 is clamped at 9998 (999800h).
- When the Pr. 503 value reaches the time set to Pr. 504 Maintenance timer alarm output set time (100h increments), the maintenance timer alarm output signal (Y95) is output.
- For the terminal used for the Y95 signal output, assign the function by setting "95" (positive logic) or "195" (negative logic) to any of Pr. 190 to Pr. 196 (output terminal function selection).

#### CAUTION

- The cumulative energization time is counted every hour. The energization time of less than 1h is not counted.
- When terminal assignment is changed using Pr. 190 to Pr. 196 (output terminal function selection), the other functions may be affected. Please make setting after confirming the function of each terminal.

#### ◆ Parameters referred to ◆

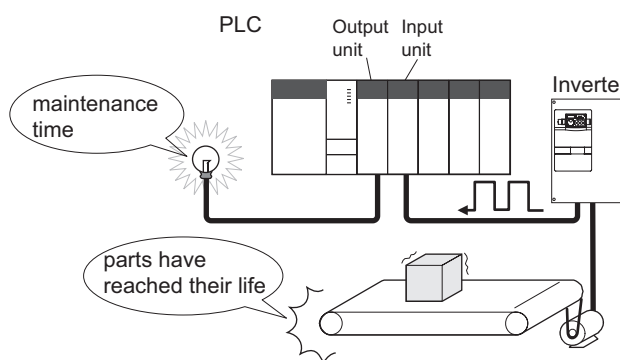
Pr. 190 to Pr. 196(output terminal function selection) Refer to page 96

### 3.20.4 Current average value monitor signal (Pr.555 to Pr.557)

The average value of the output current during constant speed operation and the maintenance timer value are output as a pulse to the current average value monitor signal (Y93).

The pulse width output to the I/O module of the PLC or the like can be used as a guideline due to abrasion of machines and elongation of belt and for aged deterioration of devices to know the maintenance time.

The current average value monitor signal (Y93) is output as pulse for 20s as 1 cycle and repeatedly output during constant speed operation.

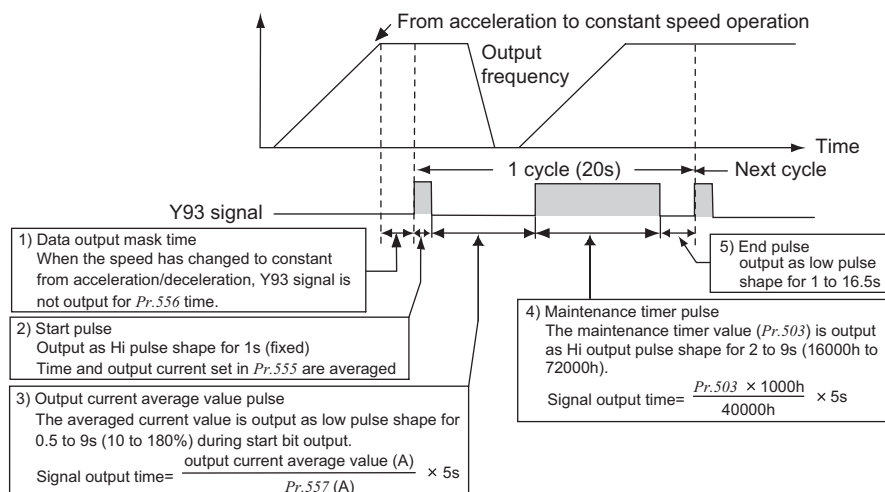


Pr.551  
page 156  
Pr.571  
page 81

| Parameter number | Name                                                          | Initial value          | Setting range<br>200V class (400V class) |            | Description                                                                      |
|------------------|---------------------------------------------------------------|------------------------|------------------------------------------|------------|----------------------------------------------------------------------------------|
| 555              | Current average time                                          | 1s                     | 0.1 to 1.0s                              |            | Set the time taken to average the current during start bit output (1s).          |
| 556              | Data output mask time                                         | 0s                     | 0.0 to 20.0s                             |            | Set the time for not obtaining (mask) transient state data.                      |
| 557              | Current average value monitor signal output reference current | Rated inverter current | 02330 (01160) or less                    | 0 to 500A  | Set the reference (100%) for outputting the signal of the current average value. |
|                  |                                                               |                        | 03160 (01800) or more                    | 0 to 3600A |                                                                                  |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145)

The above parameters allow its setting to be changed during operation in any operation mode even if "0" (initial value) is set in Pr. 77 Parameter write selection.



- The pulse output of the current average value monitor signal (Y93) is shown above.
- For the terminal used for the Y93 signal output, assign the function by setting "93" (positive logic) or "193" (negative logic) to any of Pr. 190 to Pr. 194 (output terminal function selection). (The function can not be assigned to Pr. 195 ABC1 terminal function selection and Pr. 196 ABC2 terminal function selection.)

#### (1) Setting of Pr. 556 Data output mask time

The output current is unstable (transient state) right after the operation is changed from the acceleration/deceleration state to the constant speed operation. Set the time for not obtaining (mask) transient state data in Pr. 556.

#### (2) Setting of the Pr. 555 Current average time

The average output current is calculated during Hi output of start bit (1s). Set the time taken to average the current during start bit output in Pr. 555.

(3) Setting of *Pr. 557 Current average value monitor signal output reference current*

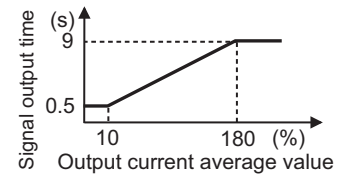
Set the reference (100%) for outputting the signal of the current average value. Obtain the time to output the signal from the following calculation.

$$\frac{\text{Output current average value}}{\text{Pr. 557 setting}} \times 5\text{s} \quad (\text{output current average value } 100\%/5\text{s})$$

Note that the output time range is 0.5 to 9s, and it is 0.5s when the output current average value is less than 10% of the setting value of *Pr. 557* and 9s when exceeds 180%.

Example) When *Pr. 557*=10A and the average value of output current is 15A

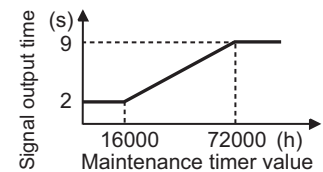
As  $15\text{A}/10\text{A} \times 5\text{s}=7.5$ , the current average value monitor signal is output as low pulse shape for 7.5s.

(4) Output of *Pr. 503 Maintenance timer*

After the output current average value is output as low pulse shape, the maintenance timer value is output as high pulse shape. The output time of the maintenance timer value is obtained from the following calculation.

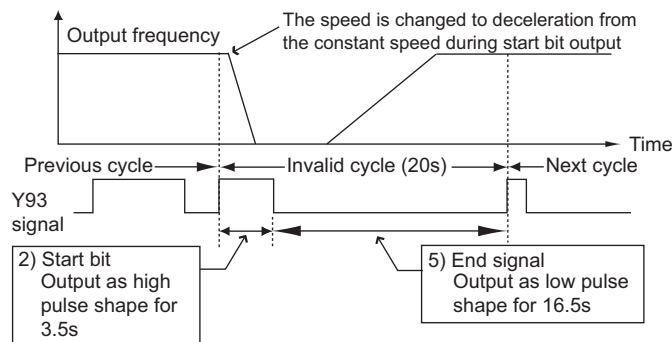
$$\frac{\text{Pr. 503}}{40000\text{h}} \times 5\text{s} \quad (\text{maintenance timer value } 100\%/5\text{s})$$

Note that the output time range is 2 to 9s, and it is 2s when *Pr. 503* is less than 16000h and 9s when exceeds 72000h.



## REMARKS

- Mask of data output and sampling of output current are not performed during acceleration/deceleration.
- When the speed is changed to acceleration/deceleration from constant speed during start bit output, the data is judged as invalid, the start bit is output as high pulse shape for 3.5s, and the end signal is output as low pulse shape for 16.5s. The signal is output for at least 1 cycle even when acceleration/deceleration state continues after the start bit output is completed.



- When the output current value (inverter output current monitor) is 0A on completion of the 1 cycle signal output, the signal is not output until the speed becomes constant next time
- The current average value monitor signal (Y93) is output as low pulse shape for 20s (without data output) under the following condition.
  - When the motor is in the acceleration/deceleration state on completion of the 1 cycle signal output
  - When 1-cycle signal output was ended during restart operation with the setting of automatic restart after instantaneous power failure (*Pr. 57* ≠ "9999")
  - When automatic restart operation was being performed with automatic restart after instantaneous power failure selected (*Pr. 57* ≠ "9999") on completion of the data output mask

## CAUTION

- When terminal assignment is changed using *Pr. 190 to Pr. 196 (output terminal function selection)*, the other functions may be affected. Please make setting after confirming the function of each terminal.

## ◆ Parameters referred to ◆

*Pr. 190 to Pr. 196 (output terminal function selection)* Refer to page 96

*Pr. 503 Maintenance timer* Refer to page 216

*Pr. 57 Restart coasting time* Refer to page 114

### 3.20.5 Free parameter (Pr.888, Pr.889)

Parameters you can use for your own purposes.

You can input any number within the setting range 0 to 9999.

For example, the number can be used:

- As a unit number when multiple units are used.
- As a pattern number for each operation application when multiple units are used.
- As the year and month of introduction or inspection.

**Pr.886**

page 211

**Pr.891**

page 124

| Parameter Number | Name             | Initial Value | Setting Range | Description |
|------------------|------------------|---------------|---------------|-------------|
| 888              | Free parameter 1 | 9999          | 0 to 9999     |             |
| 889              | Free parameter 2 | 9999          | 0 to 9999     |             |

The above parameters can be set when *Pr. 160 User group read selection* = "0". (Refer to page 145)

The above parameters allow its setting to be changed during operation in any operation mode even if "0" (initial value) is set in *Pr. 77 Parameter write selection*.

#### REMARKS

*Pr. 888* and *Pr. 889* do not influence the inverter operation.

## 3.21 Setting from the parameter unit, operation panel

| Purpose                                                                                                         | Parameter that must be set          |         | Refer to page |
|-----------------------------------------------------------------------------------------------------------------|-------------------------------------|---------|---------------|
| Switch the display language of the parameter unit                                                               | PU display language selection       | Pr. 145 | 220           |
| Use the setting dial of the operation panel like a volume for frequency setting.<br>Key lock of operation panel | Operation panel operation selection | Pr.161  | 220           |
| Control of the parameter unit, operation panel buzzer                                                           | PU buzzer control                   | Pr. 990 | 222           |
| Adjust the LCD contrast of the parameter unit                                                                   | PU contrast adjustment              | Pr. 991 | 222           |

### 3.21.1 PU display language selection (Pr.145)

You can switch the display language of the parameter unit (FR-PU04) to another.

Pr.144  
page 104

Pr.148  
page 61

| Parameter Number | Name                          | Initial Value | Setting Range | Definition |
|------------------|-------------------------------|---------------|---------------|------------|
| 145              | PU display language selection | 1             | 0             | Japanese   |
|                  |                               |               | 1             | English    |
|                  |                               |               | 2             | Germany    |
|                  |                               |               | 3             | French     |
|                  |                               |               | 4             | Spanish    |
|                  |                               |               | 5             | Italian    |
|                  |                               |               | 6             | Swedish    |
|                  |                               |               | 7             | Finnish    |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145.)

### 3.21.2 Operation panel frequency setting/key lock operation selection (Pr. 161)

The setting dial of the operation panel (FR-DU07) can be used like a potentiometer to perform operation.  
The key operation of the operation panel can be disabled.

Pr. 160  
page 145

Pr.162  
page 114

| Parameter Number | Name                                           | Initial Value | Setting Range | Description                         |                       |
|------------------|------------------------------------------------|---------------|---------------|-------------------------------------|-----------------------|
| 161              | Frequency setting/key lock operation selection | 0             | 0             | Setting dial frequency setting mode | Key lock mode invalid |
|                  |                                                |               | 1             | Setting dial volume mode            |                       |
|                  |                                                |               | 10            | Setting dial frequency setting mode | Key lock mode valid   |
|                  |                                                |               | 11            | Setting dial volume mode            |                       |

The above parameters can be set when Pr. 160 User group read selection = "0". (Refer to page 145.)

## (1) Using the setting dial like a volume to set the frequency.

**Operation example** Changing the frequency from 0Hz to 60Hz during operation

| Operation                                                                                                                         | Display                              |
|-----------------------------------------------------------------------------------------------------------------------------------|--------------------------------------|
| 1. Screen at powering on<br>The monitor display appears.                                                                          |                                      |
| 2. Press <b>(PU EXT)</b> to choose the PU operation mode.                                                                         | PU indication is lit.<br>            |
| 3. Press <b>(MODE)</b> to choose the parameter setting mode.                                                                      |                                      |
| 4. Turn  until <b>P. 16 1</b> ( <i>Pr. 161</i> ) appears.                                                                         |                                      |
| 5. Press <b>(SET)</b> to read the currently set value.<br>"0" (initial value) appears.                                            |                                      |
| 6. Turn  clockwise to change it to the setting value of "1".                                                                      |                                      |
| 7. Press <b>(SET)</b> to set.                                                                                                     |                                      |
| <b>Flicker ... Parameter setting complete!!</b>                                                                                   |                                      |
| 8. Mode/monitor check<br>Press <b>(MODE)</b> twice to choose monitor/frequency monitor.                                           |                                      |
| 9. Press <b>(FWD)</b> (or <b>(REV)</b> ) to start the inverter.                                                                   |                                      |
| 10. Turn  clockwise until "60.00" appears.<br>The flickering frequency is the set frequency.<br>You need not press <b>(SET)</b> . |                                      |
|                                                                                                                                   | The frequency flickers for about 5s. |

### REMARKS

- If the display changes from flickering "60.00" to "0.00", the setting of *Pr. 161 Frequency setting/key lock operation selection* may not be "1".
- Independently of whether the inverter is running or at a stop, the frequency can be set by merely turning the dial.
- When the frequency is changed, it will be stored in EEPROM as the set frequency after 10s.

## (2) Disable the setting dial and key operation of the operation panel (Press [MODE] long (2s))

- Operation using the setting dial and key of the operation panel can be made invalid to prevent parameter change and unexpected start and stop.
- Set "10 or 11" in *Pr. 161*, then press  for 2s to make the setting dial and key operation invalid.
- When the setting dial and key operation is made invalid, **HOLD** appears on the operation panel. When the setting dial and key operation is invalid, **HOLD** appears if the setting dial or key operation is performed. (When the setting dial or key operation is not performed for 2s, the monitor display appears.)
- To make the setting dial and key operation valid again, press  for 2s.

### REMARKS

- If the setting dial and key operation are disabled, the monitor display  is valid.

## 3.21.3 Buzzer control (Pr. 990)

Pr.899  
page 124

You can make the buzzer "beep" when you press key of the operation panel (FR-DU07) and parameter unit (FR-PU04).

| Parameter Number | Name              | Initial Value | Setting Range | Description    |
|------------------|-------------------|---------------|---------------|----------------|
| 990              | PU buzzer control | 1             | 0             | Without buzzer |
|                  |                   |               | 1             | With buzzer    |

The above parameters can be set when *Pr. 160 User group read selection* = "0". (Refer to page 145.)

The above parameters allow its setting to be changed during operation in any operation mode even if "0" (initial value) is set in *Pr. 77 Parameter write selection*.

## 3.21.4 PU contrast adjustment (Pr.991)

Contrast adjustment of the LCD of the parameter unit (FR-PU04) can be performed.  
Decreasing the setting value makes contrast light.

| Parameter Number | Name                   | Initial Value | Setting Range | Description                |
|------------------|------------------------|---------------|---------------|----------------------------|
| 991              | PU contrast adjustment | 58            | 0 to 63       | 0 : Light<br>↓<br>63: Dark |

The above parameters are displayed as simple mode parameters only when the parameter unit (FR-PU04) is connected. When the operation panel is connected, they can be set only when *Pr. 160 User group read selection* = "0". (Refer to page 145.)

### CAUTION

You should press the  to store the PU contrast setting.

## 3.22 Parameter clear

### POINT

- Set "1" in *Pr.CL* parameter clear to initialize all parameters. (Parameters are not cleared when "1" is set in *Pr. 77* Parameter write selection. In addition, calibration parameters are not cleared.)

| Operation                                                                  | Display                                         |
|----------------------------------------------------------------------------|-------------------------------------------------|
| 1. Screen at powering on<br>The monitor display appears.                   |                                                 |
| 2. Press  to choose the PU operation mode.                                 | PU indication is lit.<br>                       |
| 3. Press  to choose the parameter setting mode.                            | (The parameter number read previously appears.) |
| 4. Turn  until "Pr.CL" (parameter clear) appears.                          |                                                 |
| 5. Press  to read the currently set value.<br>"0" (initial value) appears. |                                                 |
| 6. Turn  clockwise to change it to the setting value of "1".               |                                                 |
| 7. Press  to set.                                                          |                                                 |

**Flicker ... Parameter setting complete!!**

- Turn to read another parameter.
- Press to show the setting again.
- Press twice to show the next parameter.

| Setting | Description                                                                                                       |
|---------|-------------------------------------------------------------------------------------------------------------------|
| 0       | Not executed.                                                                                                     |
| 1       | Returns all parameters except <i>calibration parameters</i> C0 (Pr. 900) to C7 (Pr. 905) to the initial values. * |

\* Pr.73, Pr.75, Pr.90, Pr.125, Pr.126, Pr.145, Pr.161, Pr.170 to Pr.174, Pr.178 to Pr.196, Pr.255 to Pr.258, Pr.267, Pr.343, Pr.496, Pr.497, Pr.503, Pr.504, Pr.563, Pr.564, Pr.888, Pr.889, Pr.989, Pr.991 are not cleared.

? and are displayed alternately ... Why?

The inverter is not in the PU operation mode.

- Press .

is lit and the monitor (4 digit LED) displays "0" (Pr.79 = "0" (initial value)).

- Carry out operation from step 6 again.



### 3.23 All parameter clear

#### POINT

- Set "1" in *ALLC* parameter clear to initialize all parameters. (Parameters are not cleared when "1" is set in *Pr. 77* Parameter write selection. In addition, calibration parameters are not cleared.)

| Operation                                                                  | Display                                         |
|----------------------------------------------------------------------------|-------------------------------------------------|
| 1. Screen at powering on<br>The monitor display appears.                   |                                                 |
| 2. Press  to choose the PU operation mode.                                 | PU indication is lit.<br>                       |
| 3. Press  to choose the parameter setting mode.                            | (The parameter number read previously appears.) |
| 4. Turn  until <i>ALLC</i> (all parameter clear) appears.                  |                                                 |
| 5. Press  to read the currently set value.<br>"0" (initial value) appears. |                                                 |
| 6. Turn  clockwise to change it to the setting value of "1".               |                                                 |
| 7. Press  to set.                                                          |                                                 |

**Flicker ... Parameter setting complete!!**

- Press to read another parameter.
- Press to show the setting again.
- Press twice to show the next parameter.

| Setting | Description                                    |
|---------|------------------------------------------------|
| 0       | Not executed.                                  |
| 1       | All parameters return to the initial values. * |

\* *Pr.75, Pr.145, Pr.171 to Pr.174, Pr.255 to Pr.258, Pr.343, Pr.496, Pr.497, Pr.503, Pr.563, Pr.564, Pr.888, Pr.889* are not cleared.

? and are displayed alternately ... Why?

The inverter is not in the PU operation mode.

- Press .

is lit and the monitor (4 digit LED) displays "0" (*Pr.79* = "0" (initial value)).

- Carry out operation from step 6 again.

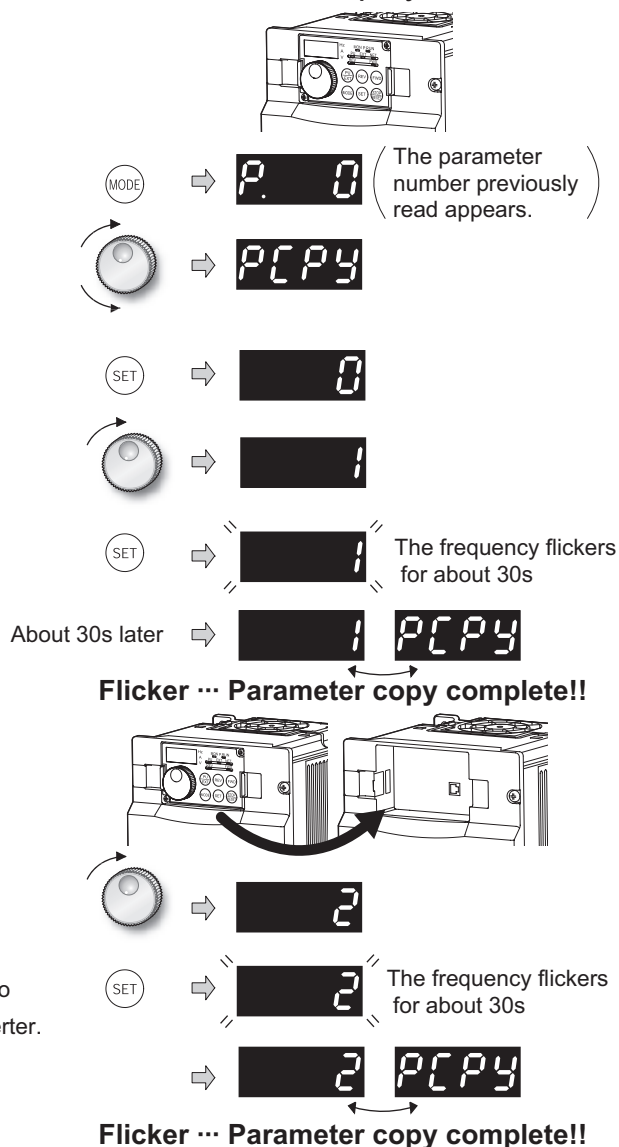
## 3.24 Parameter copy

Multiple inverters and parameter settings can be copied.

### Operation

1. Connect the operation panel to the copy source inverter.  
• **Connect it during a stop.**
2. Press **(MODE)** to choose the parameter setting mode.
3. Turn **(SEL)** until **PCPY** (parameter copy) appears.
4. Press **(SET)** to read the currently set value.  
"0" (initial value) appears.
5. Turn **(SEL)** clockwise to change it to the setting value of "1".
6. Press **(SET)** to copy the source parameters to the operation panel.
7. Connect the operation panel to the copy source inverter.
8. After performing steps 2 to 5, turn **(SEL)** clockwise to change it to "2".
9. Press **(SET)** to write the parameters copied to the operation panel to the destination inverter.
10. When copy is completed, "2" and "PCPY" flicker.
11. After writing the parameter values to the copy destination inverter, always reset the inverter, e.g. switch power off once, before starting operation.

### Display



? **PE1** appears...Why? ⚠ Parameter read error. Perform operation from step 3 again.

? **PE2** appears...Why? ⚠ Parameter write error. Perform operation from step 8 again.

? **CP** and **000** flicker alternately

⚠ Appears when parameters are copied between the inverter of FR-F720-02330 (FR-F740-01160) or less and FR-F720-03160 (FR-F740-01800) or more.

1. Set "0" in Pr. 160 User group read selection.

2. Set the following setting (initial value) in Pr. 989 Parameter copy alarm release.

|                 | FR-F720-02330 (FR-F740-01160) or less | FR-F720-03160 (FR-F740-01800) or more |
|-----------------|---------------------------------------|---------------------------------------|
| Pr. 989 Setting | 10                                    | 100                                   |

3. Reset Pr.9, Pr.30, Pr.51, Pr.52, Pr.54, Pr.56, Pr.57, Pr.61, Pr.70, Pr.72, Pr.80, Pr.90, Pr.158, Pr.190 to Pr.196, Pr.893.

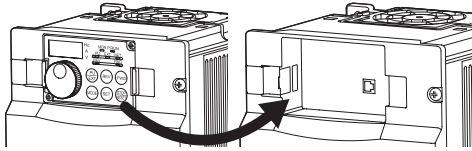
| PCPY Setting | Description                                                                       |
|--------------|-----------------------------------------------------------------------------------|
| 0            | Cancel                                                                            |
| 1            | Copy the source parameters to the operation panel.                                |
| 2            | Write the parameters copied to the operation panel into the destination inverter. |
| 3            | Verify parameters in the inverter and operation panel.<br>(Refer to page 226.)    |

### REMARKS

- When the copy destination inverter is not the FR-F700 series, "model error (PE4)" is displayed.
- Refer to the extended parameter list on the *Instruction Manual (basics)* for availability of parameter copy.

## 3.25 Parameter verification

Whether same parameter values are set in other inverters or not can be checked.

| Operation                                                                                                       | Display                                                                            |
|-----------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------|
| <p>1. Replace the operation panel on the inverter to be verified.</p> <p>• <u>Replace it during a stop.</u></p> |  |
| <p>2. Screen at powering on<br/>The monitor display appears.</p>                                                |  |
| <p>3. Press (MODE) to choose the parameter setting mode.</p>                                                    | <p>(MODE) → P. 0 (The parameter number read previously appears.)</p>               |
| <p>4. Turn ( ) until PCPY (parameter copy) appears.</p>                                                         | <p>( ) → PCPY</p>                                                                  |
| <p>5. Press (SET) to read the currently set value.<br/>"0" (initial value) appears.</p>                         | <p>(SET) → 0</p>                                                                   |
| <p>6. Turn ( ) to change it to the set value of "3" (parameter copy verification mode).</p>                     | <p>( ) → 3</p>                                                                     |
| <p>7. Press (SET) to read the parameter setting of the verified inverter to the operation panel.</p>            | <p>(SET) → 3 (The frequency flickers for about 30s)</p>                            |
| <p>• If different parameters exist, different parameter numbers and rE3 flicker.</p>                            | <p>P. 1 rE3</p>                                                                    |
| <p>• Hold down (SET) to verify.</p>                                                                             | <p>(SET) → 3 Flickering</p>                                                        |
| <p>8. If there is no difference, PCPY and 3 flicker to complete verification.</p>                               | <p>3 PCPY</p>                                                                      |

**Flicker ... Parameter verification complete!!**

### REMARKS

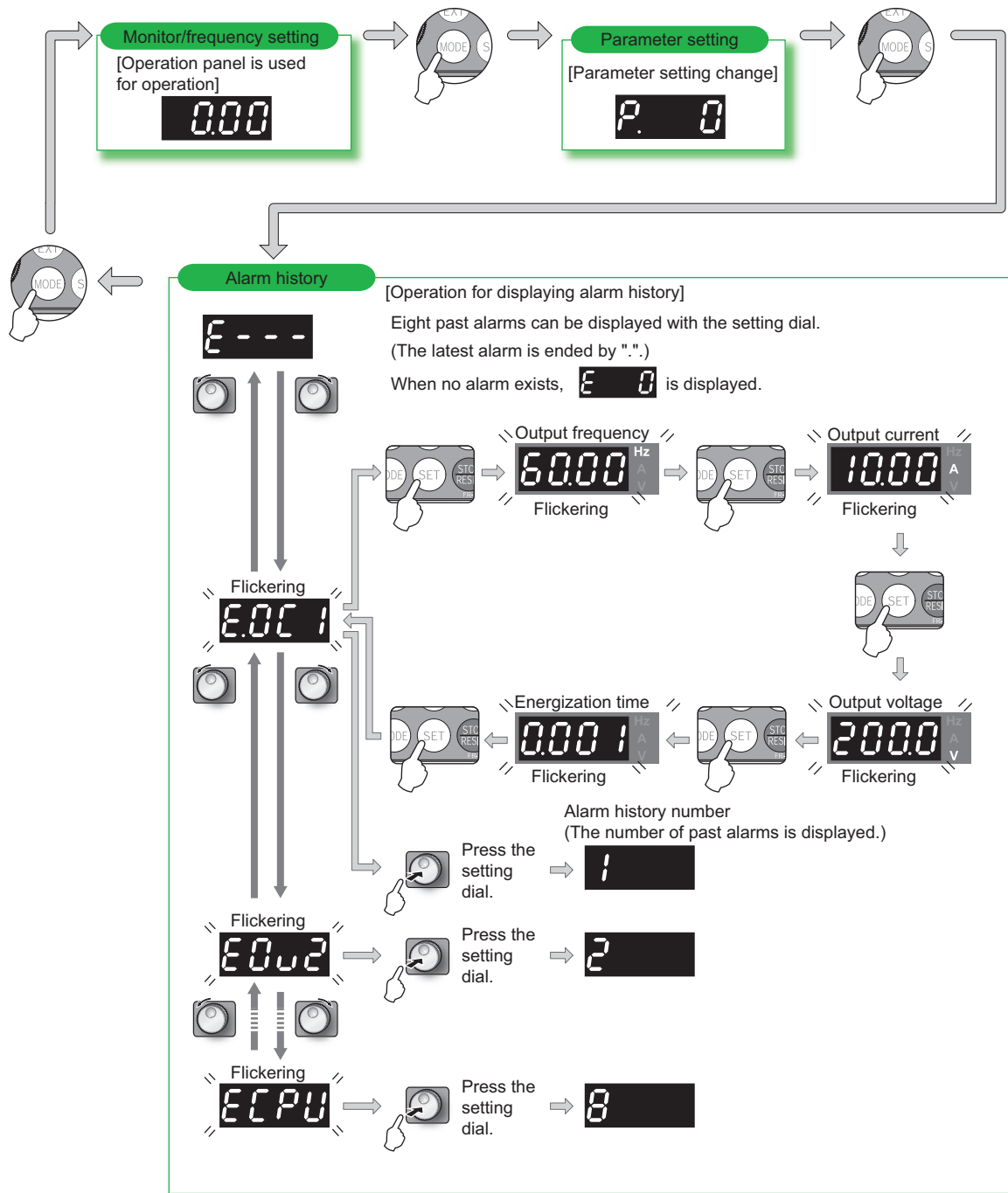
When the copy destination inverter is not the FR-F700 series, "model error (rE4)" is displayed.

? rE3 flickers ... Why?

☞ Set frequencies, etc. may be different. Check set frequencies.

## 3.26 Check and clear of the alarm history

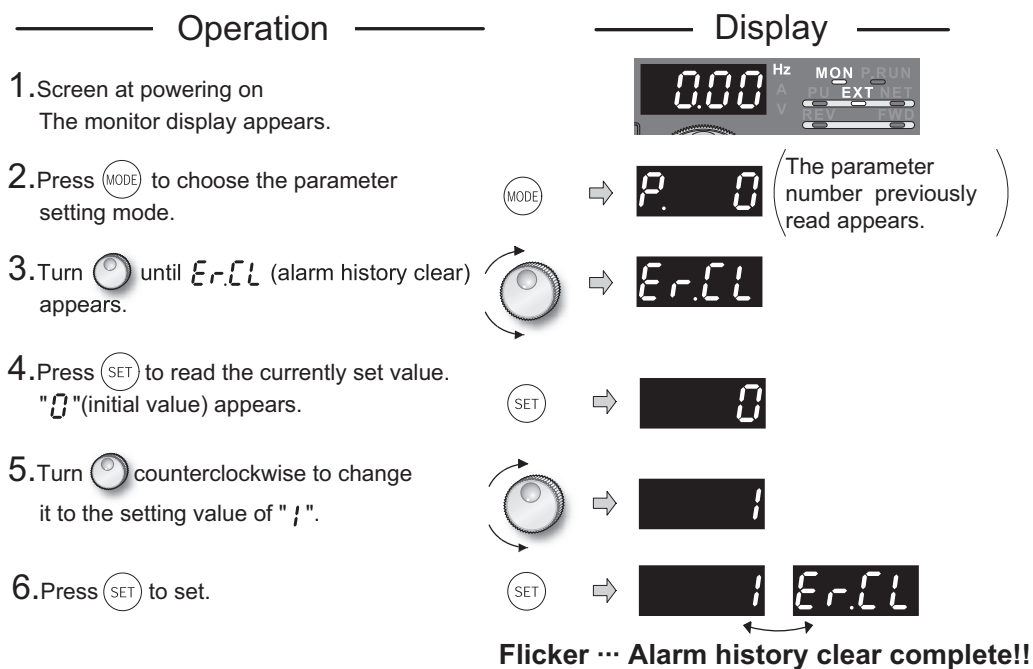
### (1) Check for the alarm (major fault) history



## (2) Clearing procedure

### POINT

- The alarm history can be cleared by setting "1" in *Er.CL Alarm history clear*. (The alarm history is not cleared when "1" is set in *Pr. 77 Parameter write selection*)



- Press  to read another parameter.
- Press  to show the setting again.
- Press  twice to show the next parameter.

# 4 PROTECTIVE FUNCTIONS

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This chapter describes the basic "PROTECTIVE FUNCTION" for use of this product.

Always read the instructions before using the equipment

---

|     |                                                             |     |
|-----|-------------------------------------------------------------|-----|
| 4.1 | List of alarm display .....                                 | 230 |
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| 4.5 | Meters and measuring methods.....                           | 243 |
| 4.6 | Check first when you have troubles. ....                    | 246 |

1

2

3

4

5



When an alarm occurs in the inverter, the protective function is activated bringing the inverter to an alarm stop and the PU display automatically changes to any of the following error (alarm) indications.  
If your fault does not correspond to any of the following errors or if you have any other problem, please contact your sales representative.

- Retention of alarm output signal ..... When the magnetic contactor (MC) provided on the input side of the inverter is opened at the activation of the protective function, the inverter's control power will be lost and the alarm output will not be held.
- Alarm display ..... When the protective function is activated, the operation panel display automatically switches to the above indication.
- Resetting method ..... When the protective function is activated, the inverter output is kept stopped. Unless reset, therefore, the inverter cannot restart. (Refer to page 242.)
- When the protective function is activated, take the corresponding corrective action, then reset the inverter, and resume operation.

## 4.1 List of alarm display

| Operation Panel Indication |                            | Name                | Refer to                                                                               |
|----------------------------|----------------------------|---------------------|----------------------------------------------------------------------------------------|
| Error message              | <b>HOLD</b>                | HOLD                | Operation panel lock                                                                   |
|                            | <b>Er1</b> to <b>Er4</b>   | Er1 to 4            | Parameter write error                                                                  |
|                            | <b>rEr1</b> to <b>rEr4</b> | rEr1 to 4           | Copy operation error                                                                   |
|                            | <b>Err.</b>                | Err.                | Error                                                                                  |
| Warnings                   | <b>OL</b>                  | OL                  | Stall Prevention (overcurrent)                                                         |
|                            | <b>oL</b>                  | oL                  | Stall prevention (overvoltage)                                                         |
|                            | <b>rb</b>                  | RB                  | Regenerative brake prealarm                                                            |
|                            | <b>TH</b>                  | TH                  | Electronic thermal relay function prealarm                                             |
|                            | <b>PS</b>                  | PS                  | PU Stop                                                                                |
|                            | <b>MT</b>                  | MT                  | Maintenance signal output                                                              |
|                            | <b>CP</b>                  | CP                  | Parameter copy                                                                         |
| Minor fault                | <b>Fn</b>                  | FN                  | Fan fault                                                                              |
| Major failures             | <b>E.OC1</b>               | E.OC1               | Overcurrent shut-off during acceleration                                               |
|                            | <b>E.OC2</b>               | E.OC2               | Overcurrent shut-off during constant speed                                             |
|                            | <b>E.OC3</b>               | E.OC3               | Overcurrent shut-off during deceleration or stop                                       |
|                            | <b>E.OV1</b>               | E.OV1               | Regenerative overvoltage shut-off during acceleration                                  |
|                            | <b>E.OV2</b>               | E.OV2               | Regenerative overvoltage shut-off during constant speed                                |
|                            | <b>E.OV3</b>               | E.OV3               | Regenerative overvoltage shut-off during deceleration or stop                          |
|                            | <b>ETHT</b>                | E.THT               | Inverter overload shut-off (electronic thermal relay function)                         |
|                            | <b>ETHM</b>                | E.THM               | Motor overload shut-off (electronic thermal relay function)                            |
|                            | <b>EFIn</b>                | E.FIN               | Fin overheat                                                                           |
|                            | <b>EIPF</b>                | E.IPF               | Instantaneous power failure protection                                                 |
|                            | <b>EUVT</b>                | E.UVT               | Undervoltage protection                                                                |
| Major failures             | <b>EILF</b>                | E.ILF*              | Input phase failure                                                                    |
|                            | <b>EOLT</b>                | E.OLT               | Stall Prevention                                                                       |
|                            | <b>E.GF</b>                | E.GF                | Output side ground fault overcurrent protection                                        |
|                            | <b>E.LF</b>                | E.LF                | Output phase failure protection                                                        |
|                            | <b>E.OHT</b>               | E.OHT               | External thermal relay operation <sup>2</sup>                                          |
|                            | <b>E.PTC</b>               | E.PTC*              | PTC thermistor operation                                                               |
|                            | <b>E.OPT</b>               | E.OPT               | Option alarm                                                                           |
|                            | <b>E.OP1</b>               | E.OP1               | Option slot alarm (e.g.communication error)                                            |
|                            | <b>E. 1</b>                | E. 1                | Option alarm (e.g.connection or contact fault)                                         |
|                            | <b>E. PE</b>               | E.PE                | Parameter storage device alarm                                                         |
|                            | <b>E.PUE</b>               | E.PUE               | PU disconnection                                                                       |
|                            | <b>E.RET</b>               | E.RET               | Retry count excess                                                                     |
|                            | <b>E.PE2</b>               | E.PE2*              | Parameter storage device alarm                                                         |
|                            | <b>E. 6 / E. 7 / E.CPU</b> | E. 6 / E. 7 / E.CPU | CPU error                                                                              |
|                            | <b>E.CTE</b>               | E.CTE               | Operation panel power supply short circuit RS-485 terminals power supply short circuit |
|                            | <b>E.P24</b>               | E.P24               | 24VDC power output short circuit                                                       |
|                            | <b>E.CDO</b>               | E.CDO*              | Output current detection value exceeded                                                |
|                            | <b>E.IOH</b>               | E.IOH*              | Inrush resistor overheat                                                               |
|                            | <b>E.SER</b>               | E.SER*              | Communication error (inverter)                                                         |
|                            | <b>E.AIE</b>               | E.AIE*              | Analog input error                                                                     |
|                            | <b>E. bE</b>               | E.BE                | Brake transistor alarm detection/internal circuit error                                |
|                            | <b>E. 13</b>               | E.13*               | Internal circuit error                                                                 |

\* If an error occurs when using the FR-PU04, "Fault 14" is displayed on the FR-PU04.

## 4.2 Causes and corrective actions

### (1) Error Message

A message regarding operational troubles is displayed. Output is not shut off.

|                            |                                                                                                                                                                          |      |
|----------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------|
| Operation Panel Indication | HOLD                                                                                                                                                                     | HOLD |
| Name                       | Operation panel lock                                                                                                                                                     |      |
| Description                | Operation lock mode is set. Operation other than  is made invalid. (Refer to page 222.) |      |
| Check point                | —                                                                                                                                                                        |      |
| Corrective action          | Press  for 2s to release lock.                                                          |      |

|                            |                                                                                                                                                                                                                                                                                                               |     |
|----------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----|
| Operation Panel Indication | Er1                                                                                                                                                                                                                                                                                                           | Er1 |
| Name                       | Write disable error                                                                                                                                                                                                                                                                                           |     |
| Description                | 1. You attempted to make parameter setting when Pr. 77 Parameter write selection has been set to disable parameter write.<br>2. Frequency jump setting range overlapped.<br>3. Adjustable 5 points V/F settings overlapped<br>4. The PU and inverter cannot make normal communication                         |     |
| Check point                | 1. Check the setting of Pr. 77 Parameter write selection (Refer to page 144.)<br>2. Check the settings of Pr. 31 to 36 (frequency jump). (Refer to page 68.)<br>3. Check the settings of Pr. 100 to Pr. 109 (Adjustable 5 points V/F). (Refer to page 71.)<br>4. Check the connection of the PU and inverter. |     |

|                            |                                                                                                                                                                                                        |     |
|----------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----|
| Operation Panel Indication | Er2                                                                                                                                                                                                    | Er2 |
| Name                       | Write error during operation                                                                                                                                                                           |     |
| Description                | When parameter write was performed during operation with a value other than "2" (writing is enabled independently of operation status in any operation mode) is set in Pr. 77 and the STF (STR) is on. |     |
| Check point                | 1. Check the Pr. 77 setting. (Refer to page 144.)<br>2. Check that the inverter is not operating.                                                                                                      |     |
| Corrective action          | 1. Set "2" in Pr. 72.<br>2. After stopping operation, make parameter setting.                                                                                                                          |     |

|                            |                                                                                       |     |
|----------------------------|---------------------------------------------------------------------------------------|-----|
| Operation Panel Indication | Er3                                                                                   | Er3 |
| Name                       | Calibration error                                                                     |     |
| Description                | Analog input bias and gain calibration values are too close.                          |     |
| Check point                | Check the settings of C3, C4, C6 and C7 (calibration functions). (Refer to page 134.) |     |

|                            |                                                                                                                                                                         |     |
|----------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----|
| Operation Panel Indication | Er4                                                                                                                                                                     | Er4 |
| Name                       | Mode designation error                                                                                                                                                  |     |
| Description                | You attempted to make parameter setting in the NET operation mode when Pr. 77 is not "2".                                                                               |     |
| Check point                | 1. Check that operation mode is "PU operation mode".<br>2. Check the Pr. 77 setting. (Refer to page 144.)                                                               |     |
| Corrective action          | 1. After setting the operation mode to the "PU operation mode", make parameter setting. (Refer to page 144.)<br>2. After setting "2" in Pr. 77, make parameter setting. |     |

|                            |                                                                                                                                                  |     |
|----------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------|-----|
| Operation Panel Indication | rE1                                                                                                                                              | rE1 |
| Name                       | Parameter read error                                                                                                                             |     |
| Description                | An error occurred in the EEPROM on the operation panel side during parameter copy reading.                                                       |     |
| Check point                | —                                                                                                                                                |     |
| Corrective action          | · Make parameter copy again. (Refer to page 225.)<br>· Check for an operation panel (FR-DU07) failure. Please contact your sales representative. |     |



|                                   |                                                                                                                                                                              |            |
|-----------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------|
| <b>Operation Panel Indication</b> | <b>rE2</b>                                                                                                                                                                   | <b>rE2</b> |
| <b>Name</b>                       | Parameter write error                                                                                                                                                        |            |
| <b>Description</b>                | 1. You attempted to perform parameter copy write during operation.<br>2. An error occurred in the EEPROM on the operation panel side during parameter copy writing.          |            |
| <b>Check point</b>                | Is the FWD or REV LED of the operation panel (FR-DU07) lit or flickering?                                                                                                    |            |
| <b>Corrective action</b>          | 1. After stopping operation, make parameter copy again. (Refer to page 225.)<br>2. Check for an operation panel (FR-DU07) failure. Please contact your sales representative. |            |

|                                   |                                                                                                                                                                                                                                                                                 |            |
|-----------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------|
| <b>Operation Panel Indication</b> | <b>rE3</b>                                                                                                                                                                                                                                                                      | <b>rE3</b> |
| <b>Name</b>                       | Parameter verification error                                                                                                                                                                                                                                                    |            |
| <b>Description</b>                | 1. Data on the operation panel side and inverter side are different.<br>2. An error occurred in the EEPROM on the operation panel side during parameter verification.                                                                                                           |            |
| <b>Check point</b>                | Check for the parameter setting of the source inverter and inverter to be verified.                                                                                                                                                                                             |            |
| <b>Corrective action</b>          | 1. Press  to continue verification.<br>Make parameter verification again. (Refer to page 226.)<br>2. Check for an operation panel (FR-DU07) failure. Please contact your sales representative. |            |

|                                   |                                                                                        |            |
|-----------------------------------|----------------------------------------------------------------------------------------|------------|
| <b>Operation Panel Indication</b> | <b>rE4</b>                                                                             | <b>rE4</b> |
| <b>Name</b>                       | Model error                                                                            |            |
| <b>Description</b>                | A different model was used for parameter write and verification during parameter copy. |            |
| <b>Check point</b>                | Check that the verified inverter is the same model.                                    |            |
| <b>Corrective action</b>          | Use the same model (FR-F700 series) for parameter copy and verification.               |            |

|                                   |                                                                                                                      |             |
|-----------------------------------|----------------------------------------------------------------------------------------------------------------------|-------------|
| <b>Operation Panel Indication</b> | <b>Err.</b>                                                                                                          | <b>Err.</b> |
| <b>Description</b>                | 1. The RES signal is on;<br>2. The PU and inverter cannot make normal communication (contact fault of the connector) |             |
| <b>Corrective action</b>          | 1. Turn off the RES signal.<br>2. Check the connection of the PU and inverter.                                       |             |

## (2) Warnings

When the protective function is activated, the output is not shut off.

When the protective function is activated, the output is not shut off.

| Operation Panel Indication | OL                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |                                                                                                                                                                                                                                                                              | FR-PU04 | OL |
|----------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------|----|
| Name                       | Stall prevention (overcurrent)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |                                                                                                                                                                                                                                                                                                                                                               |         |    |
| Description                | During acceleration                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | If a current of more than 110% <sup>*1</sup> of the rated inverter current flows in the motor, this function stops the increase in frequency until the overload current reduces to prevent the inverter from resulting in overcurrent shut-off. When the overload current has reduced below 110% <sup>*1</sup> , this function increases the frequency again. |         |    |
|                            | During constant-speed operation                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | If a current of more than 110% <sup>*1</sup> of the rated inverter current flows in the motor, this function lowers the frequency until the overload current reduces to prevent overcurrent shut-off. When the overload current has reduced below 110% <sup>*1</sup> , this function increases the frequency up to the set value.                             |         |    |
|                            | During deceleration                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | If a current of more than 110% <sup>*1</sup> of the rated inverter current flows in the motor, this function stops the decrease in frequency until the overload current reduces to prevent the inverter from resulting in overcurrent shut-off. When the overload current has reduced below 110% <sup>*1</sup> , this function decreases the frequency again. |         |    |
| Check point                | <div>1. Check that the <i>Pr. 0 Torque boost</i> setting is not too large.</div> <div>2. Check that the <i>Pr. 7 Acceleration time</i> and <i>Pr. 8 Deceleration time</i> settings are not too small.</div> <div>3. Check that the load is not too heavy.</div> <div>4. Are there any failure in peripheral devices?</div> <div>5. Check that the <i>Pr. 13 Starting frequency</i> is not too large.</div> <div>· Check the motor for use under overload.</div>                                                                                                                                                                                                                                                                                                                                                                                                                                            |                                                                                                                                                                                                                                                                                                                                                               |         |    |
| Corrective action          | <div>1. Increase or decrease the <i>Pr. 0 Torque boost</i> value 1% by 1% and check the motor status. (Refer to page 58.)</div> <div>2. Set a larger value in <i>Pr. 7 Acceleration time</i> and <i>Pr. 8 Deceleration time</i>. (Refer to page 79.)</div> <div>3. Reduce the load weight.</div> <div>4. Try simple magnetic flux vector control (<i>Pr. 80</i>).</div> <div>5. Change the <i>Pr. 14 Load pattern selection</i> setting.</div> <div>6. Set stall prevention operation current in <i>Pr. 22 Stall prevention operation level</i>. (The initial value is 110%.) The acceleration/deceleration time may change. Increase the stall prevention operation level with <i>Pr. 22 Stall prevention operation level</i>, or disable stall prevention with <i>Pr. 156 Stall prevention operation selection</i>. (Use <i>Pr. 156</i> to set either operation continued or not at OL operation.)</div> |                                                                                                                                                                                                                                                                                                                                                               |         |    |

\*1 120% when LD is selected

| Operation Panel Indication | oL                                                                                                                                                                                                   |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     | FR-PU04 | oL |
|----------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------|----|
| Name                       | Stall prevention (overvoltage)                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |         |    |
| Description                | During deceleration                                                                                                                                                                                  | <ul style="list-style-type: none"><li>· If the regenerative energy of the motor becomes excessive and exceeds the regenerative energy consumption capability, this function stops the decrease in frequency to prevent overvoltage shut-off. As soon as the regenerative energy has reduced, deceleration resumes.</li><li>· If the regenerative energy of the motor becomes excessive when regeneration avoidance function is selected (<i>Pr. 882</i> = 1), this function increases the speed to prevent overvoltage shut-off. (<i>Refer to page 144.</i>)</li></ul> |         |    |
| Check point                | <ul style="list-style-type: none"><li>· Check for sudden speed reduction.</li><li>· Regeneration avoidance function (<i>Pr. 882 to Pr. 886</i>) is being used? (<i>Refer to page 144.</i>)</li></ul> |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |         |    |
| Corrective action          | The deceleration time may change.<br>Increase the deceleration time using <i>Pr. 8 Deceleration time</i> .                                                                                           |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |         |    |

| Operation Panel Indication | PS                                                                                                                                                                                                                                     |  | FR-PU04 | PS |
|----------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------|---------|----|
| <b>Name</b>                | PU Stop                                                                                                                                                                                                                                |                                                                                     |         |    |
| <b>Description</b>         | Stop with  of the PU is set in <i>Pr. 75 Reset selection/disconnected PU detection/PU stop selection</i> . (For <i>Pr. 75</i> , refer to page 141.) |                                                                                     |         |    |
| <b>Check point</b>         | Check for a stop made by pressing  of the operation panel.                                                                                          |                                                                                     |         |    |
| <b>Corrective action</b>   | Turn the start signal off and release with  .                                                                                                       |                                                                                     |         |    |



| Operation Panel Indication | RB                                                                                                                                                                                                                                                                                | <i>rb</i> | FR-PU04 | RB |
|----------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------|---------|----|
| Name                       | Regenerative brake prealarm                                                                                                                                                                                                                                                       |           |         |    |
| Description                | Appears if the regenerative brake duty reaches or exceeds 85% of the <i>Pr. 70 Special regenerative brake duty</i> value. If the regenerative brake duty reaches 100%, a regenerative overvoltage (E. OV_) occurs.<br>Appears only for the FR-F720-03160 (FR-F740-01800) or more. |           |         |    |
| Check point                | <ul style="list-style-type: none"> <li>• Check that the brake resistor duty is not high.</li> <li>• Check that the <i>Pr. 30 Regenerative function selection</i> and <i>Pr. 70 Special regenerative brake duty</i> values are correct.</li> </ul>                                 |           |         |    |
| Corrective action          | <ul style="list-style-type: none"> <li>• Increase the deceleration time.</li> <li>• Check the <i>Pr. 30 Regenerative function selection</i> and <i>Pr. 70 Special regenerative brake duty</i> values.</li> </ul>                                                                  |           |         |    |

| Operation Panel Indication | TH                                                                                                                                                                                                                                                    | <i>TH</i> | FR-PU04 | TH |
|----------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------|---------|----|
| Name                       | Electronic thermal relay function prealarm                                                                                                                                                                                                            |           |         |    |
| Description                | Appears if the integrating value of the <i>Pr. 9 Electronic thermal O/L relay</i> reaches or exceeds 85% of the preset level. If it reaches 100% of the <i>Pr. 9 Electronic thermal O/L relay</i> setting, a motor overload shut-off (E. THM) occurs. |           |         |    |
| Check point                | 1. Check for large load or sudden acceleration.<br>2. Is the <i>Pr. 9 Electronic thermal O/L relay</i> setting is appropriate? (Refer to page 83.)                                                                                                    |           |         |    |
| Corrective action          | 1. Reduce the load weight or the number of operation times.<br>2. Set an appropriate value in <i>Pr. 9 Electronic thermal O/L relay</i> . (Refer to page 83.)                                                                                         |           |         |    |

| Operation Panel Indication | MT                                                                                                                                                   | <i>MT</i> | FR-PU04 | —— |
|----------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------|-----------|---------|----|
| Name                       | Maintenance signal output                                                                                                                            |           |         |    |
| Description                | Indicates that the cumulative energization time of the inverter has reached a given time.                                                            |           |         |    |
| Check point                | The <i>Pr. 503 Maintenance timer</i> setting is larger than the <i>Pr. 504 Maintenance timer alarm output set time</i> setting. (Refer to page 216.) |           |         |    |
| Corrective action          | Setting "0" in <i>Pr. 503 Maintenance timer</i> erases the signal.                                                                                   |           |         |    |

| Operation Panel Indication | CP                                                                                                                                                        | <i>CP</i> | FR-PU04 | —— |
|----------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------|-----------|---------|----|
| Name                       | Parameter copy                                                                                                                                            |           |         |    |
| Description                | Appears when parameters are copied between models with capacities of FR-F720-02330 (FR-F740-01160) or less and FR-F720-03160 (FR-F740-01800) or more.     |           |         |    |
| Check point                | Resetting of <i>Pr.9, Pr.30, Pr.51, Pr.52, Pr.54, Pr.56, Pr.57, Pr.61, Pr.70, Pr.72, Pr.80, Pr.90, Pr.158, Pr.190 to Pr.196, and Pr.893</i> is necessary. |           |         |    |
| Corrective action          | Set the initial value in <i>Pr. 989 Parameter copy alarm release</i> .                                                                                    |           |         |    |

## (3) Minor fault

When the protective function is activated, the output is not shut off. You can also output a minor fault signal by making parameter setting. (Set "98" in any of *Pr. 190 to Pr. 196 (output terminal function selection)*. (Refer to page 96.))

| Operation Panel Indication | FN                                                                                                                                                                                                                           | <i>Fn</i> | FR-PU04 | FN |
|----------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------|---------|----|
| Name                       | Fan fault                                                                                                                                                                                                                    |           |         |    |
| Description                | For the inverter that contains a cooling fan, <i>Fn</i> appears on the operation panel when the cooling fan stops due to a fault or different operation from the setting of <i>Pr. 244 Cooling fan operation selection</i> . |           |         |    |
| Check point                | Check the cooling fan for a fault.                                                                                                                                                                                           |           |         |    |
| Corrective action          | Check for fan fault. Please contact your sales representative.                                                                                                                                                               |           |         |    |

## (4) Major fault

When the protective function is activated, the inverter output is shut off and an alarm is output.

| Operation Panel Indication | E.OC1                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    | <i>E.OC 1</i> | FR-PU04 | OC During Accs |
|----------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------|---------|----------------|
| <b>Name</b>                | Overcurrent shut-off during acceleration                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |               |         |                |
| <b>Description</b>         | When the inverter output current reaches or exceeds approximately 170% of the rated current during acceleration, the protective circuit is activated to stop the inverter output.                                                                                                                                                                                                                                                                                                                                                                                                                        |               |         |                |
| <b>Check point</b>         | 1. Check for sudden acceleration.<br>2. Check that the downward acceleration time is not long in vertical lift application.<br>3. Check for output short circuit.<br>4. Check that the <i>Pr. 3 Base frequency</i> setting is not 60Hz when the motor rated frequency is 50Hz.<br>5. Check that stall prevention operation is correct<br>6. Check that the regeneration is not performed frequently. (Check that the output voltage becomes larger than the V/F reference voltage at regeneration and overcurrent due to increase in motor current occurs.)                                              |               |         |                |
| <b>Corrective action</b>   | 1. Increase the acceleration time.<br>(Shorten the downward acceleration time in vertical lift application.)<br>2. When "E.OC1" is always lit at starting, disconnect the motor once and start the inverter.<br>If "E.OC1" is still lit, contact your sales representative.<br>3. Check the wiring to avoid output short circuit.<br>4. Set the <i>Pr. 3 Base frequency</i> to 50Hz. (Refer to page 69.)<br>5. Perform a correct stall prevention operation. (Refer to page 69.)<br>6. Set base voltage (rated voltage of the motor, etc.) in <i>Pr. 19 Base frequency voltage</i> . (Refer to page 61.) |               |         |                |

| Operation Panel Indication | E.OC2                                                                                                                                                                                         | <i>E.OC 2</i> | FR-PU04 | Stedy Spd OC |
|----------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------|---------|--------------|
| <b>Name</b>                | Overcurrent shut-off during constant speed                                                                                                                                                    |               |         |              |
| <b>Description</b>         | When the inverter output current reaches or exceeds approximately 170% of the rated current during constant speed operation, the protective circuit is activated to stop the inverter output. |               |         |              |
| <b>Check point</b>         | 1. Check for sudden load change.<br>2. Check for output short circuit.<br>3. Check that stall prevention operation is correct                                                                 |               |         |              |
| <b>Corrective action</b>   | 1. Keep load stable.<br>2. Check the wiring to avoid output short circuit.<br>3. Check that stall prevention operation setting is correct. (Refer to page 61.)                                |               |         |              |

| Operation Panel Indication | E.OC3                                                                                                                                                                                                                                  | <i>E.OC 3</i> | FR-PU04 | OC During Dec |
|----------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------|---------|---------------|
| <b>Name</b>                | Overcurrent shut-off during deceleration or stop                                                                                                                                                                                       |               |         |               |
| <b>Description</b>         | When the inverter output current reaches or exceeds approximately 170% of the rated inverter current during deceleration (other than acceleration or constant speed), the protective circuit is activated to stop the inverter output. |               |         |               |
| <b>Check point</b>         | 1. Check for sudden speed reduction.<br>2. Check for output short circuit.<br>3. Check for too fast operation of the motor's mechanical brake.<br>4. Check that stall prevention operation setting is correct.                         |               |         |               |
| <b>Corrective action</b>   | 1. Increase the deceleration time.<br>2. Check the wiring to avoid output short circuit.<br>3. Check the mechanical brake operation.<br>4. Check that stall prevention operation setting is correct. (Refer to page 61.)               |               |         |               |

| Operation Panel Indication | E.OV1                                                                                                                                                                                                                                                                            | <i>E.OV 1</i> | FR-PU04 | OV During Acc |
|----------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------|---------|---------------|
| <b>Name</b>                | Regenerative overvoltage shutoff during acceleration                                                                                                                                                                                                                             |               |         |               |
| <b>Description</b>         | If regenerative energy causes the inverter's internal main circuit DC voltage to reach or exceed the specified value, the protective circuit is activated to stop the inverter output. The circuit may also be activated by a surge voltage produced in the power supply system. |               |         |               |
| <b>Check point</b>         | Check for too slow acceleration. (e.g. during descending acceleration with lifting load)                                                                                                                                                                                         |               |         |               |
| <b>Corrective action</b>   | · Decrease the acceleration time.<br>· Use regeneration avoidance function ( <i>Pr. 882 to Pr. 886</i> ). (Refer to page 211.)                                                                                                                                                   |               |         |               |



| Operation Panel Indication | E.OV2                                                                                                                                                                                                                                                                            | <i>E.Ov2</i> | FR-PU04 | Stedy Spd OV |
|----------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------|---------|--------------|
| <b>Name</b>                | Regenerative overvoltage shut-off during constant speed                                                                                                                                                                                                                          |              |         |              |
| <b>Description</b>         | If regenerative energy causes the inverter's internal main circuit DC voltage to reach or exceed the specified value, the protective circuit is activated to stop the inverter output. The circuit may also be activated by a surge voltage produced in the power supply system. |              |         |              |
| <b>Check point</b>         | Check for sudden load change.                                                                                                                                                                                                                                                    |              |         |              |
| <b>Corrective action</b>   | <ul style="list-style-type: none"> <li>Keep load stable.</li> <li>Use regeneration avoidance function (<i>Pr. 882 to Pr. 886</i>). (<i>Refer to page 211.</i>)</li> <li>Use the brake unit or power regeneration common converter (FR-CV) as required.</li> </ul>                |              |         |              |

| Operation Panel Indication | E.OV3                                                                                                                                                                                                                                                                                                                                                                                           | <i>E.Ov3</i> | FR-PU04 | OV During Dec |
|----------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------|---------|---------------|
| <b>Name</b>                | Regenerative overvoltage shut-off during deceleration or stop                                                                                                                                                                                                                                                                                                                                   |              |         |               |
| <b>Description</b>         | If regenerative energy causes the inverter's internal main circuit DC voltage to reach or exceed the specified value, the protective circuit is activated to stop the inverter output. The circuit may also be activated by a surge voltage produced in the power supply system.                                                                                                                |              |         |               |
| <b>Check point</b>         | Check for sudden speed reduction.                                                                                                                                                                                                                                                                                                                                                               |              |         |               |
| <b>Corrective action</b>   | <ul style="list-style-type: none"> <li>Increase the deceleration time. (Set the deceleration time which matches the inertia of moment of the load)</li> <li>Decrease the braking duty.</li> <li>Use regeneration avoidance function (<i>Pr. 882 to Pr. 886</i>). (<i>Refer to page 211.</i>)</li> <li>Use the brake unit or power regeneration common converter (FR-CV) as required.</li> </ul> |              |         |               |

| Operation Panel Indication | E.THT                                                                                                                                                                                                                                                                                                              | <i>E.THT</i> | FR-PU04 | Inv. Overload |
|----------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------|---------|---------------|
| <b>Name</b>                | Inverter overload shut-off (electronic thermal relay function)*3                                                                                                                                                                                                                                                   |              |         |               |
| <b>Description</b>         | If a current not less than 110%*2 of the rated output current flows and overcurrent shut-off does not occur (170% or less), inverse-time characteristics cause the electronic thermal relay to be activated to stop the inverter output in order to protect the output transistors. (overload immunity 110%*2 60s) |              |         |               |
| <b>Check point</b>         | Check the motor for use under overload.                                                                                                                                                                                                                                                                            |              |         |               |
| <b>Corrective action</b>   | Reduce the load weight.                                                                                                                                                                                                                                                                                            |              |         |               |

\*2 120% when LD is selected

| Operation Panel Indication | E.THM                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | <i>E.THM</i> | FR-PU04 | Motor Ovrload |
|----------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------|---------|---------------|
| <b>Name</b>                | Motor overload shut-off (electronic thermal relay function)*3                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |              |         |               |
| <b>Description</b>         | The electronic thermal relay function in the inverter detects motor overheat due to overload or reduced cooling capability during constant-speed operation and pre-alarm (TH display) is output when the temperature reaches 85% of the <i>Pr. 9 Electronic thermal O/L relay</i> setting and the protection circuit is activated to stop the inverter output when the temperature reaches the specified value. When running a special motor such as a multi-pole motor or multiple motors, provide a thermal relay on the inverter output side since such motor(s) cannot be protected by the electronic thermal relay function. |              |         |               |
| <b>Check point</b>         | <ol style="list-style-type: none"> <li>Check the motor for use under overload.</li> <li>Check that the setting of <i>Pr. 71 Applied motor</i> for motor selection is correct. (<i>Refer to page 85.</i>)</li> <li>Check that stall prevention operation setting is correct.</li> </ol>                                                                                                                                                                                                                                                                                                                                            |              |         |               |
| <b>Corrective action</b>   | <ol style="list-style-type: none"> <li>Reduce the load weight.</li> <li>For a constant-torque motor, set the constant-torque motor in <i>Pr. 71 Applied motor</i>.</li> <li>Check that stall prevention operation setting is correct. (<i>Refer to page 61.</i>)</li> </ol>                                                                                                                                                                                                                                                                                                                                                       |              |         |               |

\*3 Resetting the inverter initializes the internal thermal integrated data of the electronic thermal relay function.



| Operation Panel Indication | E.FIN                                                                                      | <i>E.FI n</i> | FR-PU04 | H/Sink O/Temp |
|----------------------------|--------------------------------------------------------------------------------------------|---------------|---------|---------------|
| Name                       | Fin overheat                                                                               |               |         |               |
| Description                | If the heatsink overheats, the temperature sensor is actuated to stop the inverter output. |               |         |               |
| Check point                | 1. Check for too high ambient temperature.<br>2. Check for heatsink clogging.              |               |         |               |
| Corrective action          | 1. Set the ambient temperature to within the specifications.<br>2. Clean the heatsink.     |               |         |               |

| Operation Panel Indication | E.IPF                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    | <i>E.I PF</i> | FR-PU04 | Inst. Pwr. Loss |
|----------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------|---------|-----------------|
| Name                       | Instantaneous power failure protection                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |               |         |                 |
| Description                | If a power failure occurs for longer than 15ms (this also applies to inverter input shut-off), the instantaneous power failure protective function is activated to stop the inverter output in order to prevent the control circuit from malfunctioning. If a power failure persists for longer than 100ms, the alarm warning output is not provided, and the inverter restarts if the start signal is on upon power restoration. (The inverter continues operating if an instantaneous power failure is within 15ms.) In some operating status (load magnitude, acceleration/deceleration time setting, etc.), overcurrent or other protection may be activated upon power restoration. |               |         |                 |
| Check point                | Find the cause of instantaneous power failure occurrence.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |               |         |                 |
| Corrective action          | <ul style="list-style-type: none"> <li>Remedy the instantaneous power failure.</li> <li>Prepare a backup power supply for instantaneous power failure.</li> <li>Set the function of automatic restart after instantaneous power failure (<i>Pr. 57</i>). (<i>Refer to page 114.</i>)</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                          |               |         |                 |

| Operation Panel Indication | E.BE                                                                                                                                                                                                                                                                                                                                                           | <i>E. bE</i> | FR-PU04 | Br. Cct. Fault |
|----------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------|---------|----------------|
| Name                       | Brake transistor alarm detection                                                                                                                                                                                                                                                                                                                               |              |         |                |
| Description                | This function stops the inverter output if an alarm occurs in the brake circuit, e.g. damaged brake transistors when using functions of the FR-F720-03160 (FR-F740-01800) or more.<br><u>In this case, the inverter must be powered off immediately.</u><br>For the FR-F720-02330 (FR-F740-01160) or less, it appears when an internal circuit error occurred. |              |         |                |
| Check point                | <ul style="list-style-type: none"> <li>Reduce the load inertia.</li> <li>Check that the frequency of using the brake is proper.</li> <li>Check that the brake resistor selected is correct.</li> </ul>                                                                                                                                                         |              |         |                |
| Corrective action          | For the FR-F720-03160 (FR-F740-01800) or more, when the protective function is activated even if the above measures are taken, replace the brake unit with a new one.<br>For the FR-F720-02330 (FR-F740-01160) or less, replace the inverter.                                                                                                                  |              |         |                |

| Operation Panel Indication | E.UVT                                                                                                                                                                                                                                                                                                                                                                                                                                               | <i>E.UvT</i> | FR-PU04 | Under Voltage |
|----------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------|---------|---------------|
| Name                       | Undervoltage protection                                                                                                                                                                                                                                                                                                                                                                                                                             |              |         |               |
| Description                | If the power supply voltage of the inverter reduces, the control circuit will not perform normal functions. In addition, the motor torque will be insufficient and/or heat generation will increase. To prevent this, if the power supply voltage reduces below about 150V (300VAC for the 400V class), this function stops the inverter output.<br>When a jumper is not connected across P/+P1, the undervoltage protective function is activated. |              |         |               |
| Check point                | 1. Check for start of large-capacity motor.<br>2. Check that a jumper or DC reactor is connected across terminals P/+P1.                                                                                                                                                                                                                                                                                                                            |              |         |               |
| Corrective action          | 1. Check the power supply system equipment such as the power supply.<br>2. Connect a jumper or DC reactor across terminals P/+P1.<br>3. If the problem still persists after taking the above measure, please contact your sales representative.                                                                                                                                                                                                     |              |         |               |

| Operation Panel Indication | E.ILF                                                                                                                                                                                                         | <i>E.I L F</i> | FR-PU04 | Fault 14 |
|----------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------|---------|----------|
| Name                       | Input phase failure                                                                                                                                                                                           |                |         |          |
| Description                | This alarm is output when function valid setting (=1) is set in <i>Pr.872 Input phase failure protection selection</i> and one phase of the three phase power input opens. ( <i>Refer to page 122.</i> )      |                |         |          |
| Check point                | Check for a break in the cable for the three-phase power supply input.                                                                                                                                        |                |         |          |
| Corrective action          | <ul style="list-style-type: none"> <li>Wire the cables properly.</li> <li>Repair a brake portion in the cable.</li> <li>Check the <i>Pr. 872 Input phase failure protection selection</i> setting.</li> </ul> |                |         |          |



| Operation Panel Indication | E.OLT                                                                                                                                                                                                 | <i>E.OLF</i> | FR-PU04 | Still Prev STP ( OL shown during stall prevention operation) |
|----------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------|---------|--------------------------------------------------------------|
| Name                       | Stall prevention                                                                                                                                                                                      |              |         |                                                              |
| Description                | If the frequency has fallen to 0.5Hz by stall prevention operation and remains for 3s, an alarm (E.OLT) appears to shutoff the inverter output. OL appears while stall prevention is being activated. |              |         |                                                              |
| Check point                | · Check the motor for use under overload. (Refer to page 62.)                                                                                                                                         |              |         |                                                              |
| Corrective action          | · Reduce the load weight.                                                                                                                                                                             |              |         |                                                              |

| Operation Panel Indication | E.GF                                                                                                                                                   | <i>E. GF</i> | FR-PU04 | Ground Fault |
|----------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------|--------------|---------|--------------|
| Name                       | Output side ground fault overcurrent protection                                                                                                        |              |         |              |
| Description                | This function stops the inverter output if a ground fault overcurrent flows due to an ground fault that occurred on the inverter's output (load) side. |              |         |              |
| Check point                | Check for a ground fault in the motor and connection cable.                                                                                            |              |         |              |
| Corrective action          | Remedy the ground fault portion.                                                                                                                       |              |         |              |

| Operation Panel Indication | E.LF                                                                                                                                          | <i>E. LF</i> | FR-PU04 | — |
|----------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------|--------------|---------|---|
| Name                       | Output phase failure protection                                                                                                               |              |         |   |
| Description                | This function stops the inverter output if one of the three phases (U, V, W) on the inverter's output side (load side) opens.                 |              |         |   |
| Check point                | · Check the wiring (Check that the motor is normal.)<br>· Check that the capacity of the motor used is not smaller than that of the inverter. |              |         |   |
| Corrective action          | · Wire the cables properly.<br>· Check the <i>Pr. 251 Output phase failure protection selection</i> setting.                                  |              |         |   |

| Operation Panel Indication | E.OHT                                                                                                                                                                                                | <i>E.OHT</i> | FR-PU04 | OH Fault |
|----------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------|---------|----------|
| Name                       | External thermal relay operation *4                                                                                                                                                                  |              |         |          |
| Description                | If the external thermal relay provided for motor overheating protection, or the internally mounted temperature relay in the motor, etc. switches on (contacts open), the inverter output is stopped. |              |         |          |
| Check point                | · Check for motor overheating.<br>· Check that the value of 7 (OH signal) is set correctly in any of <i>Pr. 178 to Pr. 189 (input terminal function selection)</i> .                                 |              |         |          |
| Corrective action          | · Reduce the load and operating duty.<br>· Even if the relay contacts are reset automatically, the inverter will not restart unless it is reset.                                                     |              |         |          |

\*4 Functions only when any of *Pr. 178 to Pr. 189 (input terminal function selection)* is set to OH.

| Operation Panel Indication | E.PTC                                                                                                                                                                                                                                              | <i>E.PTC</i> | FR-PU04 | Fault 14 |
|----------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------|---------|----------|
| Name                       | PTC thermistor operation                                                                                                                                                                                                                           |              |         |          |
| Description                | Appears when the motor overheating status is detected for 10s or more by the external PTC thermistor input connected to the terminal AU.                                                                                                           |              |         |          |
| Check point                | · Check the connection between the PTC thermistor switch and thermal protector.<br>· Check the motor for operation under overload.<br>· Is valid setting (=63) selected in <i>Pr. 184 AU terminal function selection ? (Refer to page 84, 96.)</i> |              |         |          |
| Corrective action          | Reduce the load weight.                                                                                                                                                                                                                            |              |         |          |

| Operation Panel Indication | E.OPT                                                                                                                                                                                                                                                        | <i>E.OPT</i> | FR-PU04 | Option Fault |
|----------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------|---------|--------------|
| Name                       | Option alarm                                                                                                                                                                                                                                                 |              |         |              |
| Description                | Appears when the AC power supply is connected to the terminal R/L1, S/L2, T/L3 accidentally when a high power factor converter is connected.                                                                                                                 |              |         |              |
| Check point                | · Check that the AC power supply is not connected to the terminal R/L1, S/L2, T/L3 when a high power factor converter (FR-HC, MT-HC) or power regenerative common converter (FR-CV) is connected.                                                            |              |         |              |
| Corrective action          | · Check the parameter ( <i>Pr. 30</i> ) setting and wiring.<br>· The inverter may be damaged if the AC power supply is connected to the terminal R/L1, S/L2, T/L3 when a high power factor converter is connected. Please contact your sales representative. |              |         |              |

| Operation Panel Indication | E.OP1                                                                                                                                                                                                                                                                                                                                                            | <i>E.OP 1</i> | FR-PU04 | Option slot alarm 1 |
|----------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------|---------|---------------------|
| Name                       | Option slot alarm (e.g.communication error)                                                                                                                                                                                                                                                                                                                      |               |         |                     |
| Description                | Stops the inverter output if a functional error (e.g. communication line error of the communication option or contact fault of the plug-in option other than the communication option) occurs in the plug-in option fitted to the option slot.                                                                                                                   |               |         |                     |
| Check point                | <ul style="list-style-type: none"> <li>Check for a wrong option function setting and operation.</li> <li>Check that the plug-in option is plugged into the connector securely.</li> <li>Check for a brake in the communication cable.</li> <li>Check that the terminating resistor is fitted properly.</li> <li>Check that the option card is normal.</li> </ul> |               |         |                     |
| Corrective action          | <ul style="list-style-type: none"> <li>Check the option function setting, etc.</li> <li>Connect the plug-in option securely.</li> </ul>                                                                                                                                                                                                                          |               |         |                     |

| Operation Panel Indication | E. 1                                                                                                                                                                                                                                                                                                                             | <i>E. 1</i> | FR-PU04 | Fault 1 |
|----------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------|---------|---------|
| Name                       | Option alarm (e.g.connection or contact fault)                                                                                                                                                                                                                                                                                   |             |         |         |
| Description                | Stops the inverter output if a contact fault or the like of the connector between the inverter and communication option occurs.                                                                                                                                                                                                  |             |         |         |
| Check point                | <ol style="list-style-type: none"> <li>Check that the plug-in option is plugged into the connector securely.</li> <li>Check for excess electrical noises around the inverter.</li> </ol>                                                                                                                                         |             |         |         |
| Corrective action          | <ol style="list-style-type: none"> <li>Connect the plug-in option securely.</li> <li>Take measures against noises if there are devices producing excess electrical noises around the inverter. If the problem still persists after taking the above measure, please contact your sales representative or distributor.</li> </ol> |             |         |         |

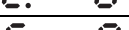
| Operation Panel Indication | E.PE                                                                                                                                                                                                                                                      | <i>E. PE</i> | FR-PU04 | Corrupt Memry |
|----------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------|---------|---------------|
| Name                       | Parameter storage device alarm (control circuit board)                                                                                                                                                                                                    |              |         |               |
| Description                | A fault occurred in parameters stored (EEPROM failure)                                                                                                                                                                                                    |              |         |               |
| Check point                | Check for too many number of parameter write times.                                                                                                                                                                                                       |              |         |               |
| Corrective action          | <p>Please contact your sales representative.</p> <p>When performing parameter write frequently for communication purposes, set "1" in <i>Pr. 342</i> to enable RAM write. Note that powering off returns the inverter to the status before RAM write.</p> |              |         |               |

| Operation Panel Indication | E.PE2                                                  | <i>E.PE2</i> | FR-PU04 | Fault 14 |
|----------------------------|--------------------------------------------------------|--------------|---------|----------|
| Name                       | Parameter storage device alarm (main circuit board)    |              |         |          |
| Description                | A fault occurred in parameters stored (EEPROM failure) |              |         |          |
| Check point                | _____                                                  |              |         |          |
| Corrective action          | Please contact your sales representative.              |              |         |          |

| Operation Panel Indication | E.PUE                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | <i>E.PUE</i> | FR-PU04 | PU Leave Out |
|----------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------|---------|--------------|
| Name                       | PU disconnected                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |              |         |              |
| Description                | This function stops the inverter output if communication between the inverter and PU is suspended, e.g. the operation panel and parameter unit is disconnected, when "2", "3", "16" or "17" was set in <i>Pr. 75 Reset selection/disconnected PU detection/PU stop selection</i> . This function stops the inverter output when communication errors occurred consecutively for more than permissible number of retries when a value other than "9999" is set in <i>Pr. 121 Number of PU communication retries</i> during the RS-485 communication with the PU connector. This function also stops the inverter output if communication is broken for the period of time set in <i>Pr. 122 PU communication check time interval</i> . |              |         |              |
| Check point                | <ul style="list-style-type: none"> <li>Check that the FR-DU07 or parameter unit (FR-PU04) is fitted tightly.</li> <li>Check the <i>Pr. 75</i> setting.</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |              |         |              |
| Corrective action          | Fit the FR-DU07 or parameter unit (FR-PU04) securely.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |              |         |              |

| Operation Panel Indication | E.RET                                                                                                              | <i>E.r ET</i> | FR-PU04 | Retry No Over |
|----------------------------|--------------------------------------------------------------------------------------------------------------------|---------------|---------|---------------|
| Name                       | Retry count excess                                                                                                 |               |         |               |
| Description                | If operation cannot be resumed properly within the number of retries set, this function stops the inverter output. |               |         |               |
| Check point                | Find the cause of alarm occurrence.                                                                                |               |         |               |
| Corrective action          | Eliminate the cause of the error preceding this error indication.                                                  |               |         |               |



|                            |                                                                                                                                                                                                                 |                                                                                   |         |           |
|----------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------|---------|-----------|
| Operation Panel Indication | E. 6                                                                                                                                                                                                            |  | FR-PU04 | Fault 6   |
|                            | E. 7                                                                                                                                                                                                            |  |         | Fault 7   |
|                            | E.CPU                                                                                                                                                                                                           |  |         | CPU Fault |
| Name                       | CPU fault                                                                                                                                                                                                       |                                                                                   |         |           |
| Description                | Stops the inverter output if the communication error of the built-in CPU occurs.                                                                                                                                |                                                                                   |         |           |
| Check point                | Check for devices producing excess electrical noises around the inverter.                                                                                                                                       |                                                                                   |         |           |
| Corrective action          | <ul style="list-style-type: none"><li>· Take measures against noises if there are devices producing excess electrical noises around the inverter.</li><li>· Please contact your sales representative.</li></ul> |                                                                                   |         |           |

|                            |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |       |         |   |
|----------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------|---------|---|
| Operation Panel Indication | E.CTE                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           | E.CTE | FR-PU04 | — |
| Name                       | Operation panel power supply short circuit, RS-485 terminal power supply short circuit                                                                                                                                                                                                                                                                                                                                                                                                                          |       |         |   |
| Description                | <p>When the operation panel power supply (PU connector) is shorted, this function shuts off the power output. At this time, the operation panel (parameter unit) cannot be used and RS-485 communication from the PU connector cannot be made. When the power supply for the RS-485 terminals are shorted, this function shuts off the power output.</p> <p>At this time, communication from the RS-485 terminals cannot be made.</p> <p>To reset, enter the RES signal or switch power off, then on again.</p> |       |         |   |
| Check point                | <ol style="list-style-type: none"> <li>Check for a short circuit in the PU connector cable.</li> <li>Check that the RS-485 terminals are connected correctly.</li> </ol>                                                                                                                                                                                                                                                                                                                                        |       |         |   |
| Corrective action          | <ol style="list-style-type: none"> <li>Check the PU and cable.</li> <li>Check the connection of the RS-485 terminals</li> </ol>                                                                                                                                                                                                                                                                                                                                                                                 |       |         |   |

|                            |                                                                                                                                                                                                                                                                                                       |       |         |       |
|----------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------|---------|-------|
| Operation Panel Indication | E.P24                                                                                                                                                                                                                                                                                                 | E.P24 | FR-PU04 | E.P24 |
| Name                       | 24VDC power output short circuit                                                                                                                                                                                                                                                                      |       |         |       |
| Description                | <p>When the 24VDC power output from the PC terminal is shorted, this function shuts off the power output. At this time, all external contact inputs switch off. The inverter cannot be reset by entering the RES signal. To reset it, use the operation panel or switch power off, then on again.</p> |       |         |       |
| Check point                | <ul style="list-style-type: none"> <li>Check for a short circuit in the PC terminal output.</li> </ul>                                                                                                                                                                                                |       |         |       |
| Corrective action          | <ul style="list-style-type: none"> <li>Remedy the ground fault portion.</li> </ul>                                                                                                                                                                                                                    |       |         |       |

|                            |                                                                                                                                                                                                                                                                                      |       |         |          |
|----------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------|---------|----------|
| Operation Panel Indication | E.CDO                                                                                                                                                                                                                                                                                | E.CDO | FR-PU04 | Fault 14 |
| Name                       | Output current detection value excess                                                                                                                                                                                                                                                |       |         |          |
| Description                | This function is activated when the output current exceeds the <i>Pr. 150 Output current detection level</i> setting.                                                                                                                                                                |       |         |          |
| Check point                | Check the settings of <i>Pr. 150 Output current detection level</i> , <i>Pr. 151 Output current detection signal delay time</i> , <i>Pr. 166 Output current detection signal retention time</i> , <i>Pr. 167 Output current detection operation selection</i> . (Refer to page 101.) |       |         |          |

|                            |                                                                                                                                                                                                                                                                               |       |         |          |
|----------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------|---------|----------|
| Operation Panel Indication | E.IOH                                                                                                                                                                                                                                                                         | E.IOH | FR-PU04 | Fault 14 |
| Name                       | Inrush resistance overheat                                                                                                                                                                                                                                                    |       |         |          |
| Description                | This function is activated when the resistor of the inrush current limit circuit overheats.                                                                                                                                                                                   |       |         |          |
| Check point                | <ol style="list-style-type: none"> <li>Check that the inrush current is not large.</li> <li>Check that frequent ON/OFF is not repeated in the circuit which starts upon powering on.</li> </ol>                                                                               |       |         |          |
| Corrective action          | <ol style="list-style-type: none"> <li>The inrush current limit circuit failure</li> <li>Configure a circuit where frequent ON/OFF is not repeated.</li> </ol> <p>If the problem still persists after taking the above measure, please contact your sales representative.</p> |       |         |          |

| Operation Panel Indication | E.SER                                                                                                                                                                                                                                                                                                                                                                                                                                             | <i>E.SEr</i> | FR-PU04 | Fault 14 |
|----------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------|---------|----------|
| Name                       | Communication error (inverter)                                                                                                                                                                                                                                                                                                                                                                                                                    |              |         |          |
| Description                | This function stops the inverter output when communication error occurs consecutively for more than permissible retry count when a value other than "9999" is set in <i>Pr. 335 RS-485 communication number of retries</i> during RS-485 communication from the RS-485 terminals. This function also stops the inverter output if communication is broken for the period of time set in <i>Pr. 336 RS-485 communication check time interval</i> . |              |         |          |
| Check point                | Check the RS-485 terminal wiring.                                                                                                                                                                                                                                                                                                                                                                                                                 |              |         |          |
| Corrective action          | Perform wiring of the RS-485 terminals properly.                                                                                                                                                                                                                                                                                                                                                                                                  |              |         |          |

| Operation Panel Indication | E.AIE                                                                                                                                                                            | <i>E.AIE</i> | FR-PU04 | Fault 14 |
|----------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------|---------|----------|
| Name                       | Analog input error                                                                                                                                                               |              |         |          |
| Description                | Appears when 30mA or more is input or a voltage (7.5V or more) is input with the terminal 2/4 set to current input.                                                              |              |         |          |
| Check point                | Check the setting of <i>Pr. 73 Analog input selection</i> and <i>Pr. 267 Terminal 4 input selection</i> . (Refer to page 130.)                                                   |              |         |          |
| Corrective action          | Either give a frequency command by current input or set <i>Pr. 73 Analog input selection</i> or <i>Pr. 267 Terminal 4 input selection</i> to voltage input. (Refer to page 130.) |              |         |          |

| Operation Panel Indication | E.13                                             | <i>E. 13</i> | FR-PU07 | Fault 14 |
|----------------------------|--------------------------------------------------|--------------|---------|----------|
| Name                       | Internal circuit error                           |              |         |          |
| Description                | Appears when an internal circuit error occurred. |              |         |          |
| Corrective action          | Please contact your sales representative.        |              |         |          |

#### CAUTION

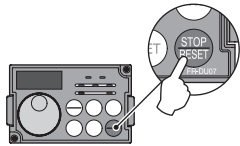
- If protective functions of E.ILF, E.PTC, E.PE2, E.CDO, E.IOH, E.SER, E.AIE, E.13 are activated when using the FR-PU04, "Fault 14" appears.  
Also when the alarm history is checked on the FR-PU04, the display is "E.14".
- If alarms other than the above appear, contact your sales representative.

### 4.3 Reset method of protective function

(1) Resetting the inverter

The inverter can be reset by performing any of the following operations. Note that the internal thermal integrated value of the electronic thermal relay function and the number of retries are cleared (erased) by resetting the inverter. It takes about 1s for reset.

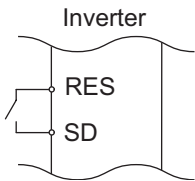
- Operation 1: ..... Using the operation panel, press  to reset the inverter.  
(Enabled only when the inverter protective function is activated (major fault) (Refer to *page 235* for major fault.))



- Operation 2: ..... Switch power off once, then switch it on again.



- Operation 3: ..... Turn on the reset signal (RES) for more than 0.1s. (If the RES signal is kept on, "Err." appears (flickers) to indicate that the inverter is in a reset status.)



### 4.4 Correspondences between digital and actual characters

There are the following correspondences between the actual alphanumeric characters and the digital characters displayed on the operation panel.

| Actual | Digital | Actual | Digital | Actual | Digital |
|--------|---------|--------|---------|--------|---------|
| 0      | 0       | A      | A       | M      | n       |
| 1      | 1       | B      | b       | N      | n       |
| 2      | 2       | C      | C       | O      | 0       |
| 3      | 3       | D      | d       | o      | o       |
| 4      | 4       | E      | E       | P      | P       |
| 5      | 5       | F      | F       | S      | S       |
| 6      | 6       | G      | G       | T      | r       |
| 7      | 7       | H      | H       | U      | U       |
| 8      | 8       | I      | I       | V      | U       |
| 9      | 9       | J      | J       | r      | r       |
|        |         | L      | L       | -      | -       |

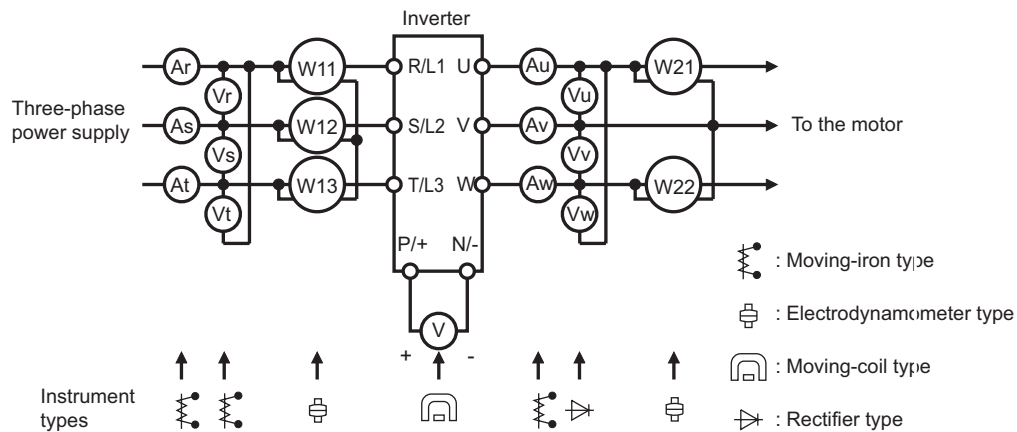
## 4.5 Meters and measuring methods

Since voltages and currents in the primary and secondary side of the inverter include harmonics, different meters indicate different measurement values. When making measurement with the meters designed for commercial frequency, use the following measuring instruments and circuits:

- When installing meters etc. on the inverter output side

When the inverter-to-motor wiring length is large, especially in the 400V class, small-capacity models, the meters and CTs may generate heat due to line-to-line leakage current. Therefore, choose the equipment which has enough allowance for the current rating.

When measuring and indicating the output voltage and output current of the inverter, it is recommended to utilize the AM-5 and CA-5 terminal output function of the inverter.



### 4.5.1 Measurement of powers

Using an electro-dynamometer type meter, measure the power in both the input and output sides of the inverter using the two- or three-wattmeter method. As the current is liable to be imbalanced especially in the input side, it is recommended to use the three-wattmeter method.

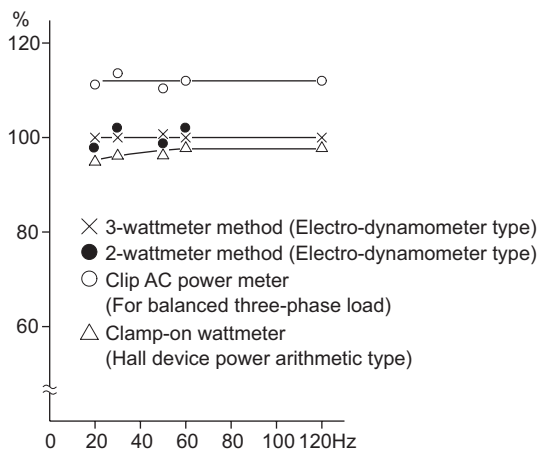
Examples of process value differences produced by different measuring meters are shown below.

An error will be produced by difference between measuring instruments, e.g. power calculation type and two- or three-wattmeter type three-phase wattmeter. When a CT is used in the current measuring side or when the meter contains a PT on the voltage measurement side, an error will also be produced due to the frequency characteristics of the CT and PT.

#### [Measurement conditions]

Constant-torque (100%) load, constant-output at 60Hz or more.

3.7kW(5HP), 4-pole motor, value indicated in 3-wattmeter method is 100%.

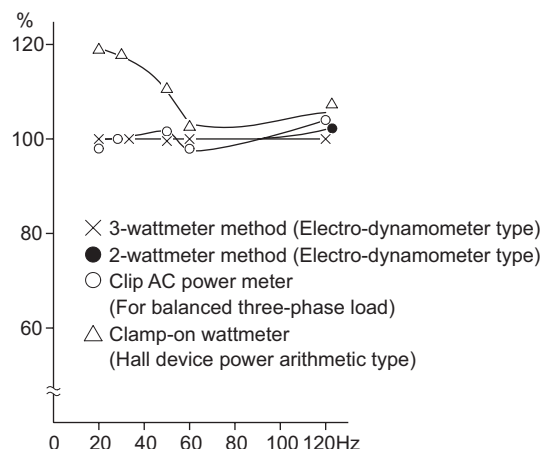


Example of measuring inverter input power

#### [Measurement conditions]

Constant-torque (100%) load, constant-output at 60Hz or more.

3.7kW(5HP), 4-pole motor, value indicated in 3-wattmeter method is 100%.



Example of measuring inverter output power



### 4.5.2 Measurement of voltages and use of PT

#### (1) Inverter input side

As the input side voltage has a sine wave and it is extremely small in distortion, accurate measurement can be made with an ordinary AC meter.

#### (2) Inverter output side

Since the output side voltage has a PWM-controlled rectangular wave, always use a rectifier type voltmeter. A needle type tester can not be used to measure the output side voltage as it indicates a value much greater than the actual value. A moving-iron type meter indicates an effective value which includes harmonics and therefore the value is larger than that of the fundamental wave. The value monitored on the operation panel is the inverter-controlled voltage itself. Hence, that value is accurate and it is recommended to monitor values (provide analog output) using the operation panel.

#### (3) PT

No PT can be used in the output side of the inverter. Use a direct-reading meter. (A PT can be used in the input side of the inverter.)

### 4.5.3 Measurement of currents

Use a moving-iron type meter on both the input and output sides of the inverter. However, if the carrier frequency exceeds 5kHz, do not use that meter since an overcurrent loss produced in the internal metal parts of the meter will increase and the meter may burn out. In this case, use an approximate-effective value type.

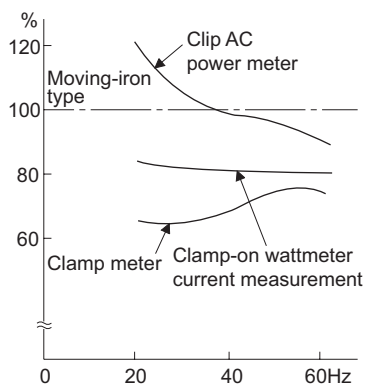
As the inverter input side current is easily imbalanced, measurement of currents in all three phases is recommended. Correct values can not be measured in one or two phases. On the other hand, the phase imbalanced ratio of the output side current must be within 10%.

When a clamp ammeter is used, always use an effective value detection type. A mean value detection type produces a large error and may indicate an extremely smaller value than the actual value. The value monitored on the operation panel is accurate if the output frequency varies, and it is recommended to monitor values (provide analog output) using the operation panel.

An example of the measurement value difference produced by different measuring meters is shown below.

#### [Measurement conditions]

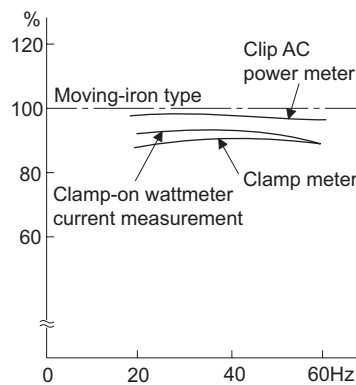
Value indicated by moving-iron type ammeter is 100%.



Example of measuring Inverter Input Current

#### [Measurement conditions]

Value indicated by moving-iron type ammeter is 100%.



Example of measuring Inverter Output Current

#### 4.5.4 Use of CT and transducer

A CT may be used in both the input and output sides of the inverter, but the one used should have the largest possible VA ability because an error will increase if the frequency gets lower.  
When using a transducer, use the effective value calculation type which is immune to harmonics.

#### 4.5.5 Measurement of inverter input power factor

Use the effective power and apparent power to calculate the inverter input power factor. A power-factor meter can not indicate an exact value.

$$\begin{aligned}\text{Total power factor of the inverter} &= \frac{\text{Effective power}}{\text{Apparent power}} \\ &= \frac{\text{Three-phase input power found by 3-wattmeter method}}{\sqrt{3} \times V \text{ (power supply voltage)} \times I \text{ (input current effective value)}}\end{aligned}$$

#### 4.5.6 Measurement of converter output voltage (across terminals P/+ - N/-)

The output voltage of the converter is developed across terminals P/+ - N/- and can be measured with a moving-coil type meter (tester). Although the voltage varies according to the power supply voltage, approximately 270V to 300V (approximately 540V to 600V for the 400V class) is output when no load is connected and voltage decreases when a load is connected.

When regenerative energy is returned from the motor during deceleration, for example, the converter output voltage rises to nearly 400V to 450V (800V to 900V for the 400V class) maximum.



## 4.6 Check first when you have troubles.

### POINT

If the cause is still unknown after every check, it is recommended to initialize the parameters (initial value) then re-set the required parameter values and check again.

### 4.6.1 Motor does not rotate as commanded

1) Check the *Pr. 0 Torque boost*. (Refer to page 58)

2) Check the main circuit.

- Check that a proper power supply voltage is applied (operation panel display is provided).
- Check that the motor is connected properly.
- Check that the jumper across P/+ - P1 is connected.

3) Check the input signals

- Check that the start signal is input.
- Check that both the forward and reverse rotation start signals are not input simultaneously.
- Check that the frequency setting signal is not zero. (When the frequency command is 0Hz and the run command is entered, FWD or REV LED on the operation panel flickers.)
- Check that the AU signal is on when the frequency setting signal is 4 to 20mA.
- Check that the output stop signal (MRS) or reset signal (RES) is not on.
- Check that the CS signal is not OFF with automatic restart after instantaneous power failure function is selected (*Pr. 57* ≠ "9999").
- Check that the sink or source jumper connector is fitted securely.

4) Check the parameter settings

- Check that the reverse rotation prevention selection (*Pr. 78*) is not selected.
- Check that the operation mode selection (*Pr. 79*) setting is correct.
- Check that the bias and gain (*calibration parameter C2 to C7*) settings are correct.
- Check that the starting frequency (*Pr. 13*) setting is not greater than the running frequency.
- Check that frequency settings of each running frequency (such as multi-speed operation) are not zero.
- Check that especially the maximum frequency (*Pr. 1*) is not zero.
- Check that the *Pr. 15 Jog frequency* setting is not lower than the *Pr. 13 Starting frequency* value.

5) Inspection of load

- Check that the load is not too heavy.
- Check that the shaft is not locked.

### 4.6.2 Motor generates abnormal noise

- No carrier frequency noises (metallic noises) are generated.
  - Soft-PWM operation to change the motor tone into an unoffending complex tone is factory-set to valid by the *Pr. 72 PWM frequency selection*.  
Adjust *Pr. 72 PWM frequency selection* to change the motor tone.  
(When operating the inverter with the carrier frequency of 3kHz or more set in *Pr. 72*, the carrier frequency will automatically decrease if the output current of the inverter exceeds the value in parenthesis of the rated output current on page 250. This may cause the motor noise to increase. But it is not a fault.)
- Check for any mechanical looseness.
- Contact the motor manufacturer.

### 4.6.3 Motor generates heat abnormally

- Is the fan for the motor is running? (Check for accumulated dust.)
- Check that the load is not too heavy. Lighten the load.
- Check that the inverter output voltages (U, V, W) balanced.
- Check that the *Pr. 0 Torque boost* setting is correct.



#### 4.6.4 Motor rotates in opposite direction

- Check that the phase sequence of output terminals U, V and W is correct.
- Check that the start signals (forward rotation, reverse rotation) are connected properly. (Refer to page 94)

#### 4.6.5 Speed greatly differs from the setting

- Check that the frequency setting signal is correct. (Measure the input signal level.)
- Check that *Pr.1*, *Pr.2*, Calibration parameter *C2* to *C7* settings are correct
- Check that the input signal lines are not affected by external noise. (Use shielded cables)
- Check that the load is not too heavy.
- Check that the *Pr. 31* to *Pr. 36* (frequency jump) settings are correct.

#### 4.6.6 Acceleration/deceleration is not smooth

- Check that the acceleration and deceleration time settings are not too short.
- Check that the load is not too heavy.

#### 4.6.7 Motor current is large

- Check that the load is not too heavy.
- Check that the *Pr.0 Torque boost* setting is correct.
- Check that the *Pr.3 Base frequency* setting is correct.
- Check that the *Pr.19 Base frequency voltage* is correct

#### 4.6.8 Speed does not increase

- Check that the maximum frequency (*Pr. 1*) setting is correct. (If you want to run the motor at 120Hz or more, set *Pr.18 High speed maximum frequency*. (Refer to page 67.)
- Check that the load is not too heavy. (In agitators, etc., load may become heavier in winter.)
- Check that the brake resistor is not connected to terminals P/+-P1 accidentally.

#### 4.6.9 Speed varies during operation

- 1) Inspection of load
  - Check that the load is not varying.
- 2) Check the input signals
  - Check that the frequency setting signal is not varying.
  - Check that the frequency setting signal is not affected by noise.
  - Check for a malfunction due to undesirable currents when the transistor output unit is connected. (Refer to page 21)
- 3) Others
  - Check that the wiring length is not too long for V/F control

#### 4.6.10 Operation panel (FR-DU07) display is not operating

- Check that the operation panel is connected to the inverter securely.

#### 4.6.11 Parameter write cannot be performed

- Make sure that operation is not being performed (signal STF or STR is not ON).
- Make sure that you are not attempting to set the parameter in the external operation mode.
- Check *Pr.77 Parameter write selection*.
- Check *Pr.161 Frequency setting/key lock operation selection*.

# MEMO

# 5 SPECIFICATIONS

This chapter provides the "SPECIFICATIONS" of this product.  
Always read the instructions before using the equipment

|     |                                  |     |
|-----|----------------------------------|-----|
| 5.1 | Rating .....                     | 250 |
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## 5.1 Rating

### •200V class

SLD is initially set.

| Type FR-F720-□□□□□-NA                                       |                                                  |     | 00046                                          | 00077        | 00105              | 00167        | 00250        | 00340         | 00490         | 00630         | 00770        | 00930        | 01250            | 01540        | 01870      | 02330      | 03160         | 03800       | 04750       |  |
|-------------------------------------------------------------|--------------------------------------------------|-----|------------------------------------------------|--------------|--------------------|--------------|--------------|---------------|---------------|---------------|--------------|--------------|------------------|--------------|------------|------------|---------------|-------------|-------------|--|
| Applied motor capacity (kW(HP)) <sup>*1</sup>               |                                                  | LD  | 0.75                                           | 1.5          | 2.2                | 3.7          | 5.5          | 7.5           | 11            | 15            | 18.5         | 22           | 30               | 37           | 45         | 55         | 75            | 90          | 110         |  |
|                                                             |                                                  | SLD | (1)                                            | (2)          | (3)                | (5)          | (7.5)        | (10)          | (15)          | (20)          | (25)         | (30)         | (40)             | (50)         | (60)       | (75)       | (100)         | (125)       | (150)       |  |
| Output                                                      | Rated capacity (kVA) <sup>*2</sup>               | LD  | 1.6                                            | 2.7          | 3.7                | 5.8          | 8.8          | 11.8          | 17.1          | 22.1          | 27           | 32           | 43               | 53           | 65         | 81         | 110           | 132         | 165         |  |
|                                                             |                                                  | SLD |                                                |              |                    |              |              |               |               |               |              |              |                  |              |            |            |               |             |             |  |
|                                                             | Rated current (A) <sup>*3</sup>                  | LD  | 4.2                                            | 7            | 9.6                | 15.2         | 23           | 31            | 45            | 58            | 70           | 85           | 114              | 140          | 170        | 212        | 288           | 346         | 432         |  |
|                                                             |                                                  | SLD | (3.6)                                          | (6.0)        | (8.2)              | (12.9)       | (20)         | (26)          | (38)          | (49)          | (60)         | (72)         | (97)             | (119)        | (145)      | (180)      | (244)         | (294)       | (367)       |  |
|                                                             | Overload current rating <sup>*4</sup>            | LD  | 4.6                                            | 7.7          | 10.5               | 16.7         | 25           | 34            | 49            | 63            | 77           | 93           | 125              | 154          | 187        | 233        | 316           | 380         | 475         |  |
|                                                             |                                                  | SLD | (3.9)                                          | (6.5)        | (8.9)              | (14.2)       | (21)         | (29)          | (42)          | (54)          | (65)         | (79)         | (106)            | (131)        | (159)      | (198)      | (268)         | (323)       | (403)       |  |
|                                                             | Voltage <sup>*5</sup>                            |     | Three-phase 200 to 240V                        |              |                    |              |              |               |               |               |              |              |                  |              |            |            |               |             |             |  |
| Power supply                                                | Rated input AC voltage/frequency                 |     | Three-phase 200 to 220V 50Hz, 200 to 240V 60Hz |              |                    |              |              |               |               |               |              |              |                  |              |            |            |               |             |             |  |
|                                                             | Permissible AC voltage fluctuation               |     | 170 to 242V 50Hz, 170 to 264V 60Hz             |              |                    |              |              |               |               |               |              |              |                  |              |            |            |               |             |             |  |
|                                                             | Permissible frequency fluctuation                |     | ±5%                                            |              |                    |              |              |               |               |               |              |              |                  |              |            |            |               |             |             |  |
|                                                             | Power supply system capacity (kVA) <sup>*6</sup> |     | 2.5                                            | 4.5          | 5.5                | 9            | 12           | 17            | 20            | 28            | 34           | 41           | 52               | 65           | 79         | 99         | 110           | 132         | 165         |  |
| Protective structure (JEM 1030(NEMA250-1997)) <sup>*8</sup> |                                                  |     | Enclosed type (IP20 NEMA1) <sup>*7</sup>       |              |                    |              |              |               |               |               |              |              | Open type (IP00) |              |            |            |               |             |             |  |
| Cooling system                                              |                                                  |     | Self-cooling                                   |              | Forced air cooling |              |              |               |               |               |              |              |                  |              |            |            |               |             |             |  |
| Approx. mass (kg (lbs))                                     |                                                  |     | 1.9<br>(4.1)                                   | 2.3<br>(5.0) | 3.6<br>(7.9)       | 3.6<br>(7.9) | 3.6<br>(7.9) | 6.6<br>(14.5) | 6.6<br>(14.5) | 7.6<br>(16.7) | 13<br>(28.6) | 13<br>(28.6) | 14<br>(30.8)     | 23<br>(50.6) | 35<br>(77) | 35<br>(77) | 67<br>(147.4) | 70<br>(154) | 70<br>(154) |  |

\*1 The applied motor capacity indicated is the maximum capacity applicable for use of the Mitsubishi 4-pole standard motor.

\*2 The rated output capacity indicated assumes that the output voltage is 220V.

\*3 When operating the inverter with the carrier frequency set to 3kHz or more, the carrier frequency automatically decreases if the inverter output current exceeds the value in parenthesis of the rated current. This may cause the motor noise to increase.

\*4 The % value of the overload current rating indicated is the ratio of the overload current to the inverter's rated output current. For repeated duty, allow time for the inverter and motor to return to or below the temperatures under 100% load.

\*5 The maximum output voltage does not exceed the power supply voltage. The maximum output voltage can be changed within the setting range. However, the pulse voltage value of the inverter output side voltage remains unchanged at about  $\sqrt{2}$  that of the power supply.

\*6 The power supply capacity varies with the value of the power supply side inverter impedance (including those of the input reactor and cables).

\*7 When the hook of the inverter front cover is cut off for installation of the plug-in option, the inverter changes to an open type (the structure is no longer NEMA1).

\*8 FR-DU07: IP40 (except for the PU connector)

# •400V class

SLD is initially set.

| Type FR-F740-□□□□□-NA                                       |                                                  | 00023                                    | 00038                                                          | 00052 | 00083              | 00126 | 00170  | 00250  | 00310  | 00380  | 00470  | 00620  | 00770            | 00930  | 01160  |      |
|-------------------------------------------------------------|--------------------------------------------------|------------------------------------------|----------------------------------------------------------------|-------|--------------------|-------|--------|--------|--------|--------|--------|--------|------------------|--------|--------|------|
| Applied motor capacity (kW(HP)) <sup>*1</sup>               |                                                  | LD                                       | 0.75                                                           | 1.5   | 2.2                | 3.7   | 5.5    | 7.5    | 11     | 15     | 18.5   | 22     | 30               | 37     | 45     | 55   |
|                                                             |                                                  | SLD                                      | (1)                                                            | (2)   | (3)                | (5)   | (7.5)  | (10)   | (15)   | (20)   | (25)   | (30)   | (40)             | (50)   | (60)   | (75) |
| Output                                                      | Rated capacity (kVA) <sup>*2</sup>               | LD                                       | 1.6                                                            | 2.7   | 3.7                | 5.8   | 8.8    | 12.2   | 17.5   | 22.1   | 26.7   | 32.8   | 43.4             | 53.3   | 64.8   | 80.8 |
|                                                             |                                                  | SLD                                      |                                                                |       |                    |       |        |        |        |        |        |        |                  |        |        |      |
|                                                             | Rated current (A) <sup>*3</sup>                  | LD                                       | 2.1                                                            | 3.5   | 4.8                | 7.6   | 11.5   | 16     | 23     | 29     | 35     | 43     | 57               | 70     | 85     | 106  |
|                                                             |                                                  | SLD                                      | (1.8)                                                          | (3.0) | (4.1)              | (6.5) | (9.8)  | (13.6) | (20)   | (25)   | (30)   | (37)   | (48)             | (60)   | (72)   | (90) |
|                                                             | Overload current rating <sup>*4</sup>            | LD                                       | 120% 60s, 150% 3s, 50°C (122°F) (inverse time characteristics) |       |                    |       |        |        |        |        |        |        |                  |        |        |      |
|                                                             |                                                  | SLD                                      | 110% 60s, 120% 3s, 40°C (104°F) (inverse time characteristics) |       |                    |       |        |        |        |        |        |        |                  |        |        |      |
|                                                             | Voltage <sup>*5</sup>                            |                                          | Three-phase 380 to 480V                                        |       |                    |       |        |        |        |        |        |        |                  |        |        |      |
| Power supply                                                | Rated input AC voltage/frequency                 | Three-phase 380 to 480V 50Hz/60Hz        |                                                                |       |                    |       |        |        |        |        |        |        |                  |        |        |      |
|                                                             | Permissible AC voltage fluctuation               | 323 to 528V 50Hz/60Hz                    |                                                                |       |                    |       |        |        |        |        |        |        |                  |        |        |      |
|                                                             | Permissible frequency fluctuation                | ±5%                                      |                                                                |       |                    |       |        |        |        |        |        |        |                  |        |        |      |
|                                                             | Power supply system capacity (kVA) <sup>*6</sup> | 2.5                                      | 4.5                                                            | 5.5   | 9                  | 12    | 17     | 20     | 28     | 34     | 41     | 52     | 66               | 80     | 100    |      |
| Protective structure (JEM 1030(NEMA250-1997)) <sup>*8</sup> |                                                  | Enclosed type (IP20 NEMA1) <sup>*7</sup> |                                                                |       |                    |       |        |        |        |        |        |        | Open type (IP00) |        |        |      |
| Cooling system                                              |                                                  | Self-cooling                             |                                                                |       | Forced air cooling |       |        |        |        |        |        |        |                  |        |        |      |
| Approx. mass (kg (lbs))                                     |                                                  | 3.6                                      | 3.6                                                            | 3.6   | 3.6                | 3.6   | 6.6    | 6.6    | 7.6    | 7.6    | 13     | 13     | 23               | 35     | 35     |      |
|                                                             |                                                  | (7.9)                                    | (7.9)                                                          | (7.9) | (7.9)              | (7.9) | (14.5) | (14.5) | (16.7) | (16.7) | (28.7) | (28.7) | (50.7)           | (77.2) | (77.2) |      |

| Type FR-F740-□□□□□-NA                                          |                                                     | 01800              | 02160                                                          | 02600         | 03250         | 03610         | 04320        | 04810        | 05470        | 06100        | 06830        | 07700        | 08660        | 09620        | 10940        | 12120         |                |
|----------------------------------------------------------------|-----------------------------------------------------|--------------------|----------------------------------------------------------------|---------------|---------------|---------------|--------------|--------------|--------------|--------------|--------------|--------------|--------------|--------------|--------------|---------------|----------------|
| Applied motor capacity<br>(kW(HP)) <sup>*1</sup>               |                                                     | LD                 | 75<br>(100)                                                    | 90<br>(150)   | 110<br>(150)  | 132<br>(200)  | 160<br>(250) | 185<br>(300) | 220<br>(350) | 250<br>(400) | 280<br>(450) | 315<br>(500) | 355<br>(550) | 400<br>(600) | 450<br>(700) | 500<br>(750)  | 560<br>(800)   |
|                                                                |                                                     | SLD                | 90<br>(150)                                                    | 110<br>(150)  | 132<br>(200)  | 160<br>(250)  | 185<br>(300) | 220<br>(350) | 250<br>(400) | 280<br>(450) | 315<br>(500) | 355<br>(550) | 400<br>(600) | 450<br>(700) | 500<br>(750) | 560<br>(800)  | 630<br>(850)   |
| Output                                                         | Rated capacity<br>(kVA) <sup>*2</sup>               | LD                 | 110                                                            | 137           | 165           | 198           | 247          | 275          | 329          | 366          | 416          | 464          | 520          | 586          | 659          | 733           | 833            |
|                                                                |                                                     | SLD                | 137                                                            | 165           | 198           | 247           | 275          | 329          | 366          | 416          | 464          | 520          | 586          | 659          | 733          | 833           | 923            |
|                                                                | Rated current (A) <sup>*3</sup>                     | LD                 | 144<br>(122)                                                   | 180<br>(153)  | 216<br>(184)  | 260<br>(221)  | 325<br>(276) | 361<br>(306) | 432<br>(367) | 481<br>(408) | 547<br>(464) | 610<br>(518) | 683<br>(580) | 770<br>(654) | 866<br>(736) | 962<br>(817)  | 1094<br>(929)  |
|                                                                |                                                     | SLD                | 180<br>(153)                                                   | 216<br>(184)  | 260<br>(221)  | 325<br>(276)  | 361<br>(306) | 432<br>(367) | 481<br>(408) | 547<br>(464) | 610<br>(518) | 683<br>(580) | 770<br>(654) | 866<br>(736) | 962<br>(817) | 1094<br>(929) | 1212<br>(1030) |
|                                                                | Overload current<br>rating <sup>*4</sup>            | LD                 | 120% 60s, 150% 3s, 50°C (122°F) (inverse time characteristics) |               |               |               |              |              |              |              |              |              |              |              |              |               |                |
|                                                                |                                                     | SLD                | 110% 60s, 120% 3s, 40°C (104°F) (inverse time characteristics) |               |               |               |              |              |              |              |              |              |              |              |              |               |                |
|                                                                | Voltage <sup>*5</sup>                               |                    | Three-phase 380 to 480V                                        |               |               |               |              |              |              |              |              |              |              |              |              |               |                |
| Power supply                                                   | Rated input AC voltage/frequency                    |                    | Three-phase 380 to 480V 50Hz/60Hz                              |               |               |               |              |              |              |              |              |              |              |              |              |               |                |
|                                                                | Permissible AC voltage fluctuation                  |                    | 323 to 528V 50Hz/60Hz                                          |               |               |               |              |              |              |              |              |              |              |              |              |               |                |
|                                                                | Permissible frequency<br>fluctuation                |                    | ±5%                                                            |               |               |               |              |              |              |              |              |              |              |              |              |               |                |
|                                                                | Power supply system<br>capacity (kVA) <sup>*6</sup> | LD                 | 110                                                            | 137           | 165           | 198           | 247          | 275          | 329          | 366          | 416          | 464          | 520          | 586          | 659          | 733           | 833            |
|                                                                |                                                     | SLD                | 137                                                            | 165           | 198           | 247           | 275          | 329          | 366          | 416          | 464          | 520          | 586          | 659          | 733          | 833           | 923            |
| Protective structure<br>(JEM 1030(NEMA250-1997)) <sup>*8</sup> |                                                     | Open type (IP00)   |                                                                |               |               |               |              |              |              |              |              |              |              |              |              |               |                |
| Cooling system                                                 |                                                     | Forced air cooling |                                                                |               |               |               |              |              |              |              |              |              |              |              |              |               |                |
| Approx. mass (kg (lbs))                                        |                                                     | 37<br>(81.6)       | 50<br>(110.2)                                                  | 57<br>(125.4) | 72<br>(158.4) | 72<br>(158.4) | 110<br>(242) | 110<br>(242) | 220<br>(484) | 220<br>(484) | 220<br>(484) | 260<br>(572) | 260<br>(572) | 370<br>(814) | 370<br>(814) | 370<br>(814)  |                |

\*1 The applied motor capacity indicated is the maximum capacity applicable for use of the Mitsubishi 4-pole standard motor.

\*2 The rated output capacity indicated assumes that the output voltage is 440V.

\*3 When operating the inverter with the carrier frequency set to 3kHz or more, the carrier frequency automatically decreases if the inverter output current exceeds the value in parenthesis of the rated current. This may cause the motor noise to increase.

\*4 The % value of the overload current rating indicated is the ratio of the overload current to the inverter's rated output current. For repeated duty, allow time for the inverter and motor to return to or below the temperatures under 100% load.

\*5 The maximum output voltage does not exceed the power supply voltage. The maximum output voltage can be changed within the setting range. However, the pulse voltage value of the inverter output side voltage remains unchanged at about  $\sqrt{2}$  that of the power supply.

\*6 The power supply capacity varies with the value of the power supply side inverter impedance (including those of the input reactor and cables).

\*7 When the hook of the inverter front cover is cut off for installation of the plug-in option, the inverter changes to an open type (the structure is no longer NEMA1).

\*8 FR-DU07: IP40 (except for the PU connector)



## 5.2 Common specifications

|                                  |                                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
|----------------------------------|----------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Control specifications           | Control system                         |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | High carrier frequency PWM control (V/F control)/optimum excitation control/simple magnetic flux vector control                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
|                                  | Output frequency range                 |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | 0.5 to 400Hz                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
|                                  | Frequency setting resolution           | Analog input                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           | 0.015Hz/0 to 60Hz (terminal 2, 4: 0 to 10V/12bit)<br>0.03Hz/0 to 60Hz (terminal 2, 4: 0 to 5V/11bit, 0 to 20mA/11bit, terminal 1: -10V to +10V/11bit)<br>0.06Hz/0 to 60Hz (terminal 1: 0 to ±5V/10bit)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
|                                  |                                        | Digital input                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          | 0.01Hz                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
|                                  | Frequency accuracy                     | Analog input                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           | Within ±0.2% of the max. output frequency (25°C ± 10°C (77°F ± 50°F))                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
|                                  |                                        | Digital input                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          | Within 0.01% of the set output frequency                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
|                                  | Voltage/frequency characteristics      |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | 0 to 400Hz of the base frequency can be set from constant torque/adjustable 5 points V/F can be selected.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
|                                  | Starting torque                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | 120% (3Hz) when simple magnetic flux vector control and slip compensation are set                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
|                                  | Acceleration/deceleration time setting |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | 0 to 3600s (acceleration and deceleration can be set individually), linear or S-pattern acceleration/deceleration mode can be selected.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
|                                  | DC injection brake                     |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | Operation frequency (0 to 120Hz), operation time (0 to 10s), operation voltage (0 to 30%) variable                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
| Stall prevention operation level |                                        | Operation current level can be set (0 to 150% variable), whether to use the function or not can be set.                                                                                                                                                                                                                                                                                                                                                                                                                                                                |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
| Operation specifications         | Frequency setting signal               | Analog input                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           | Terminal 2, 4: 0 to 10V, 0 to 5V, 4 to 20mA can be selected<br>Terminal 1: -10 to +10V, -5 to 5V can be selected                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
|                                  |                                        | Digital input                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          | Four-digit BCD or 16-bit binary using the setting dial of the operation panel or parameter unit (when used with the option FR-A7AX)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
|                                  | Start signal                           |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | Available individually for forward rotation and reverse rotation. Start signal automatic self-holding input (3-wire input) can be selected.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
|                                  | Input signals                          |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | You can select any twelve signals using <i>Pr.178 to Pr.189 (input terminal function selection)</i> from among multi speed selection, second function selection, terminal 4 input selection, JOG operation selection, selection of automatic restart after instantaneous power failure, external thermal relay input, HC connection (inverter operation enable signal), HC connection (instantaneous power failure detection), PU operation/external interlock signal, External DC injection brake operation start, PID control enable terminal, PU operation, external operation switchover, output stop, start self-holding selection, forward rotation command, reverse rotation command, inverter reset, PTC thermistor input, PID forward reverse operation switchover, PU-NET operation switchover, External-NET operation switchover, command source switchover. |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
|                                  | Operational functions                  |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | Maximum and minimum frequency settings, frequency jump operation, external thermal relay input selection, polarity reversible operation, automatic restart after instantaneous power failure operation, original operation continuation at an instantaneous power failure, commercial power supply-inverter switchover operation, forward/reverse rotation prevention, operation mode selection, external DC injection braking start, PID control, computer link operation (RS-485).                                                                                                                                                                                                                                                                                                                                                                                    |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
|                                  | Output signals                         | Operating status                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | You can select any seven signals using <i>Pr.190 to Pr.196 (output terminal function selection)</i> from among inverter running, up-to-speed, instantaneous power failure /undervoltage, overload warning, output frequency detection, second output frequency detection, regenerative brake prealarm <sup>4</sup> , electronic thermal relay function pre-alarm, PU operation mode, inverter operation ready, output current detection, zero current detection, PID lower limit, PID upper limit, PID forward rotation reverse rotation output, commercial power supply-inverter switchover MC1 to MC3, commercial power supply side moter 1 to 4 connection, inverter side moter 1 to 4 connection, fan fault output, heatsink overheat pre-alarm, inverter running start command on, deceleration at an instantaneous power failure, PID control activated, during retry, during PID output suspension, life alarm, alarm output 3 (power-off signal), power savings average value update timing, current average monitor, alarm output 2, maintenance timer alarm, remote output, minor failure output, alarm output. Open collector output (5 points), relay output (2 points) and alarm code of the inverter can be output (4 bit) from the open collector. |
|                                  |                                        | When used with the FR-A7AY, FR-A7AR (option)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | You can select any seven signals using <i>Pr.313 to Pr. 319 (extension output terminal function selection)</i> from among control circuit capacitor life, main circuit capacitor life, cooling fan life, inrush current limit circuit life. (Only positive logic can be set for extension terminals of the FR-A7AR)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |
| Pulse/analog output              |                                        | Selection can be made from output frequency, motor current (steady or peak value), output voltage, frequency setting value, running speed, converter output voltage (steady or peak value), electronic thermal relay function load factor, input power, output power, load meter, reference voltage output, motor load factor, power saving effect, regenerative brake duty <sup>4</sup> , PID set value, PID measured value using <i>Pr.54 CA terminal function selection (pulse train output)</i> and <i>Pr.158 AM terminal function selection (analog output)</i> . |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |

|                             |                                   |                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
|-----------------------------|-----------------------------------|-----------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Display                     | PU<br>(FR-DU07/<br>FR-PU04)       | Operating status      | Output frequency, motor current (steady or peak value), output voltage, alarm indication, frequency setting, running speed, converter output voltage (steady or peak value), electronic thermal relay function load factor, input power, output power, load meter, cumulative energization time, actual operation time, motor load factor, cumulative power, power saving effect, cumulative saving power, regenerative brake duty <sup>*4</sup> , PID set point, PID measured value, PID deviation value, inverter I/O terminal monitor, input terminal option monitor <sup>*1</sup> , output terminal option monitor <sup>*1</sup> , option fitting status monitor <sup>*2</sup> , terminal assignment status <sup>*2</sup>                                                                                                                                                                                                                                                                                                                                                                                                                                     |
|                             |                                   | Alarm definition      | Alarm definition is displayed during the protective function is activated, output voltage/ current/frequency/cumulative energization time and eight past alarm definition is stored.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |
|                             |                                   | Interactive guidance  | Operation guide/trouble shooting with a help function <sup>*2</sup>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |
| Protective/warning function |                                   |                       | Overcurrent during acceleration, overcurrent during constant speed, overcurrent during deceleration, overvoltage during acceleration, overvoltage during constant speed, overvoltage during deceleration, inverter protection thermal operation, motor protection thermal operation, heatsink overheat, instantaneous power failure occurrence, undervoltage, input phase failure, motor overload, output side ground fault overcurrent, output phase failure, external thermal relay operation, PTC thermistor operation, option alarm, parameter error, PU disconnection, retry count excess, CPU alarm, operation panel power supply short circuit, 24VDC power output short circuit, output current detection value excess, inrush resistance overheat, communication alarm (inverter), analog input alarm, internal circuit error (15V power supply), fan fault, overcurrent stall prevention, overvoltage stall prevention, electronic thermal relay function prealarm, PU stop, maintenance timer alarm <sup>*1</sup> , brake transistor alarm detection <sup>*4</sup> , parameter write error, copy operation error, operation panel lock, parameter copy |
| Environment                 | Ambient temperature               | LD                    | -10°C to +50°C(14°F to 122°F) (non-freezing)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |
|                             |                                   | SLD (initial setting) | -10°C to +40°C(14°F to 104°F) (non-freezing)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |
|                             | Ambient humidity                  |                       | 90%RH or less (non-condensing)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |
|                             | Storage temperature <sup>*3</sup> |                       | -20°C to +65°C (-4°F to +149°F)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
|                             | Atmosphere                        |                       | Indoors (without corrosive gas, flammable gas, oil mist, dust and dirt etc.)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |
|                             | Altitude, vibration               |                       | Maximum 1000m (3280.80 feet) above sea level for standard operation. After that derate by 3% for every extra 500m (1640.40 feet) up to 2500m (8202.10 feet) (92%) 5.9m/s <sup>2</sup> or less <sup>*5</sup> (conforming to JIS C 60068-2-6)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |

\*1 Can be displayed only on the operation panel (FR-DU07).

\*2 Can be displayed only on the parameter unit (FR-PU04).

\*3 Temperature applicable for a short period in transit, etc.

\*4 Only the FR-F720-03160 (FR-F740-01800) or more functions.

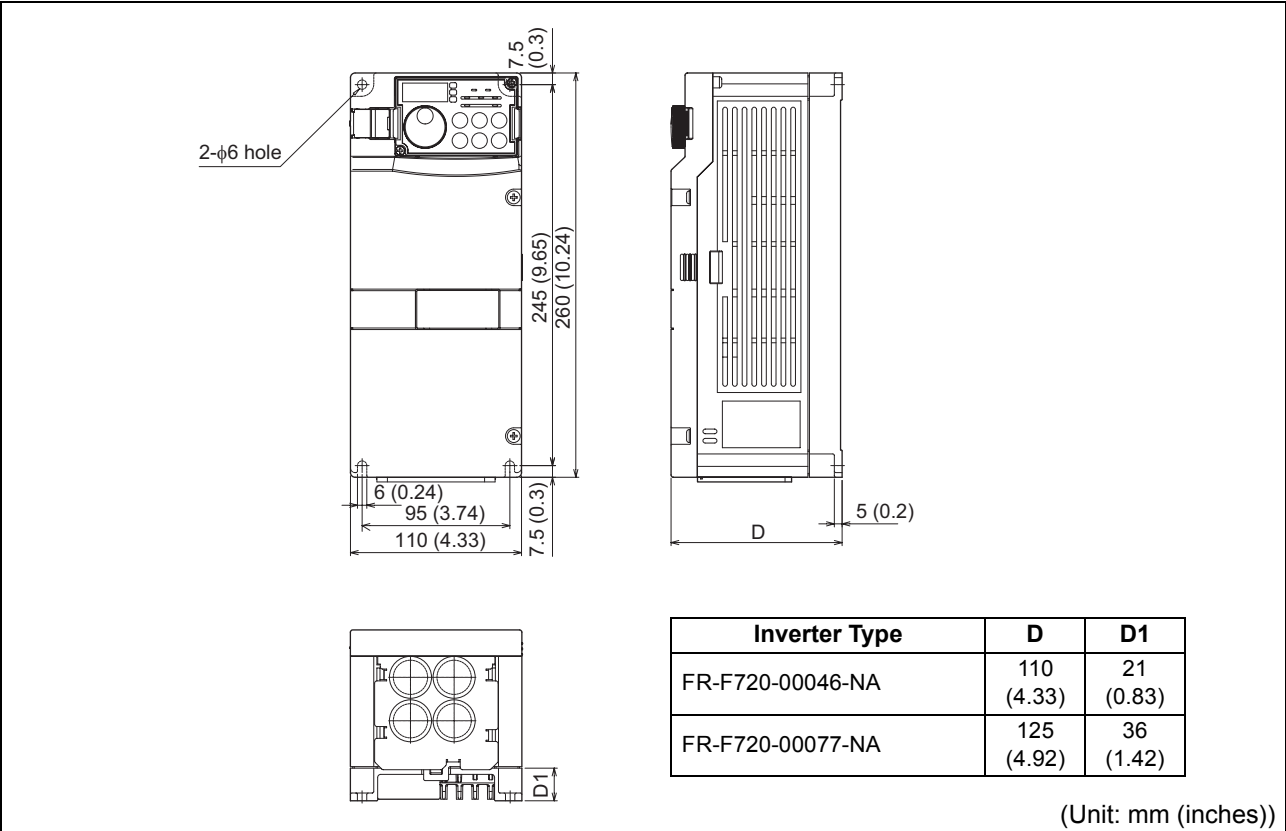
\*5 2.9m/s<sup>2</sup> or less for the FR-F740-04320 or more.



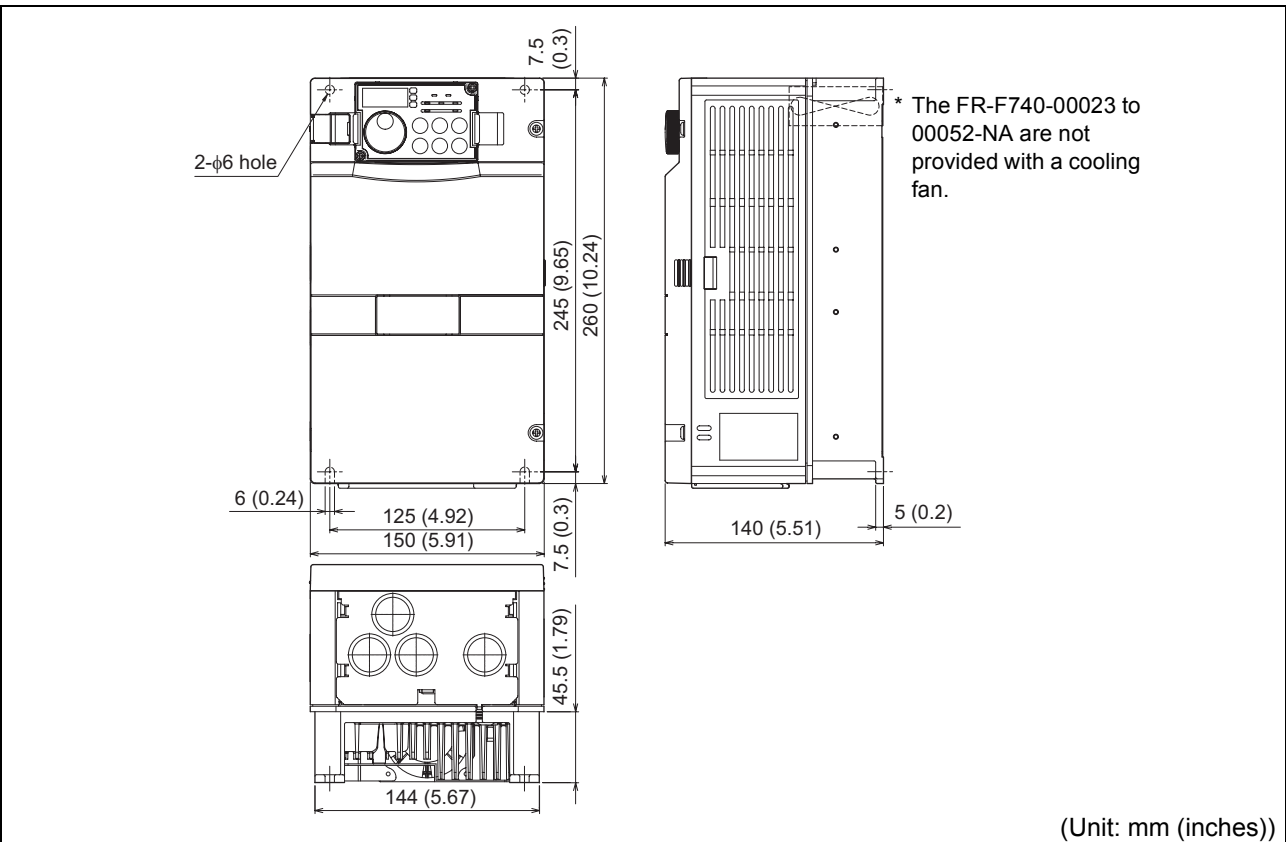
# 5.3 Outline dimension drawings

## 5.3.1 Inverter outline dimension drawings

- FR-F720-00046, 00077-NA

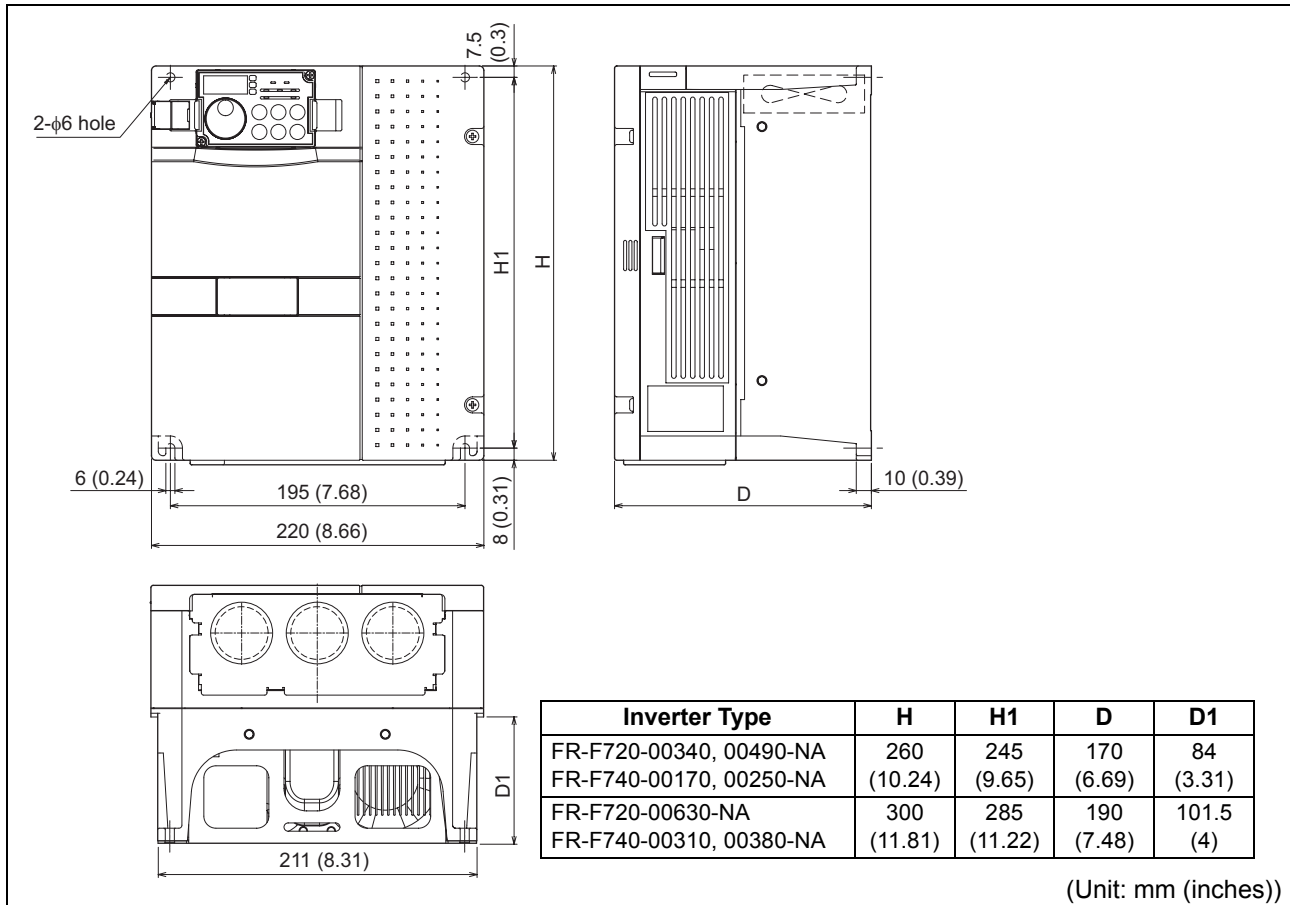


- FR-F720-00105, 00167, 00250-NA
- FR-F740-00023, 00038, 00052, 00083, 00126-NA

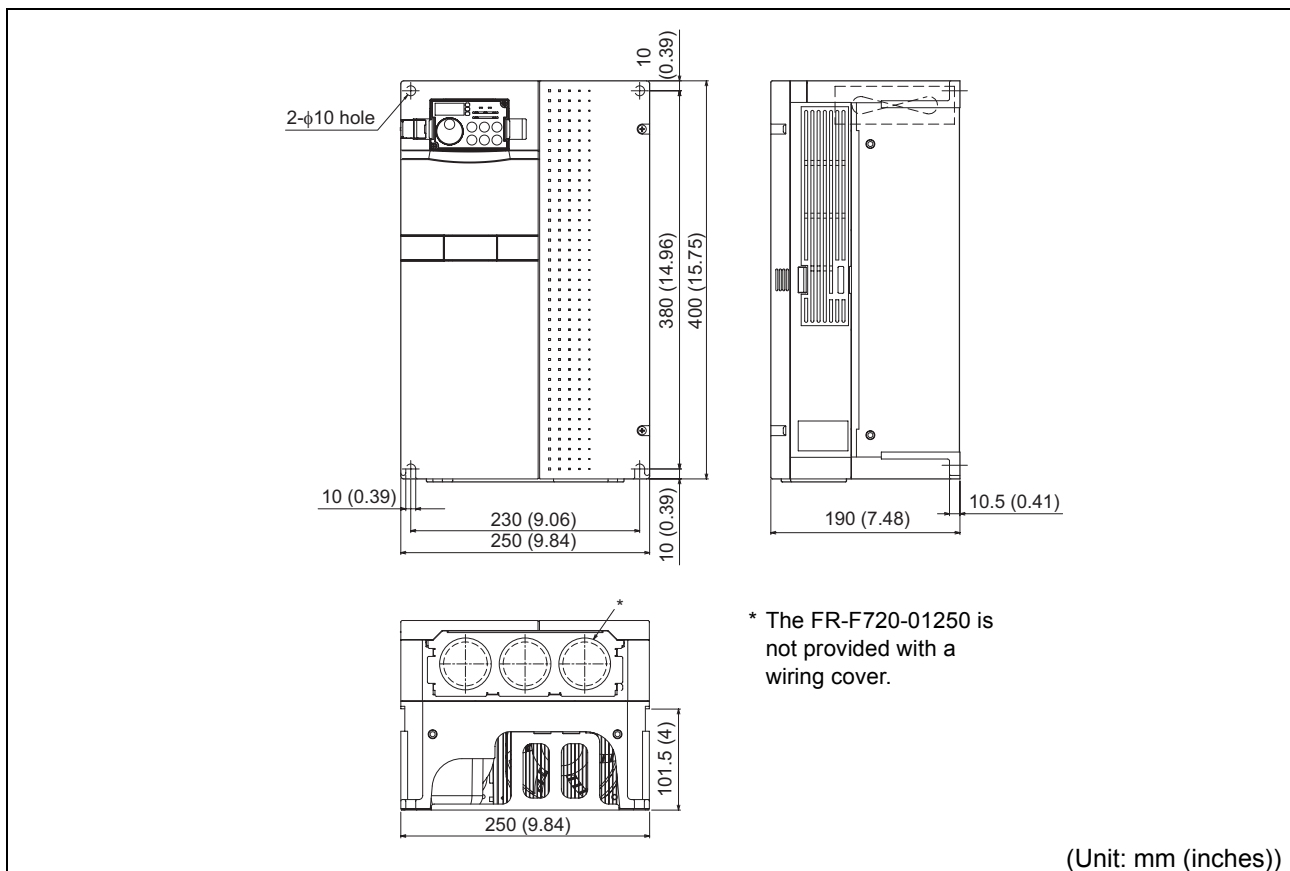




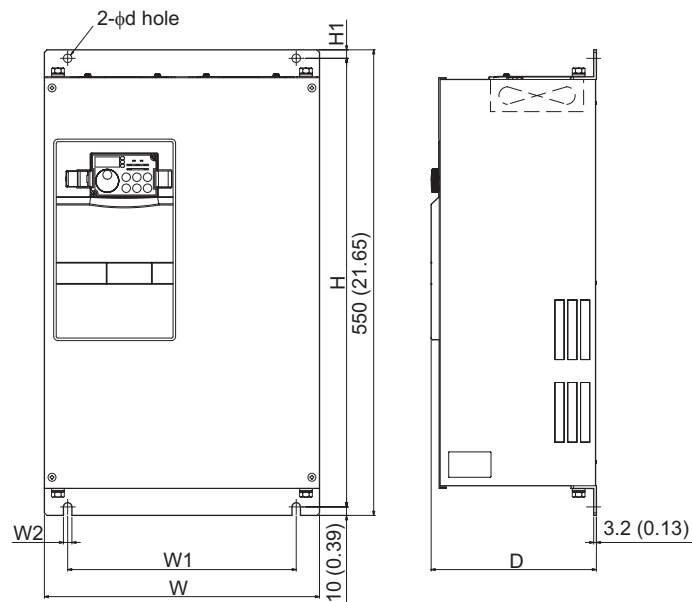
- FR-F720-00340, 00490, 00630-NA
- FR-F740-00170, 00250, 00310, 00380-NA



- FR-F720-00770, 00930, 01250-NA
- FR-F740-00470, 00620-NA



- FR-F720-01540, 01870, 02330-NA
- FR-F740-00770, 00930, 01160-NA

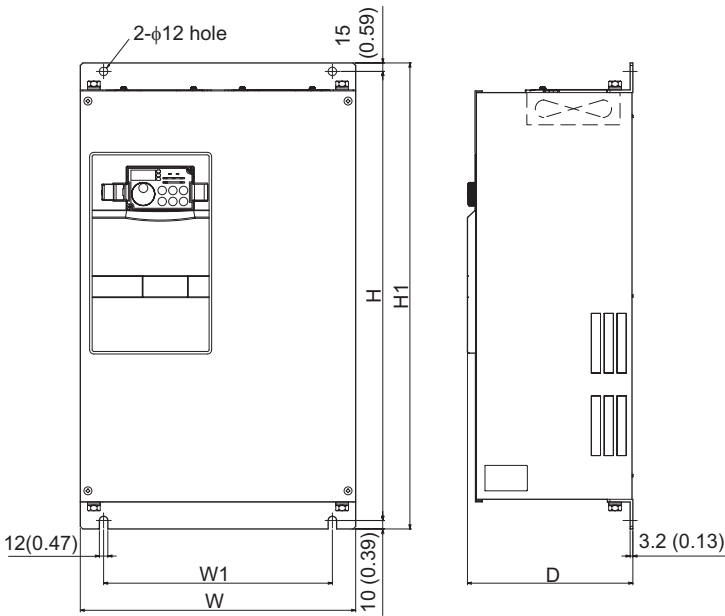


| Inverter Type                                      | W              | W1             | W2           | H              | H1           | d            | D             |
|----------------------------------------------------|----------------|----------------|--------------|----------------|--------------|--------------|---------------|
| FR-F720-01540-NA<br>FR-F740-00770-NA               | 325<br>(12.8)  | 270<br>(10.63) | 10<br>(0.39) | 530<br>(20.87) | 10<br>(0.39) | 10<br>(0.39) | 195<br>(7.68) |
| FR-F720-01870, 02330-NA<br>FR-F740-00930, 01160-NA | 435<br>(17.13) | 380<br>(14.96) | 12<br>(0.47) | 525<br>(20.67) | 15<br>(0.59) | 12<br>(0.47) | 250<br>(9.84) |

(Unit: mm (inches))



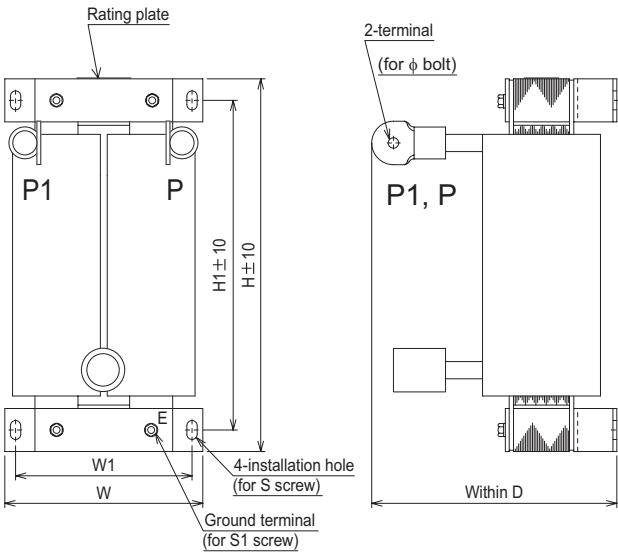
• FR-F740-01800-NA



| Inverter Type    | W              | W1             | H              | H1             | D             |
|------------------|----------------|----------------|----------------|----------------|---------------|
| FR-F740-01800-NA | 435<br>(17.13) | 380<br>(14.96) | 525<br>(20.67) | 550<br>(21.65) | 250<br>(9.84) |

(Unit: mm (inches))

• DC reactor supplied

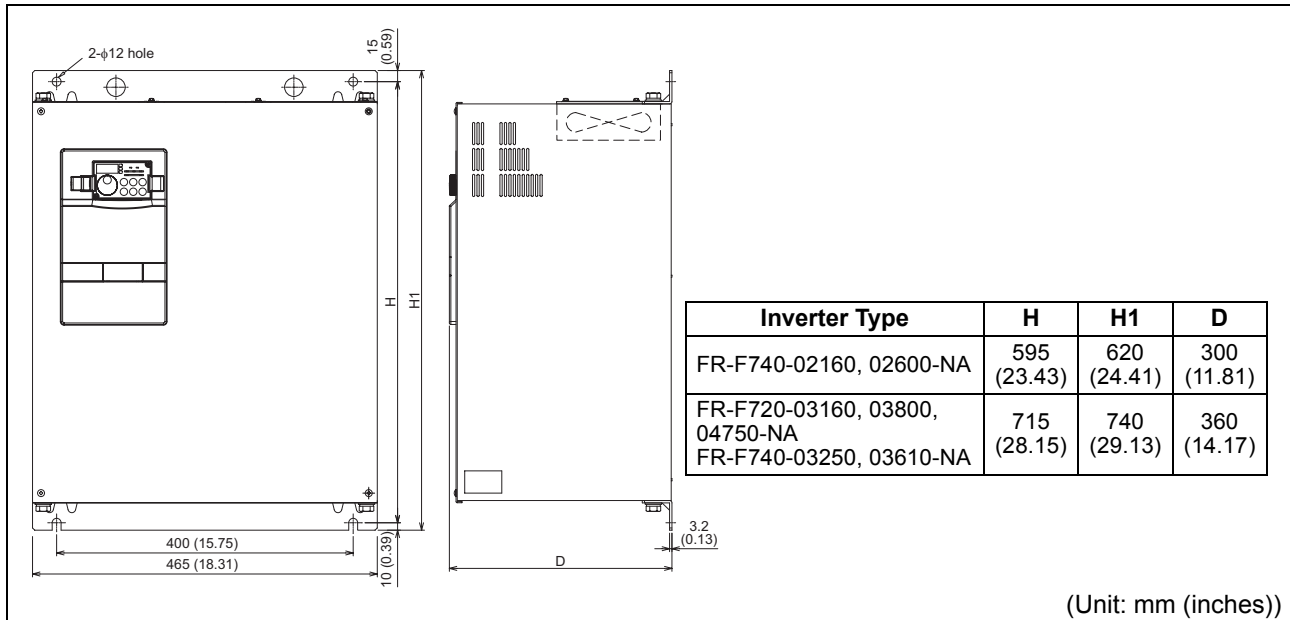


| Inverter Type                 | W             | W1            | H              | H1             | D             | S  | S1 | φ   | Mass<br>(kg(lbs)) |
|-------------------------------|---------------|---------------|----------------|----------------|---------------|----|----|-----|-------------------|
| FR-F740-01800-NA(FR-HEL-H90K) | 150<br>(5.91) | 130<br>(5.12) | 340<br>(13.39) | 310<br>(12.20) | 190<br>(7.48) | M6 | M6 | M12 | 20<br>(44)        |

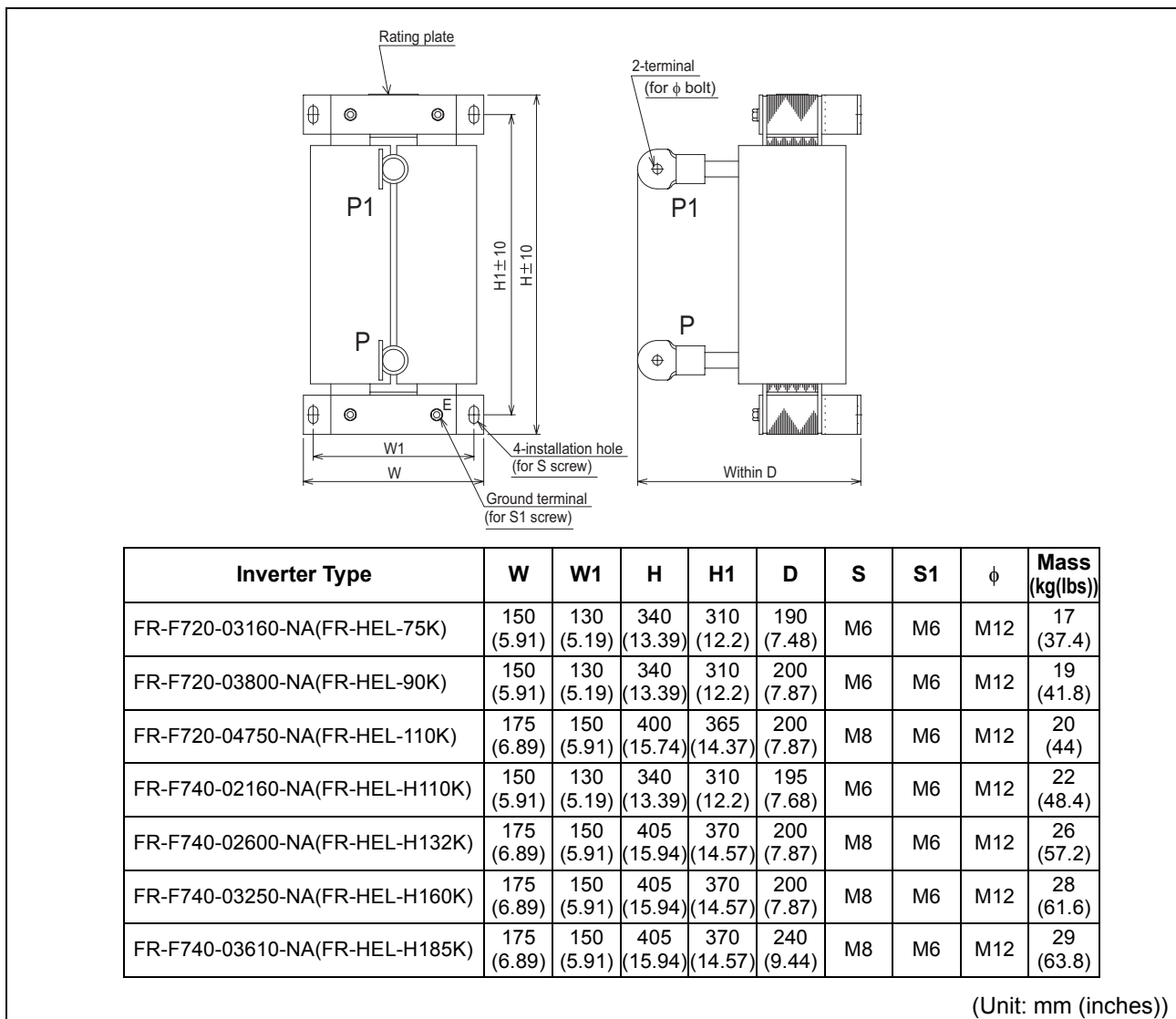
(Unit: mm (inches))



- FR-F720-03160, 03800, 04750-NA
- FR-F740-02160, 02600, 03250, 03610-NA

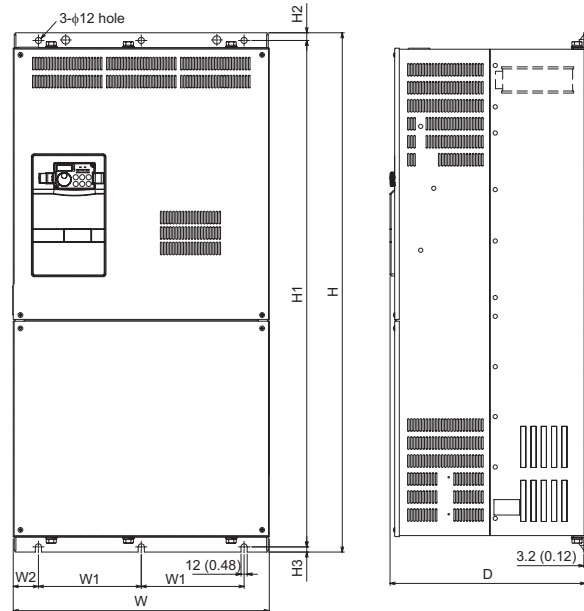


- DC reactor supplied





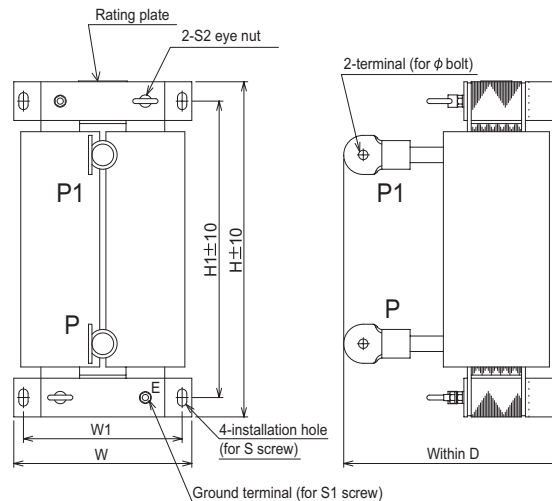
• FR-F740-04320, 04810, 05470, 06100, 06830-NA



| Inverter Type                  | W              | W1             | W2           | H               | H1             | H2           | H3           | D              |
|--------------------------------|----------------|----------------|--------------|-----------------|----------------|--------------|--------------|----------------|
| FR-F740-04320, 04810-NA        | 498<br>(19.6)  | 200<br>(7.87)  | 49<br>(1.92) | 1010<br>(39.76) | 985<br>(38.77) | 15<br>(0.59) | 10<br>(0.39) | 380<br>(14.96) |
| FR-F740-05470, 06100, 06830-NA | 680<br>(26.77) | 300<br>(11.81) | 40<br>(1.57) | 1010<br>(39.76) | 985<br>(38.77) | 15<br>(0.59) | 10<br>(0.39) | 380<br>(14.96) |

(Unit: mm (inches))

• DC reactor supplied



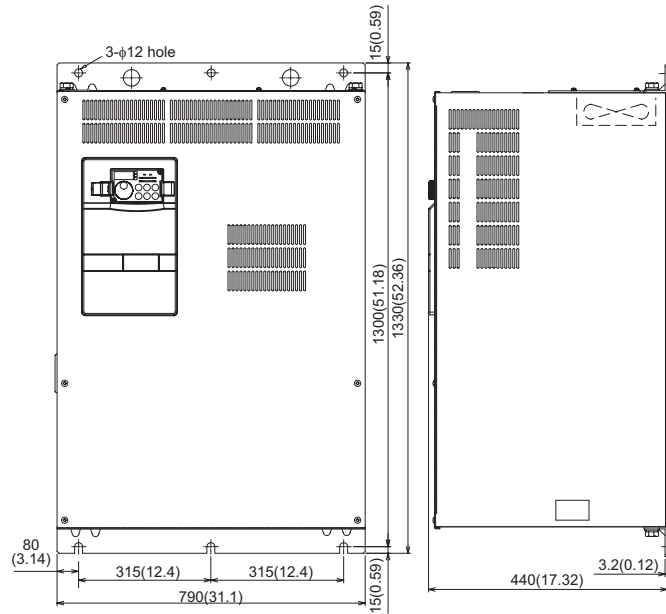
\* Remove the eye nut after installation of the product.

| Inverter Type                  | W             | W1            | H              | H1             | D              | S   | S1 | S2 | φ   | Mass<br>(kg(lbs)) |
|--------------------------------|---------------|---------------|----------------|----------------|----------------|-----|----|----|-----|-------------------|
| FR-F740-04320-NA(FR-HEL-H220K) | 175<br>(6.88) | 150<br>(5.9)  | 405<br>(15.94) | 370<br>(14.56) | 240<br>(9.44)  | M8  | M6 | M6 | M12 | 30<br>(66)        |
| FR-F740-04810-NA(FR-HEL-H250K) | 190<br>(7.48) | 165<br>(6.49) | 440<br>(17.32) | 400<br>(15.74) | 250<br>(9.84)  | M8  | M8 | M8 | M12 | 35<br>(77)        |
| FR-F740-05470-NA(FR-HEL-H280K) | 190<br>(7.48) | 165<br>(6.49) | 440<br>(17.32) | 400<br>(15.74) | 255<br>(10.03) | M8  | M8 | M8 | M16 | 38<br>(83.6)      |
| FR-F740-06100-NA(FR-HEL-H315K) | 210<br>(8.26) | 185<br>(7.28) | 495<br>(19.48) | 450<br>(17.71) | 250<br>(9.84)  | M10 | M8 | M8 | M16 | 42<br>(92.4)      |
| FR-F740-06830-NA(FR-HEL-H355K) | 210<br>(8.26) | 185<br>(7.28) | 495<br>(19.48) | 450<br>(17.71) | 250<br>(9.84)  | M10 | M8 | M8 | M16 | 46<br>(101.2)     |

(Unit: mm (inches))

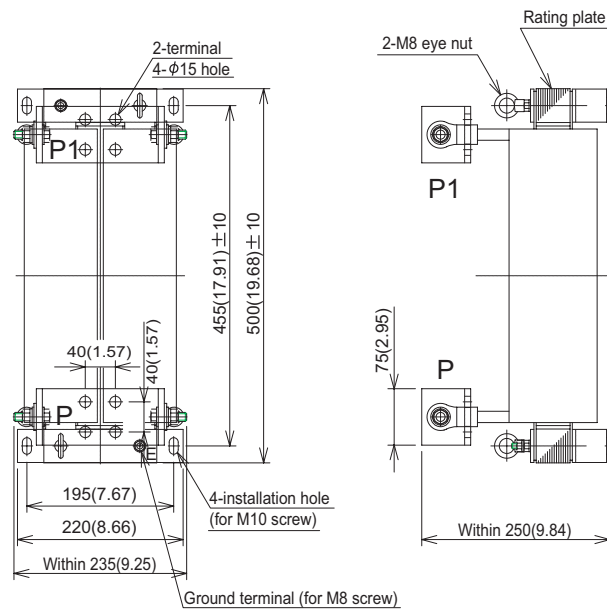


• FR-F740-07700, 08660-NA



(Unit: mm (inches))

• DC reactor supplied

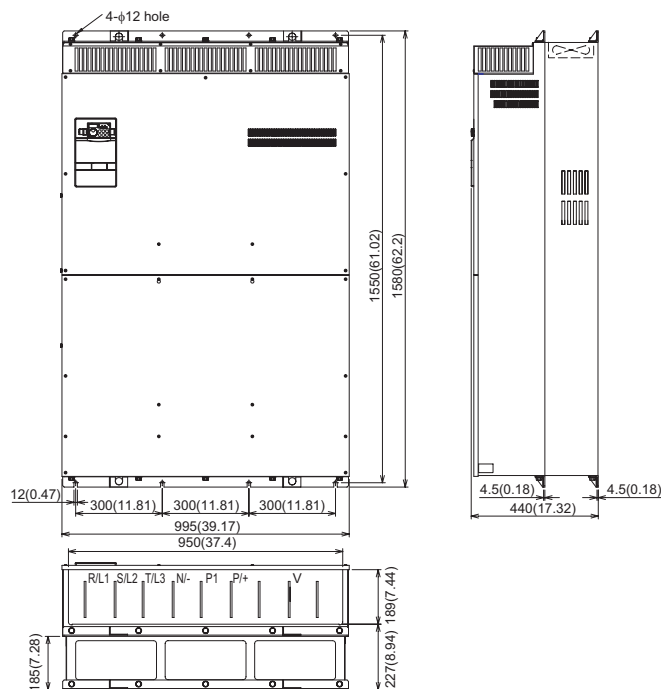


\* Remove the eye nut after installation of the product.

| Inverter Type                  | Mass<br>(kg(lbs)) |
|--------------------------------|-------------------|
| FR-F740-07700-NA(FR-HEL-H400K) | 50<br>(110)       |
| FR-F740-08660-NA(FR-HEL-H450K) | 57<br>(125.4)     |

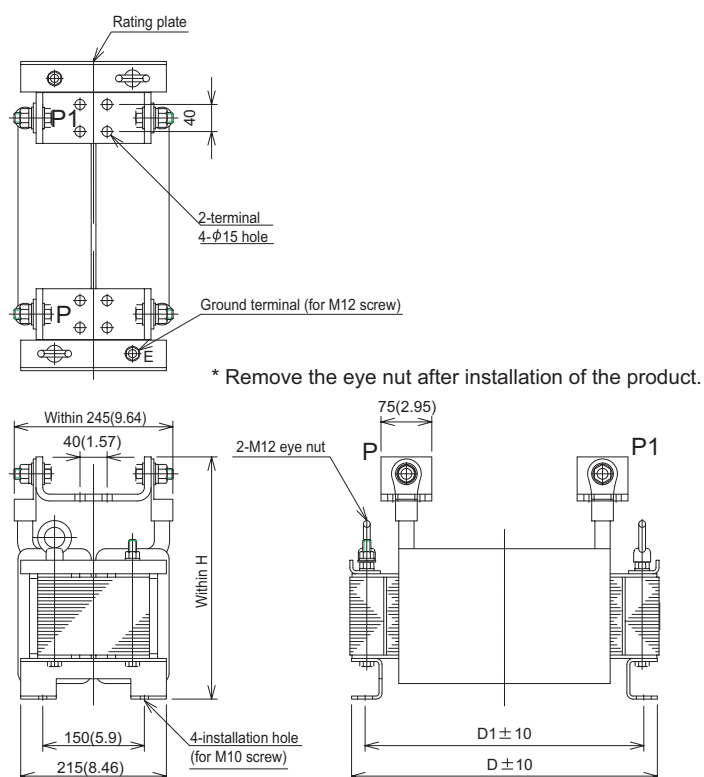
(Unit: mm (inches))

- **FR-F740-09620, 10940, 12120-NA**



(Unit: mm (inches))

- DC reactor supplied

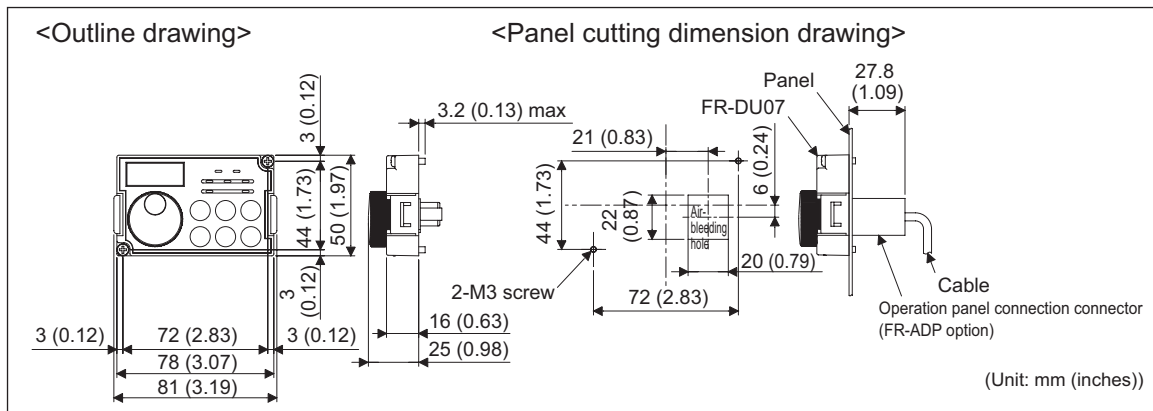


| Inverter Type                  | H              | D              | D1             | Mass<br>(kg)(lbs) |
|--------------------------------|----------------|----------------|----------------|-------------------|
| FR-F740-09620-NA(FR-HEL-H500K) | 345<br>(13.5)  | 455<br>(17.91) | 405<br>(15.94) | 67<br>(147.4)     |
| FR-F740-10940-NA(FR-HEL-H560K) | 360<br>(14.17) | 460<br>(18.11) | 410<br>(16.14) | 85<br>(187)       |
| FR-F740-12120-NA(FR-HEL-H630K) | 360<br>(14.17) | 460<br>(18.11) | 410<br>(16.14) | 95<br>(209)       |

(Unit: mm (inches))

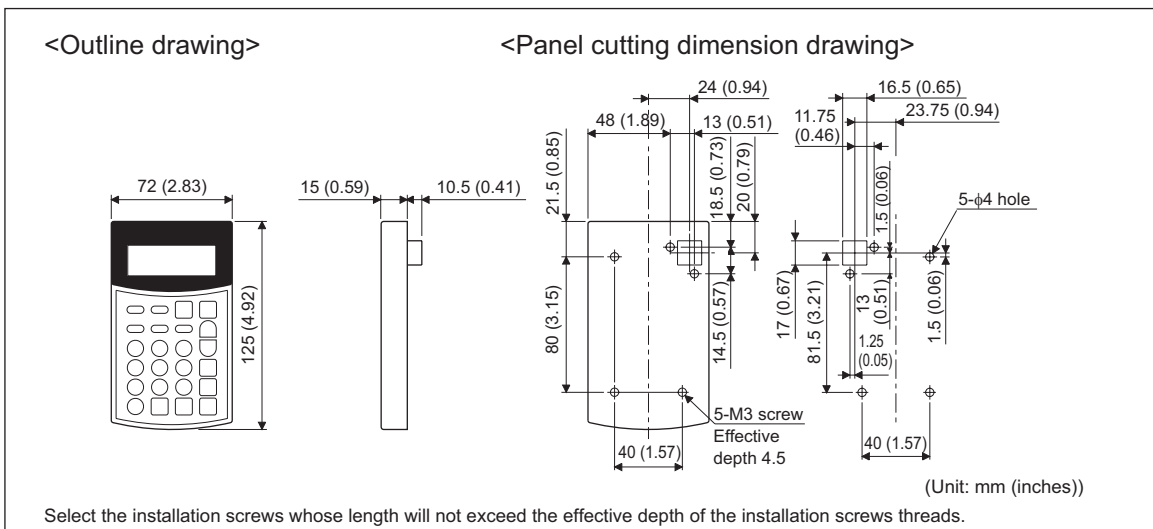


### 5.3.2 Operation panel (FR-DU07) outline dimension drawings



### 5.3.3 Parameter unit (FR-PU04) outline dimension drawings

#### • FR-PU04



REVISIONS

\*The manual number is given on the bottom left of the back cover.

| Print Date | *Manual Number      | Revision                                                                                                             |
|------------|---------------------|----------------------------------------------------------------------------------------------------------------------|
| Sep., 2004 | IB(NA)-0600217ENG-A | First edition                                                                                                        |
| Dec., 2004 | IB(NA)-0600217ENG-B | <div>Additions</div> <div><div>· FR-F720 - 03160 to 04750 - NA</div><div>· FR-F740 - 04320 to 12120 - NA</div></div> |
|            |                     |                                                                                                                      |